



# **SiD IR & MDI Status & Comments**

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ALCPG, Fermilab  
26 October 2007

A horizontal dotted line of small yellow-green dots is located at the bottom of the slide, mirroring the one at the top.



## IR Engineering Workshop

“Critical Issues from the IRENG’07 Workshop” at SLAC Sept. 17-21, 2007 were presented by Andrei Seryi on Wednesday evening.

- Most discussions at IRENG’07 regarding detectors concepts and Push-Pull / Surface-Assembly touched on
  - **Civil: Cavern & surface layout, cranes, services**
  - **Cryo: 2°K/4°K Refrigerators for QD0 & plumbing**
  - **Andrei discussed these**



# Interaction with the BDS Group

A number of IR design choices were made for the RDR which were not optimized from the SiD perspective

Major contributions of CERN civil group to layout/cavern/assembly/platform/access discussion beginning after LCWS'07 in preparation for IRENG'07 via detailed layout schematics motivated by LEP and LHC experience

Machine CFS group constantly asking for engineering details of detector when only concepts exist

Detector Engineering lags Machine Engineering

Fear growing that IR design decoupling from Si D and being driven by GLDc/LDC consortium



# Baseline IR design

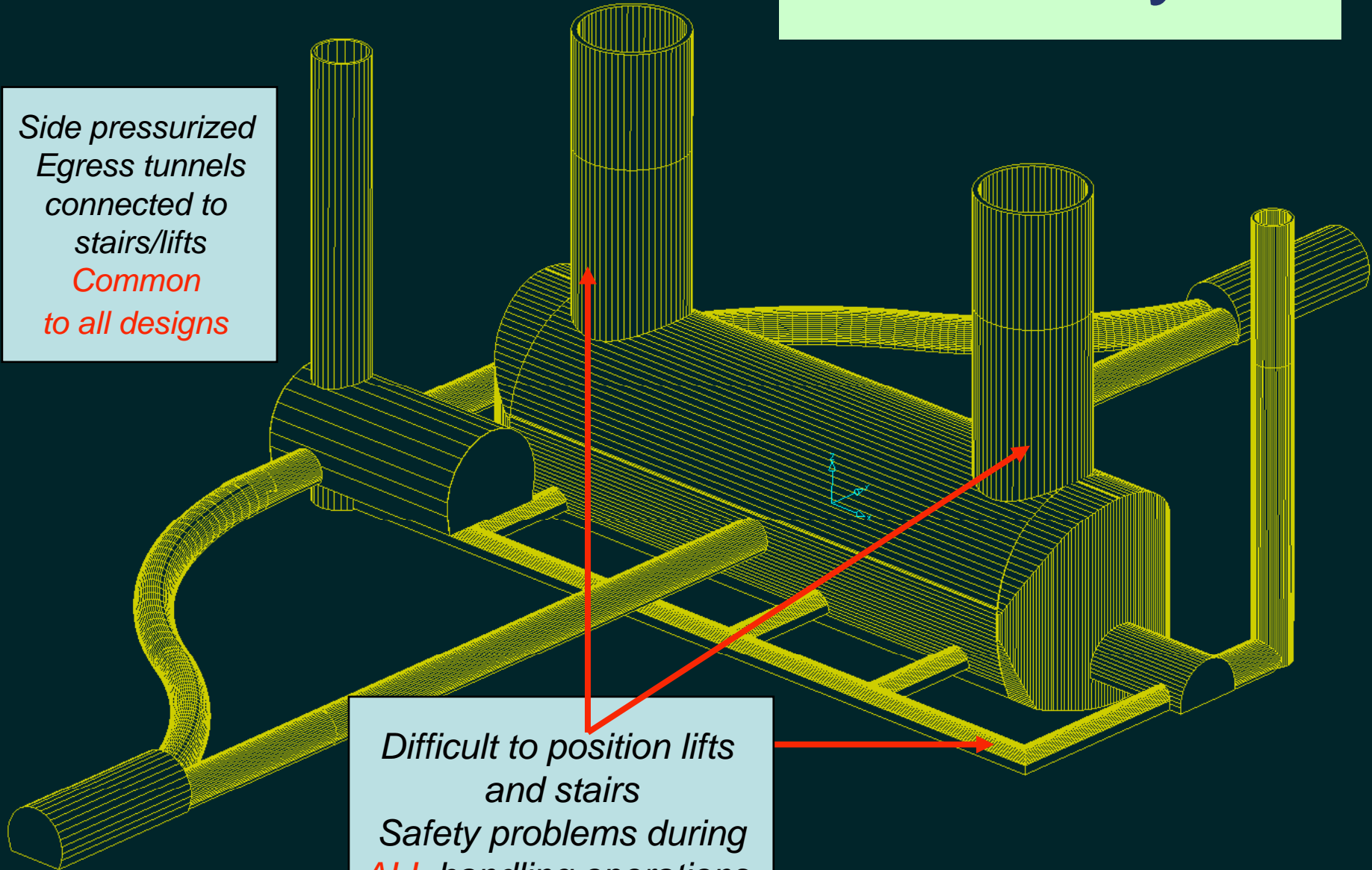
- Hall sized in width for GLDc
- Shaft diameter & crane/gantry capacity sized for GLDc/LDC
- RDR layout shows shafts over assembly hall and an asymmetric service cavern layout
- IRENG'07 version with offset shafts and symmetric service caverns will be submitted for change control
- All CERN produced civil x-sections show platform as mechanism for push-pull motion and boundary between detector and accelerator systems
- All BDS produced civil hall x-sections show a shielding wall separating the two detectors



VUES 3D

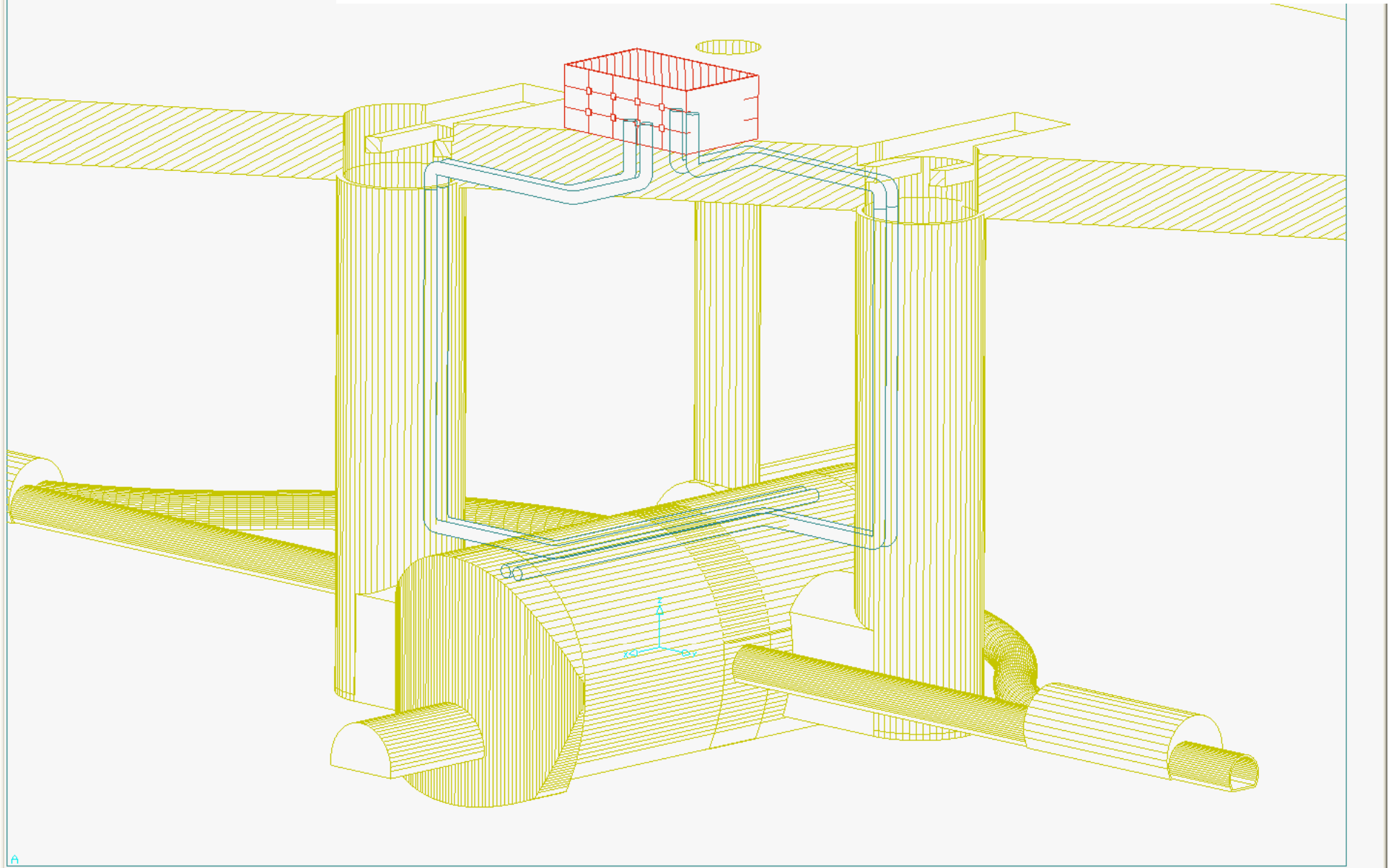
# RDR Layout

Side pressurized  
Egress tunnels  
connected to  
stairs/lifts  
*Common  
to all designs*



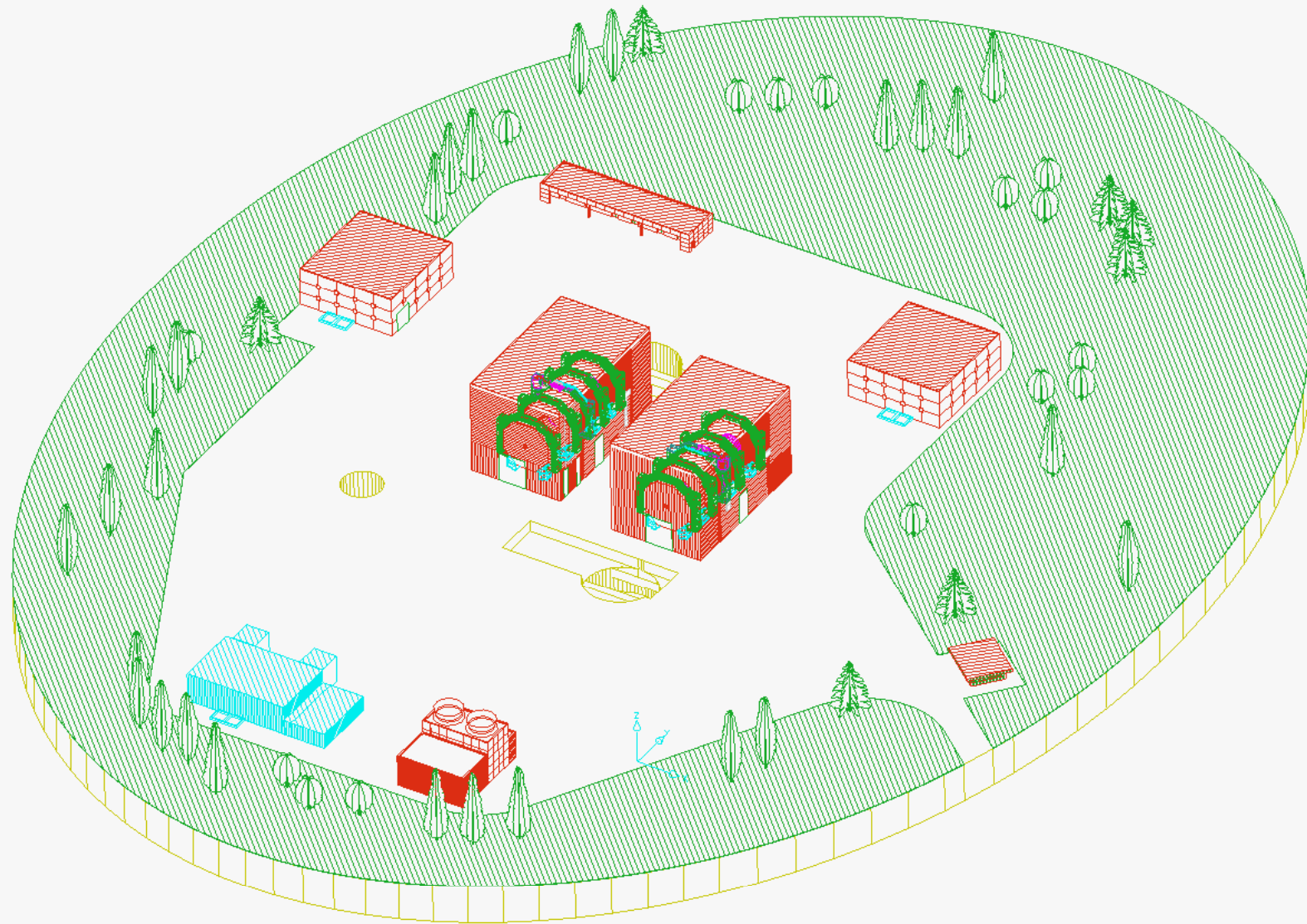
Difficult to position lifts  
and stairs  
Safety problems during  
*ALL* handling operations

# Offset Shaft Proposed at IRENG

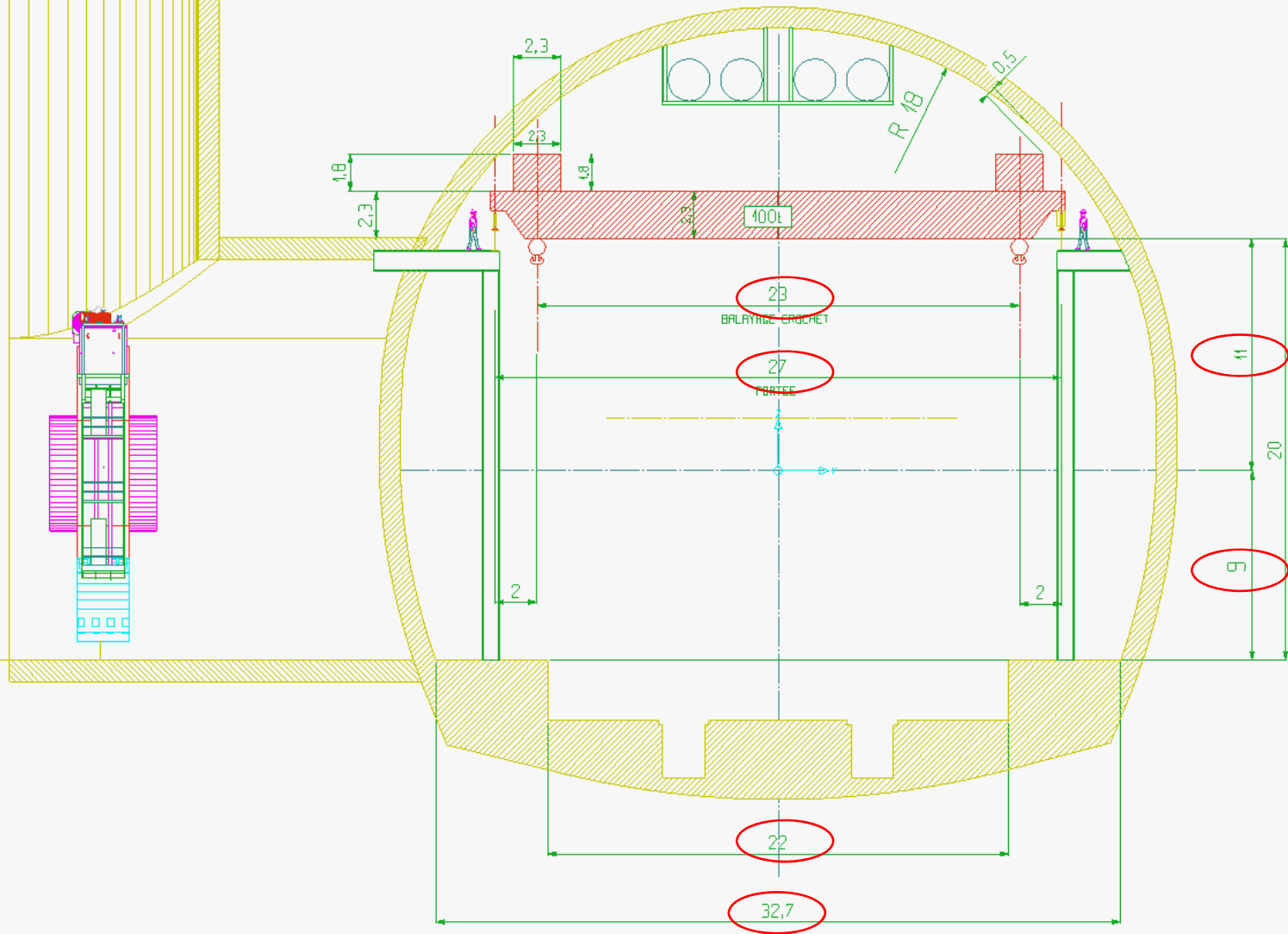




# Proposal for 2 Parallel Surface Assembly Buildings

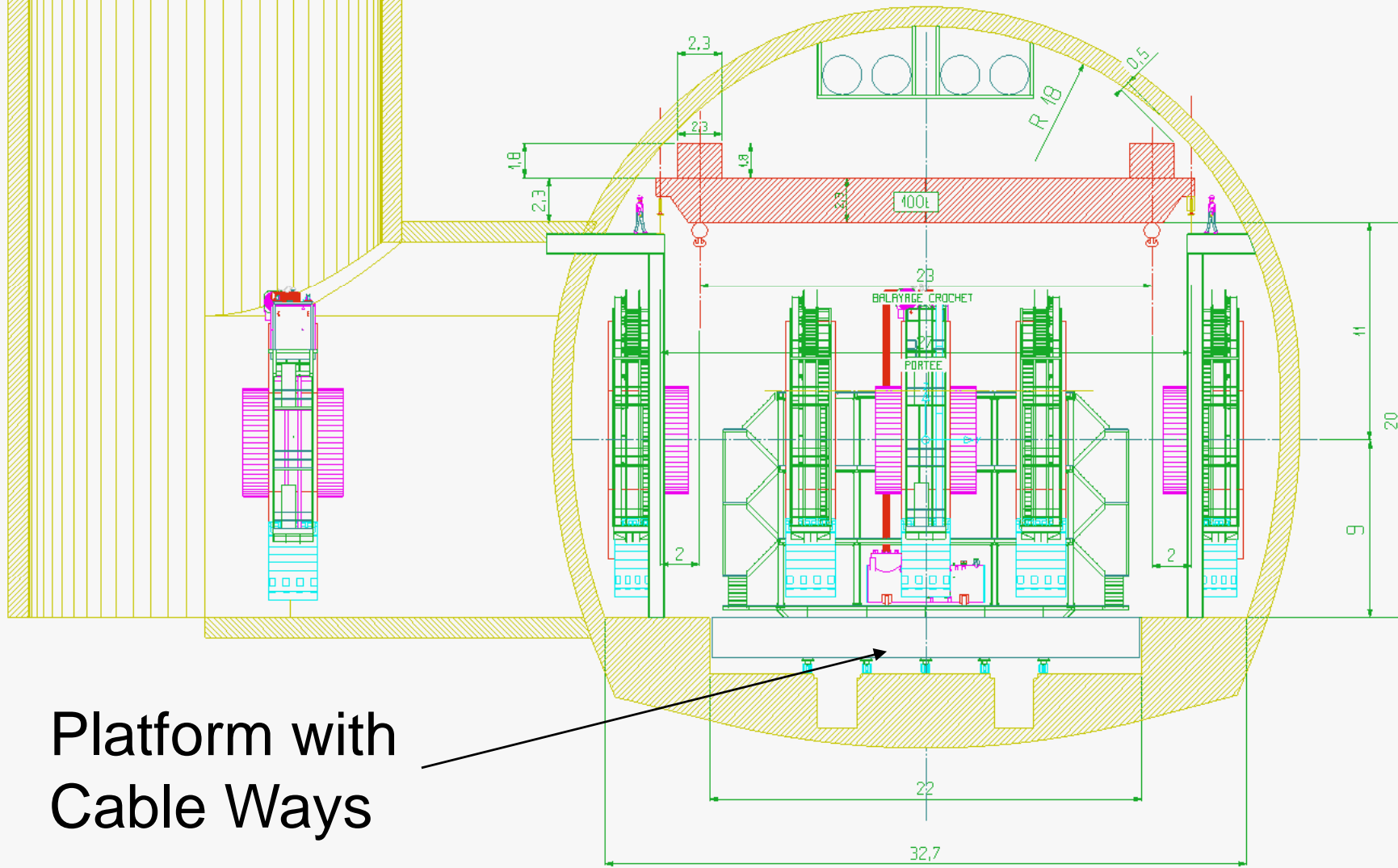


# GLDc Sized Cavern X-Sect



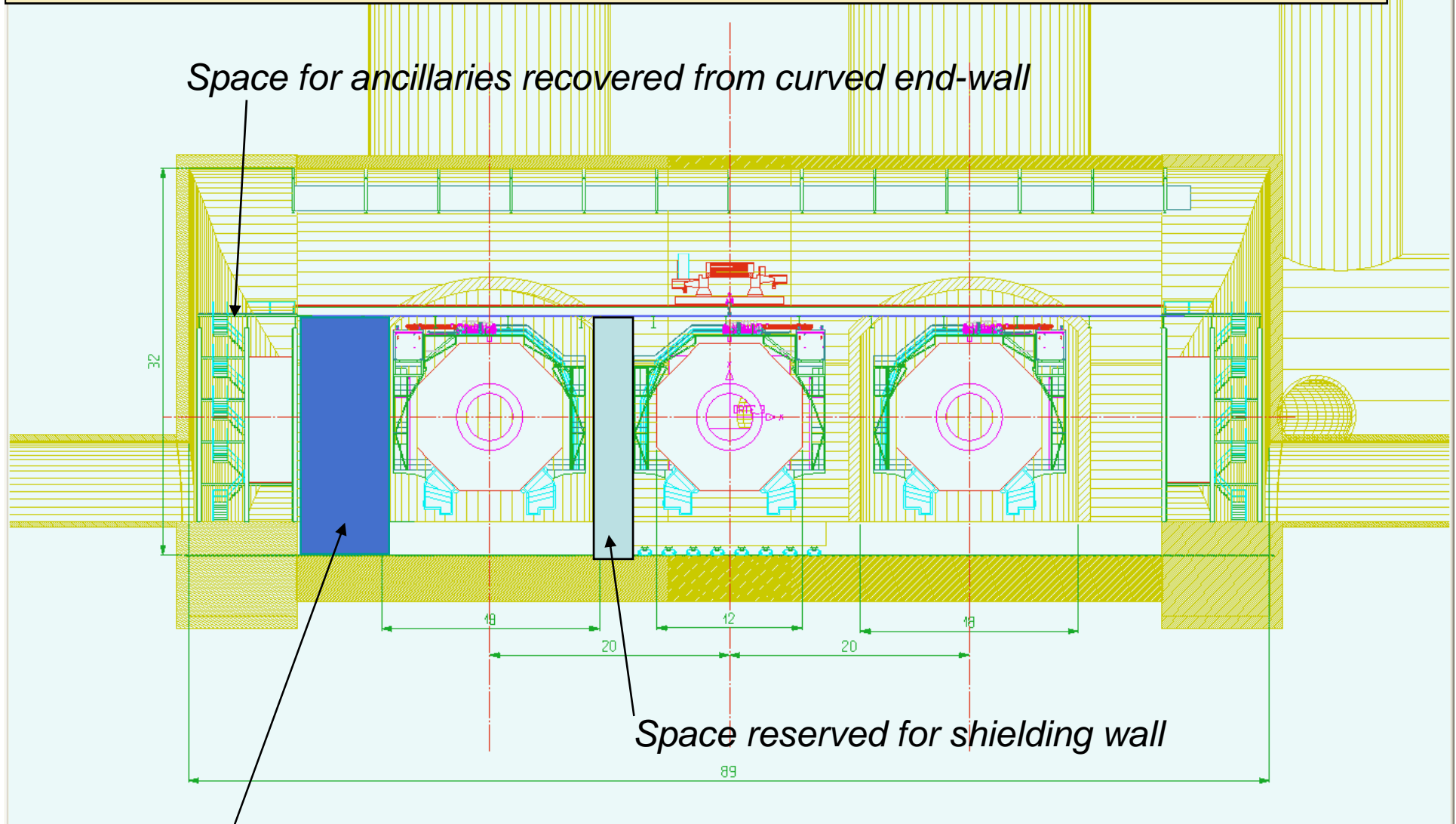


# Useful Hall Width in Garage Position is 32.7m



Platform with  
Cable Ways

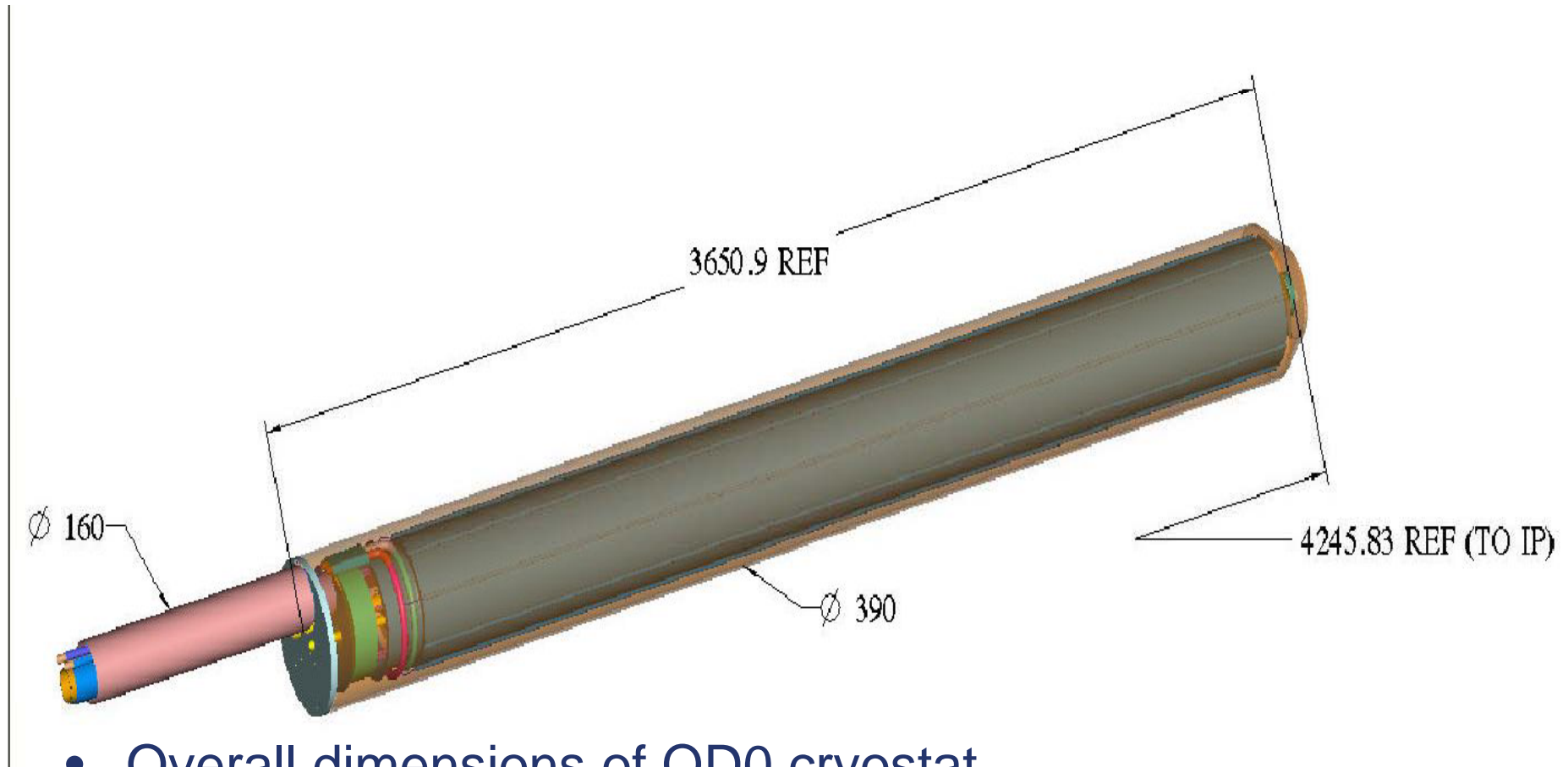
# Hall Parameters - Length around 90 m



8 m working corridor, could be from 0 to 100% on any one side of experiment in 2-m increments, using 'working platforms' to fill the gaps



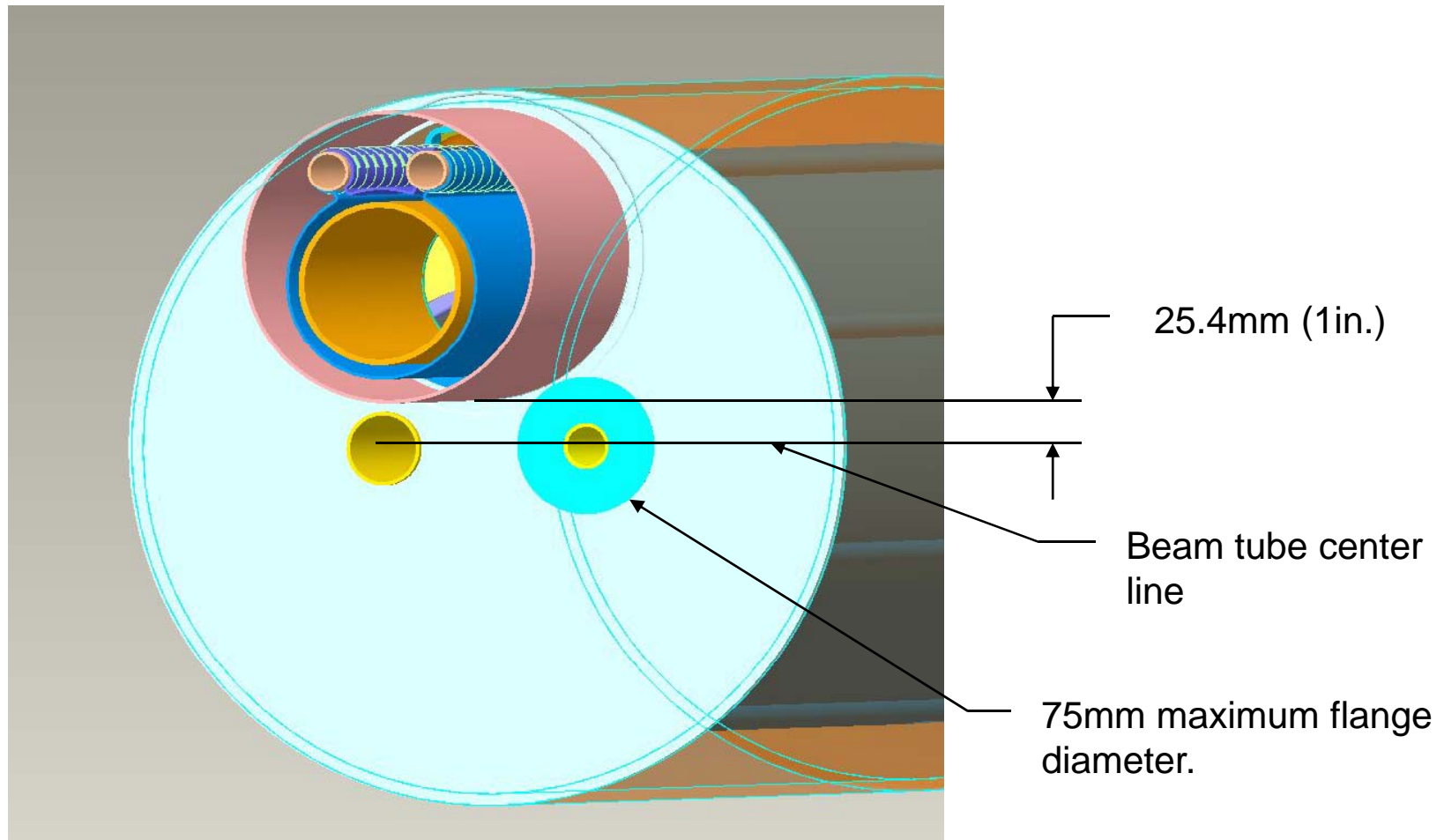
# QD0 CRYOSTAT @ IRENG'07



- Overall dimensions of QD0 cryostat.
- For  $L^* = 3500\text{mm}$  distance to IP would be 3245mm

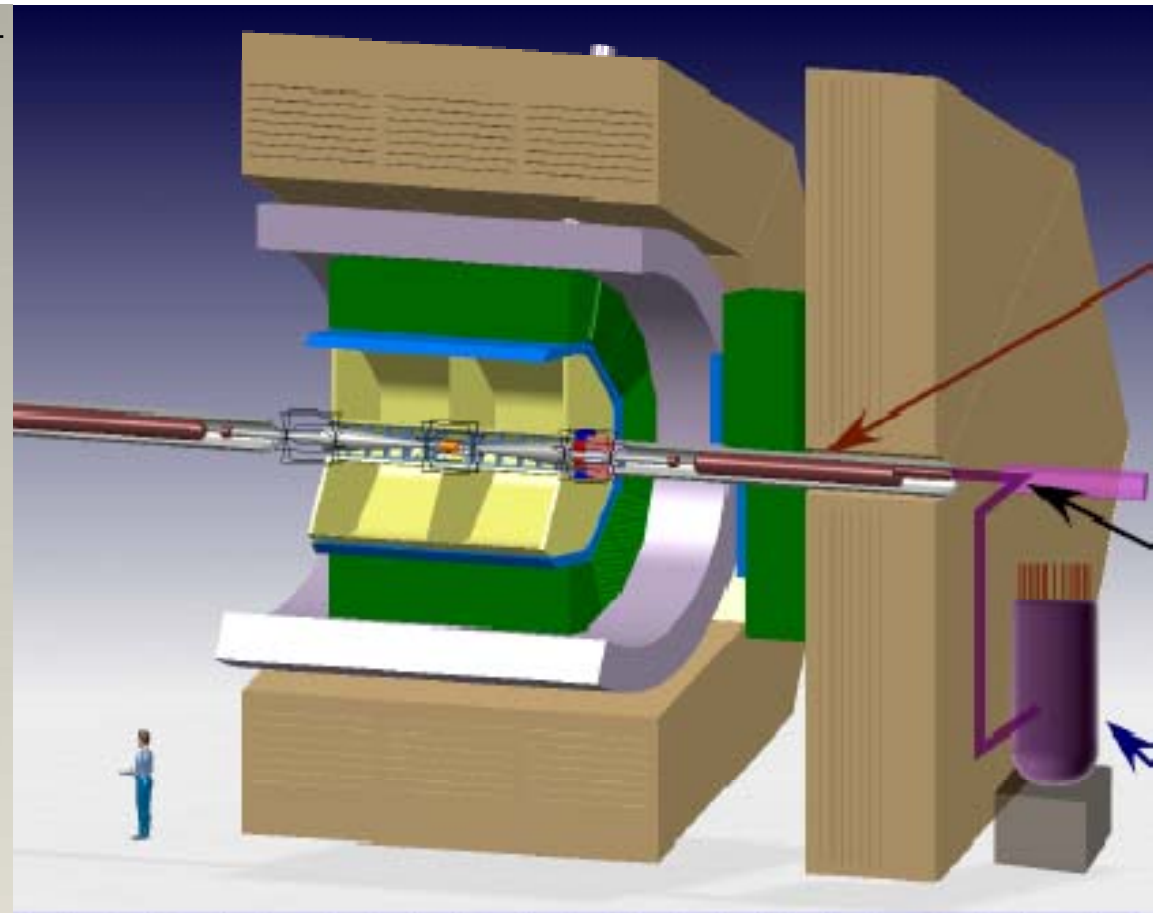
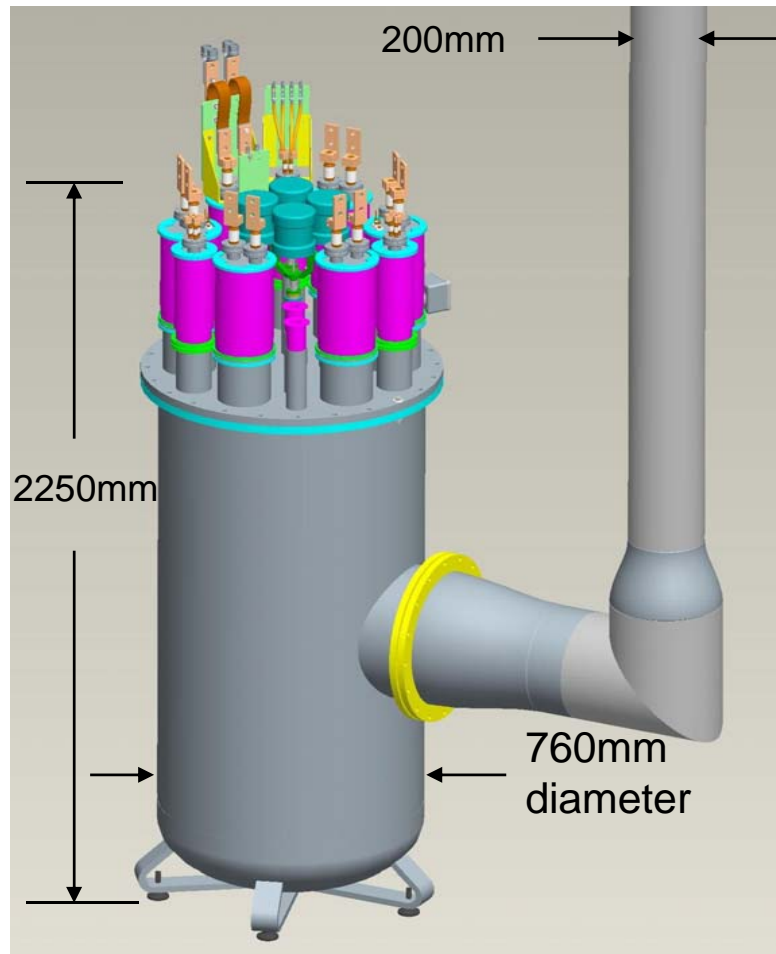


# Back End of QD0





# Interference Between Movable Door & QD0 Service Cryostat



Overall service cryostat dimensions



## Personal Comments and Observations

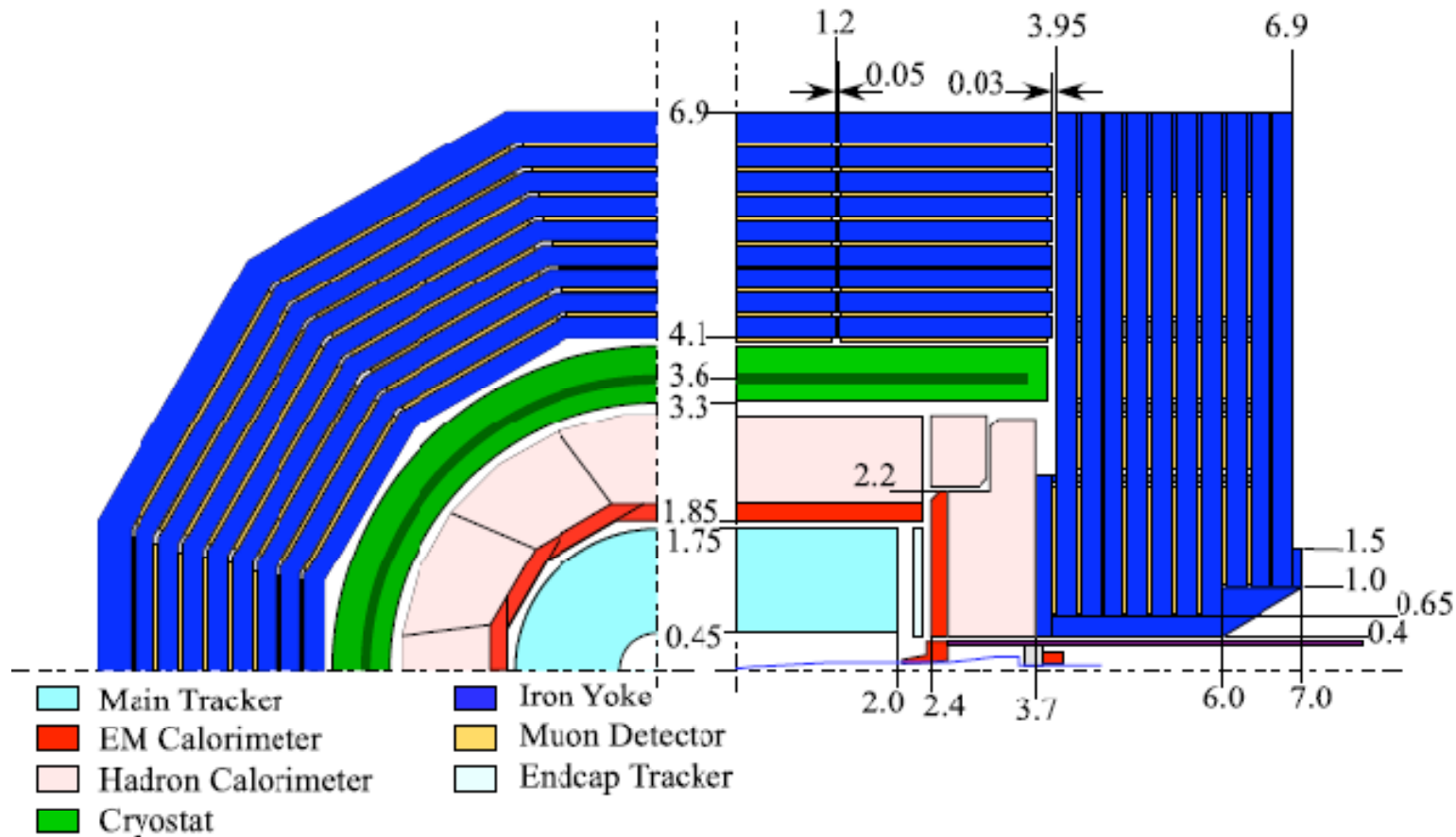
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- GLDc, LDC, & SiD are seriously treating Push-Pull (P-P) & Surface Assembly (S-A)
- 4<sup>th</sup> concept does not treat either P-P or S-A seriously
- GLDc design was introduced for IRENG'07 which incorporates a complete self-consistent model for push-pull, surface assembly, QD0 Support and PACMAN shielding
- Currently independent LDC design conceptually identical to GLDc





# Compact GLD = GLDc





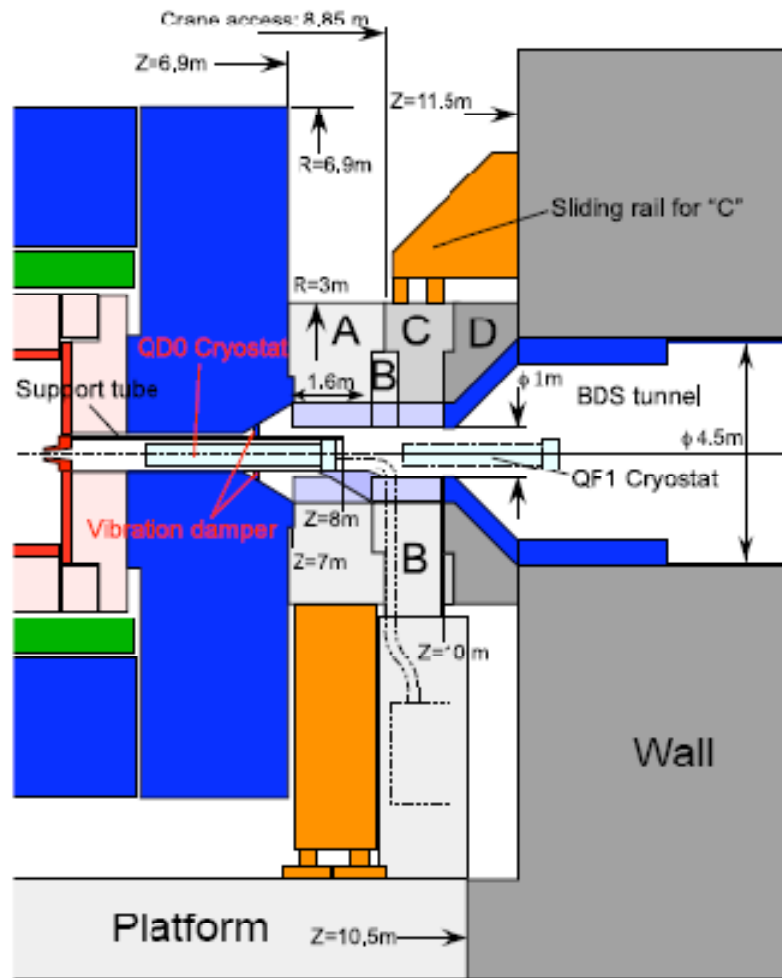


# GLDc Assembly: 7 major pieces

- Barrel part (Yoke+ECAL+HCAL)
  - **5080+1130 T = 6210 T**
  - **Pure CMS style assembly can be done by splitting the barrel part into 3 rings**
- Each Door (Yoke + ECAL+HCAL)
  - **3050 T + 270T = 3320 T**
  - **and splitting each end cap part into two halves**
- Cranes:
  - **50~100 T underground depending on Pacman design**
  - **2,000 T crane for the shaft**
  - **80 T crane in the surface assembly hall**
    - set by 24 Fe yoke octants
- Shaft sizes, crane access and underground vault sized by CFS for GLDc as discussed by J. Osborne



# GLDc QD0 Support Based on Cantilevered Support Tube with Base on 2 x 10.5m wide Platform

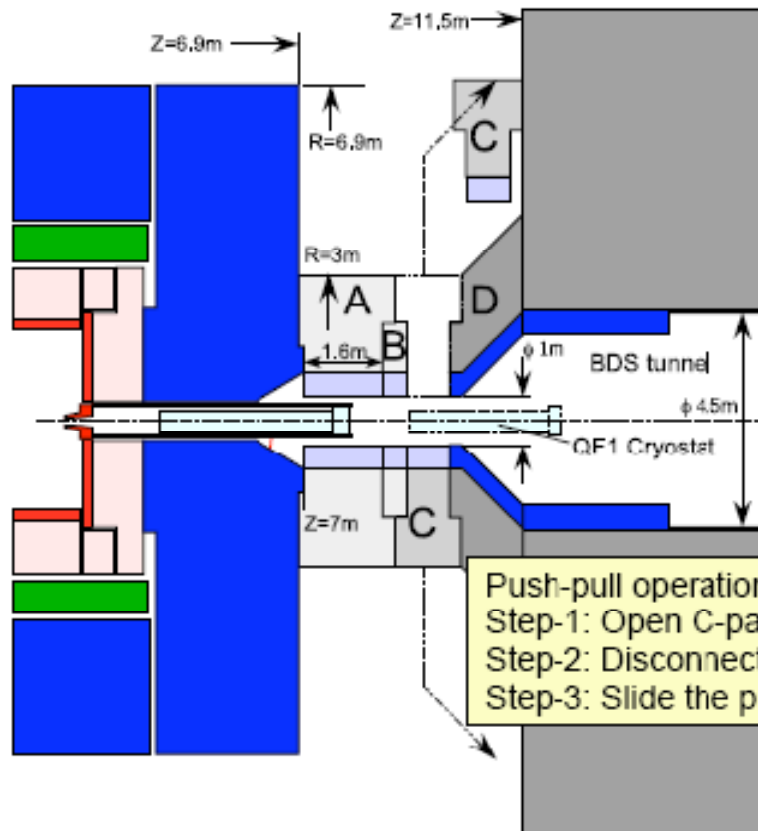


- A: slide sideways using air pad
- B: supported from the floor of platform
- QD0 cryostat is supported by the support tube and the support tube is supported from B
- We can put additional support for the support tube at the entrance of endcap yoke to damp the vibration, if necessary
- Upper part of B (~10 ton) must be removable by crane for installation and removal of the support tube
- C: slide along the wall (D) (common to both experiments) ~50 tonx2
- D: part of the wall
- Wall distance can be as small as 11.5 m from IP, if the crane can access to 2.65m from the wall
- Construction of C is done by a mobile crane (CMS style)
- Inner radius of pacman should be determined after design of gate valve etc. between QD0 and QF1 is fixed

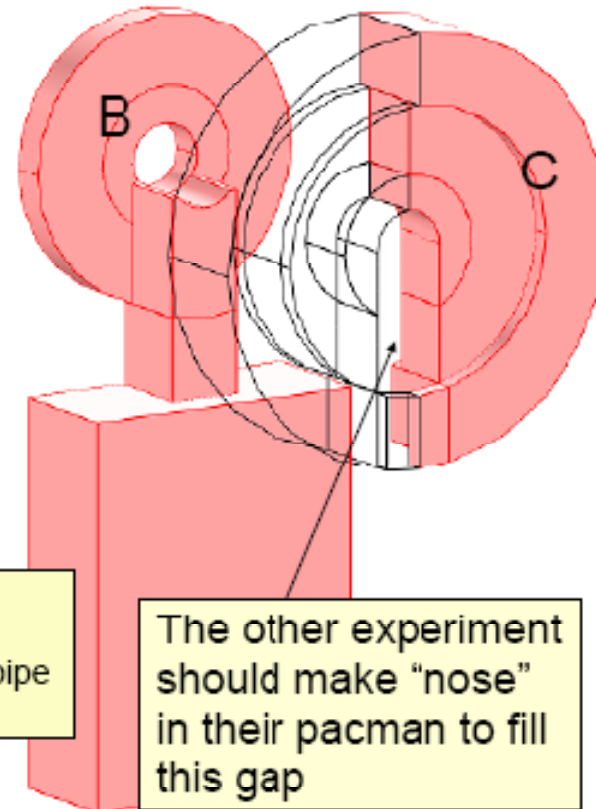


# Disassembly of PACMAN for Push-Pull

- Plan view

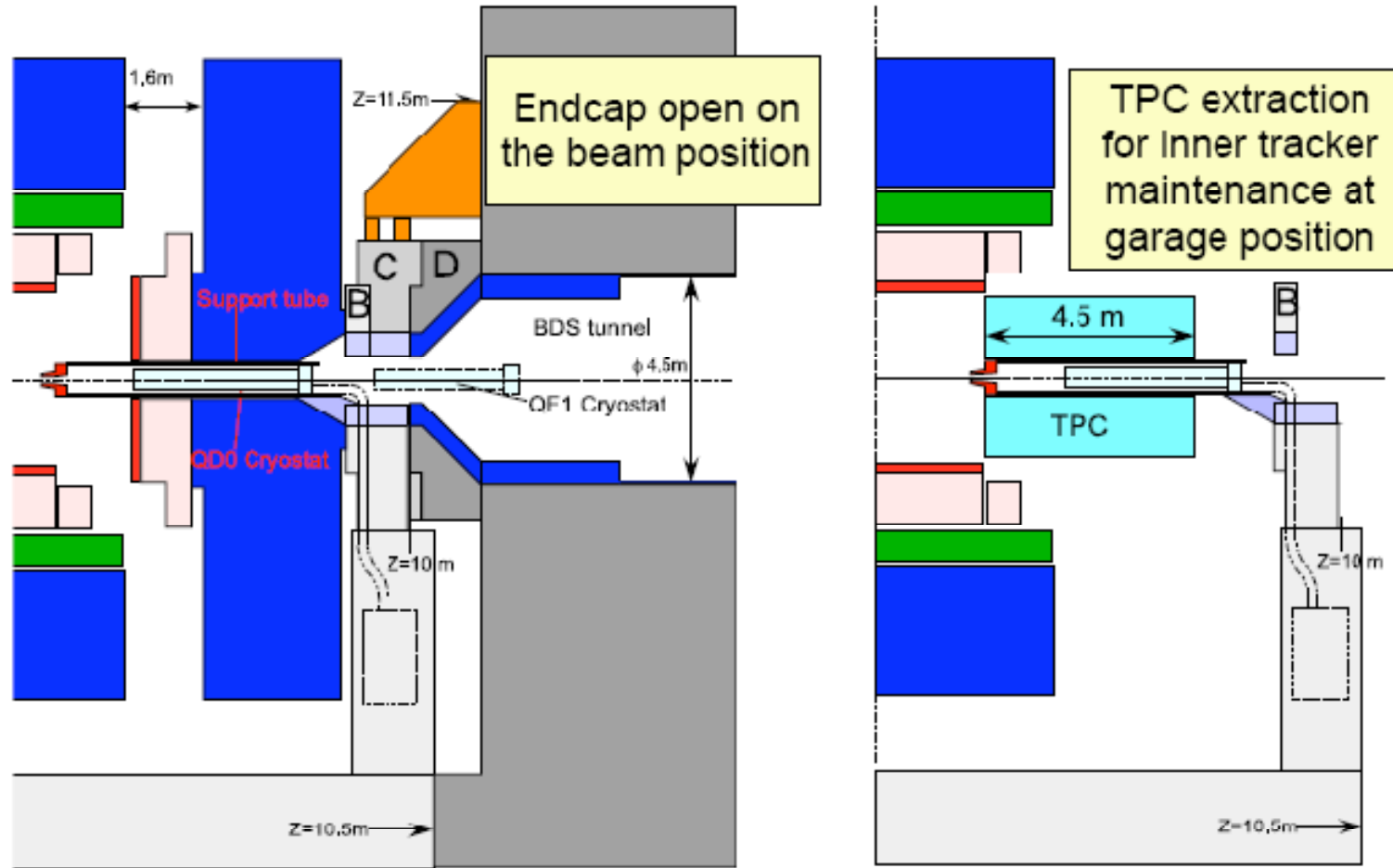


- 3D view





# On-beamline & Off-beamline Access

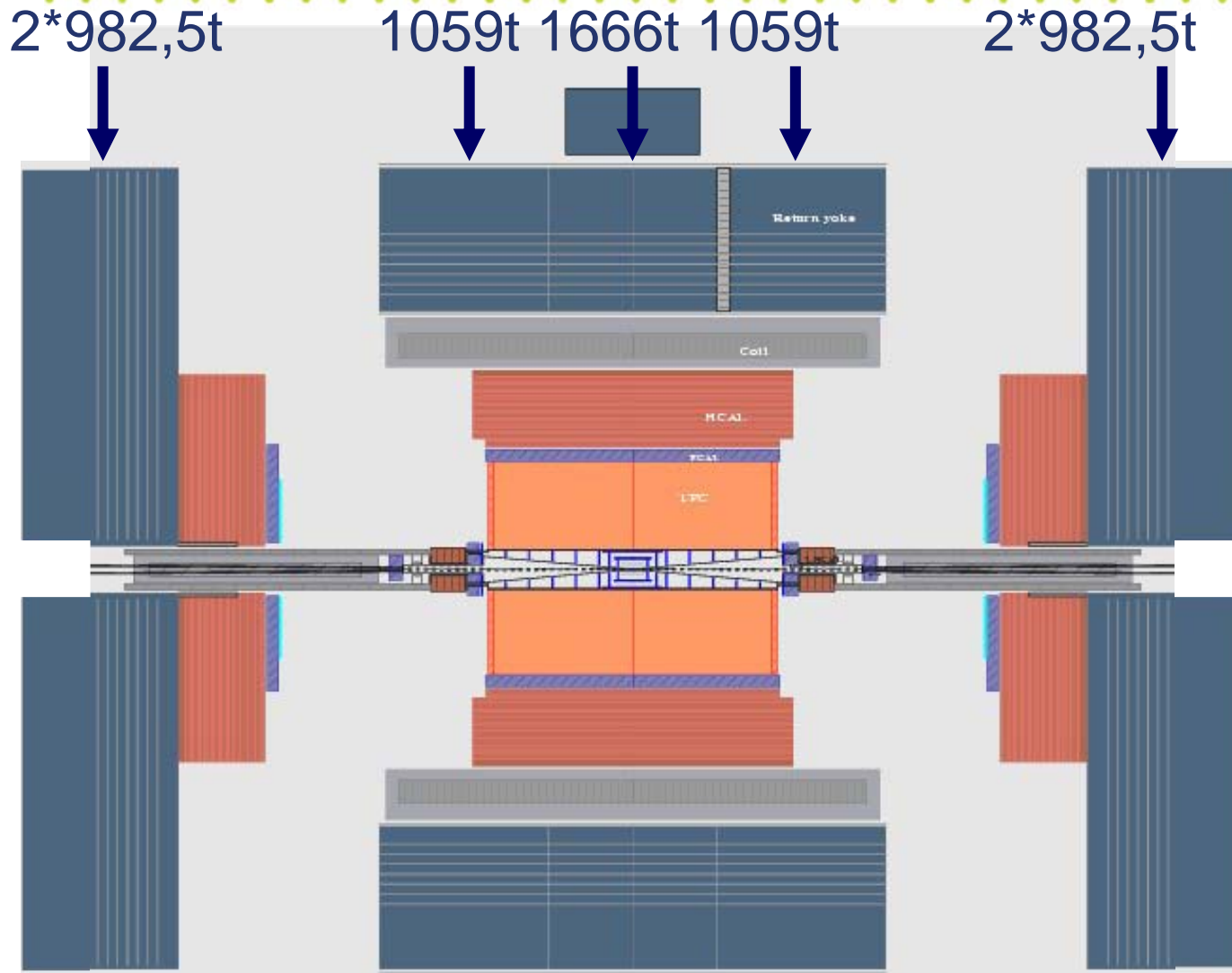


“A” Pacman split back and unsplit door rolls to tube support pillar

“A” & “B” Pacmen and Endcap Door split back



# LDC Assembly & Access Model Similar to GLDc



If not split the end cap pieces would be the heaviest part to be lowered!

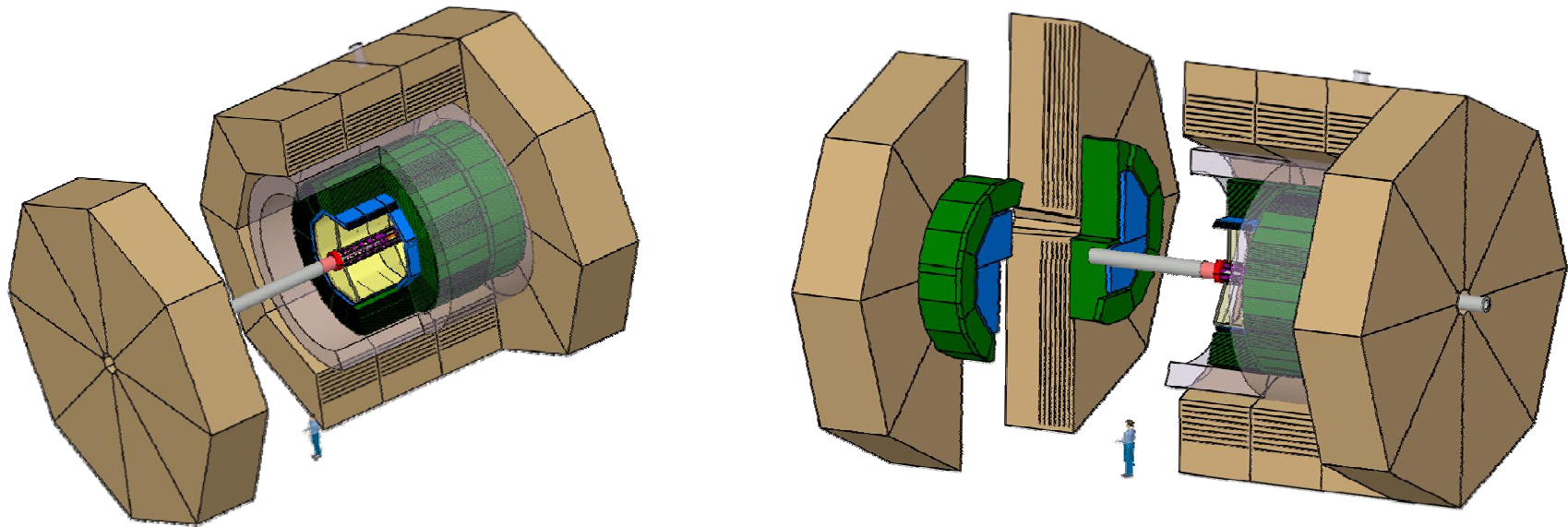


# Split Endcaps not Fundamental to Design

## Under Study!

- The structure of the detector should allow both.

**Factor 2 more bending if split!**



At the moment we prefer end cap halves bolted together with the possibility to open in an major operation if necessary!

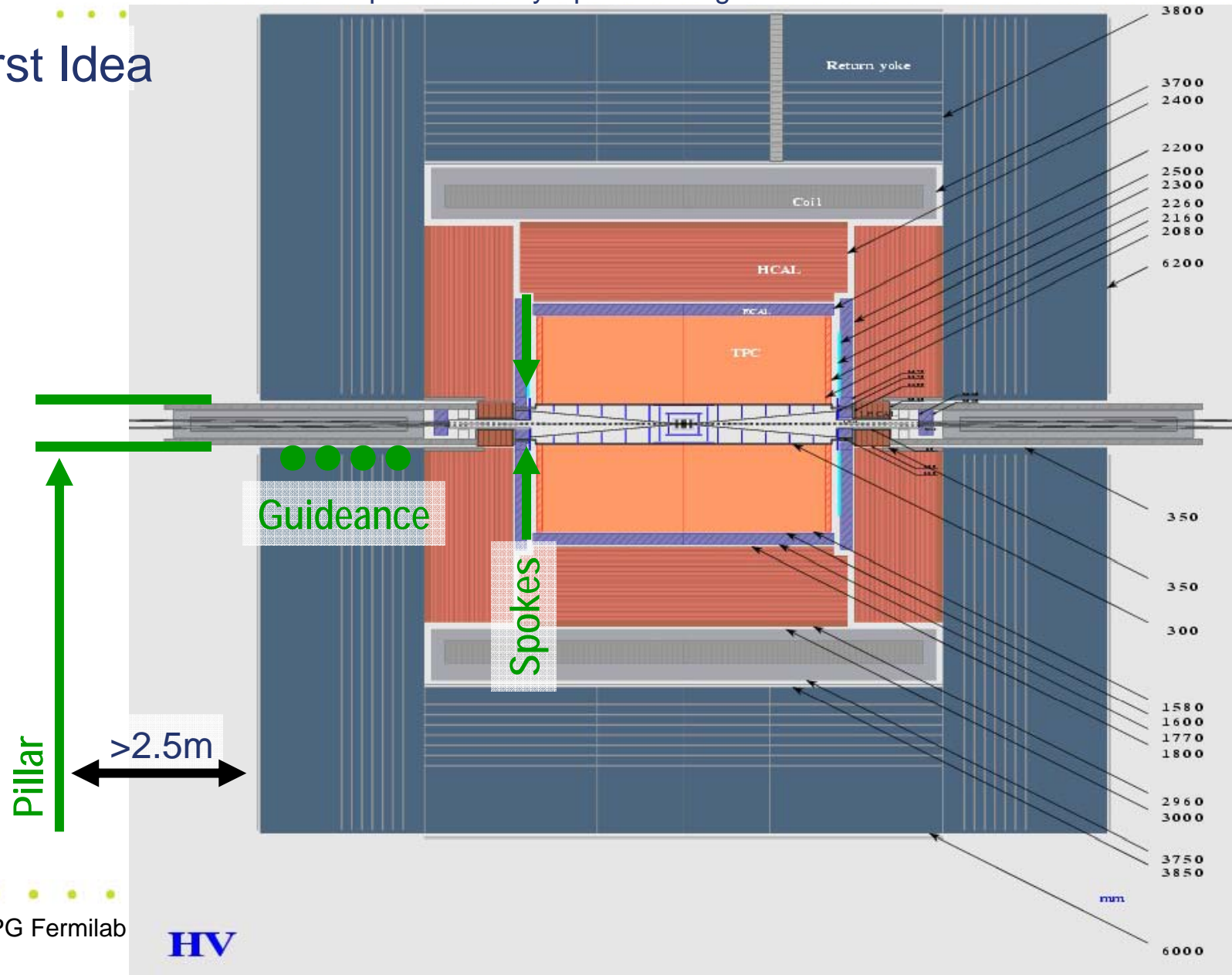




# QD0/FCAL Held in Support Tube Support Tube Pillar Sets Max Door Opening

Tube Guided in EndCap and Held by Spoke Arrangement at TPC/ECAL Juncture

First Idea

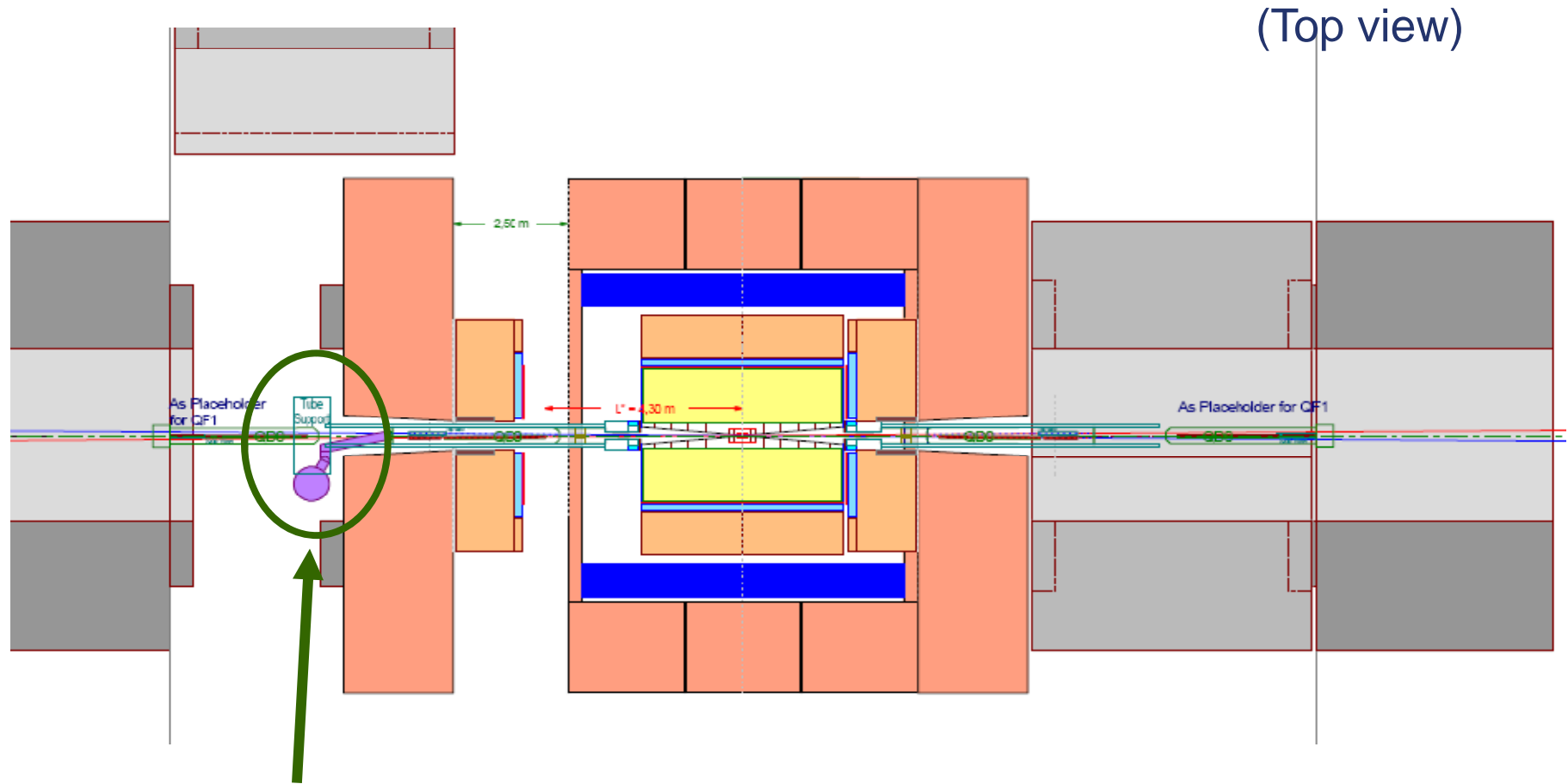






# LDC Opens On-Beamline Via Split PacMan

Need 2.5-3m to access the detector

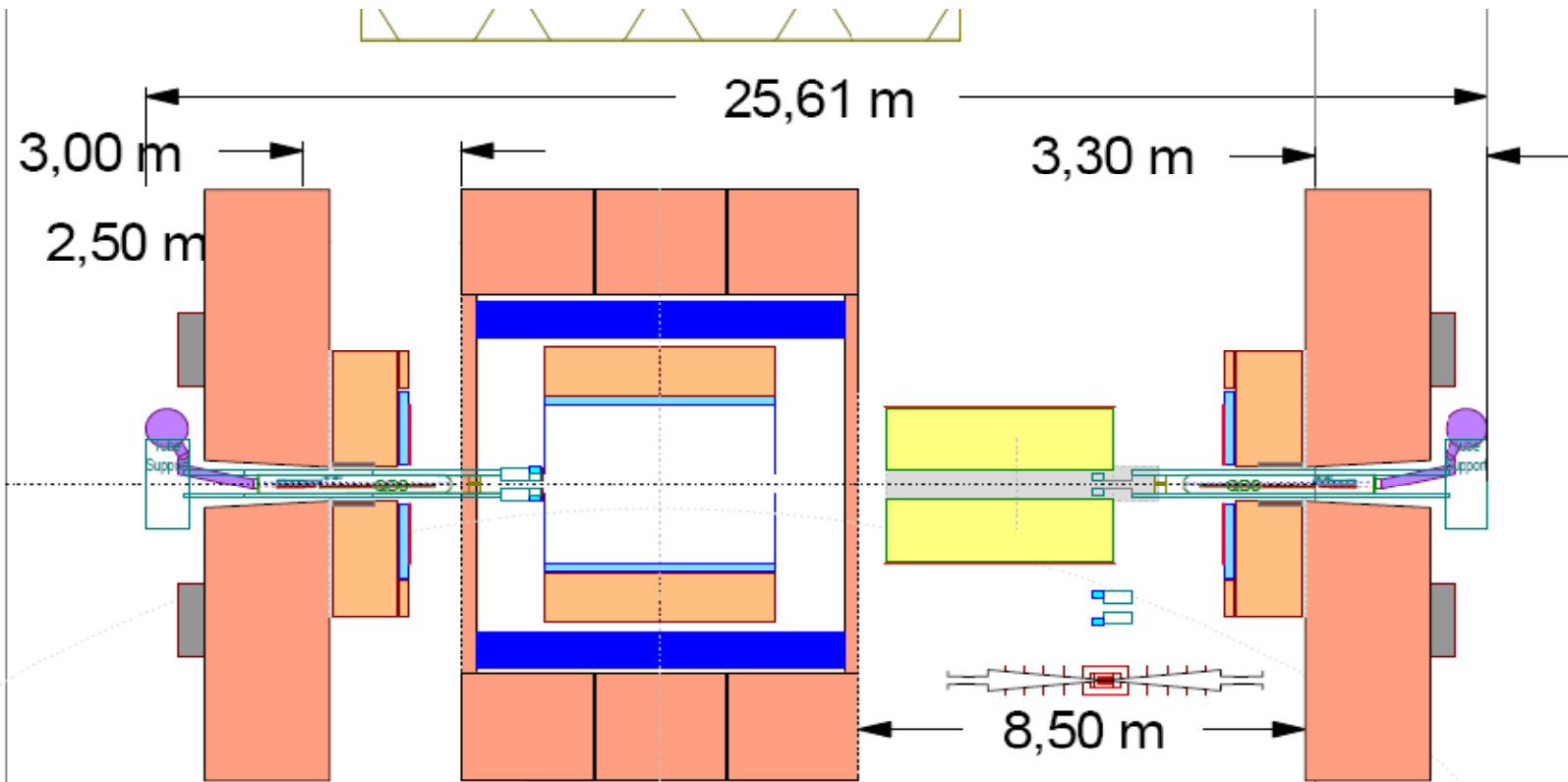


- Support Structure Support
- Service Cryostat
- Supply Line close to QF1



# TPC Exchange Off Beamline

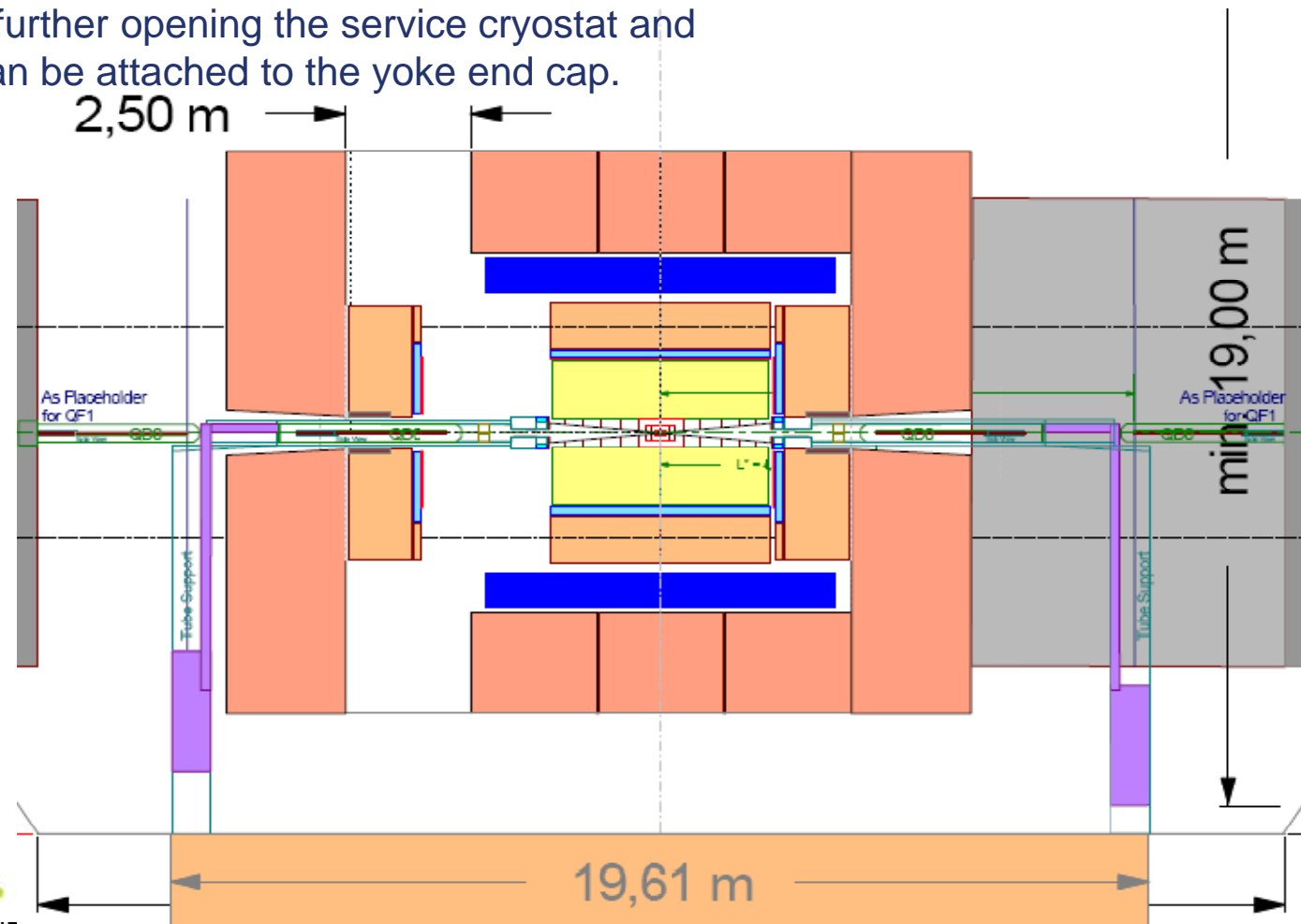
- If not split, the end cap yoke has to be moved 8,5m longitudinal (or aside) for TPC exchange!
- QD0 and service cryostat have to go with the end cap yoke while the Helium supply line is not cut!





# Similar Width “Platform” to GLDc

- The supply lines from the service cryostat to the QD0s go from the bottom through the shielding.
- The cryostats are connected via flexible lines to Helium supply.
- To allow a further opening the service cryostat and the QD0 can be attached to the yoke end cap.



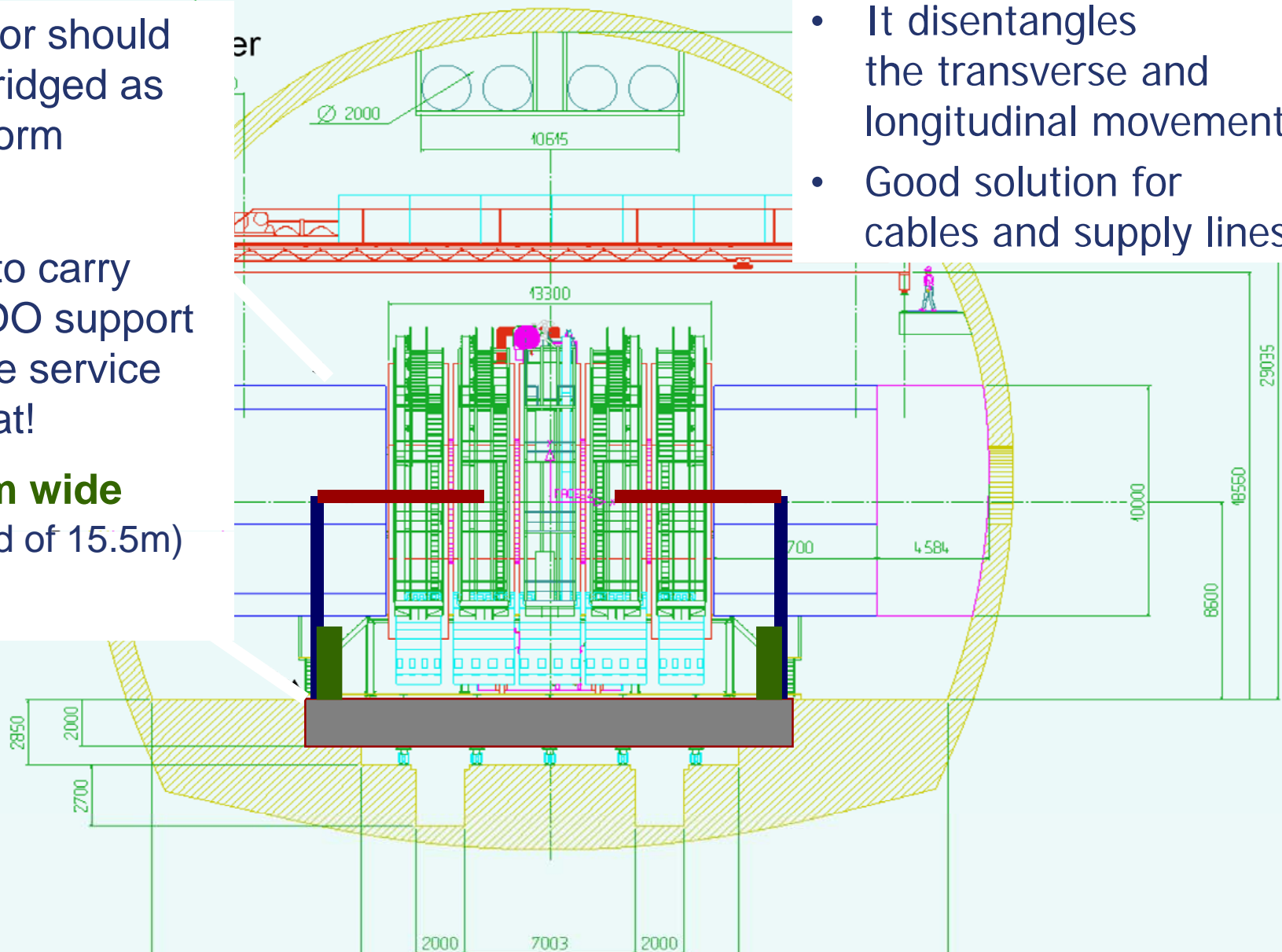


# Relative Merits of Platform Under Discussion

EXPERIENCE FERMÉE SUR FAISCEAU

PORTEE PONT ROULANT 4.0L 29120

- Detector should be as ridged as a platform
  - It has to carry the QDO support and the service cryostat!
- **20m wide**  
(Instead of 15.5m)



## Charming!

- It disentangles the transverse and longitudinal movement
- Good solution for cables and supply lines



## SiD IR & MDI Design Philosophy

SiD has traditionally tried to incorporate self-consistent IR/MDI design based on assumptions that detector would

- **Have solid endcap doors**
- **Be self-shielded**

We have assumed push-pull would require

- **No connection of FCAL/Doublet support structure to a fixed point other than the detector**



# SiD MDI Developments

Formation of ~10 member Si D Engineering team

- **Some work by Marco Orunnio on push-pull cryo & magnet connections**
- **No new work on FCAL/QD0 support**

Detailed engineering calculations of beampipe by Bill Cooper for designs being put forward by FCAL group

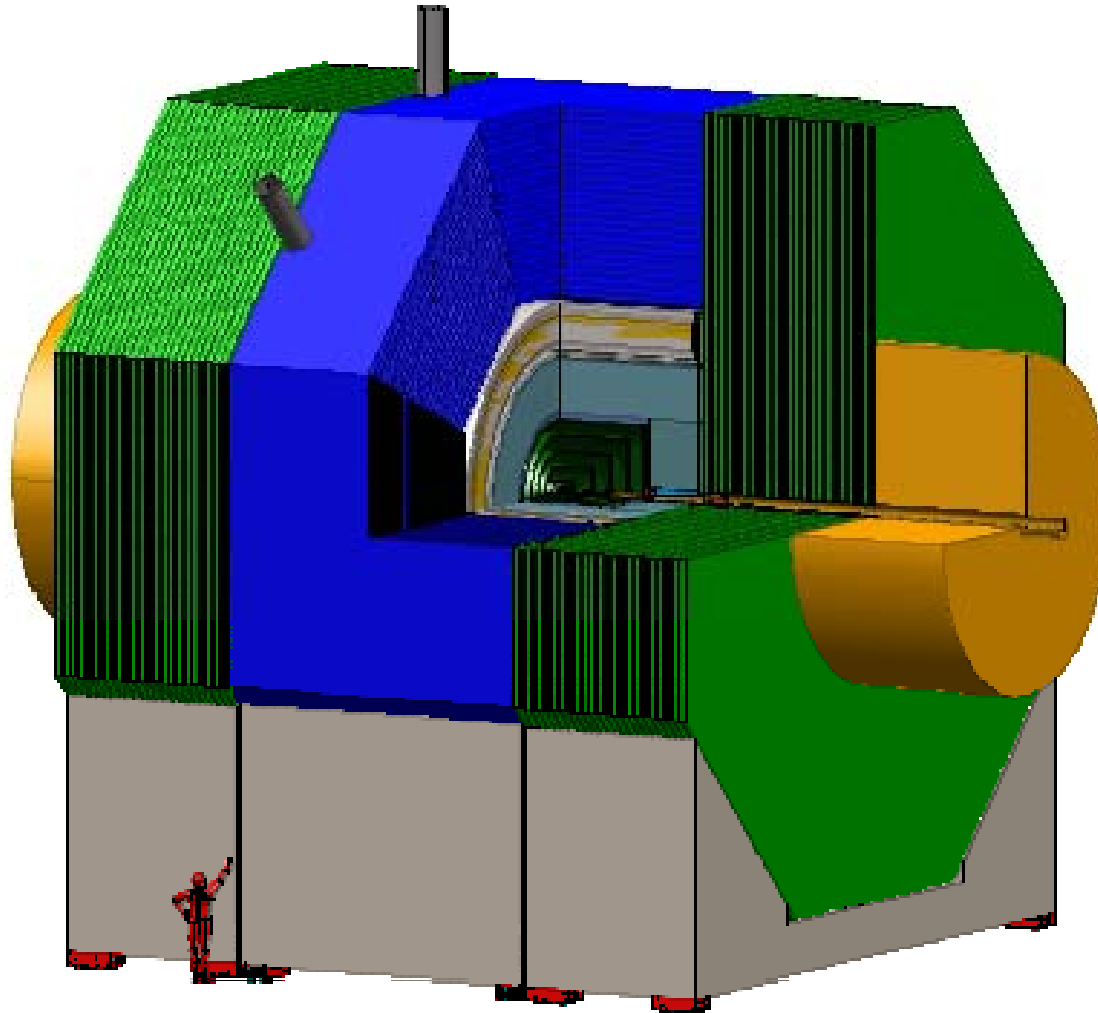
Clear design wishes by Bill Morse for beampipe/Lumical/FHcal/Beamcal that have not been blessed by SiD management

Bill Cooper's IRENG'07 calculations show that FCAL/QD0 package mass requires more than two support bars

Realization that FCAL/QD0 support will need some form of z-restraint



# SiD: Doors & Barrel Are Not Split Minimum of 3 pieces to lower



“Pure CMS” concept  
gantry requirements:

- 4000T Barrel
  - Arch supports,  
Yoke, H/E-cals, coil
- 2500 T Doors
  - Yoke, H/E-cals

See M. Breidenbach  
animations





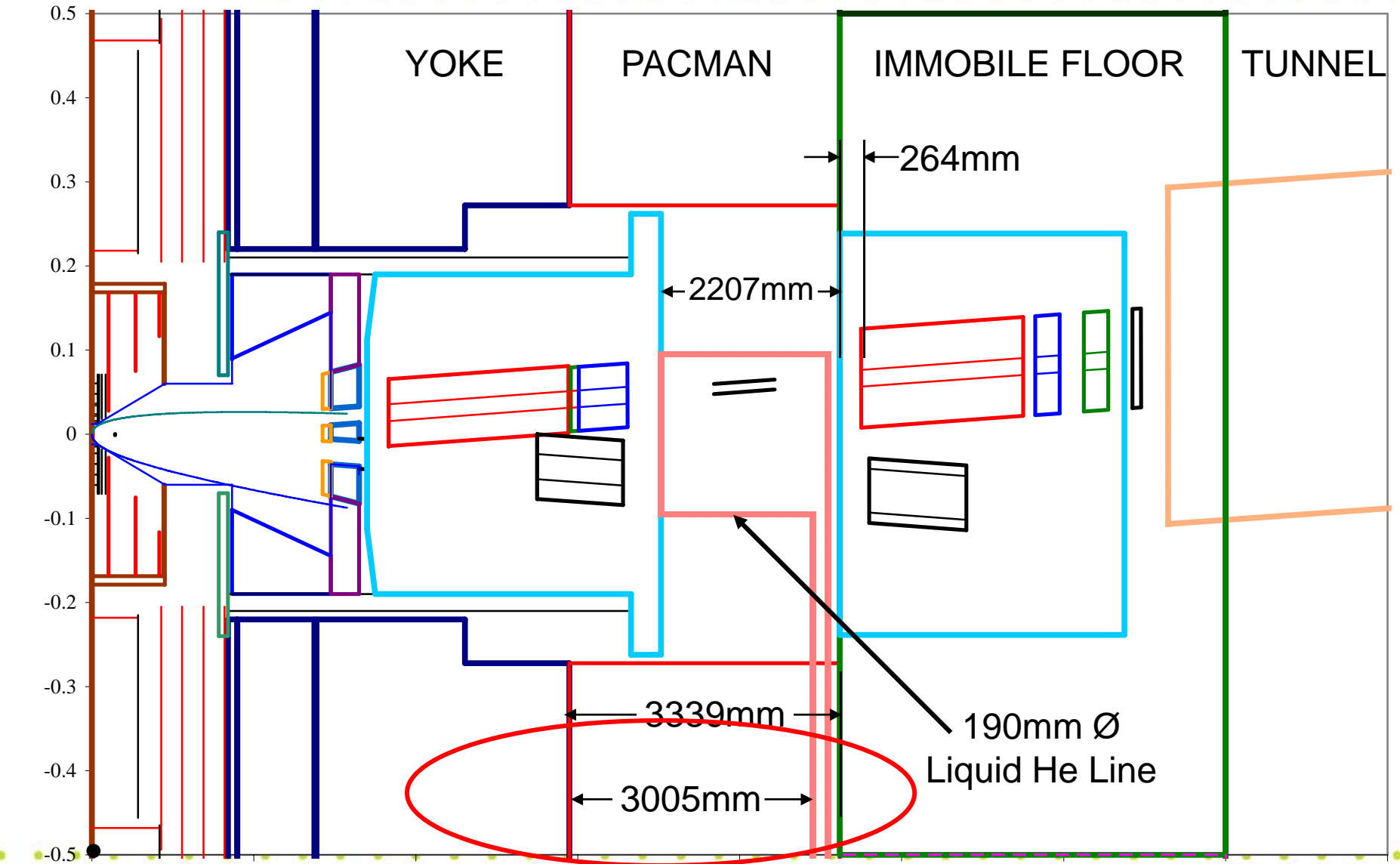
# A Surface Assembly/ Underground Reassembly Scenario for SiD

## 600T Surface crane & No Gantry

M-Tons	Stainless HCAL Radiator		Tungsten HCAL Radiator	
	Barrel	Endcap x2	Barrel	Endcap x2
EM Cal	59	19	59	19
HCAL	354	33	367	46
Coil	160		116	
Iron	2966/8= 374.5	2130/4= 532.5	1785/8= 223.125	1284
Support x 2 (each ~5%Fe)	150	110	90	65
Total to Lower	Loaded Coil=573	Assembled Door=2402	Loaded Coil=542	Assembled Door=1479
Shaft Diameter(m)	8.3m	10.4+2.0m		

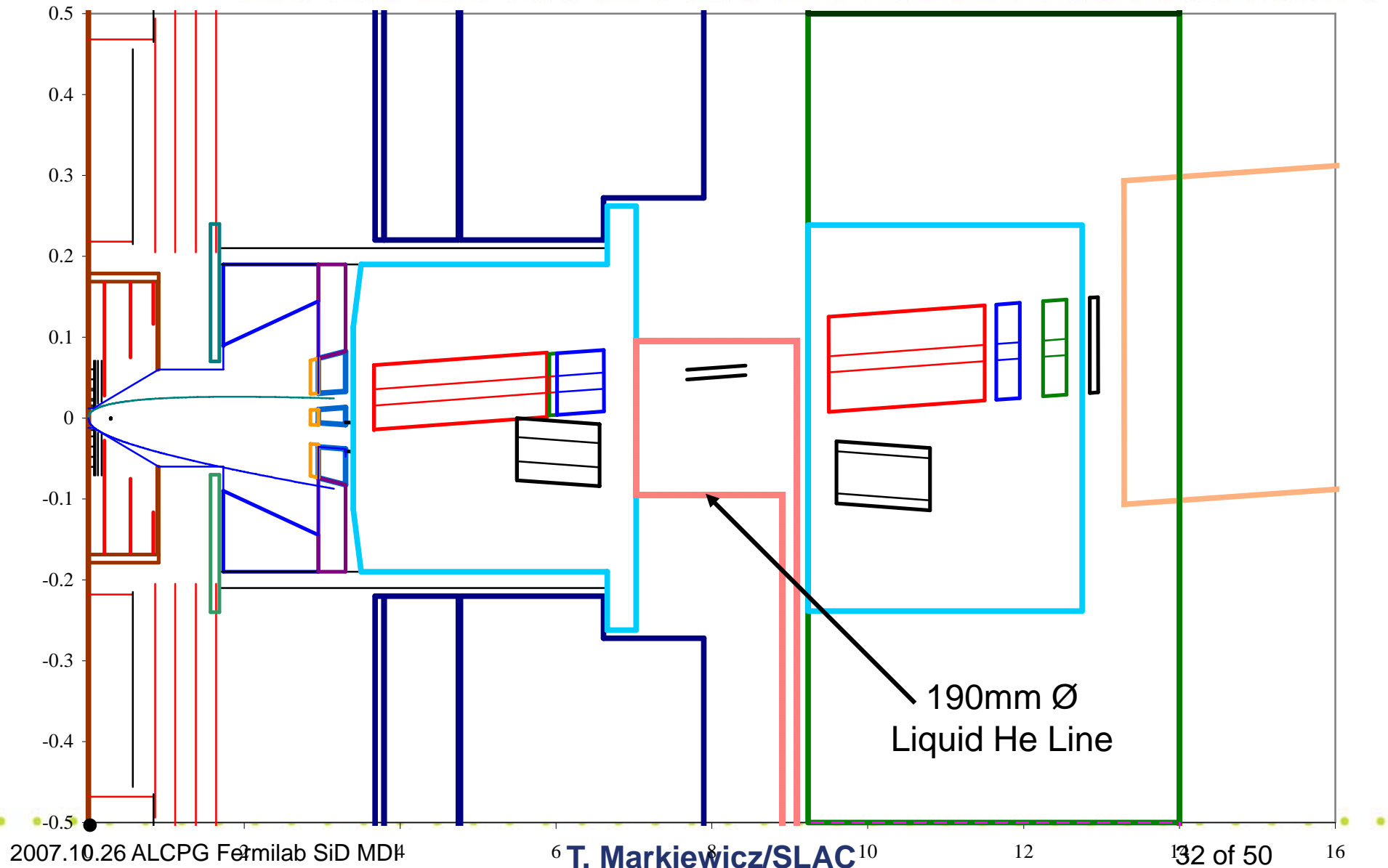


# SiD $r < 50\text{cm}$ , $L^* = 3.664\text{m}$ , $14\text{mrad}$ , Push-Pull, QF @ $9.5\text{m}$ , Door Closed



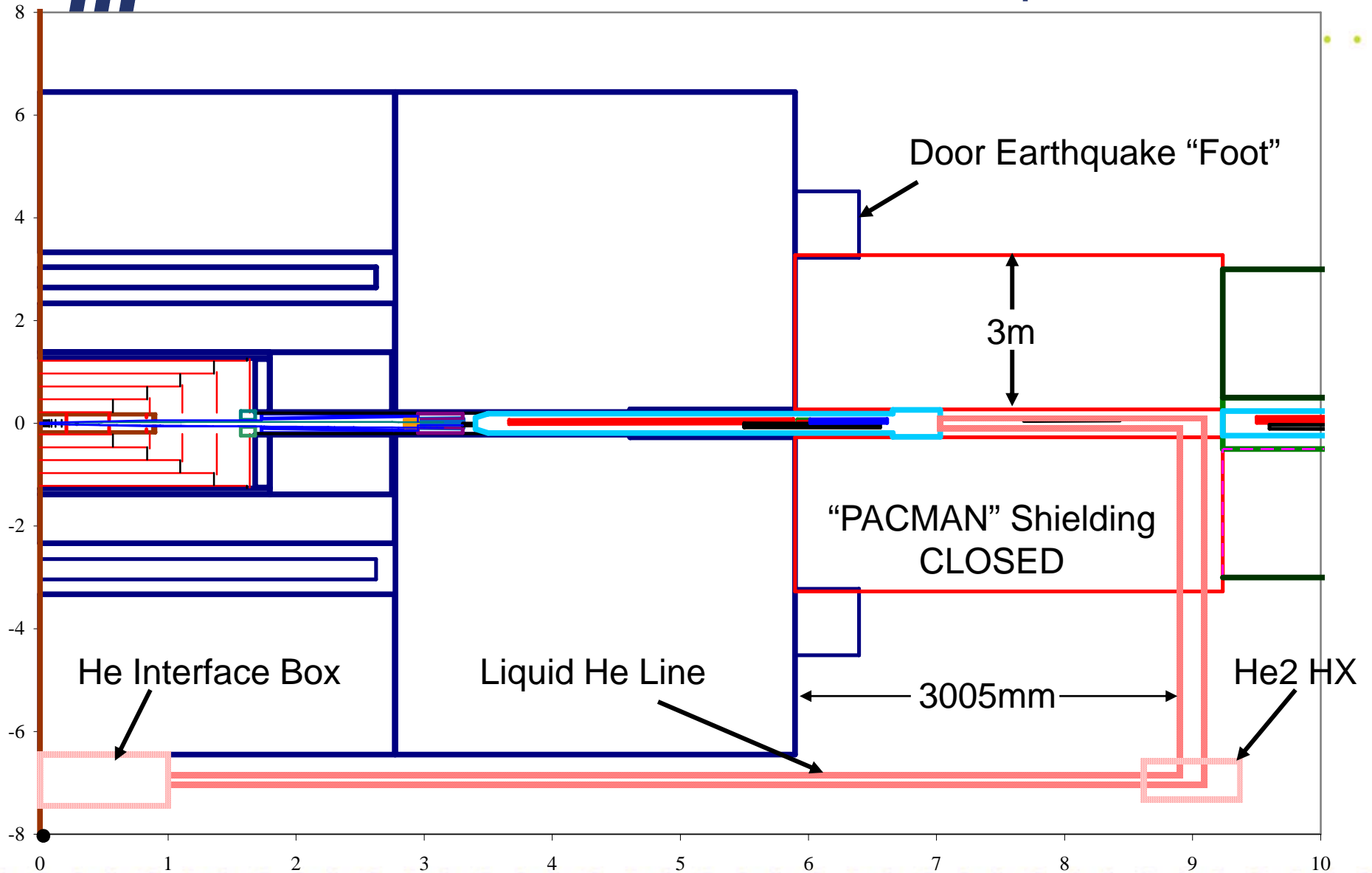


# SiD $r < 50\text{cm}$ , $L^* = 3.664$ , 14mrad Crossing Angle, Push-Pull, Door **Open 2m**



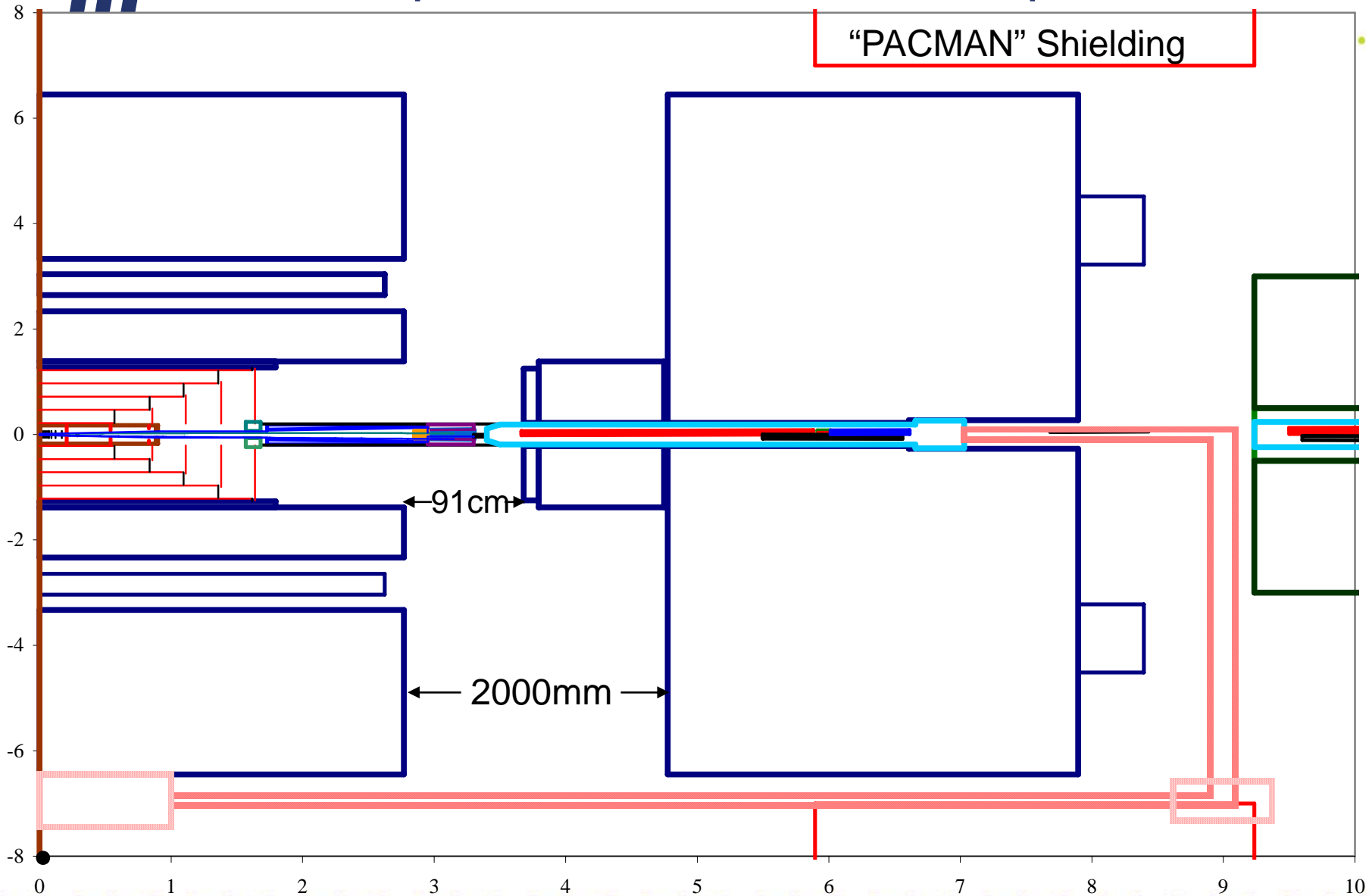


# Door Closed, Permanent QD0 Liquid He Line



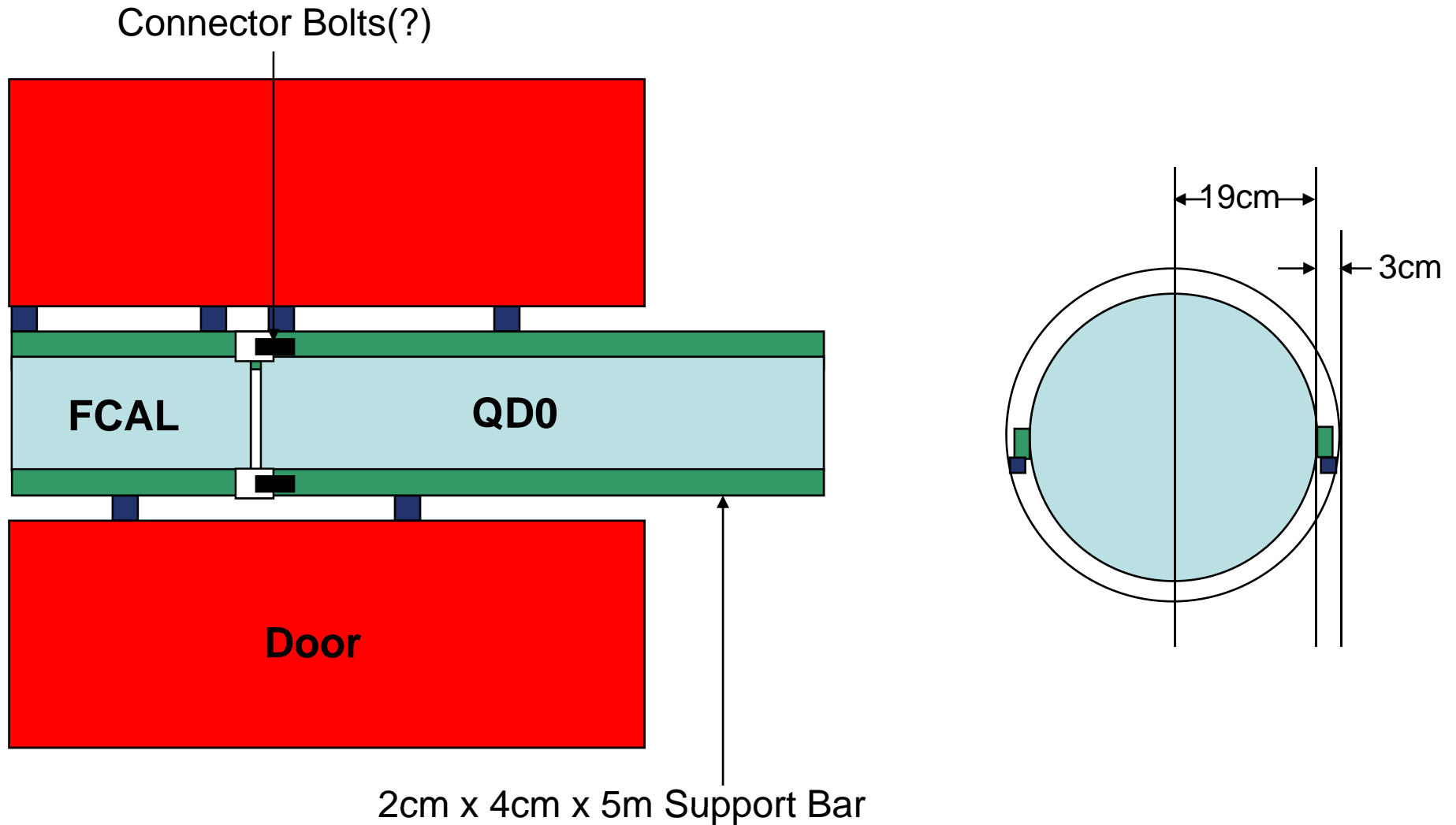


# Door Open, Permanent QD0 Liquid He Line



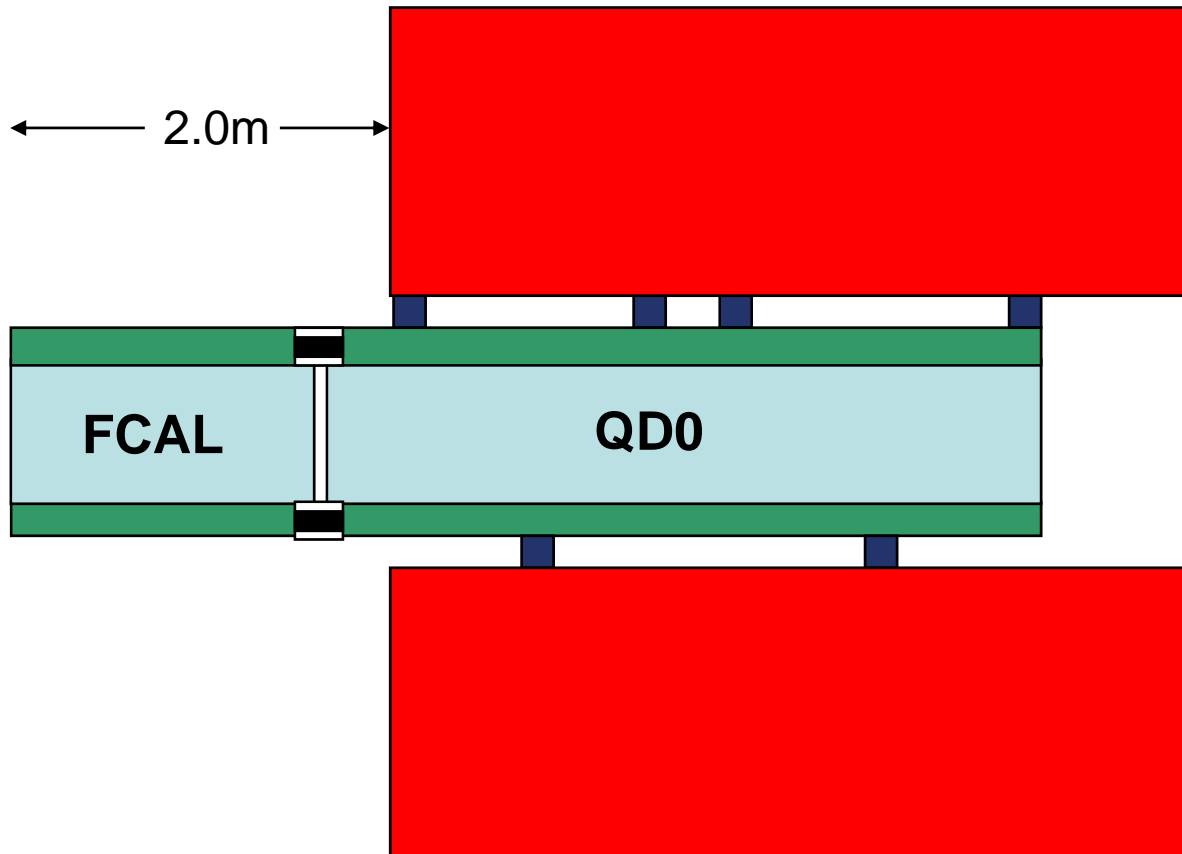


# FCAL/QD0 Supported with Door Closed





# FCAL/QD0 Supported with Door Open



Whether Spider or tube used for Support, SiD has assumed it will be completely supported by door (not cantilevered off a post to the ground) but has not proposed a way to fix it in z when door opens





# Deflections of 2cm x 2cm Support Bars when Door Opens 2m

- Support points with rollers were assumed at front and rear of HCAL ( $Z = 3820, 4770$  mm).
- Forward calorimeters supported at their ends as dead weights
- QD0 weight ignored

4 - 20 mm x 20 mm bars

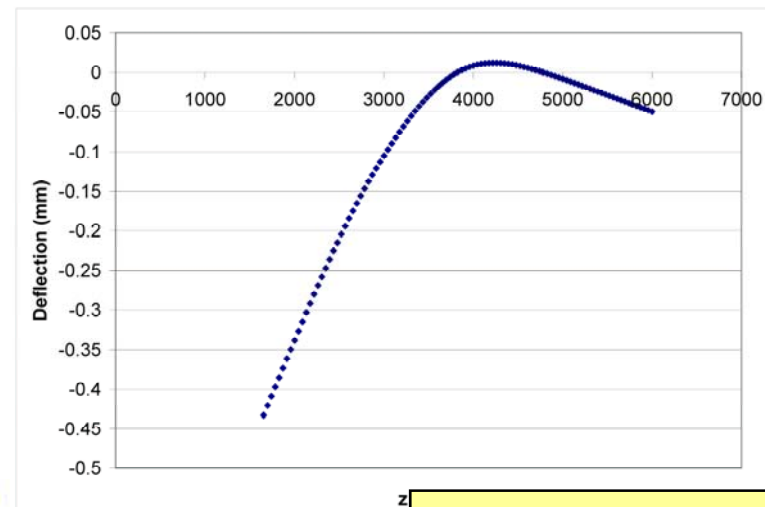
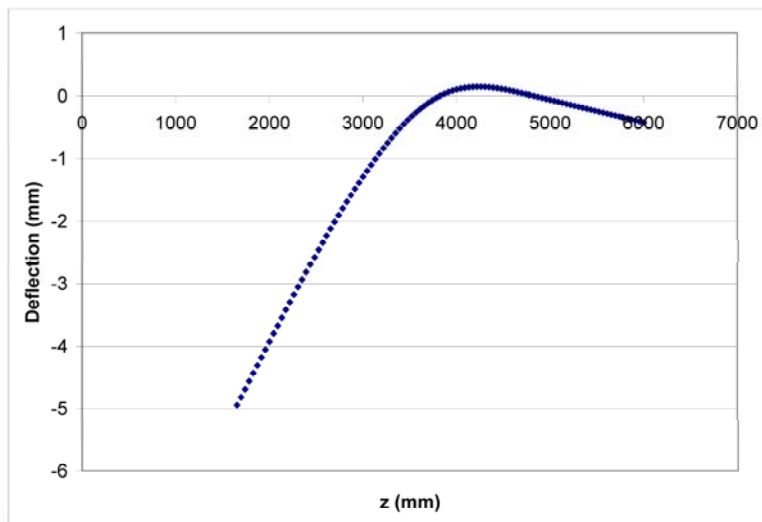
Deflection at front of Lumi-CAL = 4.9 mm

Stress in bars = 12.7 ksi

Stepped cylinders (3, 10, 20 mm walls)

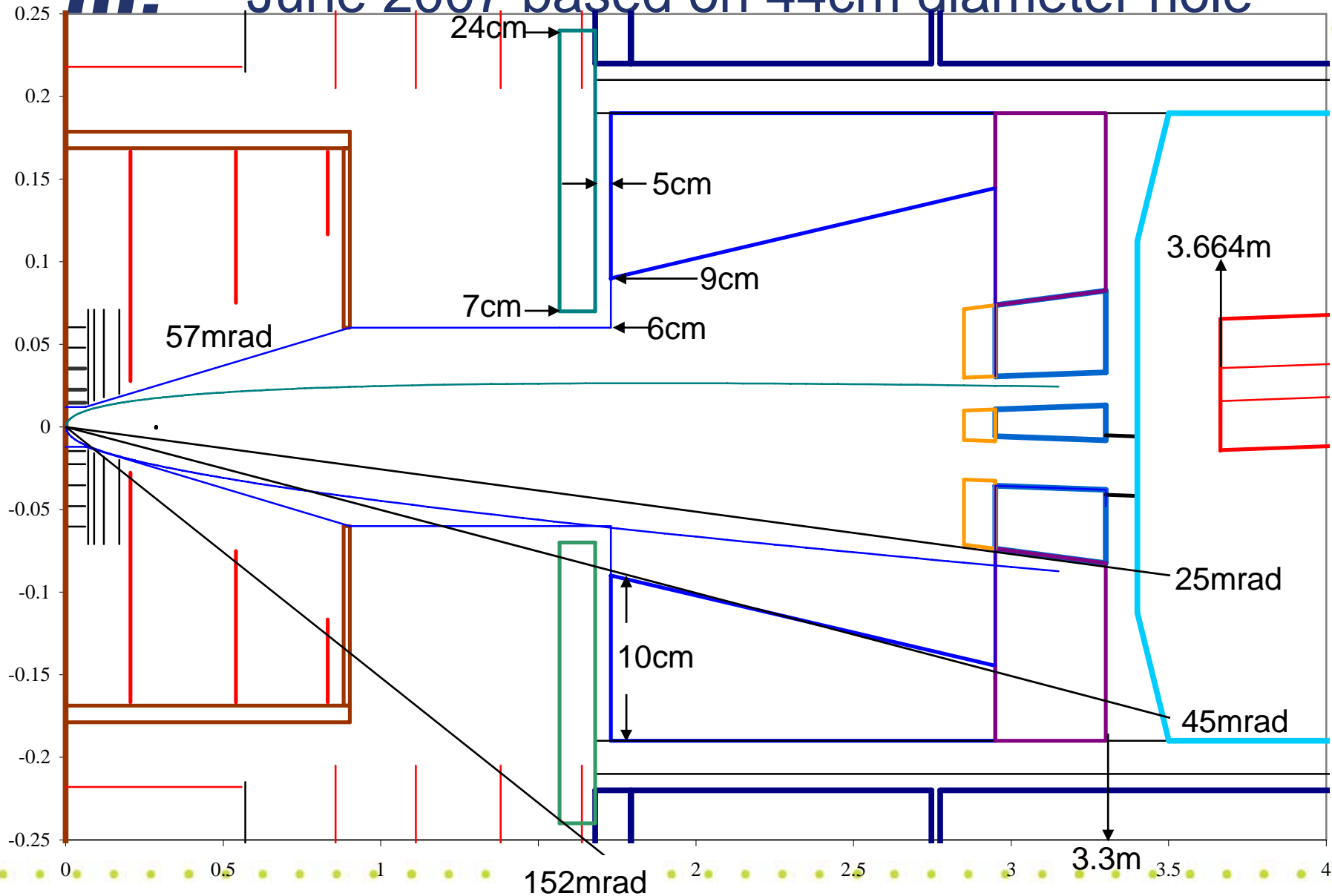
Deflection at front of Lumi-CAL = 0.43 mm

Stress in cylinders = 1.0 ksi





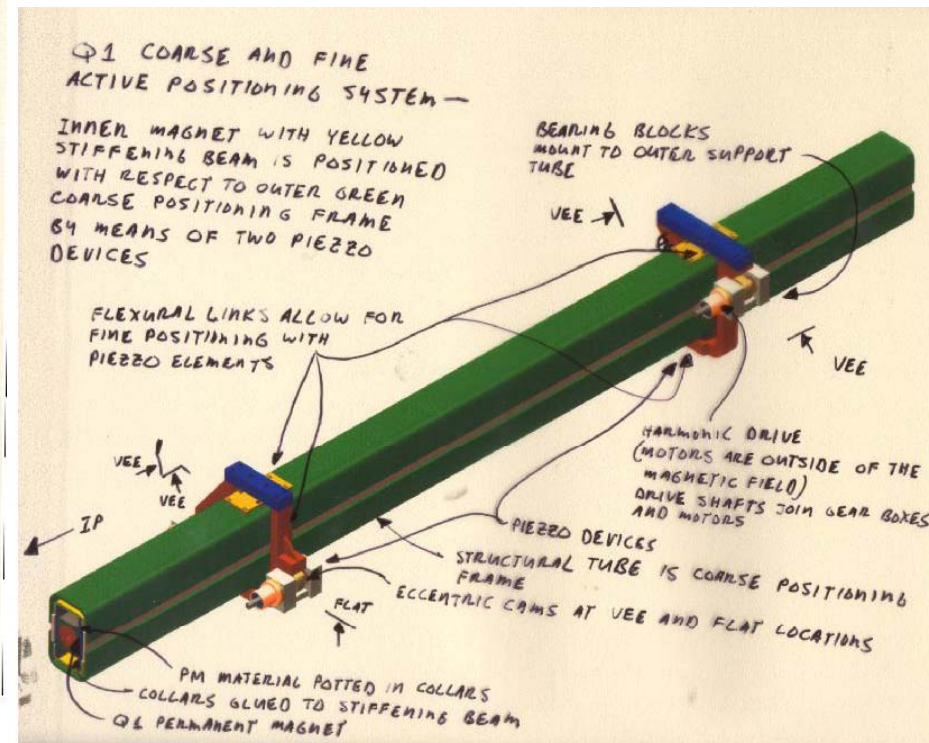
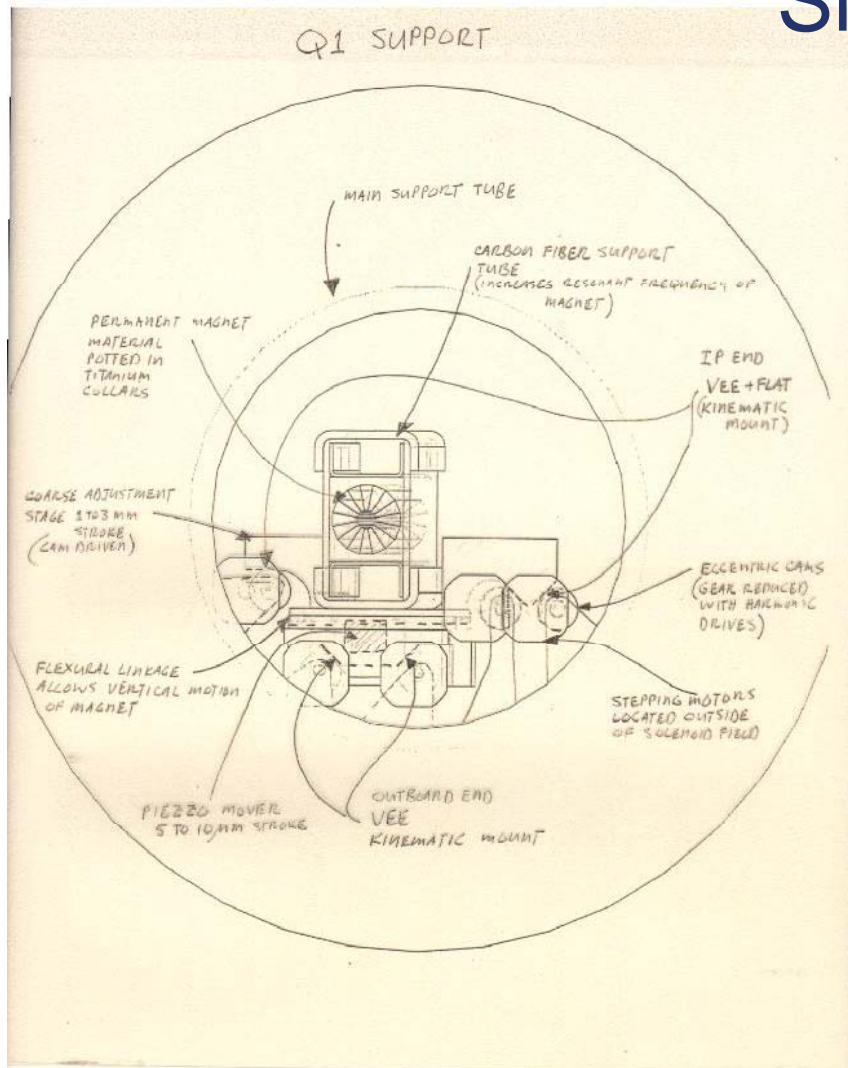
# Suggested FCAL Layout for Discussion June 2007 based on 44cm diameter hole





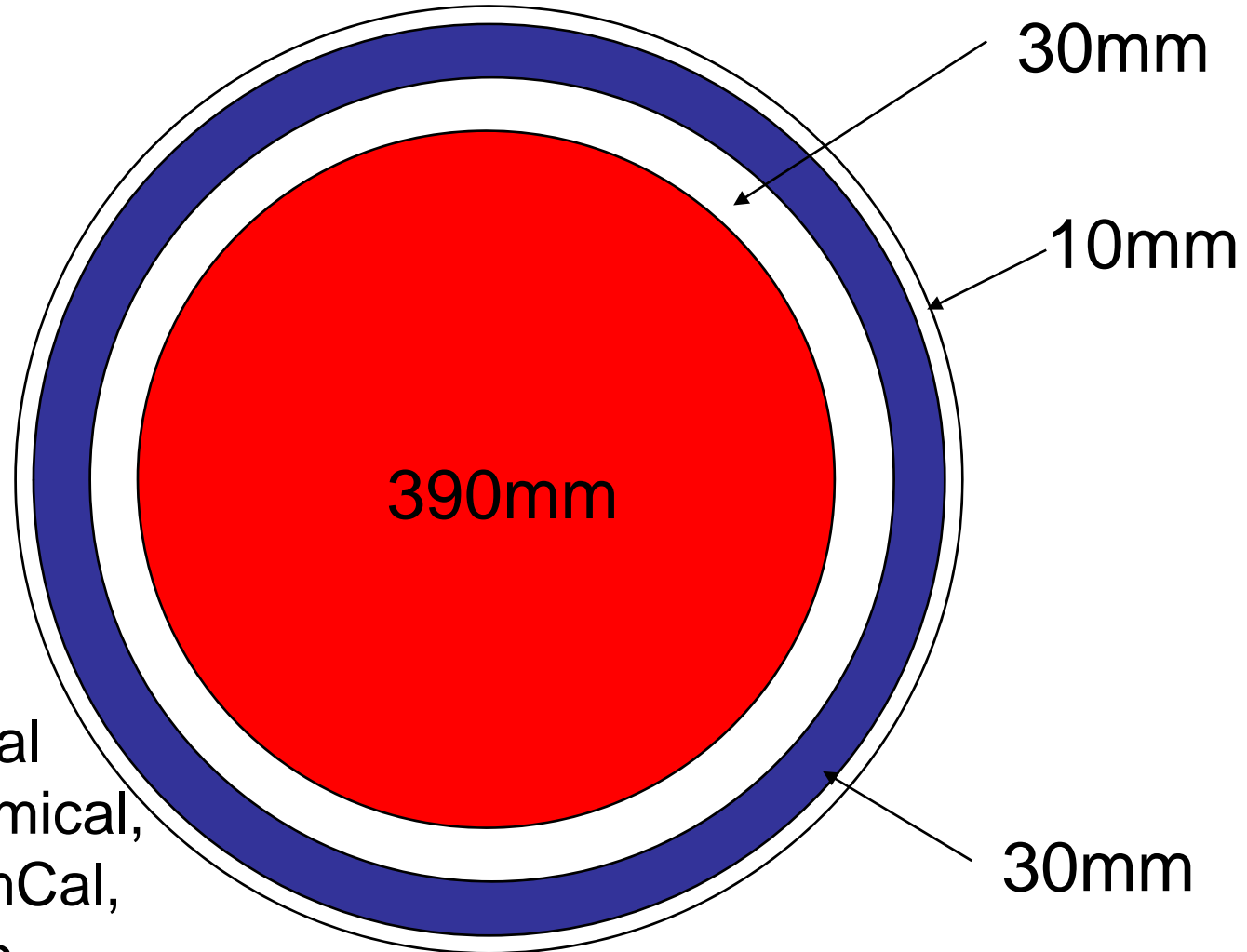
# QD0 Package Adjustment Mechanism Likely to Require Significant Radial Space

Knut Skarpaas 2000 Design of Integrated Coarse/Fine Cam/Piezo Mover System for a stiffened PM QD0





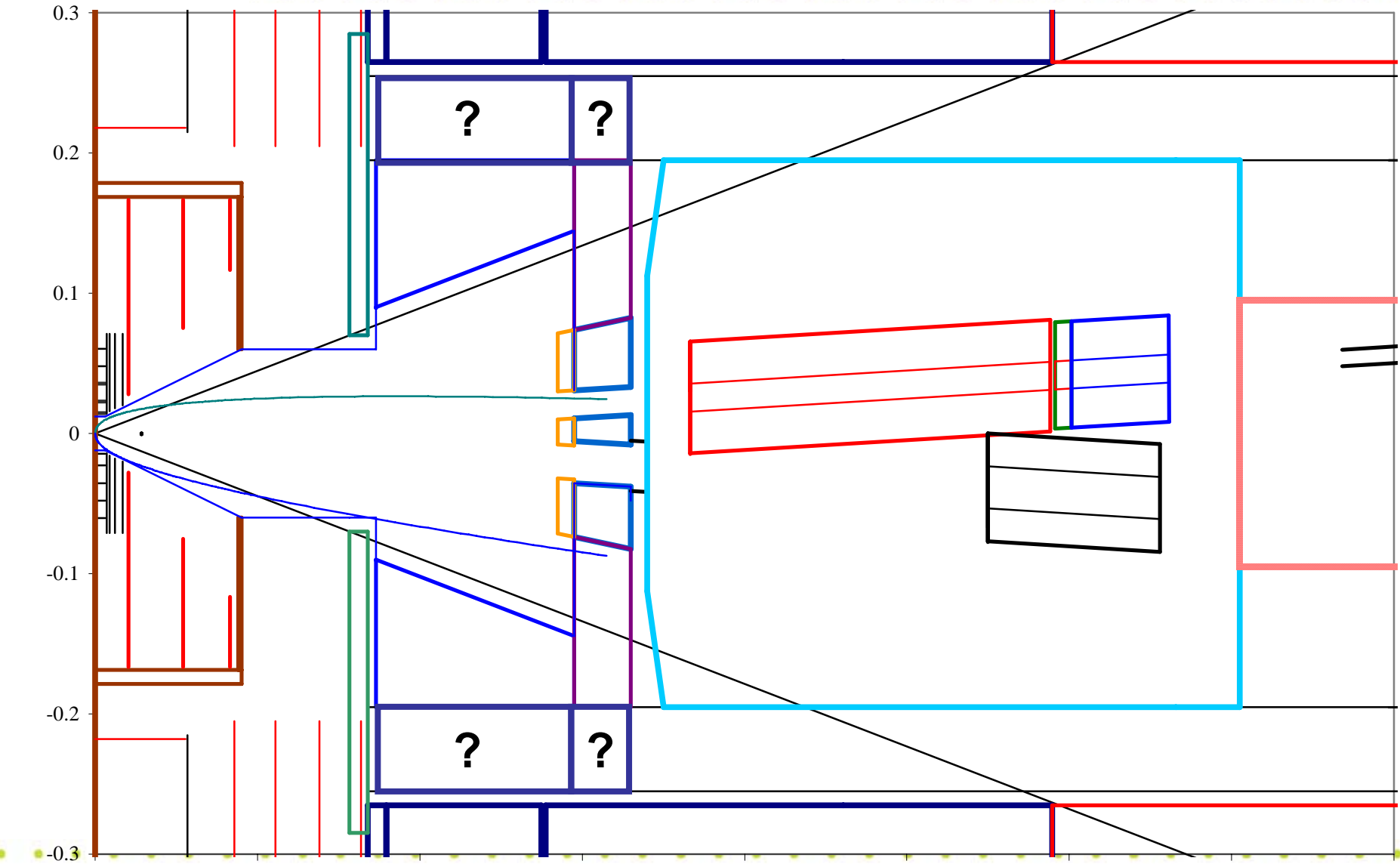
390mm QD0 + 2 x 30mm Support Tube Wall  
+ 2 x 30mm space for adjustment mechanism  
+ 2 x 10mm clearance = 530mm hole in door



530mm total diameter of Lumical, FHCAL, BeamCal, Masks, etc.

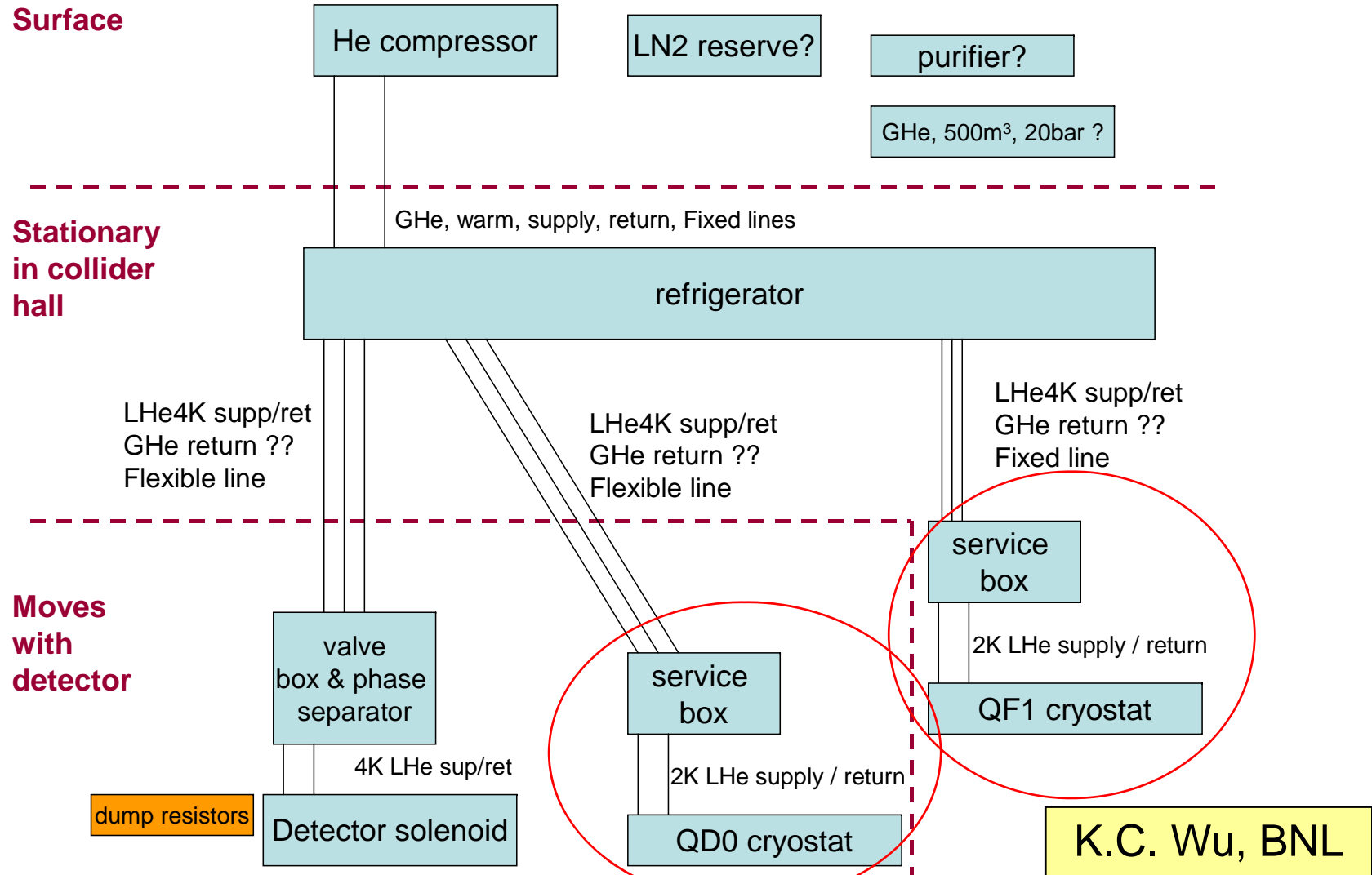


# FCAL Region with $r=26.5\text{cm}$ "R20" design





# Cryogenic Block Diagram in ILC IR Hall

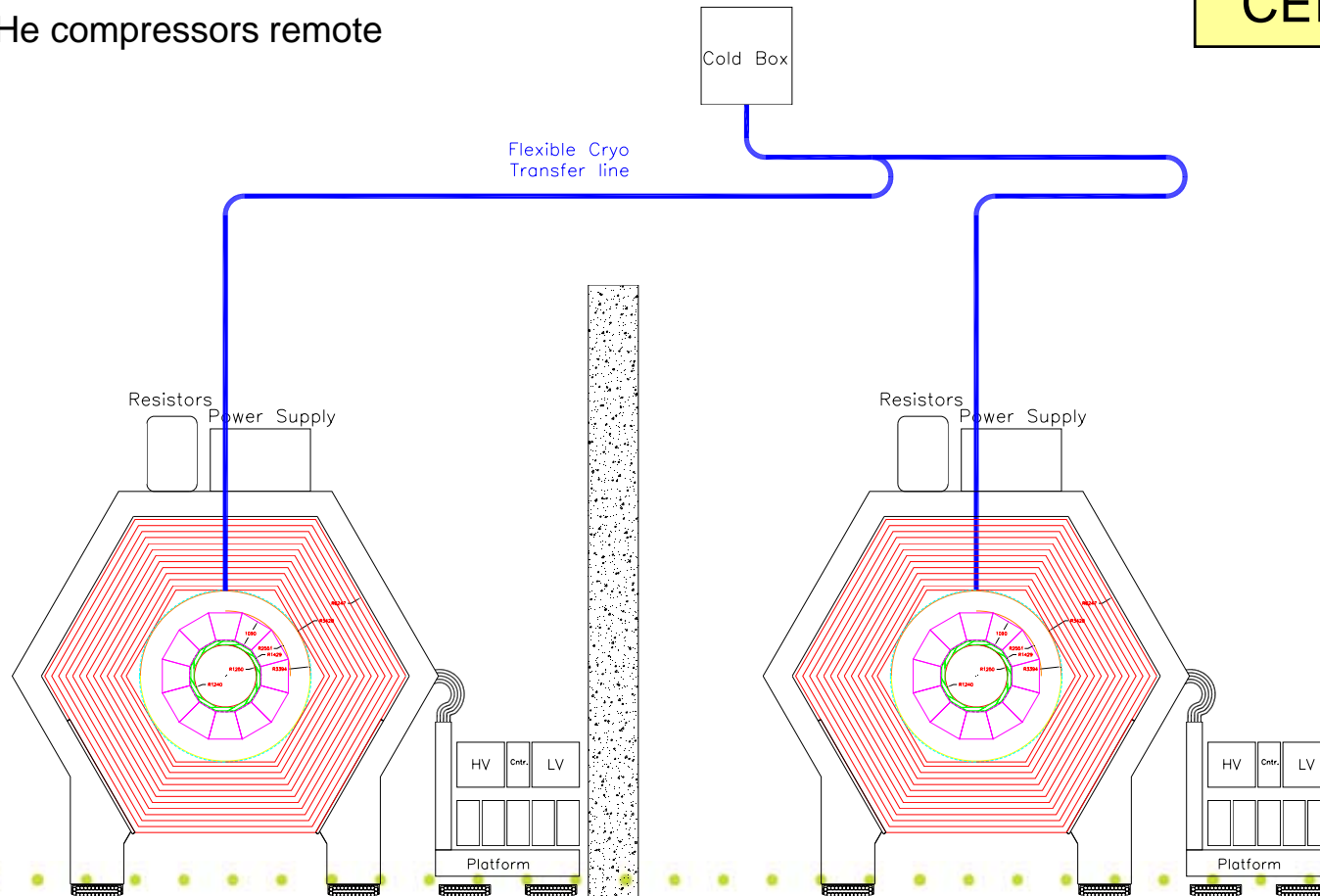




# SiD IR Hall Assumptions

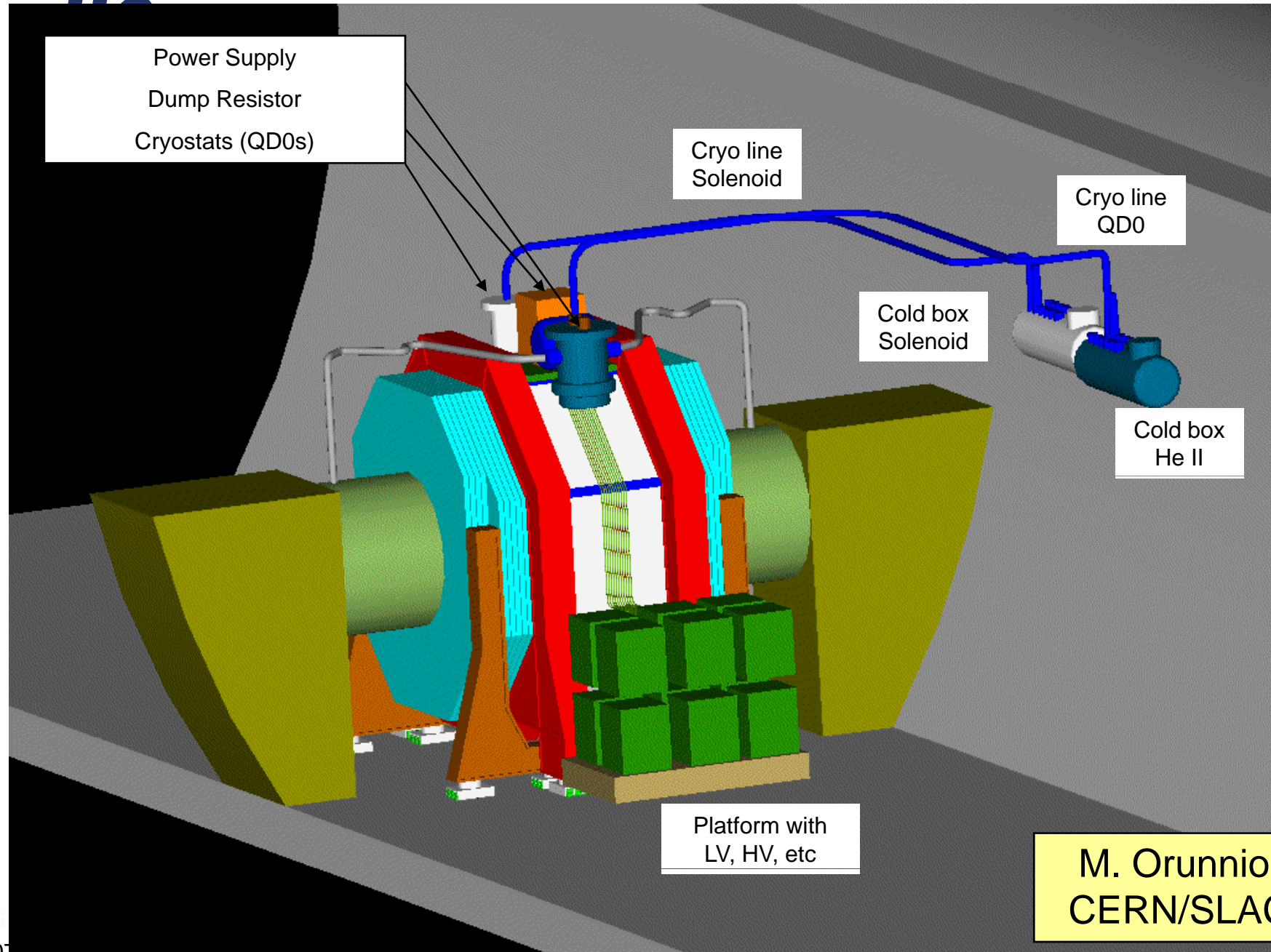
1. Push-Pull and doors opening with Hilman Rollers
2. Racks and ancillaries on SiD or on a side platforms (location driven by the the fringe field)
3. Cold Box off detector (in the hall)
4. Flexible cryogenic transfer line (100mm OD) Solenoid-Cold box
5. He compressors remote

M. Orunnio,  
CERN/SLAC



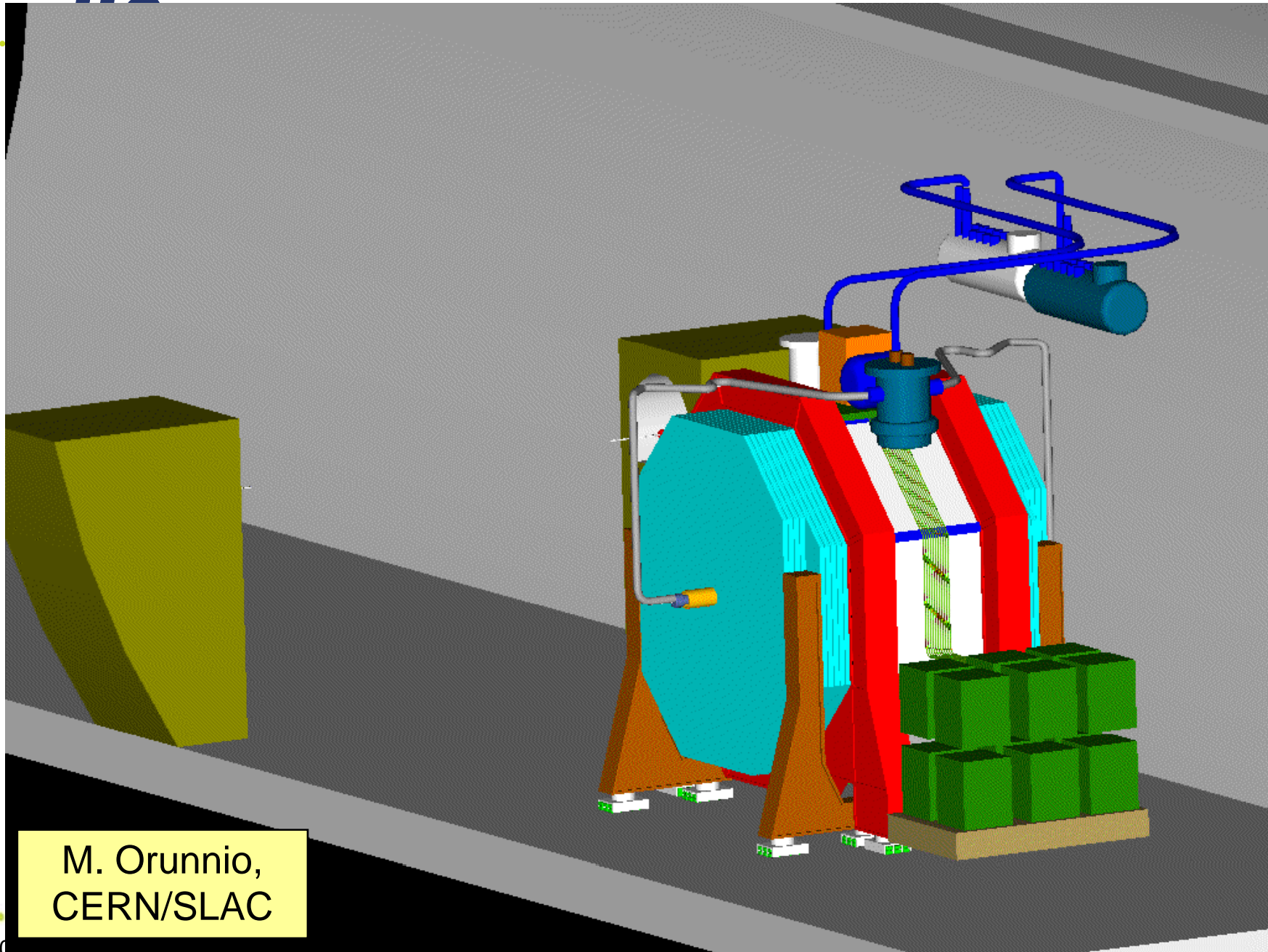


# SiD closed on the beam



M. Orunnio,  
CERN/SLAC

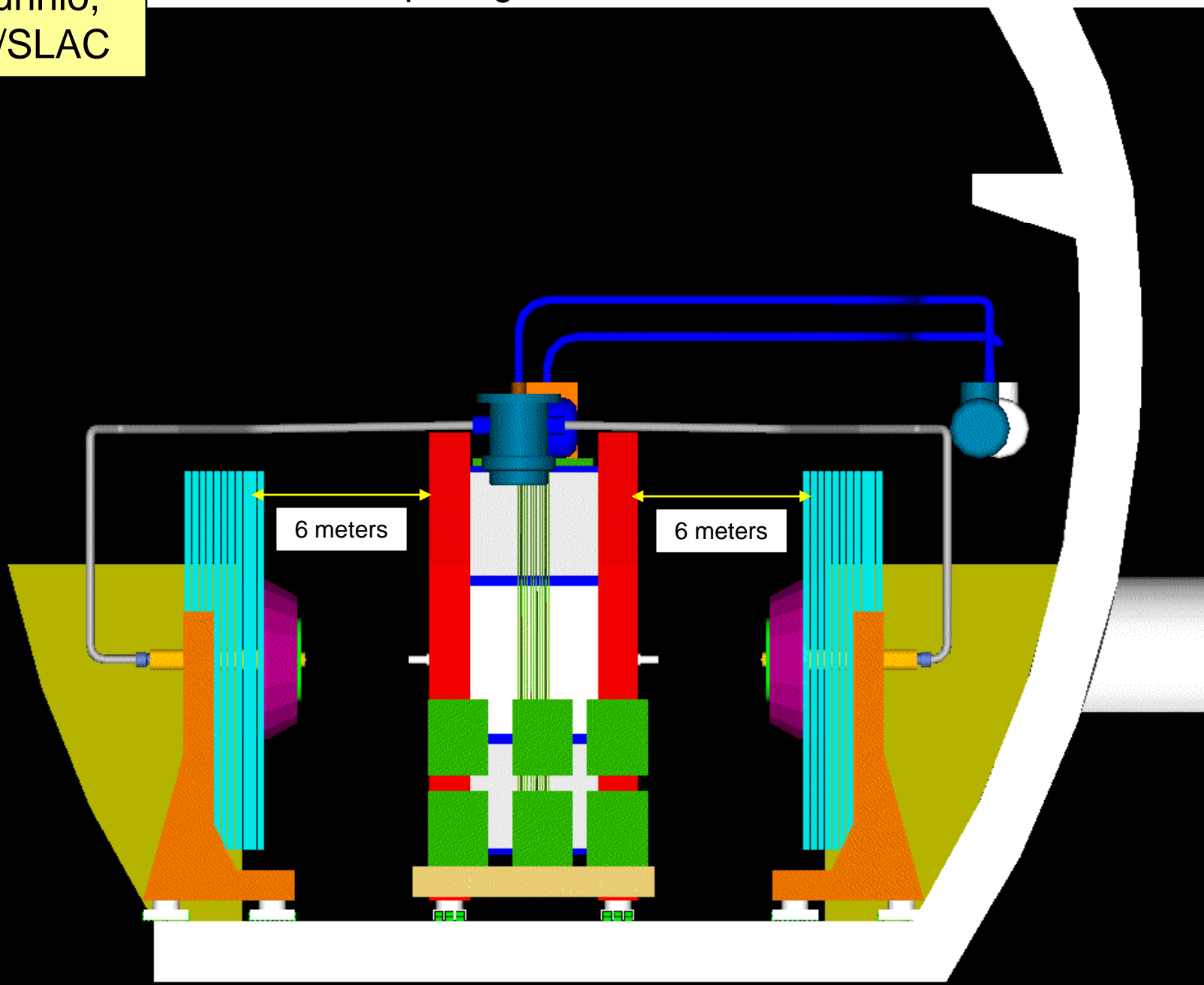
# SiD push-pull (30 meters stroke)



M. Orunnio,  
CERN/SLAC

M. Orunnio,  
CERN/SLAC

SiD opening @ 6 m off the beam







# Summary of Push Pull & Surface Assembly Aspects of MDI

- GLDc and LDC have similar designs with similar crane/shaft requirements wherein FCAL/mask/QDO package supported in a tube off cantilevered off a pillar to ground (or platform)
- GLDc shows a moving platform while LDC says either platform or rollers would work
- SiD requires 2x gantry capacity for “CMS” surface assembly
  - **not convinced that non-CMS-like underground assembly is better**
  - **Feels (MIB at least) that platform is expensive solution germane to CERN geology & LHC detector complexity**
- SiD FCAL/mask/QDO package supported in a spider or tube directly from doors
  - **Needs to address how z motion of support tube is controlled**



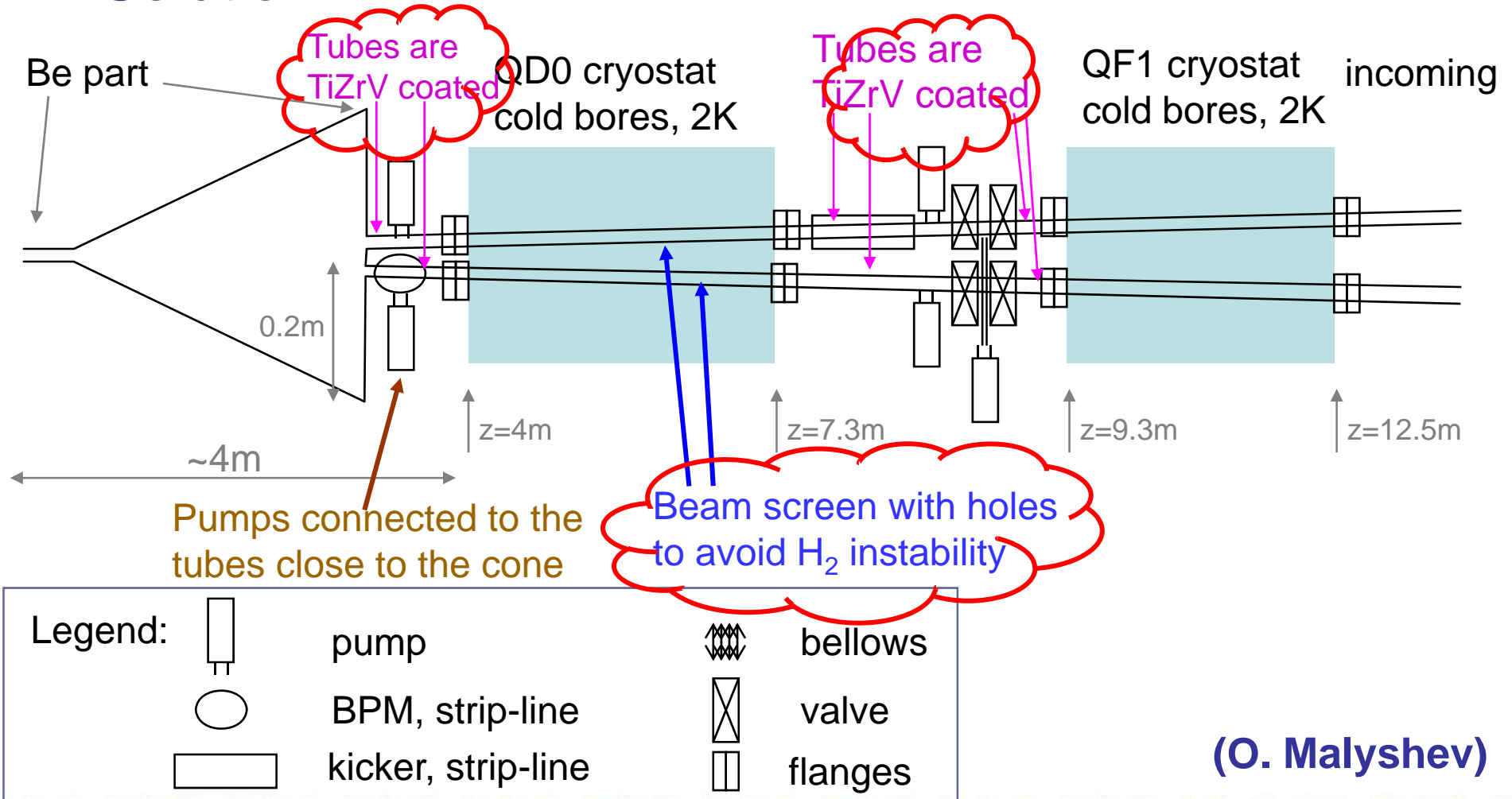
# Interface Issues

- 1<sup>st</sup> order self-consistent PACMAN shielding invoked by GLDc, LDC, SiD. However, engineering required
  - **To see underground crane capacity required**
    - GLDc shows 0.5m Fe / 2.0m concrete from  $r=0.5\text{m}$
    - SiD shows 1.0m Fe/ 2.0m concrete from  $f=0.25\text{m}$
    - Rad Phys calculation done for 0.5 m Fe / 2.0m Con from  $r=1.25\text{m}$
  - **To understand where detector A to detector B PACMAN interface occurs**
  - **To understand how to remove detector A specific PACMAN shielding “trapped” on detector B side of the beamline**
    - Hinged to the doors of detector A?
- Platform A, platform B, Floor, detector A, detector B interfaces
  - **If “A” needs/desires moving platform solution, must “B” adopt as well**



# IR Vacuum\_12: Potential Big Deal

## • Solution 2

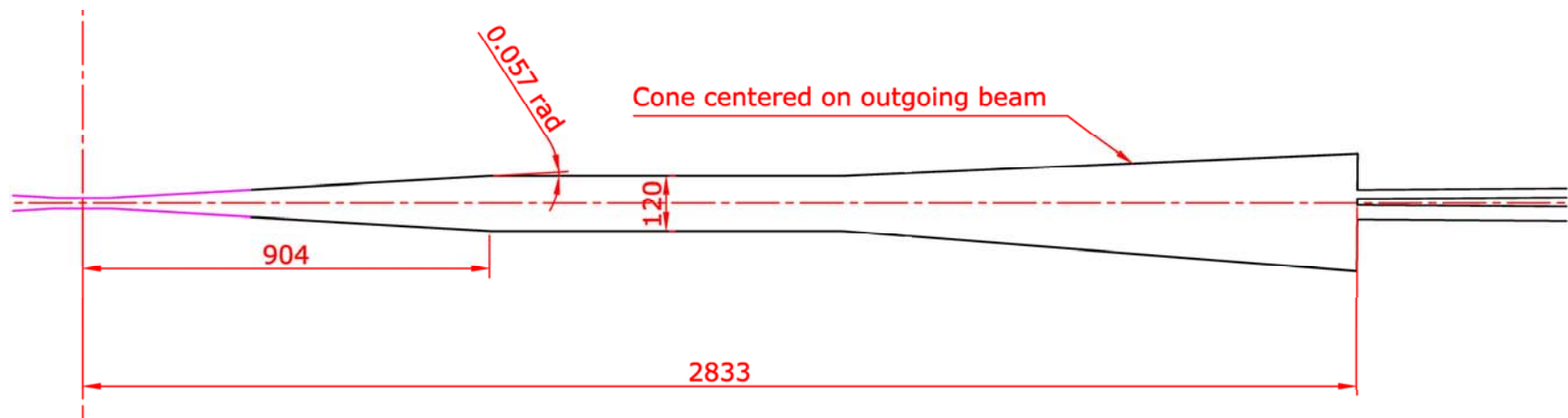


(O. Malyshev)



# Beam Pipe Fabrication

- The present SiD design assumes stainless steel beyond  $Z = 759$  mm.
  - That allows more standard welding and fabrication techniques.
  - Beryllium to stainless transitions should be done by the fabricator of beryllium portions, but the stainless steel portions could be made by a different vendor.
  - Uriel Nauenberg has asked about the feasibility of using other materials (beryllium, aluminum) in the BeamCAL region; materials for that region are under discussion.







# SiD MDI Recommendations

- Don't worry about BDS costs
  - **Embrace IRENG'07 shaft/support model**
  - **Insist on one gantry sized to lower loaded SiD barrel**
  - **Assume sliding platform for push-pull**
- Adopt same cantilevered support tube + fixed pillar as GLDc/LDC
- Size radius of support tube from ~20cm to ~30cm for the 390mm QD0 cryostat diameter and incorporate Knut Skarpaas 2000 design of cam + piezo mover system.
- Resize LumiCAL for this radius and develop an optimized design which accounts for increased mass of lumical, FHCAL, BEamcal, shielding, beampipe shape, electronics, and service pipe/cable ways
  - **Decide whether FCAL package shares QD0 mover system or not**