

Using TBT data at ATF DR

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Introduction

The Fourier analysis of TBT data has been first applied at LEP in 1992 as a tool for measuring the *uncoupled linear optics*.

TBT data at the j^{th} BPM following a **single** kick in the z plane ($z \equiv x, y$)

$$z_n^j = \frac{1}{2} \sqrt{\beta_z^j} e^{i\Phi_z^j} A_z e^{iQ_z(\theta_j + 2\pi n)} + c.c.$$

with $n \equiv$ turn number $A_z = |A_z| e^{i\delta_z} \equiv$ constant of motion

$$\Phi_z \equiv \mu_z - Q_z \theta \quad (\text{periodic phase function})$$

Twiss functions:

$$\beta_z^j = |Z_j(Q_z)|^2 / A_z^2 \quad \mu_z^j = \arg(Z_j) - \delta_z$$

$$Z_j(Q_z) \equiv \text{Fourier component of } z_j$$

Amplitude fit:

$$|A_z|^2 = \frac{\sum_j 1/\beta_z^{0j}}{\sum_j 1/|Z_j(Q_z)|^2}$$

Linear Coupling

Method of the **variation of constants**:

The general solution of the perturbed motion keeps the form of the unperturbed one with constants depending on time^a

Hamiltonian in presence of a perturbation, H_1 ,

$$H = [H_0 + H_1](q_1, \dots, q_n, p_1, \dots, p_n) = [U_0 + U_1](c_1, \dots, c_{2n})$$

Equations of motion

$$\frac{dc_j}{dt} = \sum_m [c_j, c_m] \frac{\partial U_1}{\partial c_m}$$

When the unperturbed Hamiltonian describe the **betatron motion**, thus

$$\frac{dA_z}{d\theta} = i \frac{\partial U_1}{\partial A_z^*} \quad \frac{dA_z^*}{d\theta} = -i \frac{\partial U_1}{\partial A_z}$$

^a θ or s in our case

For perturbation fields generating **linear coupling** (Guignard)

$$U_1(\vec{a}) = \frac{1}{2} [C_+(\theta) a_x a_y + C_+^*(\theta) a_x^* a_y^* + C_-(\theta) a_x a_y^* + C_-^*(\theta) a_x^* a_y]$$
$$a_z \equiv A_z e^{iQ_z \theta}$$

where

$$C_{\pm}(\theta) \equiv \frac{R\sqrt{\beta_x\beta_y}}{2B\rho} \left\{ \left(\frac{\partial B_x}{\partial x} - \frac{\partial B_y}{\partial y} \right) + B_\theta \left[\left(\frac{\alpha_x}{\beta_x} - \frac{\alpha_y}{\beta_y} \right) - i \left(\frac{1}{\beta_x} \mp \frac{1}{\beta_y} \right) \right] \right\} e^{i(\Phi_x \pm \Phi_y)}$$

and

$$\Phi_z \equiv \mu_z - Q_z \theta$$

“Ansatz” (Yuri Alexahin)

$$a_x(\theta) = a_{x0}(\theta) + w_-^*(\theta)a_{y0}(\theta) + w_+^*(\theta)a_{y0}^*(\theta)$$

$$a_y(\theta) = a_{y0}(\theta) - w_-(\theta)a_{x0}^*(\theta) + w_+(\theta)a_{x0}^*(\theta)$$

Inserting into the equation of motion and keeping 1th order terms one finds the equations for w_{\pm}

$$2ie^{-iQ_{\pm}\theta} \frac{d}{d\theta} e^{iQ_{\pm}\theta} w_{\pm}(\theta) = C_{\pm}(\theta)$$

The **periodic** solutions are

$$w_{\pm}(\theta) = - \int_0^{2\pi} d\theta' \frac{C_{\pm}(\theta')}{4 \sin \pi Q_{\pm}} e^{-iQ_{\pm}[\theta-\theta' - \pi \text{sign}(\theta-\theta')]}$$

with

$$Q_{\pm} \equiv Q_x \pm Q_y$$

The functions $\tilde{w}_{\pm} \equiv w_{\pm} e^{iQ_{\pm}\theta}$ are

- **constant** in coupler **free** regions
- experience a **discontinuity** $-iC_{\pm}\ell/2R$ at coupler locations \Rightarrow **diagnostics tool !**
- are **constant** on the resonances $Q_x \pm Q_y = int.$

Minimum tune split (Guignard)

$$\Delta \equiv |\bar{C}_-^{n-}| \quad \bar{C}_{\pm}^{n_{\pm}} = \frac{1}{2\pi} \int_0^{2\pi} d\theta C_{\pm} e^{in_{\pm}\theta} = \frac{n_{\pm} - Q_{\pm}}{\pi} \int_0^{2\pi} d\theta w_{\pm} e^{in_{\pm}\theta}$$

with

$$n_{\pm} \equiv \text{Round}(Q_x \pm Q_y)$$

Linear coupling computation through TBT analysis

TBT beam position at the j^{th} vertical BPM following a horizontal kick

$$y_n^j = \left[\sqrt{\beta_y^j} \left(e^{-i\Phi_y^j} w_+^j - e^{i\Phi_y^j} w_-^j \right) \right] A_x e^{iQ_x(\theta_j + 2\pi n)} + c.c.$$

TBT beam position at the j -th horizontal BPM following a vertical kick

$$x_n^j = \left[\sqrt{\beta_x^j} \left(e^{-i\Phi_x^j} w_+^j + e^{i\Phi_x^j} w_-^{*j} \right) \right] A_y e^{iQ_y(\theta_j + 2\pi n)} + c.c.$$

The FFT of y^j at Q_x , $Y^j(Q_x)$, for a horizontal kick ($X^j(Q_y)$ for a vertical one) is proportional to the coupling functions $w_{\pm}(\theta_j)$.

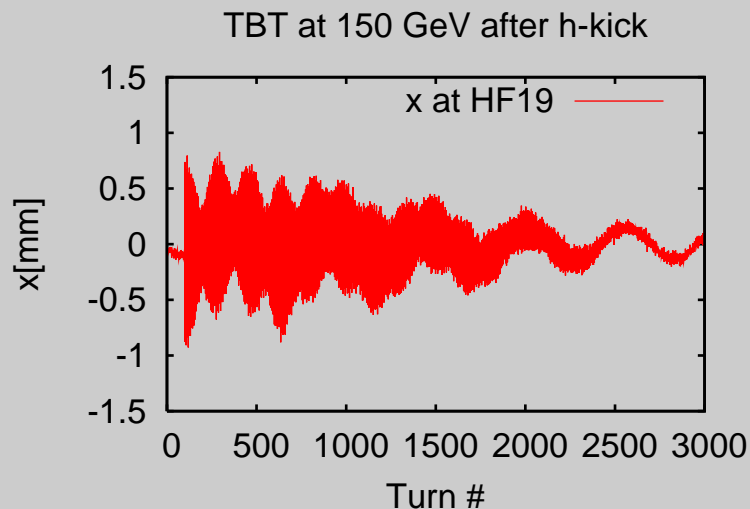
We get per each BPM 2 real equations in 4 unknowns. When between two consecutive monitors there are no strong source of coupling, the four equations can be solved in favor of $w_{\pm}(\theta_j) = w_{\pm}(\theta_{j+1})$.

Examples of Tevatron Measurements

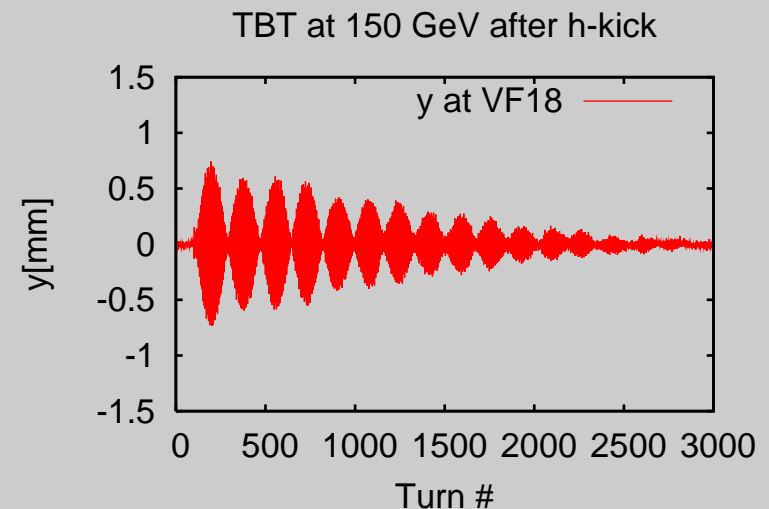
Tevatron is a $p\bar{p}$ collider working close to the $Q_x \pm Q_y$ resonances. The machine has 118 horizontal and 118 vertical BPM's. They can store 8192 positions data per BPM. The electronics upgrade allows a high resolution ($\simeq 50 \mu\text{m}$) measurement of the TBT beam position.

Under "ideal" conditions the oscillations following a kick last some thousand turns

TBT position after a horizontal kick

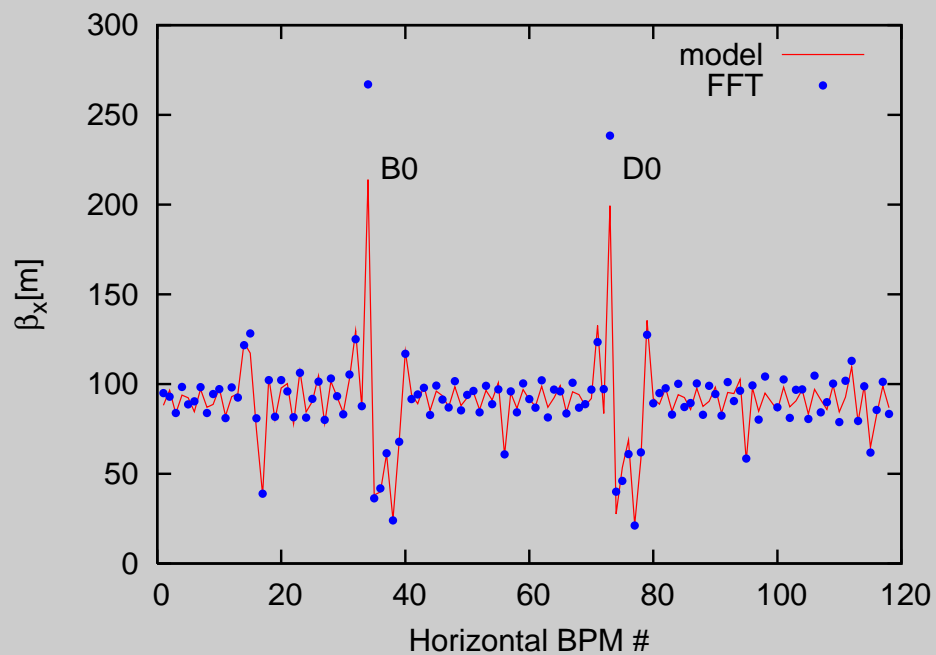


TBT position at HF19

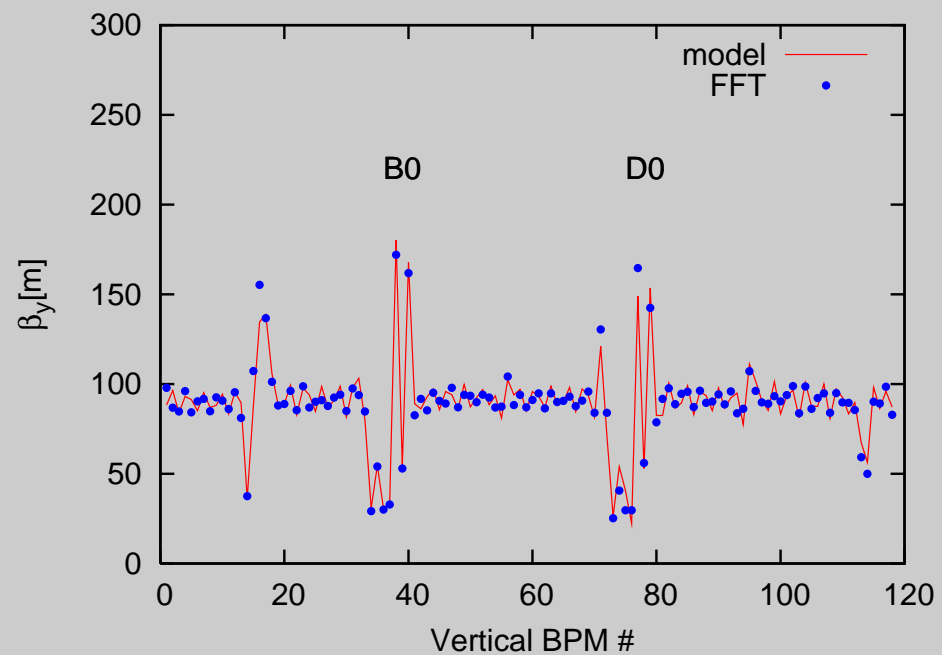


TBT position at VF18

Reconstructed Injection Optics (November 2005 data)

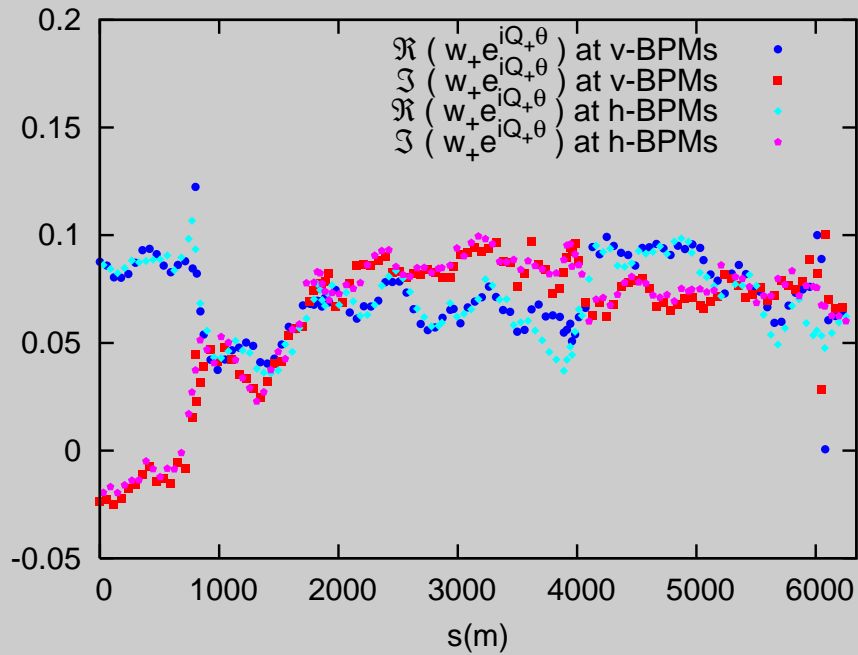


Horizontal

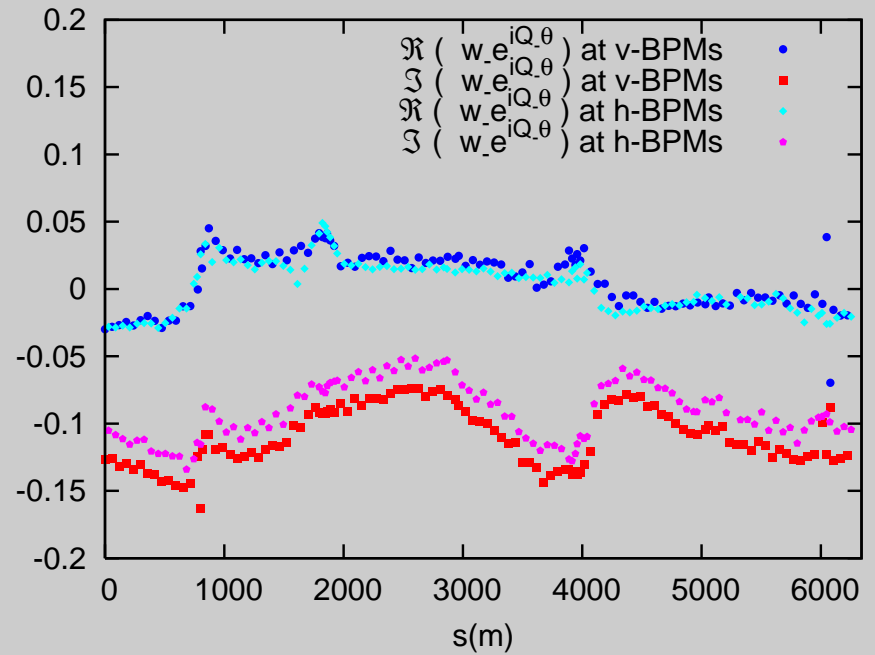


Vertical

Coupling functions (November 2005 data)



\tilde{w}^+

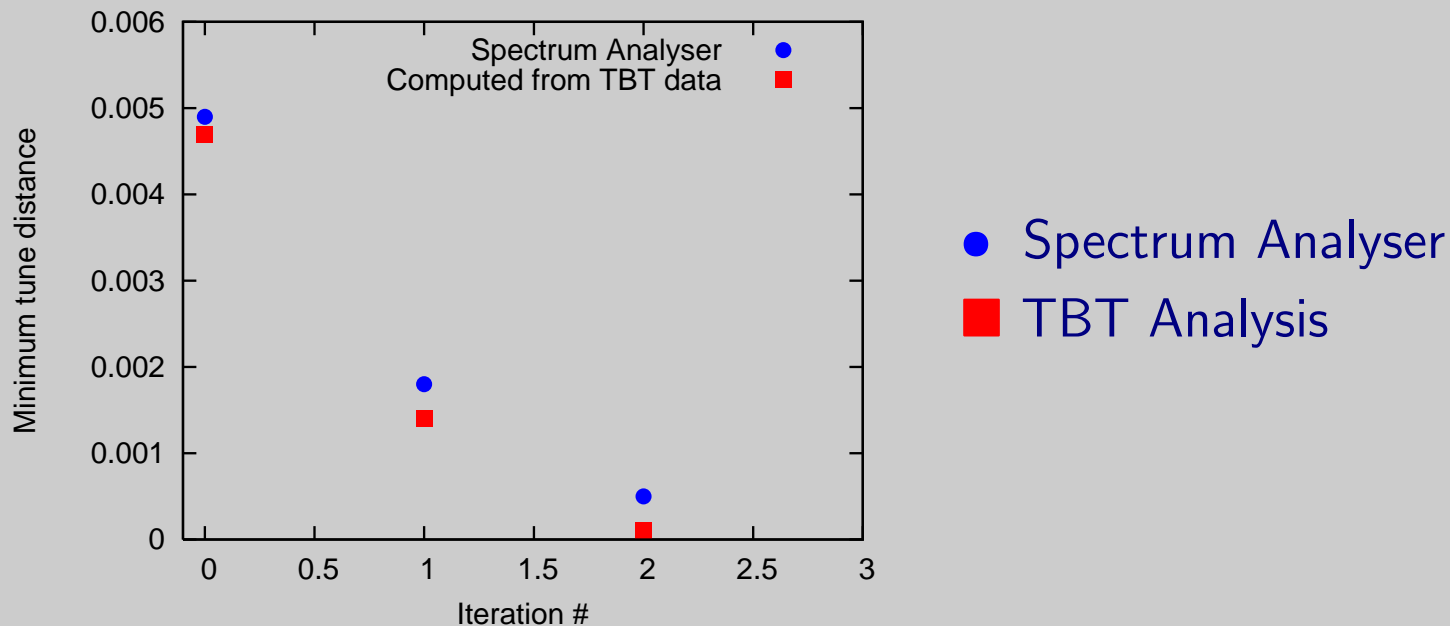


\tilde{w}^-

Jumps visible around 1000 (SQA0), 1500 (A38) and 4000 (D16) meters.

An application program for the TBT analysis has been integrated in the TEVATRON control system and is used **routinely** at **shot set up** for correcting the **minimum tune split** $\Delta \equiv |\bar{C}_-|$ with **two skew quadrupole circuits**. TEVATRON being a **fast ramping** machine (83 seconds from 150 to 980 GeV), the TBT analysis is a very practical method for measuring optics and coupling also during **acceleration**.

Minimum tune split measured with S.A. and computed from TBT data



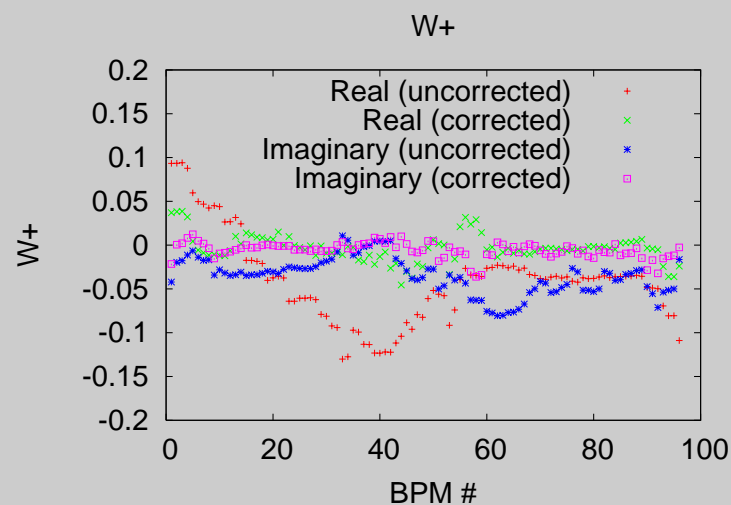
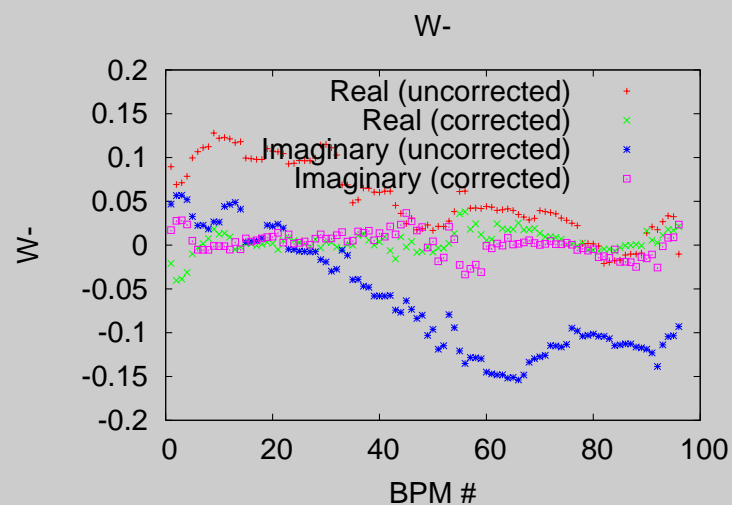
Simulations for ATF DR

Main goal: preserve design small vertical emittance, beside optics correction.

Therefore one must correct betatron coupling *and* spurious vertical dispersion.

Error simulation^a: gaussian random roll errors (rms value: 5 mrad) for all normal quadrupoles (ideal model from M.Woodley).

Correction: simultaneous correction of w^\pm and spurious vertical dispersion using all skew quadrupoles and assuming 96 BPMs.



^aMADX-PTC used for generating trajectories and computing the Mais-Ripken coupled twiss functions

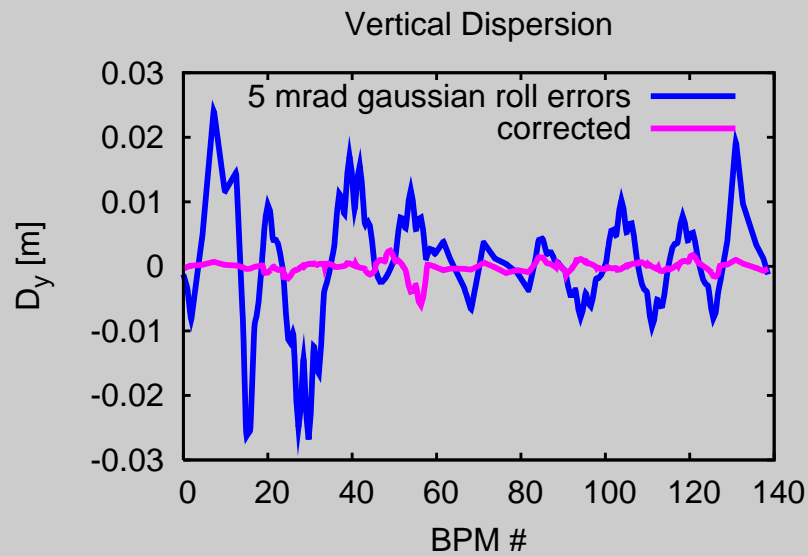
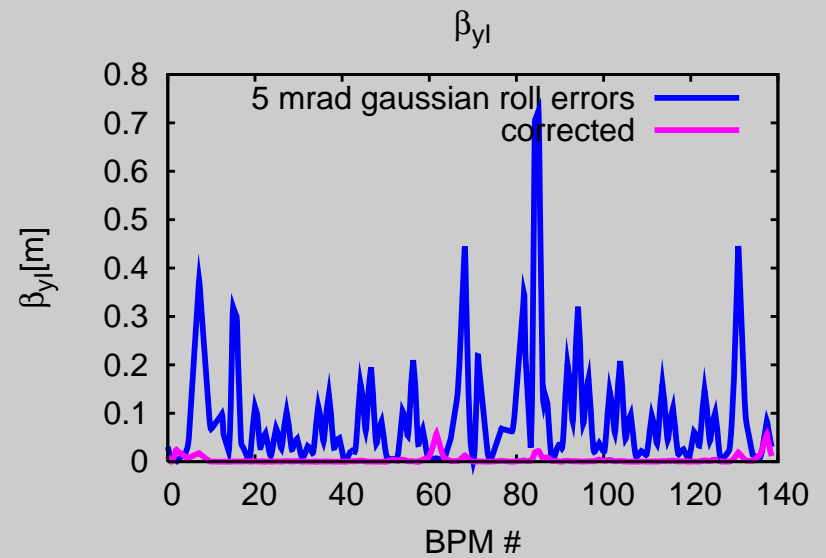
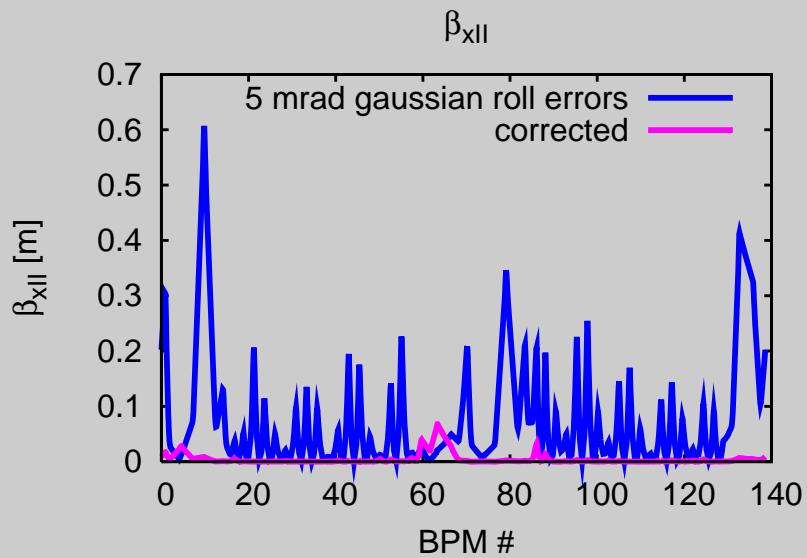


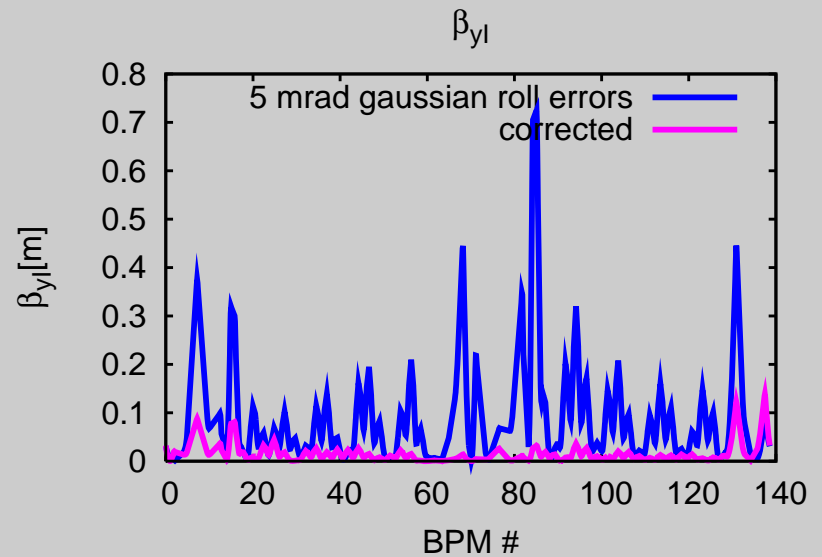
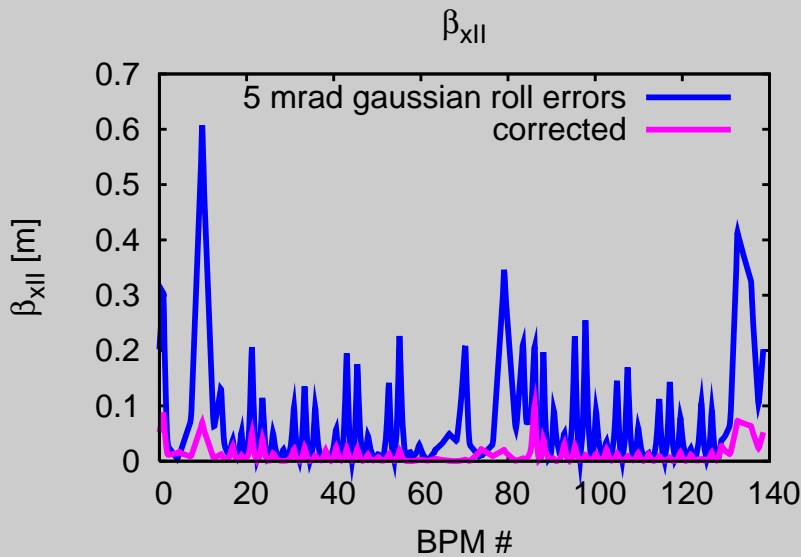
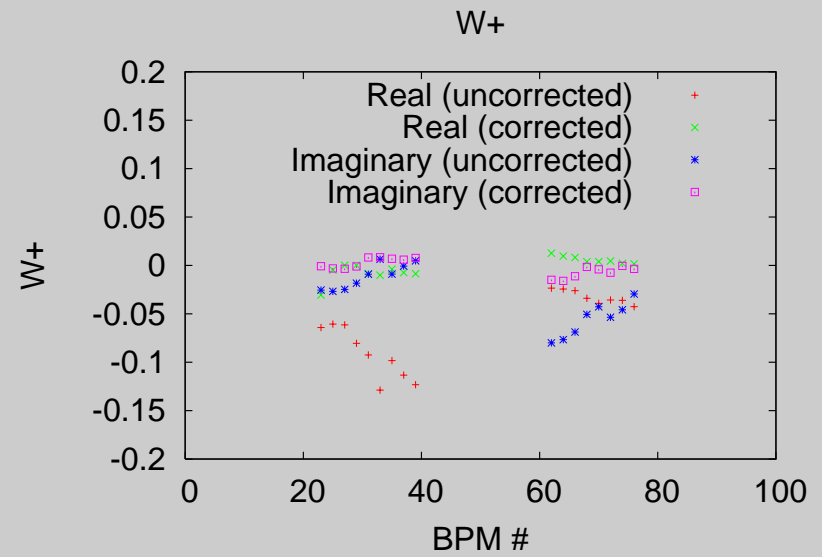
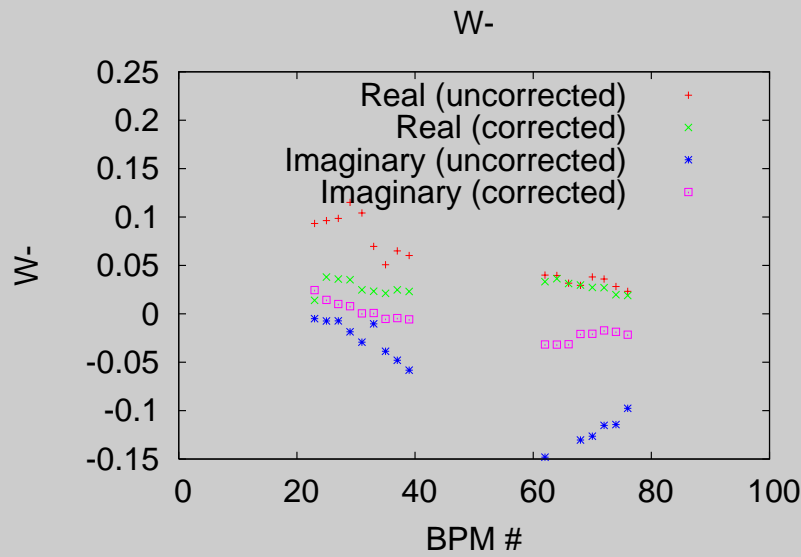
Table 1: Transverse Emittance

	ϵ_x (nm)	ϵ_y (nm)
Nominal	0.973	0.000
with errors	0.971	0.042
β -tron coupling correction	0.973	0.012
D_y correction	0.970	0.013
correcting both	0.973	0.001

Currently 20 BPMs are available: what can we expect?

For measuring D_y the TBT capability is not needed.

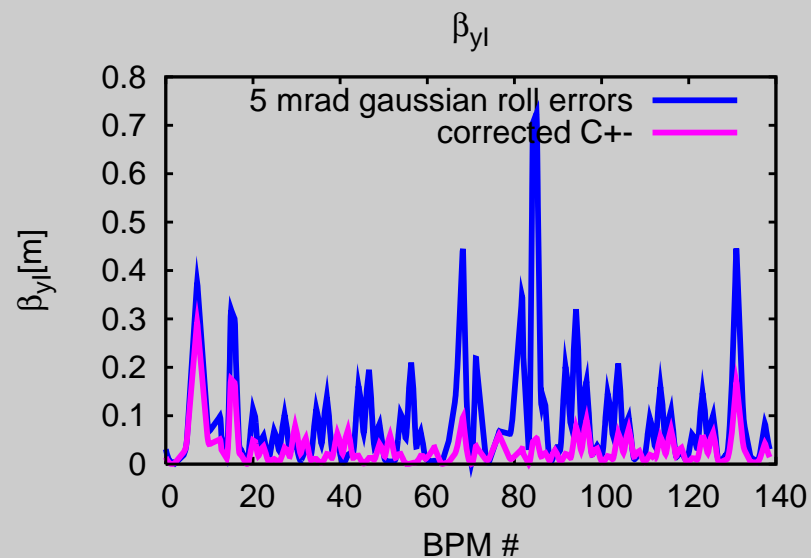
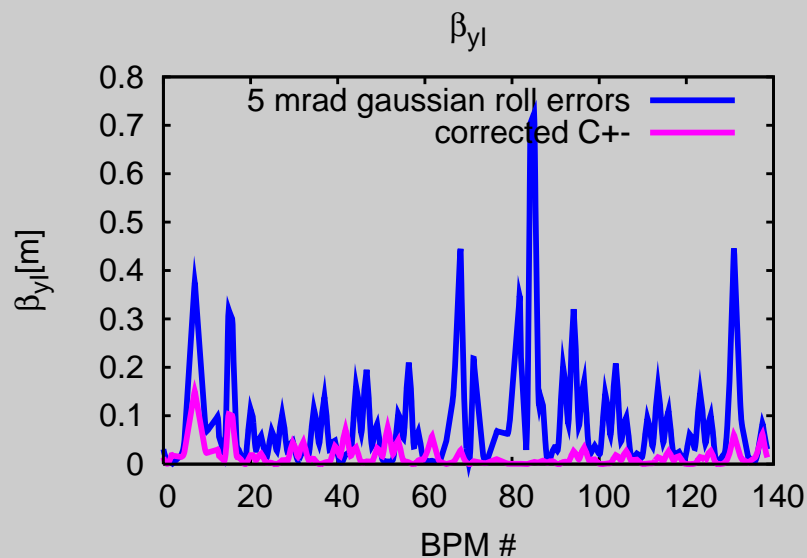
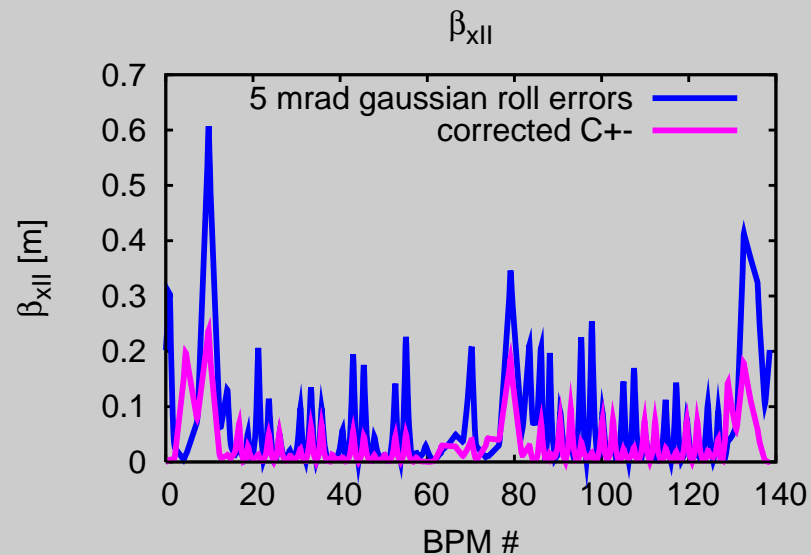
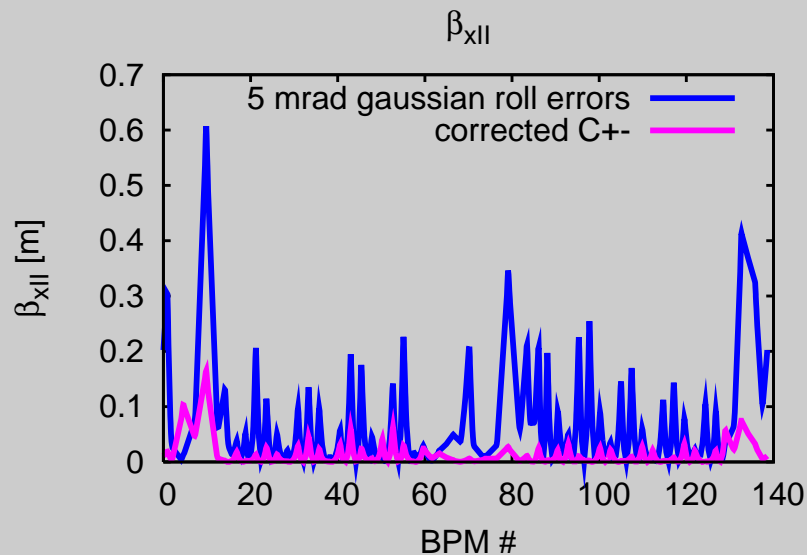
We can compensate the betatron coupling where the values of w^\pm are known and correct the spurious vertical dispersion at all BPMs.



$\epsilon_y = 0.022$ nm (only betatron coupling correction)

$\epsilon_y = 0.004$ nm (betatron coupling + dispersion correction)

We can also correct just the coupling coefficients C^\pm , together with D_y



96 BPMs $\epsilon_y = 0.006$ nm

20 BPMs $\epsilon_y = 0.013$ nm

Summary

- the simultaneous correction of betatron coupling and spurious vertical dispersion presented here looks promising
- also with 20 BPMs we should be able to see the effect of the skew quadrupoles on the coupling functions and eventually correct the machine linear coupling
- for localizing coupling sources a larger number of observation points (BPMs) is needed
- caution with numbers: results are just qualitative, no statistics, and in particular no quadrupole misalignment considered!

Machine Modeling using TBT Data

The Fourier analysis^a of the measured TBT data

$$\begin{aligned}x_n &= A_I \sqrt{\beta_{xI}} \cos(\phi_{xI} + \delta_I + 2\pi n Q_I) + \\ &\quad A_{II} \sqrt{\beta_{xII}} \cos(\phi_{xII} + \delta_{II} + 2\pi n Q_{II}) \\ y_n &= A_I \sqrt{\beta_{yI}} \cos(\phi_{yI} + \delta_I + 2\pi n Q_I) + \\ &\quad A_{II} \sqrt{\beta_{yII}} \cos(\phi_{yII} + \delta_{II} + 2\pi n Q_{II})\end{aligned}$$

gives the coupled **Mais-Ripken** twiss functions $\beta_{zI,II}$ and $\phi_{zI,II}$ ($z \equiv x, y$), a part for the constants of motion $A_{I,II}$ and $\delta_{I,II}$.

^athere are other ways of analysing the TBT data, such as MIA and ICA

The **eigenvectors** of the coupled transport matrix are related to the Mais-Ripken twiss functions

$$\begin{aligned} V_{11} &\equiv \sqrt{\beta_{xI}} \cos \phi_{xI} & V_{12} &\equiv \sqrt{\beta_{xI}} \sin \phi_{xI} \\ V_{13} &\equiv \sqrt{\beta_{xII}} \cos \phi_{xII} & V_{14} &\equiv \sqrt{\beta_{xII}} \sin \phi_{xII} \\ V_{31} &\equiv \sqrt{\beta_{yI}} \cos \phi_{yI} & V_{32} &\equiv \sqrt{\beta_{yI}} \sin \phi_{yI} \\ V_{33} &\equiv \sqrt{\beta_{yII}} \cos \phi_{yII} & V_{34} &\equiv \sqrt{\beta_{yII}} \sin \phi_{yII} \end{aligned}$$

Taking into account that the BPMs may have (unknown) calibration errors and may be tilted around the longitudinal axis^a the actual eigenvector components are related to the measured ones, \bar{V}_{lk}^i ($i \equiv$ BPM index), by

$$\begin{aligned} \frac{1}{A_I} [\cos(\delta_I) \bar{V}_{11}^i + \bar{V}_{12}^i \sin(\delta_I)] &= \frac{1}{r_i} V_{11}^i + \frac{\chi_i}{r_i} V_{31}^i \\ \frac{1}{A_I} [-\sin(\delta_I) \bar{V}_{11}^i + \bar{V}_{12}^i \cos(\delta_I)] &= \frac{1}{r_i} V_{12}^i + \frac{\chi_i}{r_i} V_{32}^i \\ \frac{1}{A_{II}} [\cos(\delta_{II}) \bar{V}_{13}^i + \bar{V}_{14}^i \sin(\delta_{II})] &= \frac{1}{r_i} V_{13}^i + \frac{\chi_i}{r_i} V_{33}^i \\ \frac{1}{A_{II}} [-\sin(\delta_{II}) \bar{V}_{13}^i + \bar{V}_{14}^i \cos(\delta_{II})] &= \frac{1}{r_i} V_{14}^i + \frac{\chi_i}{r_i} V_{34}^i \\ \frac{1}{A_I} [\cos(\delta_I) \bar{V}_{31}^i + \bar{V}_{32}^i \sin(\delta_I)] &= \frac{1}{r_i} V_{31}^i - \frac{\chi_i}{r_i} V_{11}^i \\ \frac{1}{A_I} [-\sin(\delta_I) \bar{V}_{31}^i + \bar{V}_{32}^i \cos(\delta_I)] &= \frac{1}{r_i} V_{32}^i - \frac{\chi_i}{r_i} V_{12}^i \\ \frac{1}{A_{II}} [\cos(\delta_{II}) \bar{V}_{33}^i + \bar{V}_{34}^i \sin(\delta_{II})] &= \frac{1}{r_i} V_{33}^i - \frac{\chi_i}{r_i} V_{13}^i \\ \frac{1}{A_{II}} [-\sin(\delta_{II}) \bar{V}_{33}^i + \bar{V}_{34}^i \cos(\delta_{II})] &= \frac{1}{r_i} V_{34}^i - \frac{\chi_i}{r_i} V_{14}^i \end{aligned}$$

^aThe BPM reading is related to the actual beam position by

$$x^{meas} = \frac{x + y \tan \chi}{r_x} \quad y^{meas} = \frac{y - x \tan \chi}{r_y}$$

with $\chi \equiv$ BPM tilt and $r_z \equiv z/z^{meas}$ ($z \equiv x, y$).

Goal: adjust

- quadrupole **gradient** and **tilt**
- BPMs **calibration** and **tilt**
- $A_{I,II}$ and $\delta_{I,II}$

in order to fit the values of the eigenvectors measured at the BPMs.

Data taking being very fast, this approach could be a good alternative to time consuming Orbit Response Matrix methods.

Application to Tevatron

- Number of observation points: 2×118
- Current Tevatron model (A.Valishev): 216 normal and 216 skew thin quadrupoles to simulate gradient and tilt errors. We must add the unknown BPM calibrations and tilts (with the additional condition $\langle r_i \rangle = 1$) and the oscillation amplitude and phase.

Attempts of using MAD-X for fitting have failed (too slow, no convergence when applied to real data).

Project for the immediate future: write our own task-optimised minimisation code.

It could be of interest for ATF DR too. Larger the number of observation points, better constrained is the problem, especially for finding out *the* model: as much as possible BPMs should be upgraded for such an application.

Acknowledgements: Yuri Alexahin