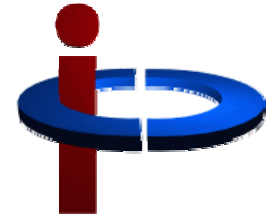


EDR Positron Source KoM,
CI, Oct 2007



Pair-Production Target

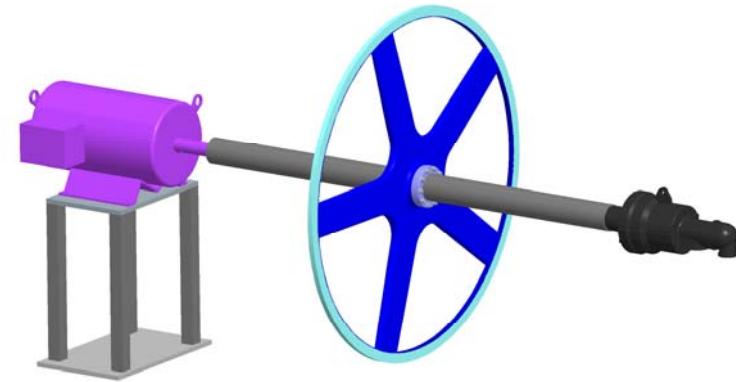
Ian Bailey

University of Liverpool / Cockcroft Institute



RDR Target Design

- Wheel rim speed (100m/s) fixed by thermal load (~8% of photon beam power)
- Rotation reduces pulse energy density (averaged over beam spot) from ~900 J/g to ~24 J/g
- Cooled by internal water-cooling channel
- Wheel diameter (~1m) fixed by radiation damage and capture optics
- Materials fixed by thermal and mechanical properties and pair-production cross-section (Ti6%Al4%V)
- Wheel geometry (~30mm radial width) constrained by eddy currents.
- 20cm between target and rf cavity.
- Axial thickness ~0.4 radiation lengths.



T. Piggott, LLNL

Drive motor and water union are mounted on opposite ends of through-shaft.

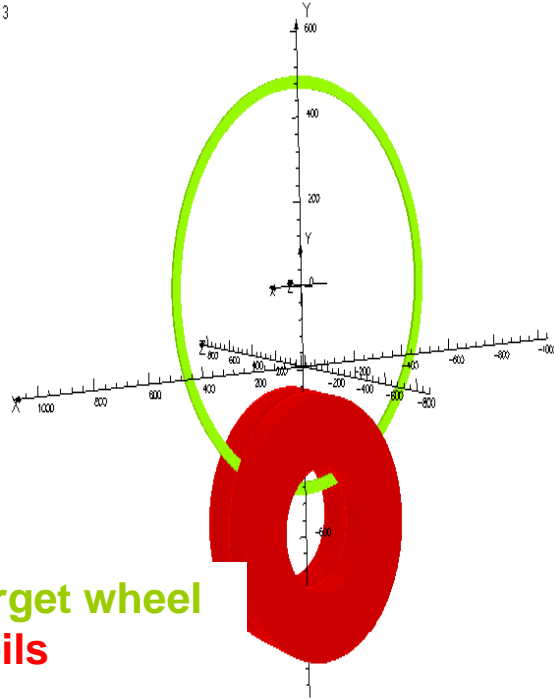


Current Baseline Target Activities

- Prototyping
- Simulation
 - Eddy currents
 - Rotordynamics
 - Fatigue modelling (microstructure)
 - Thermal modelling
 - Thermal stress simulations (shock waves)
 - Radiation damage modelling
 - Activation modelling (see target hall)

RDR Target Wheel Eddy Current Simulations

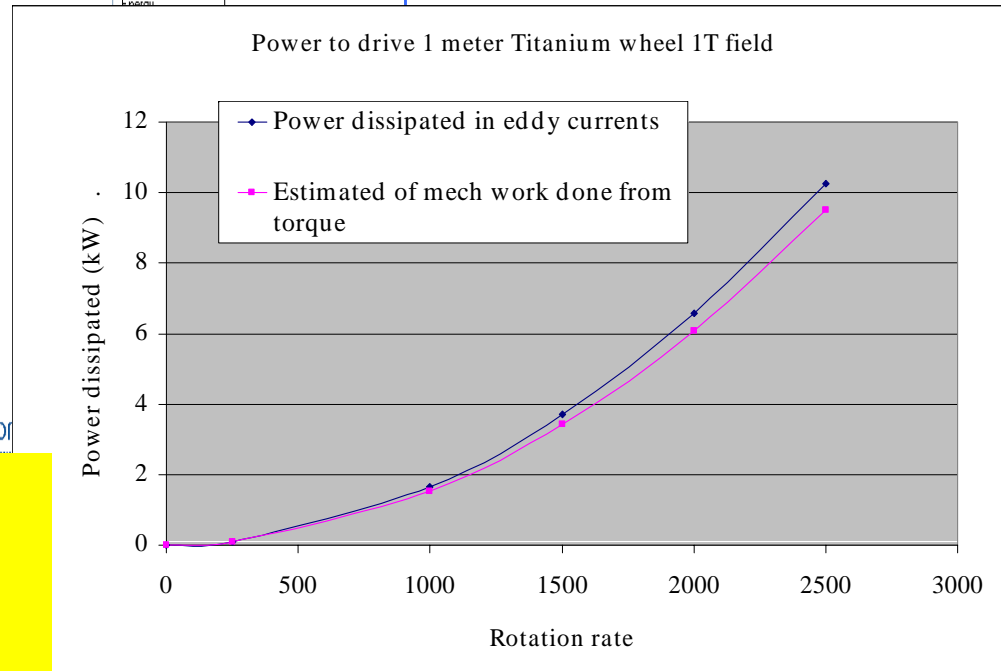
26/Mar/2007 16:46:13



Target wheel
Coils

UNITS	
Length	mm
Magn Flux Density	T
Magn Field	A m ⁻¹
Magn Scalar Pot	A
Magn Vector Pot	Wb m ⁻¹
Elec Flux Density	C m ⁻²
Elec Field	V m ⁻¹
Conductivity	S mm ⁻¹
Current Density	A mm ⁻²
Power	W
Force	N
Energy	J

Immersed target \Rightarrow
up to a factor 2.5
increase in capture
efficiency c.f. QWT



•For 1T field at ~2000rpm

•RAL predicts ~6.6kW

•ANL predicts ~9.5kW

•LLNL predicts ~15kW?

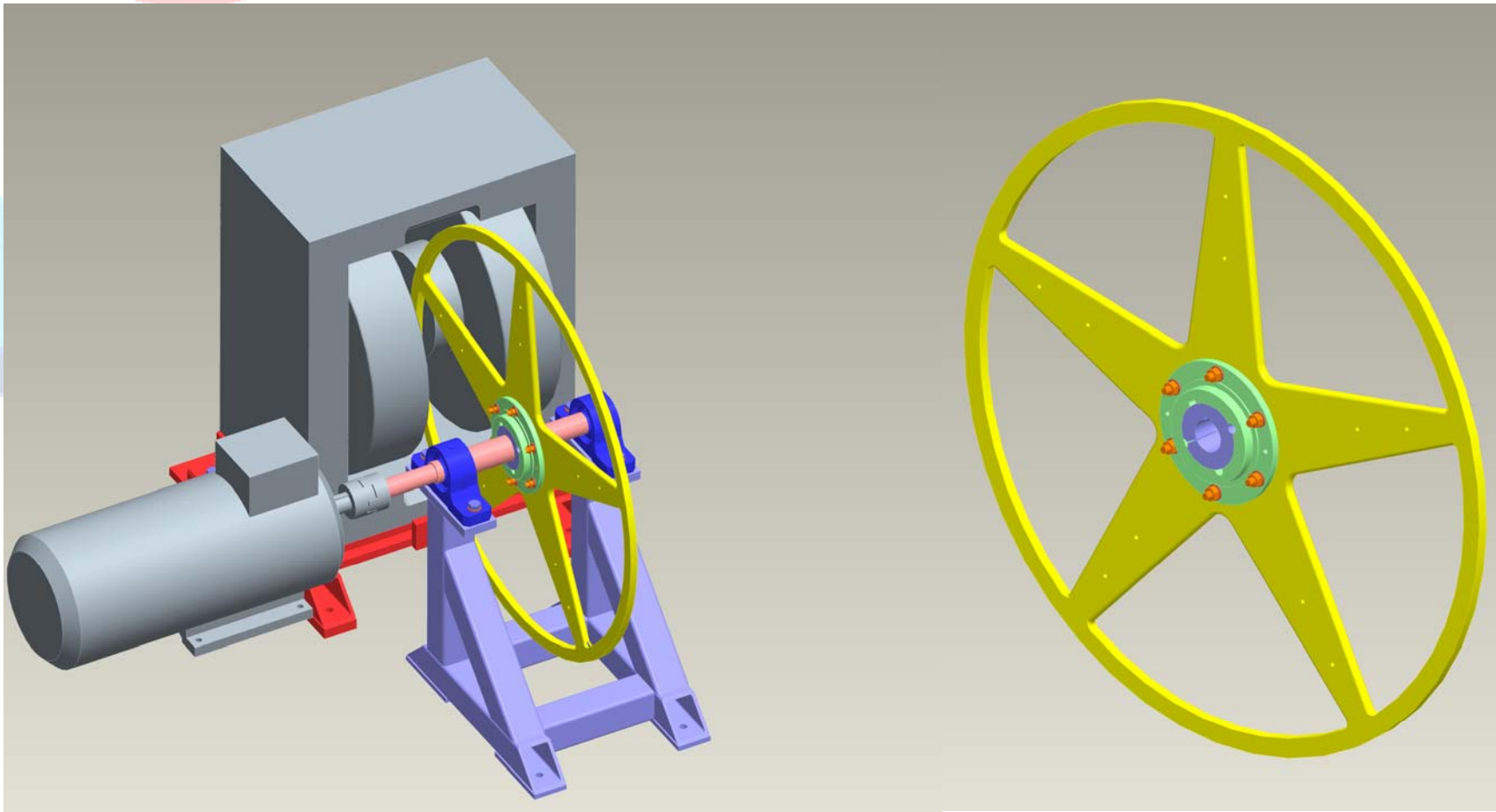
•Difference not yet understood...

\Rightarrow Alternative capture optics,
alternative materials, prototyping

Target Prototype Design

Prototype I - eddy current evaluation

Ken Davies - Daresbury Laboratory



Target Prototyping Status

- Experimental area at DL allocated
 - Area caged. Services (water cooling, etc) available.
- Magnet has been sourced
 - Model 3474-140 GMW water-cooled electromagnet
 - Variable pole gap (0mm to 160mm)
- Drive motor (15kW) purchased
 - Interlock circuit designed and under construction
- Ti alloy wheel is being manufactured
 - Delivery expected in next couple of weeks
 - Also possible Al wheel (grade 5083).
- Assembly to begin Oct '07
- Most instrumentation ordered
 - DAQ design still being finalised
- Cooling system not yet designed
 - Rim temperature estimated to reach 200°C for convective cooling in air.
- Guarding being designed

Experiment Programme

- Balancing and initial commissioning ~Nov 07
- Operation of wheel without magnet ~Dec 07 Cooling needed
 - Calibrating transducers and DAQ
- Operation of wheel in magnetic field ~Jan to Mar 08
 - Systematic scan of field strength (0T to 1T in 0.2T steps)
 - Systematic scan of ang. vel. (0rpm to 2000rpm in 50rpm steps)
 - Avoiding critical speeds.
 - Torque and temperature readings to be compared with the predictions of computer simulations.
 - Optionally scan immersion depths
- Long-term operation of wheel to monitor stability ~Apr 08
- Additional investigations using aluminium wheel
- Experiment complete by May 08.

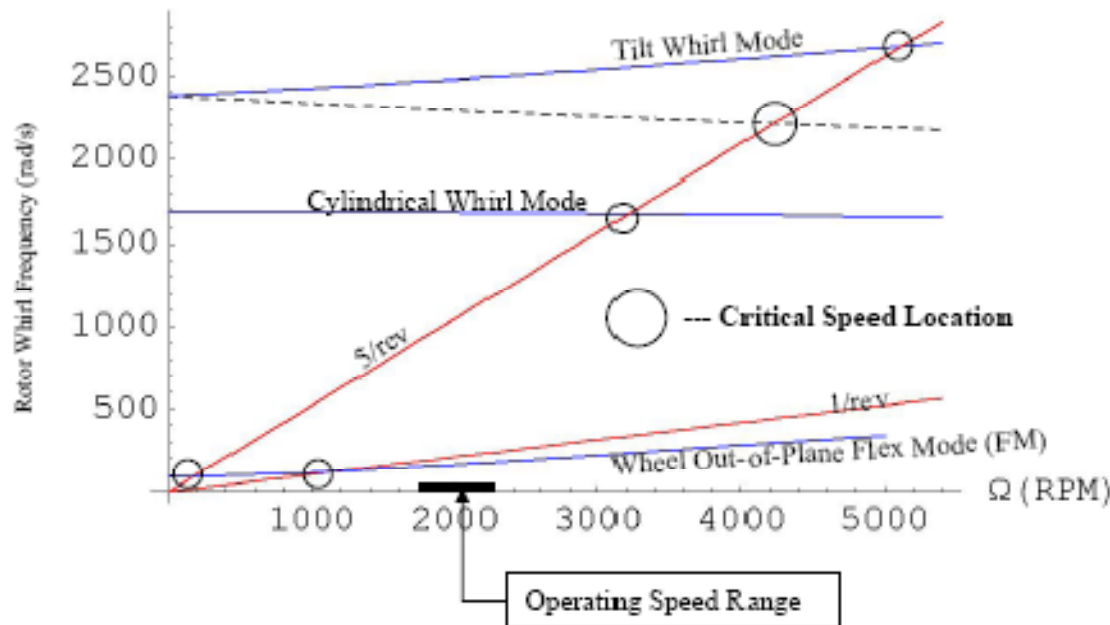
Flywheel Critical Speeds (Stainless Steel Drive Shaft)

Nominal Design Basis Bearing + Mount Stiffnesses

Support Translational Stiffness = 1,000,000 lbf/in

Support Rotational Stiffness = 10,000 lbf*in/rad

Campbell Diagram



• All critical speeds sufficiently far removed from operating speed range

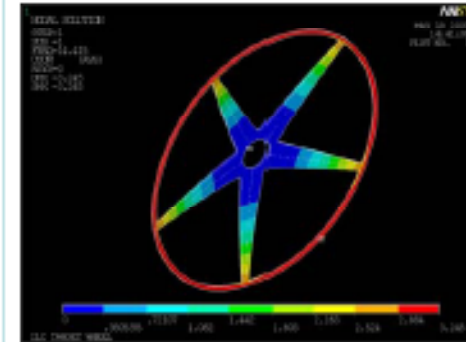
Sources of Rotor Excitation

- Lorentz Force @ 5/rev
- Unbalance @ 1/rev

Major Critical Speeds

- 1st Wheel FM @ ~ 200 RPM
- 2nd Wheel FM @ ~ 1100 RPM
- Cylindrical Whirl @ ~ 3200 RPM
- Forward Tilt Whirl @ ~ 5000 RPM
- Reverse Tilt Whirl @ ~ 4200 RPM

Wheel Out-of-Plane Flex Mode



T. Piggott, L. Hagler LLNL

Figures show rotordynamics for prototype
(same studies carried out for RDR target wheel)

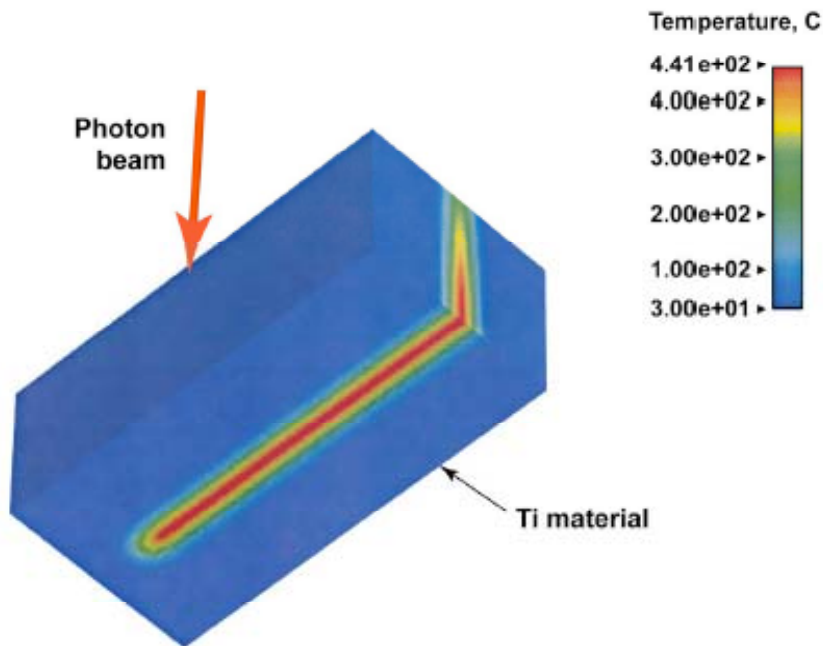
Thermal Stress / Shock



Undulator photon beam target temperature, C,
100 m/s wheel rim velocity



W. Stein, LLNL, 2005



TOPAZ-3D and DYNA-3D simulations

ENG-05-0055-NTED-#23

- Rapid energy deposition generates a pressure shock wave
- Maximum stress is experienced at the back surface of the target
- For older beam parameters (small beam spot), peak stress was $\sim 4 \times 10^8 \text{ Pa}$
- This is a factor of two below the yield stress
- Simulation is being re-evaluated with updated parameters and target design.
- Disagreement between Cornell and LLNL results

Outstanding issues that could lead to design change

- Target shock wave studies
 - Beam tests (TTF?)
- Eddy currents and target immersion
- Downstream beam window survival
 - Gas cooling between two windows?
- Vacuum studies
- Rotating coupling performance / radiation hardness
- Water union and cooling channels
- Radiation damage studies
 - Wheel size

} Alternative target materials

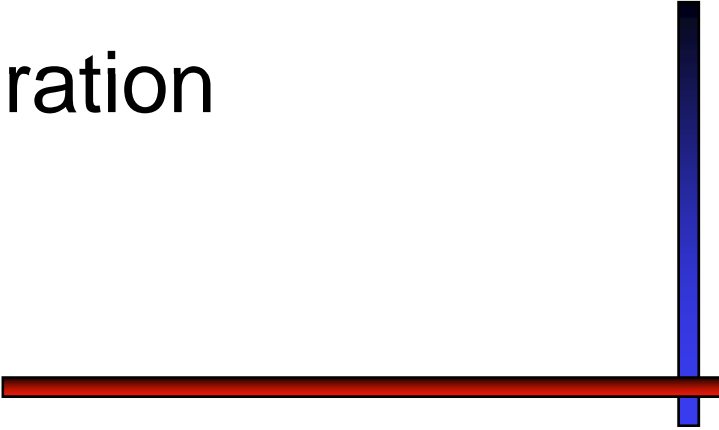
Alternative Targets and Materials

- Machiolated Ti alloy rim (eddy current studies)
- W-Re
 - LLNL studies indicate shock wave problems
- Hybrid
 - E.g. W-Re wheel with Ti alloy rim
 - How to cool rim?
- Ceramics (eddy current studies)
 - Initial study carried out at RAL
- Graphite
 - High density graphite wheel exists at BINP
 - Radiative cooling
 - Probably not suitable for ILC
- Liquid metals
 - Cornell Pb-Bi and Hg designs (cavitation and window survival)
 - BINP liquid Pb design (not suitable for ILC)

Continue
in EDR
phase



Target EDR Phase

- Scope of work package
 - Everything inside the target vacuum vessel excluding the capture optics
 - Drive
 - Cooling
 - Target wheel
 - Vacuum Vessel/ Hall Integration
 - Instrumentation/Controls
- 



Drive


- Vibration/Rotordynamics
- Ferrofluidic seals
- Mechanical Simulations
- Drawings

Cooling

- Water union coupling to driveshaft
- Cooling channel techniques
- Drawings
- Simulation
- Alternatives
 - Radiative cooling (of Ti alloy)




Target Wheel

- Physics simulations
 - Thermal/Mechanical simulation
 - Failure analysis
 - Material property changes
(thermal/radiation degradation)
 - Design & drawings
- 




Instrumentation/Controls

- Accelerometers/vibration sensing
 - Torque transducer
 - Temperature sensing
 - Cooling flow sensors
 - Motor diagnostics
 - Coupling with fast/safety controls and shutoffs
 - Design and specification
- 



Vacuum Vessel/ Hall Integration

- Vacuum seals
 - Vessel design
 - Achievable vacuum studies
 - Coupling with services
 - Beam windows
- 

Summary

- Current initiatives need to continue into EDR phase
 - Eddy currents
 - Thermal studies (material tests, etc)
- New initiatives required
 - Vacuum studies (seal tests, etc)
 - Instrumentation and controls
- Could organise work by system or by issue