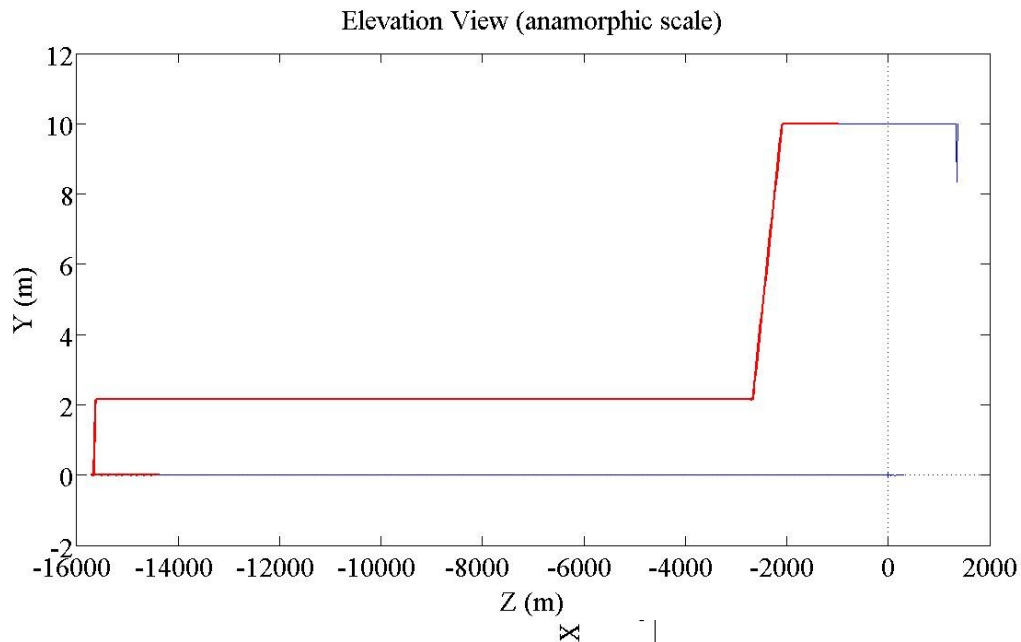


# Status of RTML studies using Lucretia

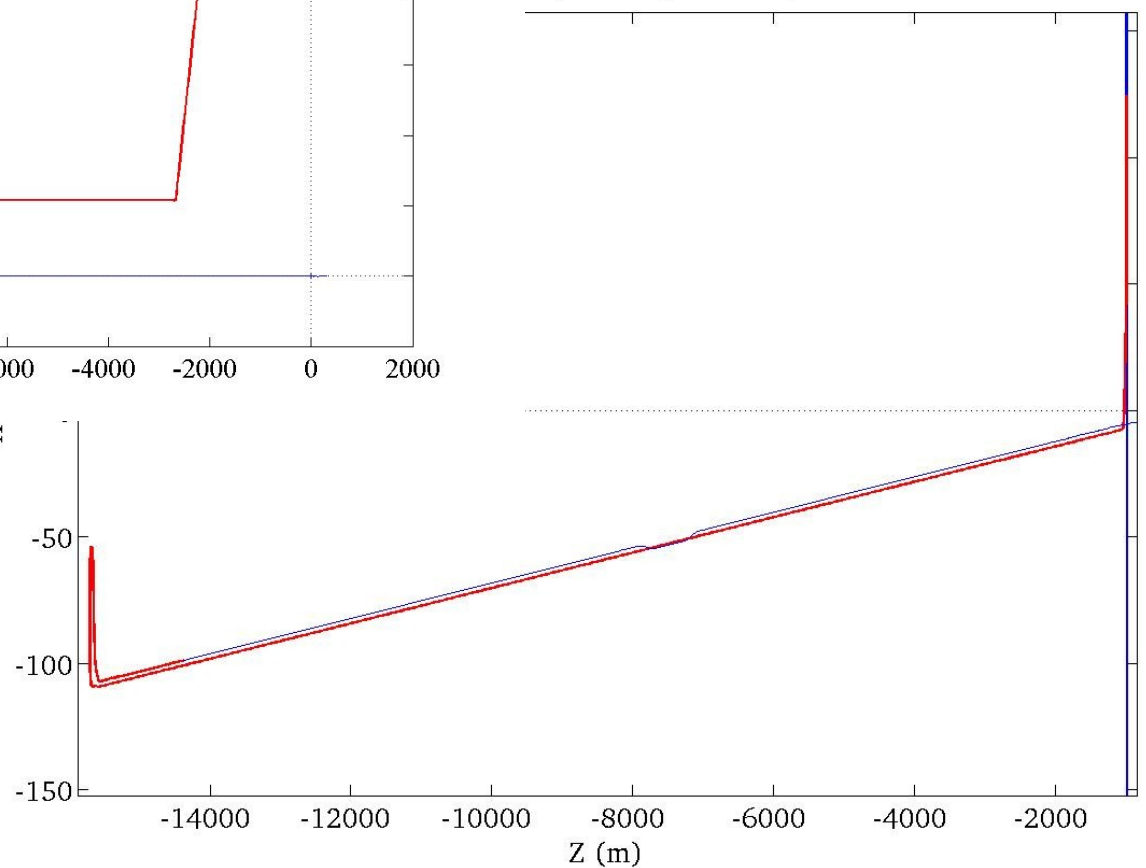
Steve Molloy – 11<sup>th</sup> December, 2007

With many thanks to Jeff Smith, PT,  
Glen White, and Mark Woodley

# Latest RTML layout



w (anamorphic scale)



Slightly different  
from the decks in  
the rest of this talk.

## Plan of Attack (I)

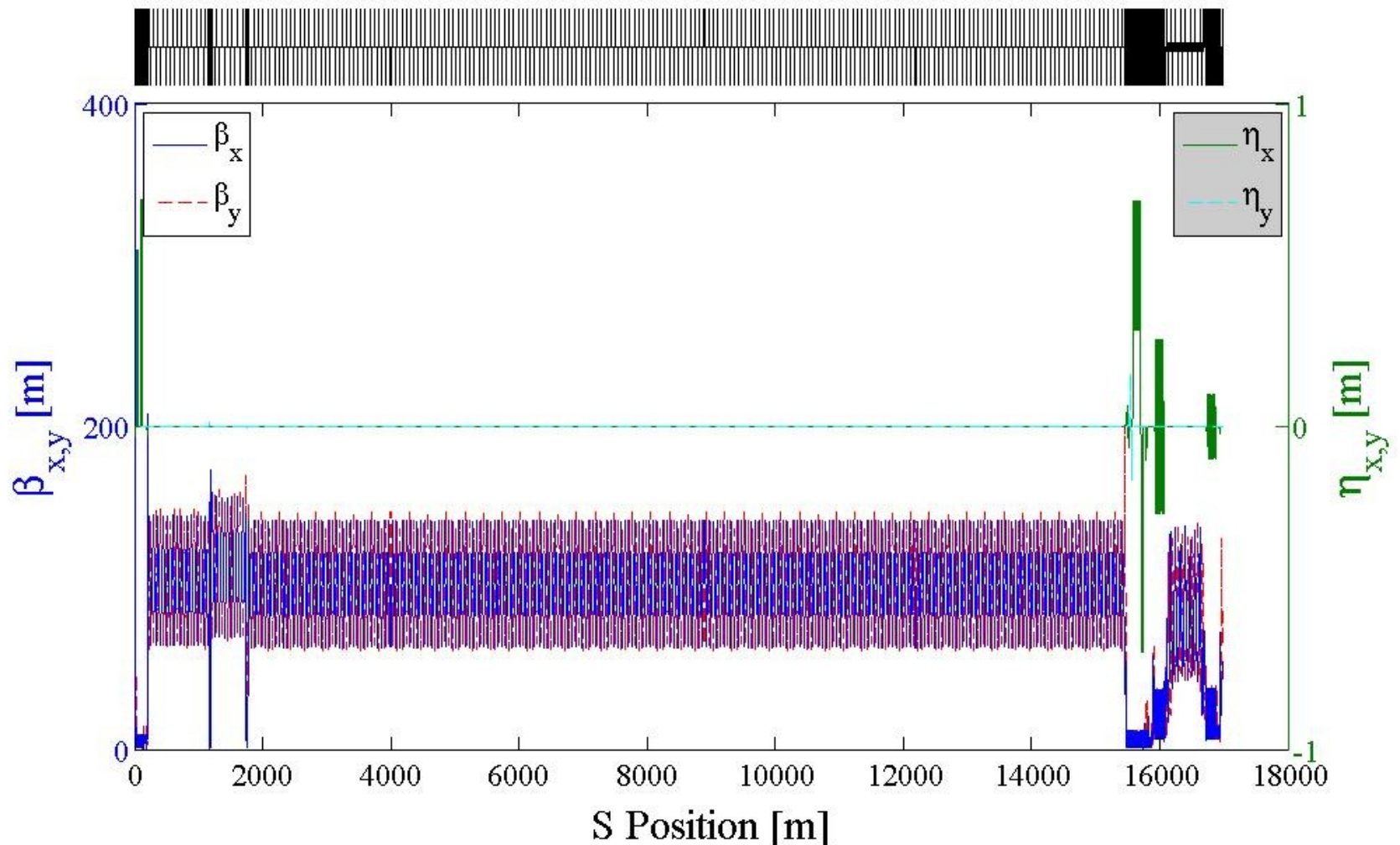
- **Use Lucretia as simulation package**
- **Apply standard set of errors.**
- **Develop static tuning techniques.**
  - (No GM, beam jitter, etc.)
    - yet...
  - **Aim for <4 nm vertical emittance growth.**
    - DR exit through to linac entrance.
- **Determine “best” tuning technique for each region**
  - **One-to-one? KM? DFS? Magic dispersion bumps?**

## Plan of Attack (II)

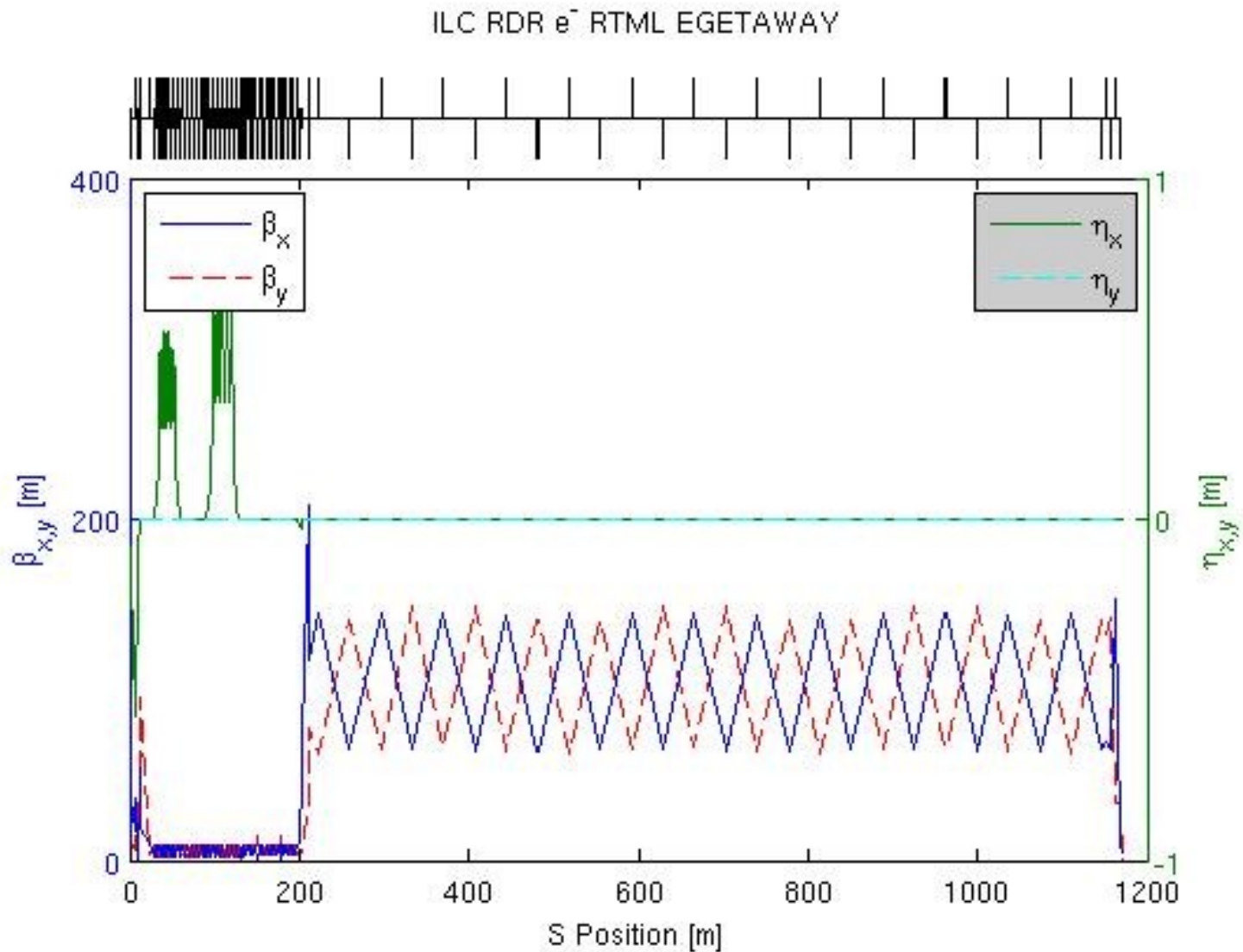
- **I'm very new to this!**
  - Start with something “simple”
- **Tune-up long transport line**
  - No design coupling
  - No acceleration or compression
- **Apply a couple of cheats**
  - Perfect alignment between quad centres and BPMs
  - Turn off bend rolls
- **Decided,**
  - One-to-one first, then KM
  - DFS not appropriate (upstream of BC1).

# RTML Twiss Plots

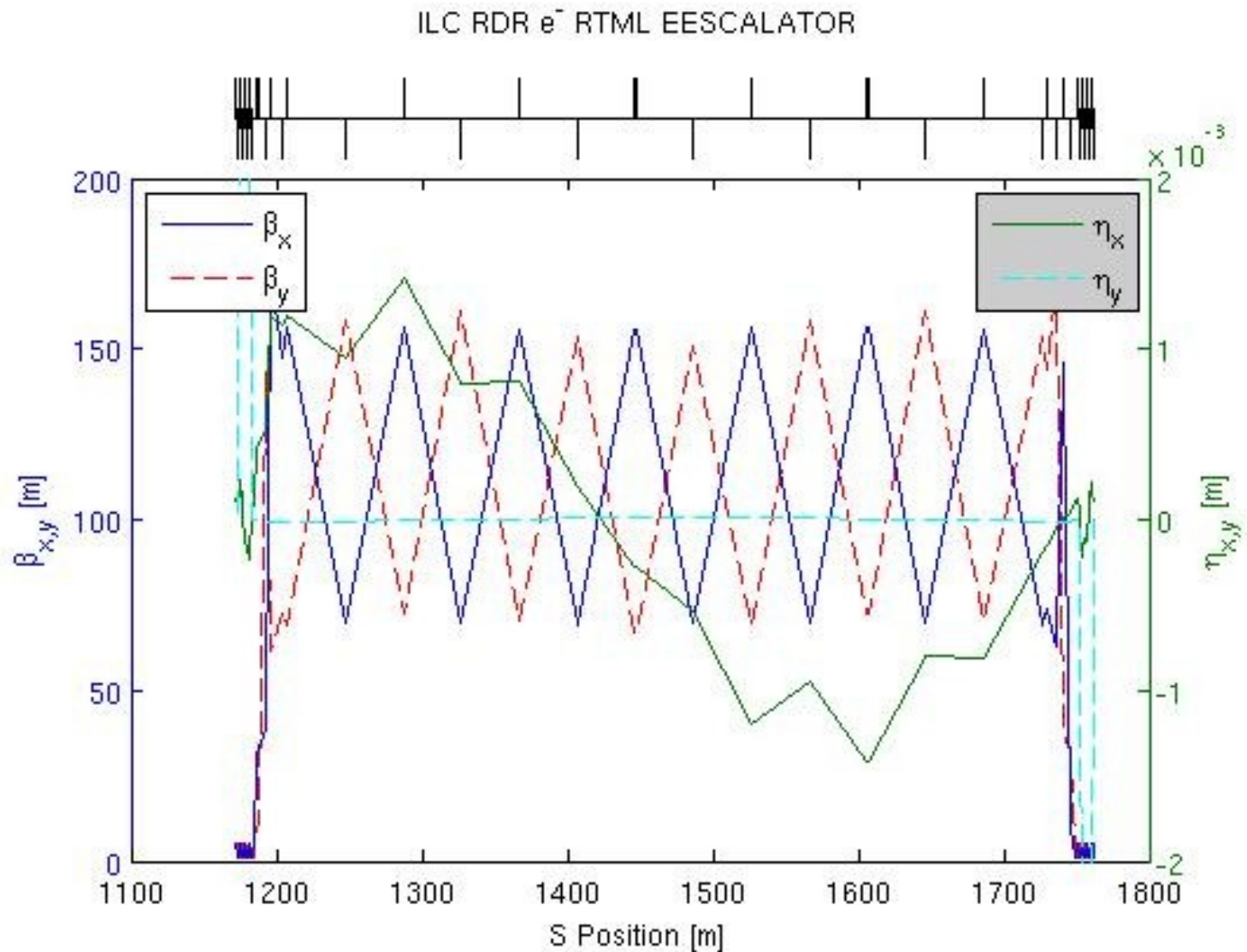
ILC RDR  $e^-$  RTML



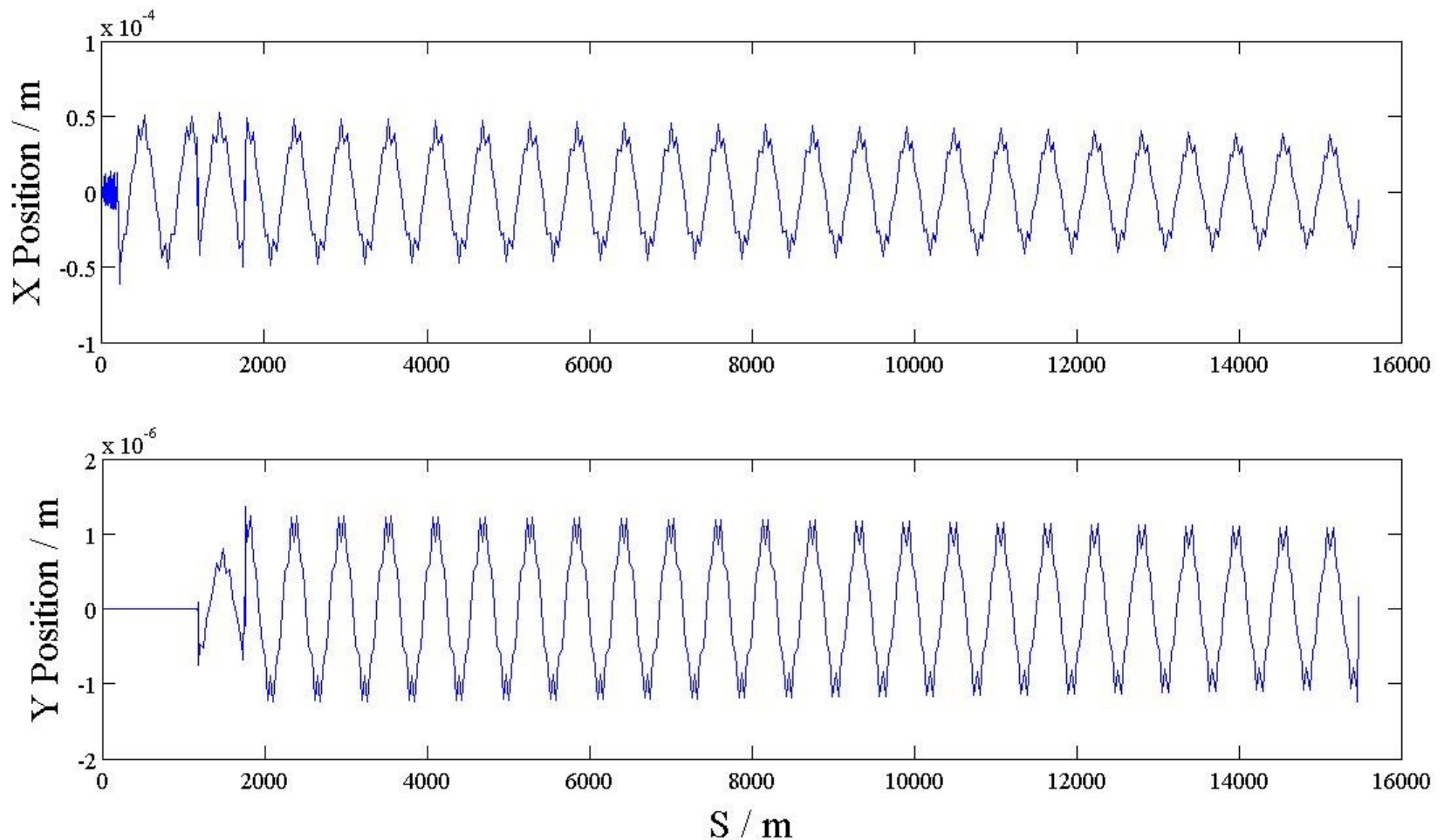
# RTML Twiss Plots



# RTML Twiss Plots



# Perfect Lattice – 2<sup>nd</sup> Order Dispersive Orbit



Zero momentum spread beam results in flat orbit.

# Tuning Procedure

## Misalign

One-to-one steering  
(steer beam through centre of BPMs)

Kick minimisation (KM)  
(Use correctors to cancel off-centre quad kicks)

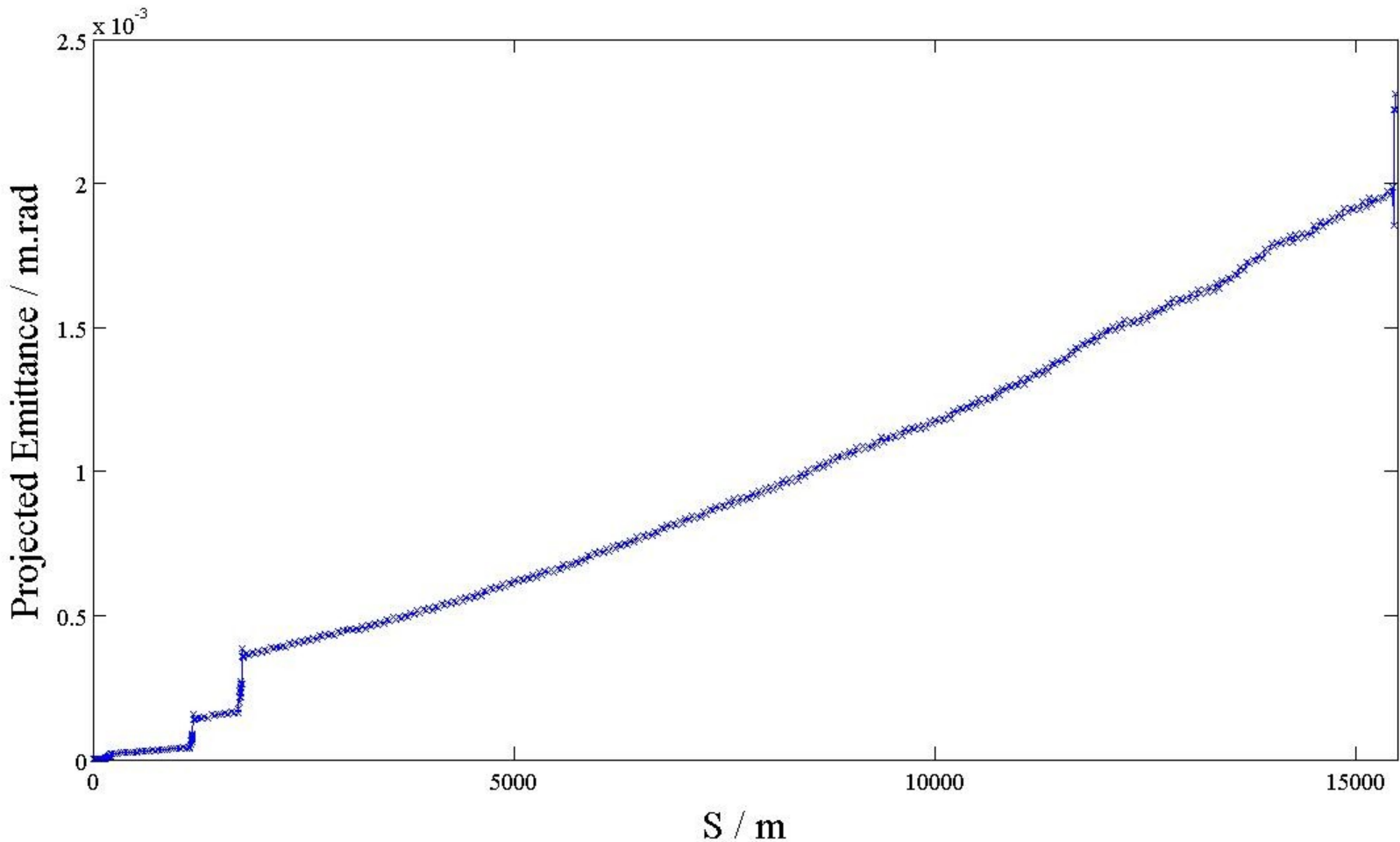
## Errors

**cav\_misalign = 300e-6;**  
**cav\_pitch = 300e-6;**  
**quad\_misalign = 300e-6;**  
**quad\_rot = 300e-6;**  
**bpm\_misalign = 200e-6;**  
cryo\_misalign = 200e-6;  
cryo\_pitch = 25e-6;  
**quad\_strength = 2.5e-3;**  
**bend\_strength = 5e-3;**  
**bend\_rot = 0;**

Fixed to quad centre  
in these studies

Have since confirmed  
tuning works with bend  
rotation of 300e-6 rad

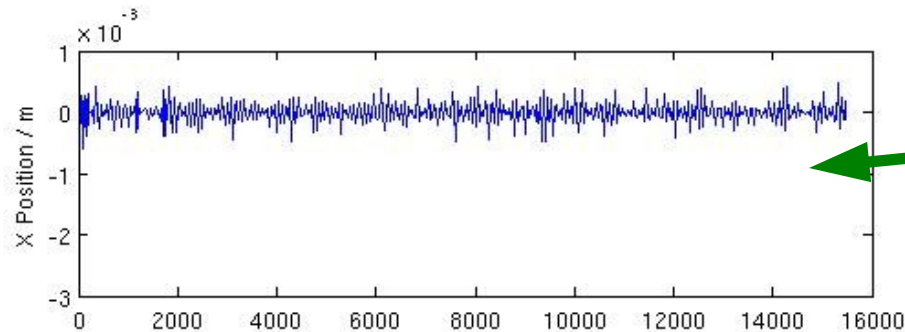
# Projected Emittance (after errors)



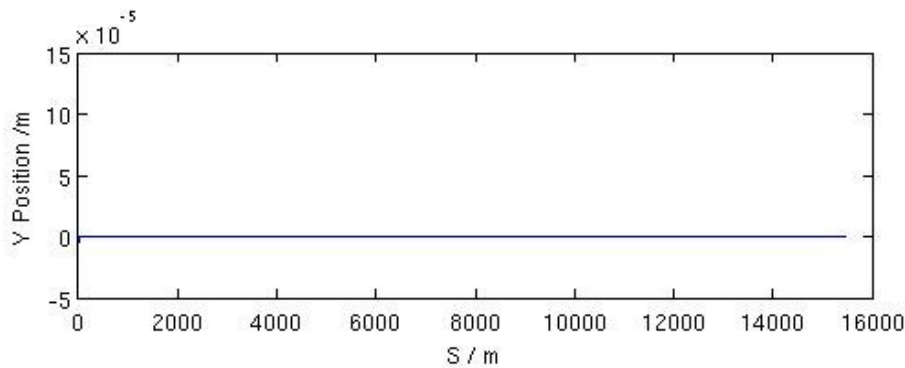
# One-to-one steering on entire line

- **Build giant response matrix for whole line**
  - Response of all BPMs to all correctors
    - Both planes simultaneously
  - R12, R14, R32, R34
    - Measuring is easy, and reduces errors
- **Record BPM readings**
  - Static tuning so no averaging needed
- **Invert matrix and multiply**
  - Find corrector settings to zero BPMs
- **Iterate**
  - Five times in these studies
    - Overkill – three is enough

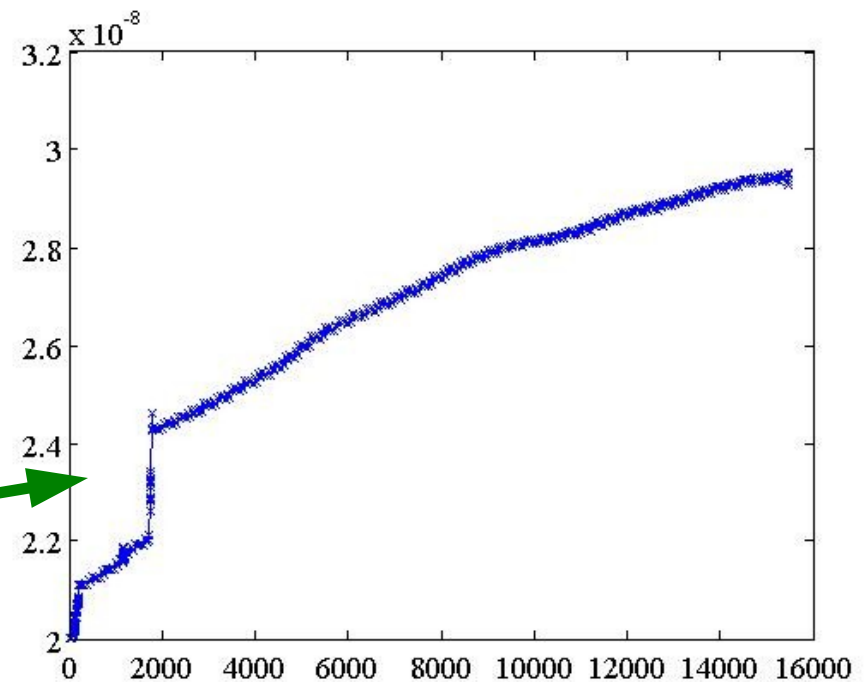
# One-to-one results



Imperfect results in x due to  
“sparse” corrector arrangement



Normal-mode y emittance



P. TENENBAUM

January 30, 2007

## 2.1 The Matrix Equation and its Solution

Let us define  $\vec{B}_x$  as the vector of horizontal BPM readings, and  $\vec{B}_y$  as the vector of vertical BPM readings. We can then define vectors of BPM readings which have been adjusted to take into account the strength of the nearby corrector magnets:  $\vec{C}_x \equiv \vec{B}_x - \vec{\theta}_x/KL$ ,  $\vec{C}_y \equiv \vec{B}_y + \vec{\theta}_y/KL$ , where we take the usual convention that positive  $KL$  values are horizontally focusing and where the division is array division (ie, the resulting vector components are  $\theta_i/(KL)_i$ ).

Now define the usual steering response matrices: matrix  $M_{xx}$  is the response of the horizontal BPMs to the horizontal correctors;  $M_{xy}$  is the response of the horizontal BPMs to the vertical correctors; and so on. Now let us define a set of steering matrices which are modified by the quad strengths: for example,  $N_{xx}$ ,

$$\begin{aligned} N_{xx,ij} &\equiv -\frac{1}{KL_i} + M_{xx,ij}, \quad i = j, \\ &\equiv M_{xx,ij}, \quad i \neq j. \end{aligned} \quad (2)$$

The matrix  $N_{yy}$  is similarly defined except that the  $1/KL$  term comes in with a positive sign and not a negative sign. The matrices  $N_{xy}$  and  $N_{yx}$  are identically equal to  $M_{xy}$  and  $N_{yx}$ , respectively.

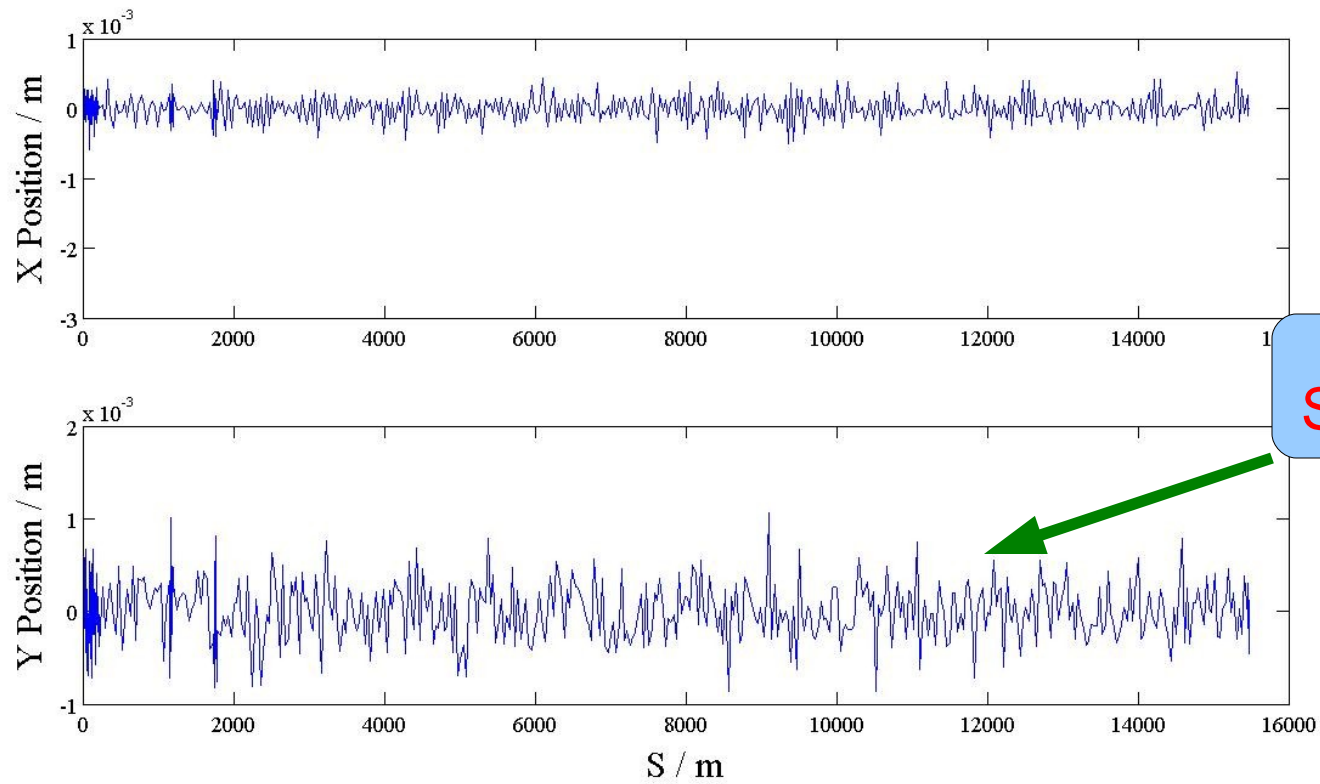
We can now put this together into a matrix equation as follows:

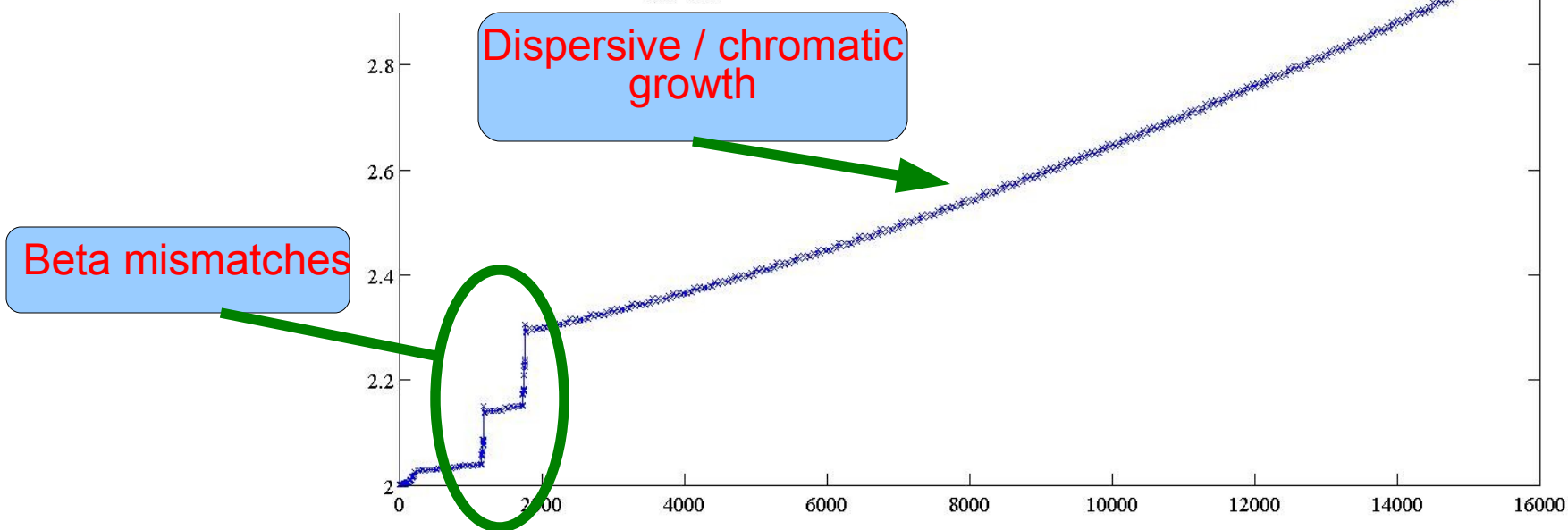
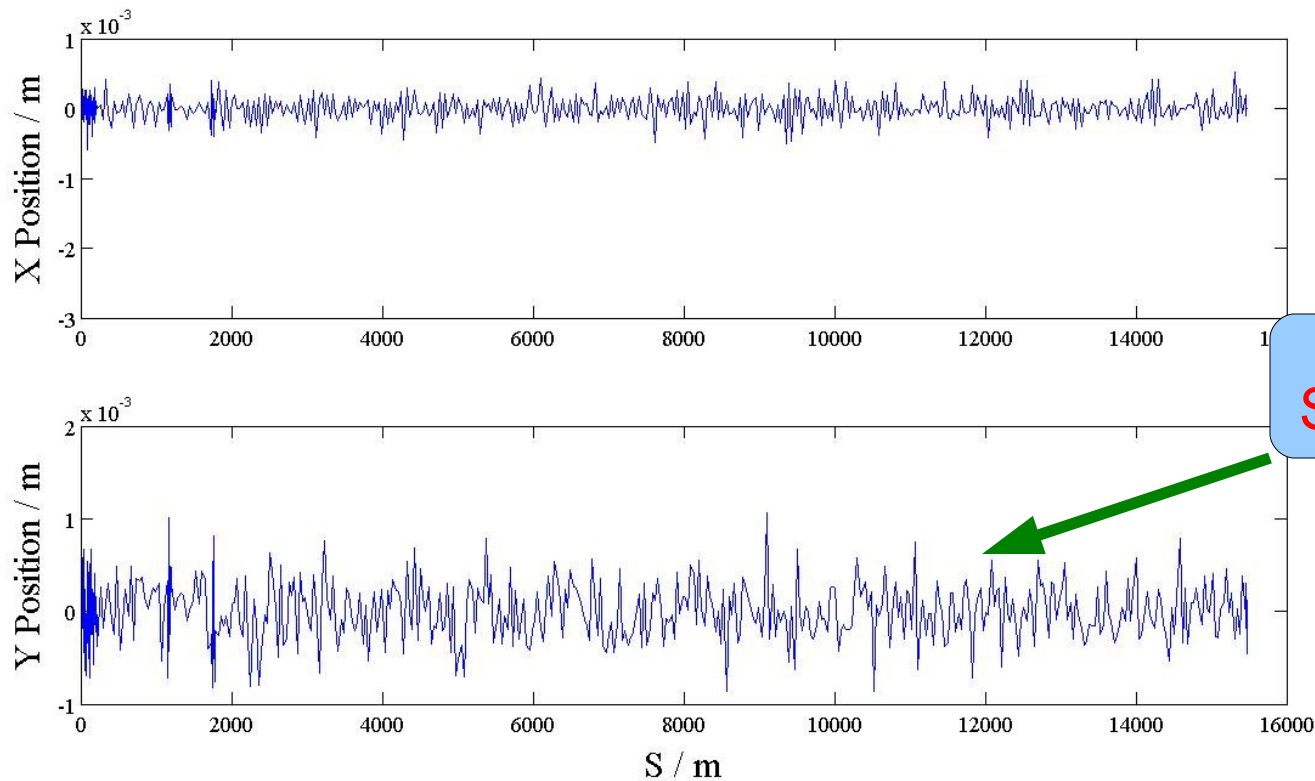
$$\begin{bmatrix} \vec{B}_x \\ \vec{B}_y \\ \vec{C}_x \\ \vec{C}_y \end{bmatrix} = - \begin{bmatrix} M_{xx} & M_{xy} \\ M_{yx} & M_{yy} \\ N_{xx} & N_{xy} \\ N_{yx} & N_{yy} \end{bmatrix} \begin{bmatrix} \vec{\Delta\theta}_x \\ \vec{\Delta\theta}_y \end{bmatrix}, \quad (3)$$

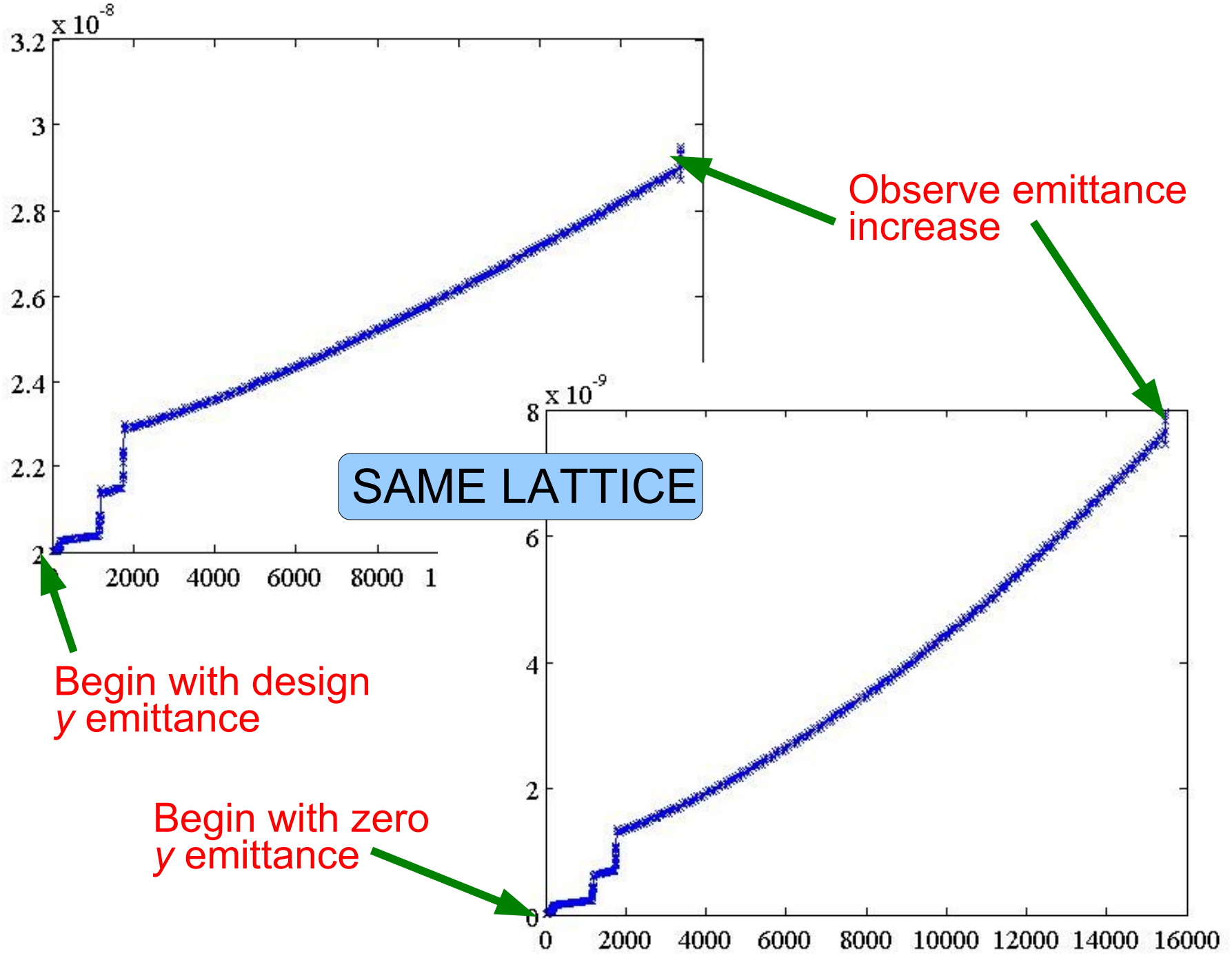
where  $\vec{\Delta\theta}_{x,y}$  is the vector of corrector *changes* which are needed, relative to their current settings.

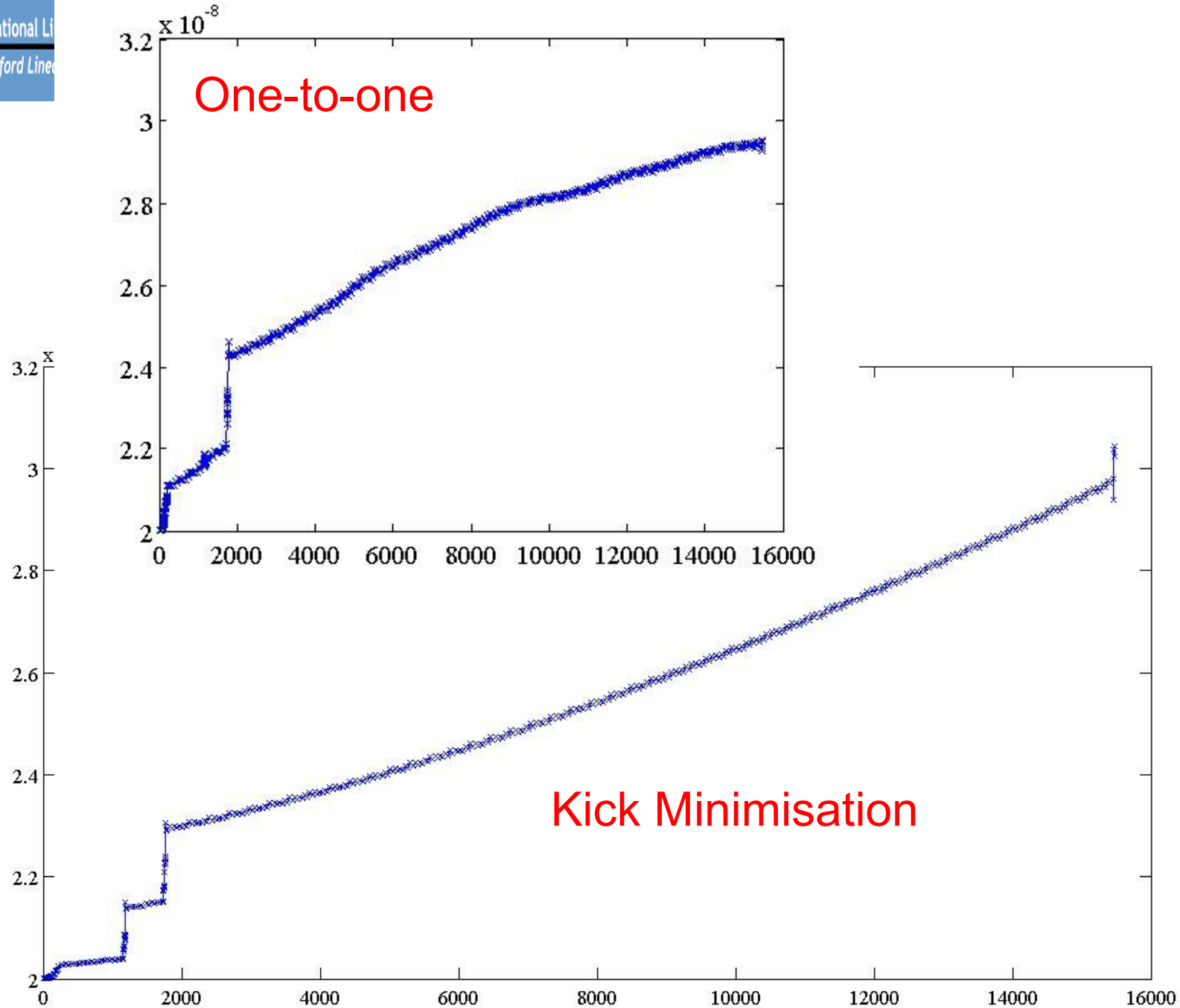
# Application of KM

- **Value of weighting,**
  - “B” = square of RMS quad misalignment (300  $\mu\text{m}$ )
  - “C” = square of RMS quad-bpm difference (7  $\mu\text{m}$ )
- **Applied only in y**
  - Problems in x due to “sparse” corrector layout
    - More on that later...
- **Applied to entire line in one go**
  - Not practical in real life, but that's why we simulate!
- **Iterate three times**
  - Errors result in imperfect R matrices
  - Iterate to converge on solution









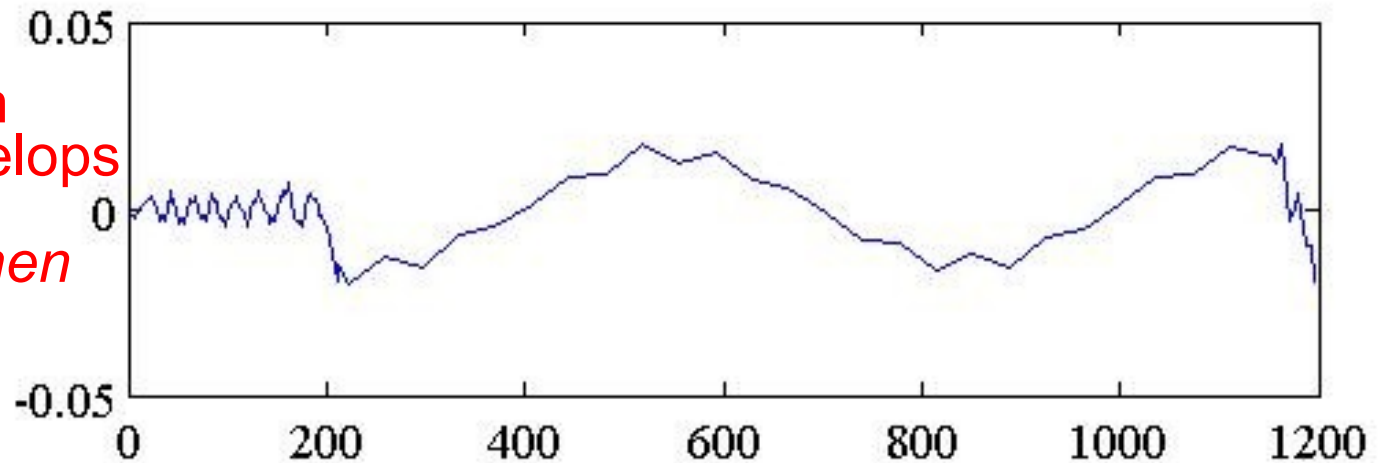
## Some “issues”

- **KM breaks in the presence of kick sources not included in response matrix**
  - Kubo discovered this with tilted cavities in the linac
  - Bends are problematic in RTML
- **Sparse xcors make KM unstable**
  - Similar to previous problem
  - No XCORS at QDs
    - Kick direction is systematic
    - “Correct” solution is not stable
- **Tuning lattice in segments does not yet work**
  - Incoming position/angle not accounted for?
    - This is only a theory...

## Simultaneous KM in x & y

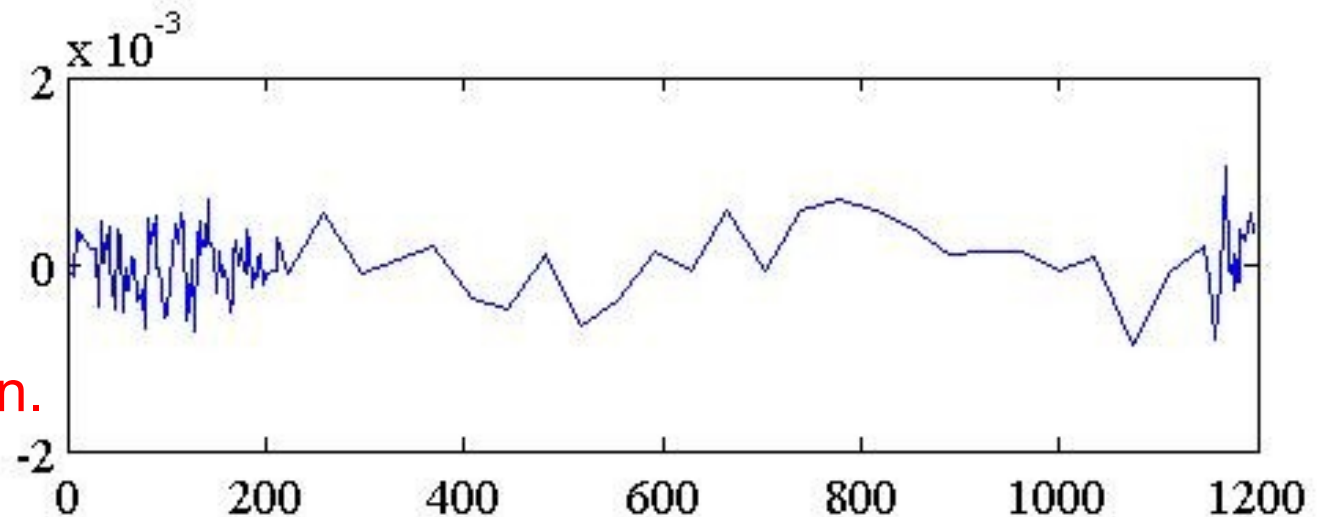
Large betatron  
oscillation develops

*Not present when  
xcors added at  
every quad.*



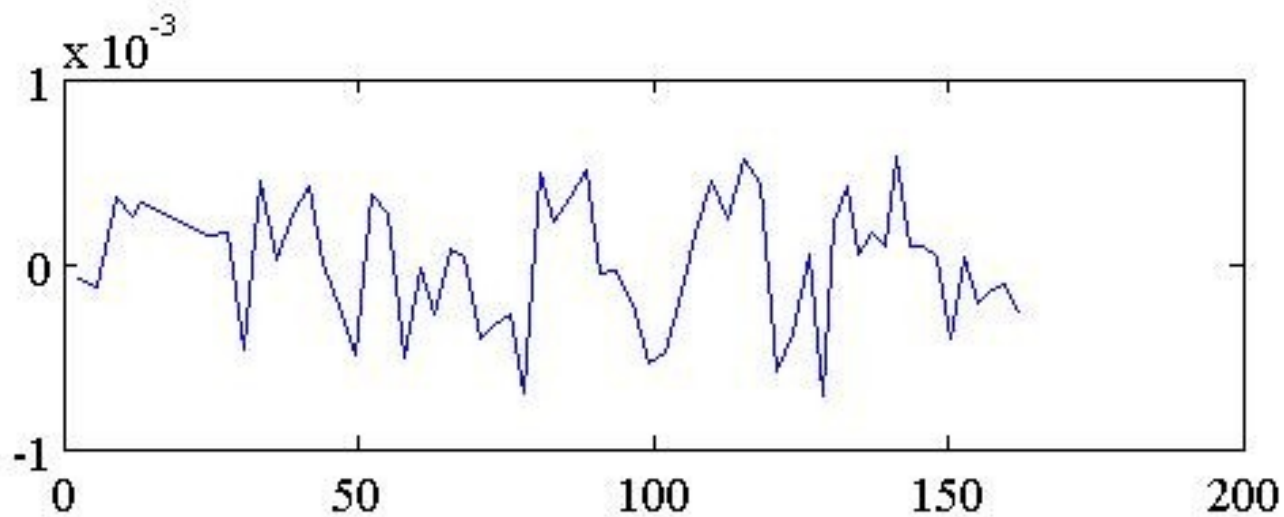
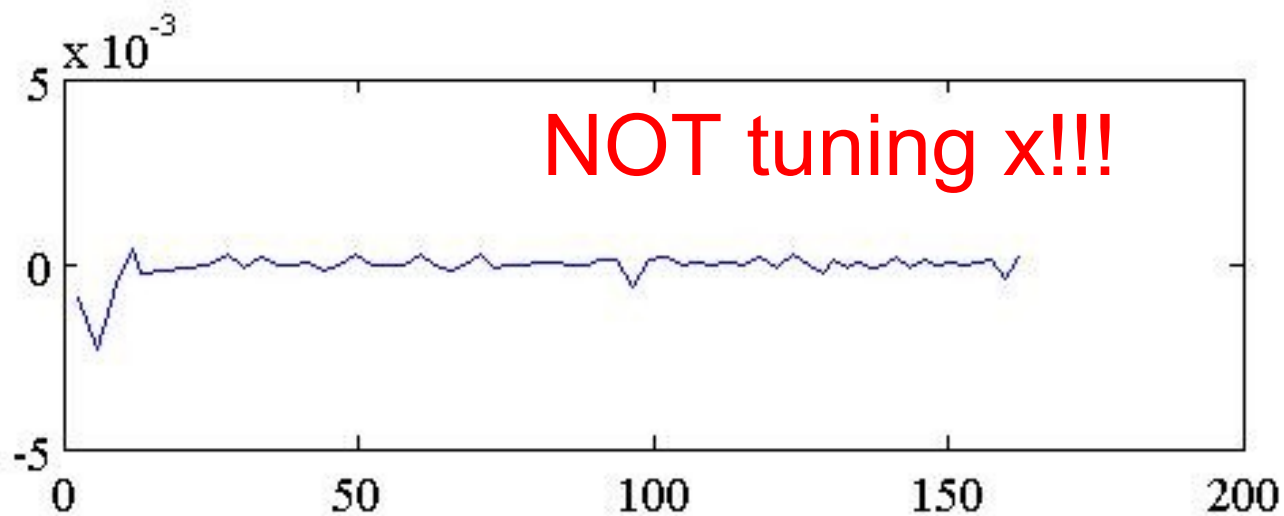
y plane works fine.

Deteriorates with  
iterating due to  
growing x oscillation.

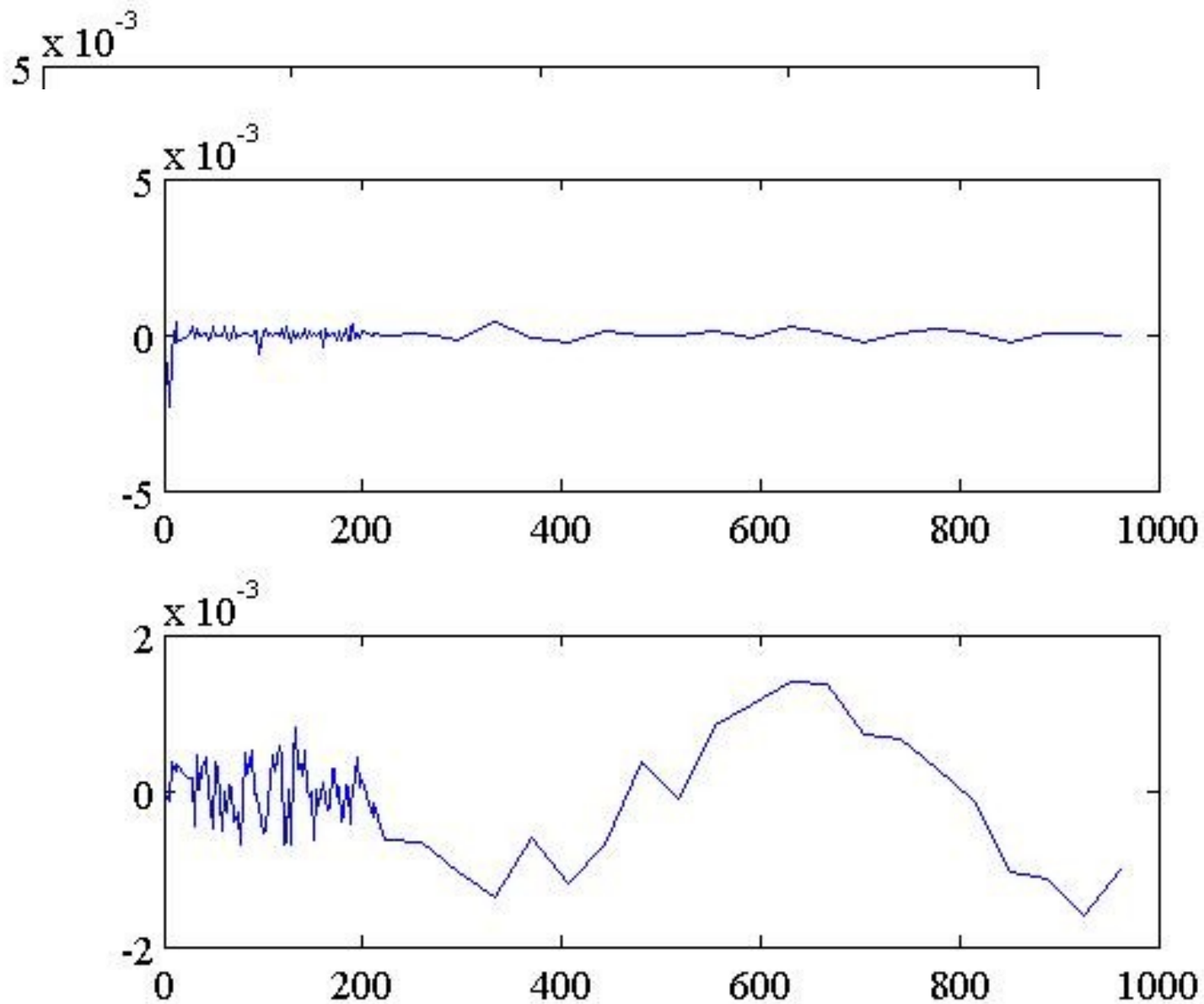


# Tune machine in segments

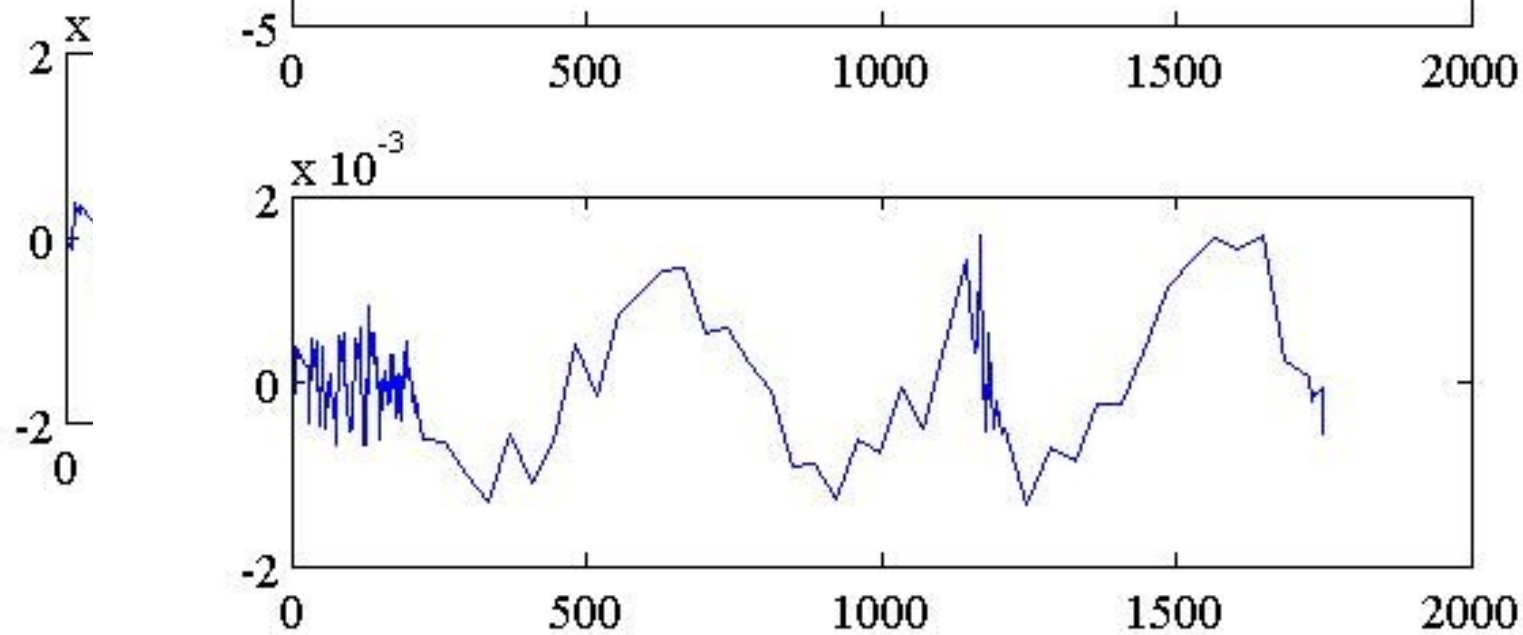
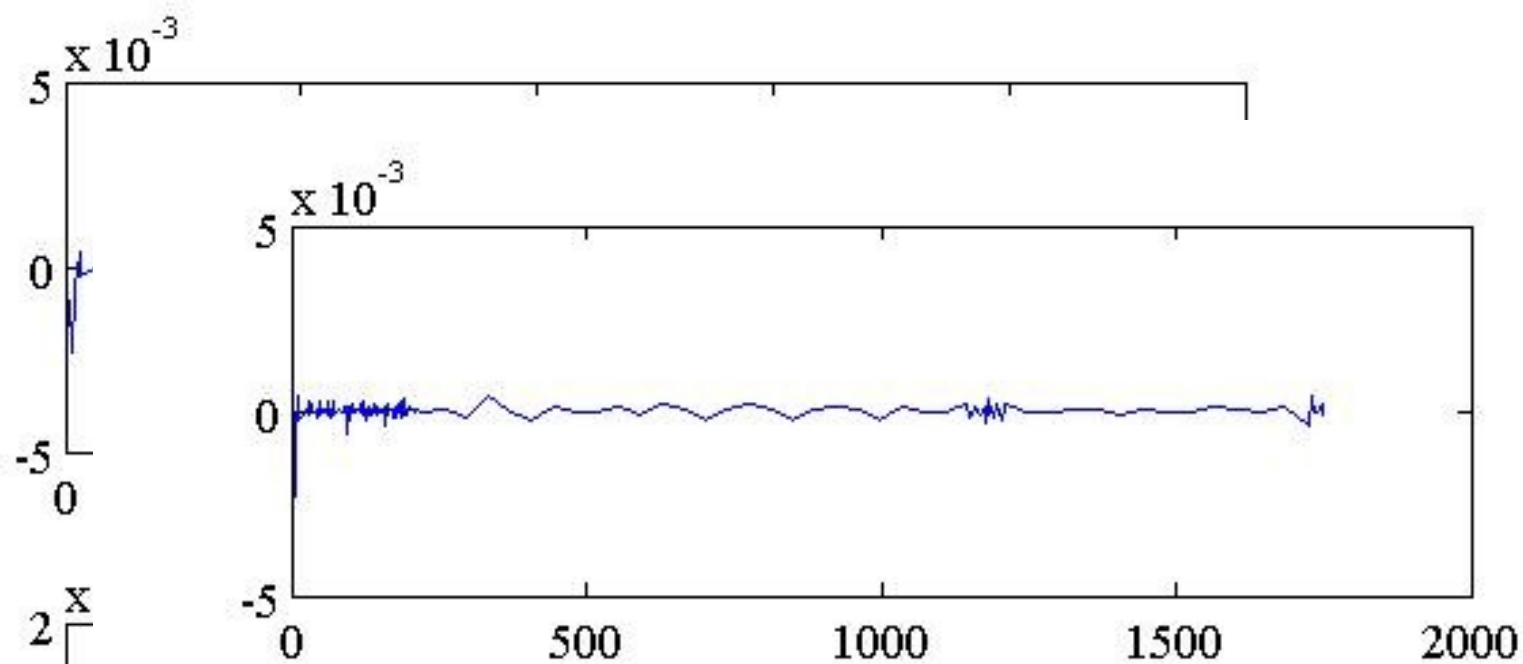
- **Tuning ~16 km in one go is not practical (!)**
- **Instead,**
  - Tune region containing  $n$  BPMs
    - e.g.  $n = 40$
  - Move on to next  $n$  BPM region, overlapping with previous by  $n/2$
- **Doesn't work (see next slides)**
  - Region #1 is fine
  - KM misbehaves in subsequent regions
    - Smoking gun is that these begin with non-zero position and angle
    - Haven't proved this yet...



Works fine on this segment...



Obvious betatron oscillation develops in segment 2...



# Summary

- **Developed one-to-one and KM tuning algorithms in Lucretia**
- **Have tuned up to end of the return line.**
  - **~10 nm emittance growth**
    - Many problems may be fixed by beta matching
    - Also coupling-correction & dispersion knobs.
  - **Expecting BC1&2 to be troublesome...**
- **Encountered problems with KM**
  - **Tuning one region at a time does not (yet) work**
  - **Tuning in x-plane (with no QD correctors) is unstable**
    - One-to-one may suffice for x-plane
- **Practical tests....**

## Future: Practical test?

- **A demonstration of KM, etc., would be comforting**
- **This month, LCLS will begin work on their linac + BC2**
  - They need to tune the machine, and we need to demonstrate our algorithms
    - Win-win situation!!
  - Apply 1-to-1, KM, DFS, etc., to LCLS to test and develop our techniques
- **Just a proposal at present**
  - Many details needed to be worked out
  - Simulations will show feasibility