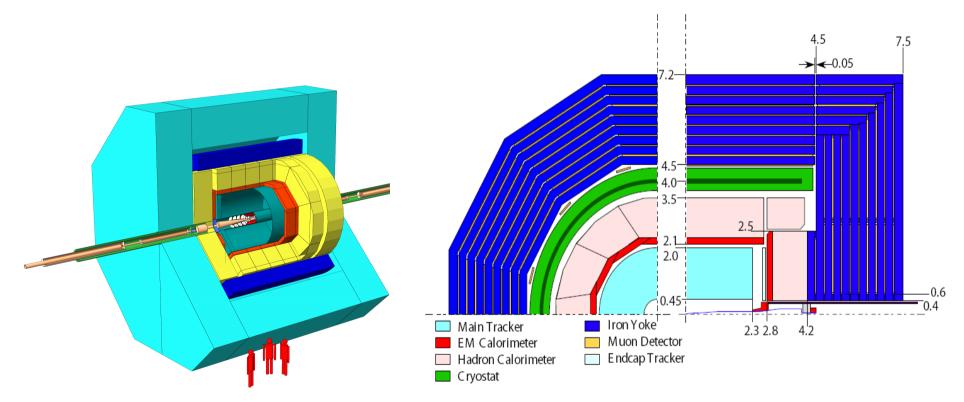
## GLD and LDC: where do we start from

Ties Behnke, DESY



LDC DOD: see http://www.ilcldc.org

Large Detector Concept

GLD DOD see arXiv:physics/0607154v1

Global Detector Concept

# Starting point

Starting point of LDC and GLD are the same:

• Use particle flow as the basic reconstruction paradigm

Excellent particle separation required
Extremely efficient tracking is required

Particle flow relies on "SUBSTITUTION" in the calorimeter on a particle-by-particle basis: excellent spatial separation even within jets is needed

# **PFLOW and DETOPT**

Separation of particles:

- Charged track separation ∝ B R<sub>in</sub><sup>2</sup>
- Neutral separation ∝ R<sub>in</sub>



Moliere radius (= material)
Segmentation of CALO

d=0.15BR<sup>2</sup>/p<sub>t</sub>

in the barrel!

But only applicable

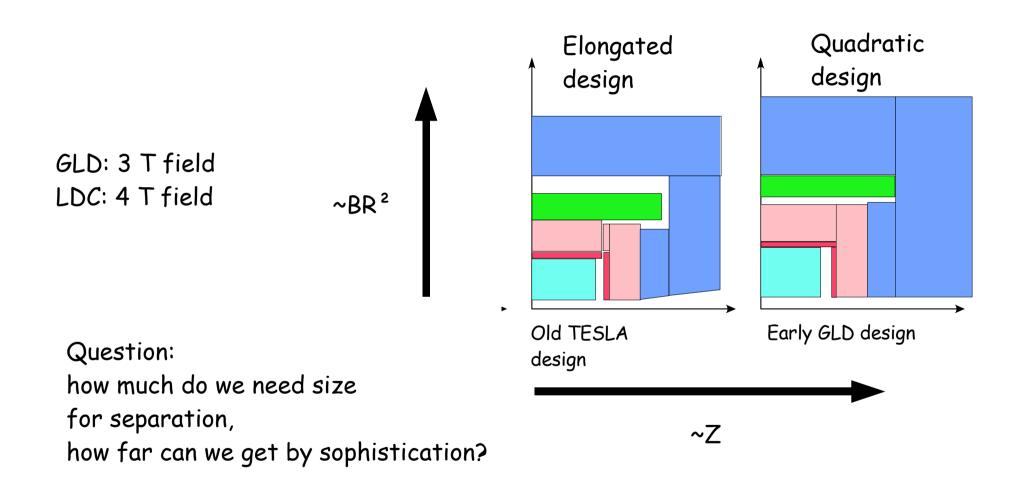
Questions: what is the optimal size? (including aspect ratio) What is the optimal B-field

GLD and LDC

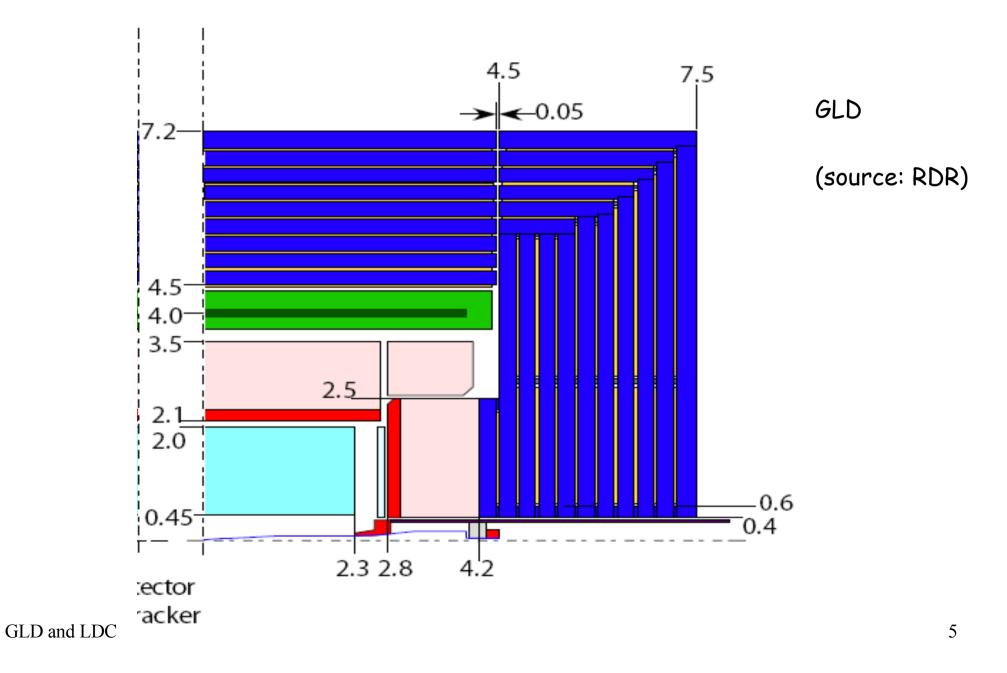
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R

# **General Layout**

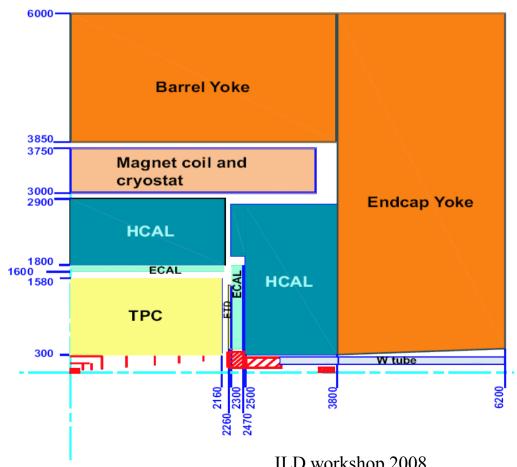


Does energy reach play a role?



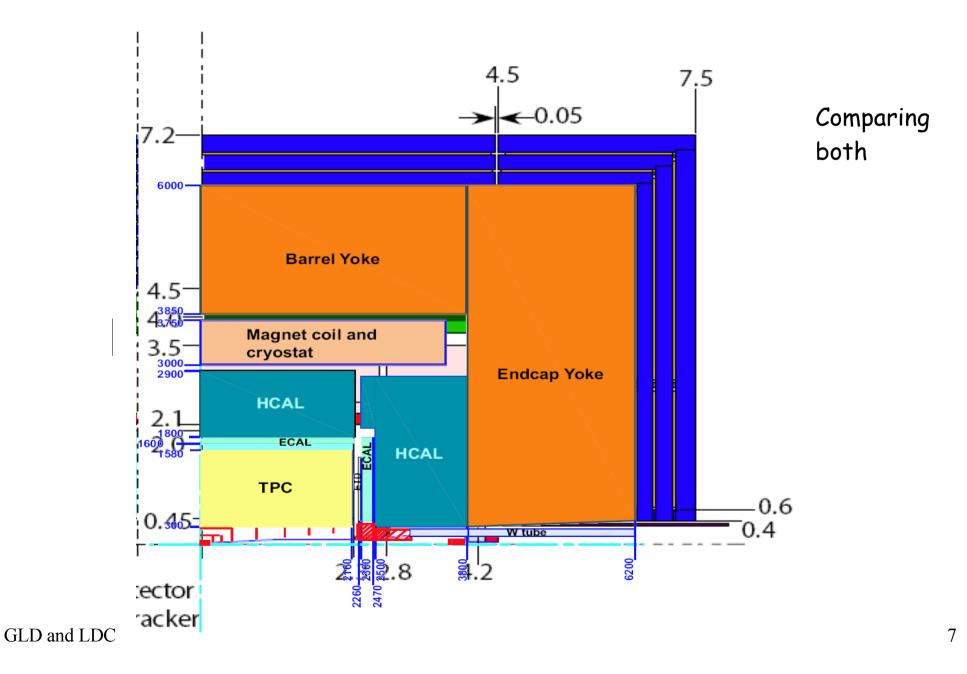
LDC

source: RDR



GLD and LDC

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# **First Conclusion**

Globally LDC and GLD are not that different

Size does matter, we need a real optimization strategy to understand the best optimization

(see Marks talk later today)

Particle Flow performance will dictate in the end the overall size

together with energy reach and cost considerations.

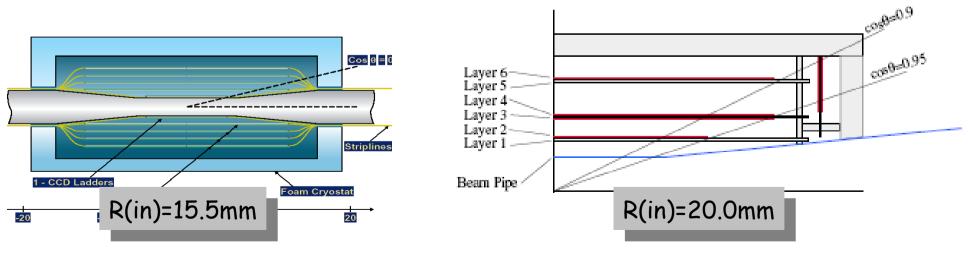
### VTX detector

Pixel technology, many different technologies are under consideration

### LDC

5 layers equally spaced no endcap for VTX no technology baseline GLD:

6 layers paired, on common support structure one endcap disk baseline fine pixel

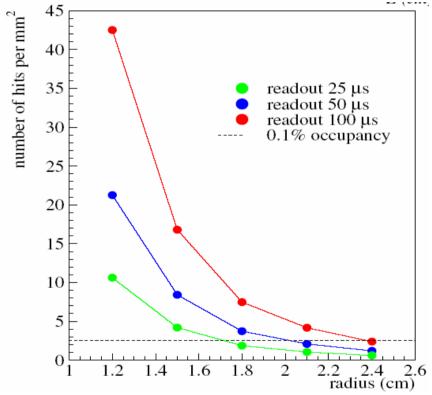


GLD and LDC

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## **VTX** parameters

Most critical parameter: inner radius

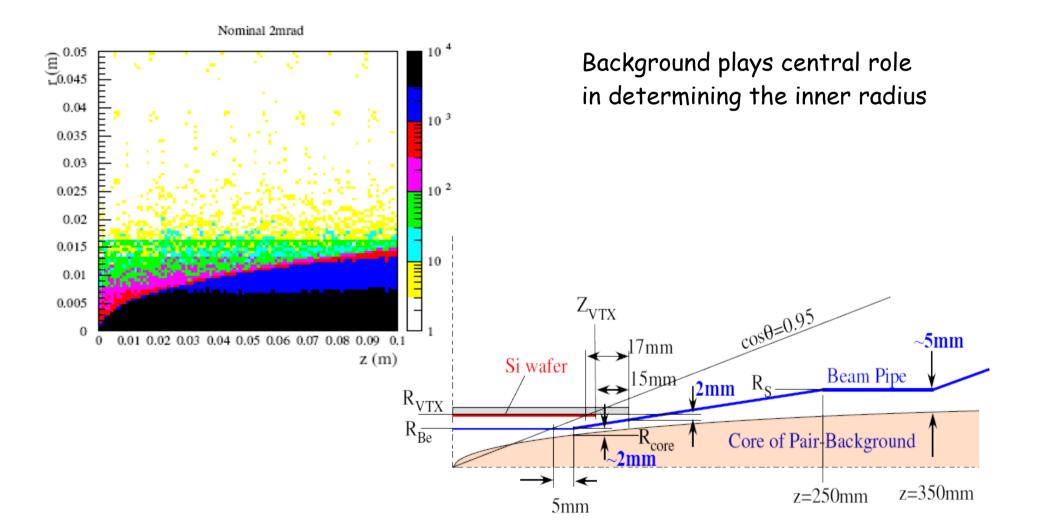


Background hit occupancy as a function of radius

Possible inner radius is mostly driven by magnetic field

Detailed layout will depend on final choice of field (or determine final field value) and machine parameters

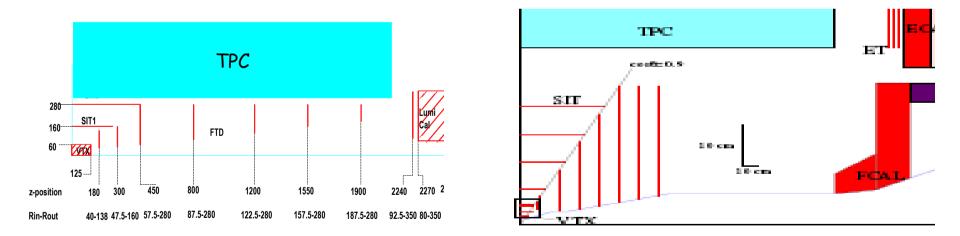
## **VTX** optimization



## The inner detector

Basic layout:

high precision VTX detector auxiliary SI tracking to bridge the gap between VTX and TPC high precision many point TPC



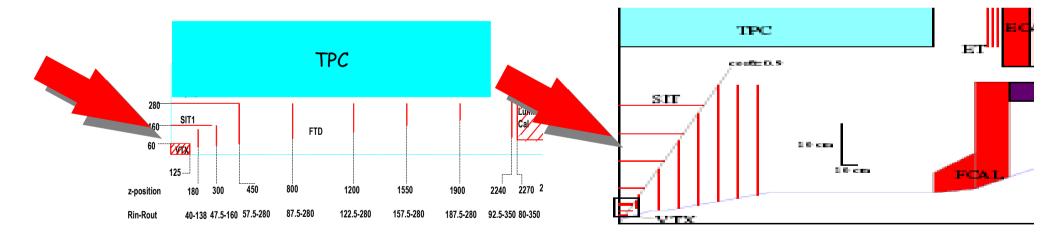
2 SIT layers

4 SIT layers

## The inner detector

Basic layout:

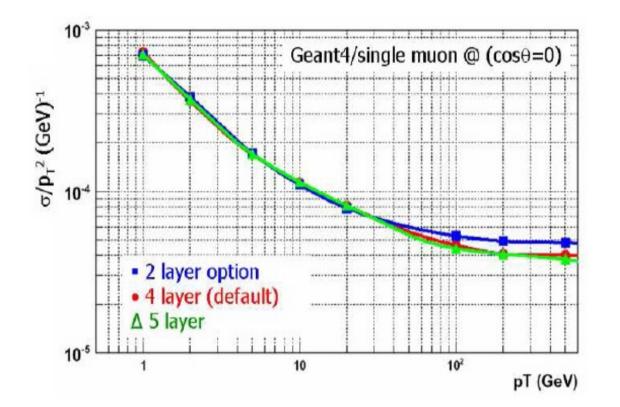
number of SIT layers?



2 SIT layers

4 SIT layers

## Number of SIT layers



4 layers: better momentum resolution

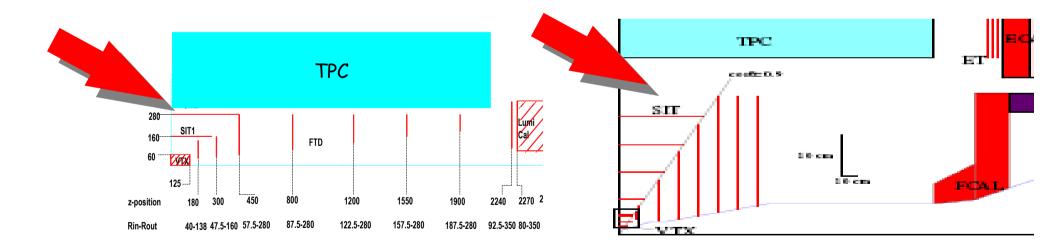
Material?

Tracking efficiency?

## The inner detector

Basic layout:

number of SIT layers? Position of last SIT layer?



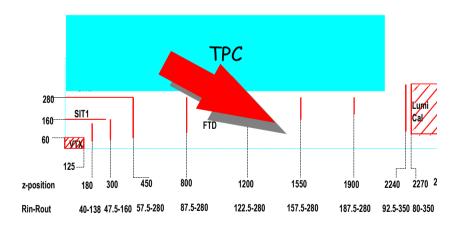
2 SIT layers

4 SIT layers

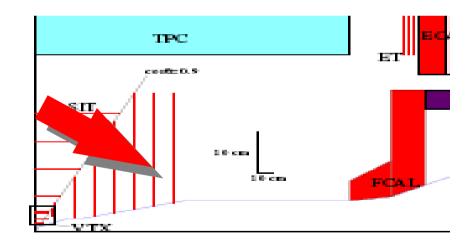
## The inner detector

#### Basic layout:

number of SIT layers? Position of last SIT layer? Position of FTD layers in forward direction



2 SIT layers



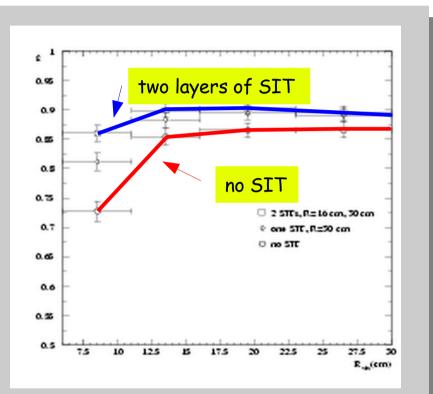
### 4 SIT layers

#### GLD and LDC

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# Silicon tracking

- SIT between GLD and LDC is different
- We need to understand the role of the SIT better
- Dedicated set of studies needed to determine the final layout



Example: KO finding efficiency with and without the SIT (LDC case)

## TPC

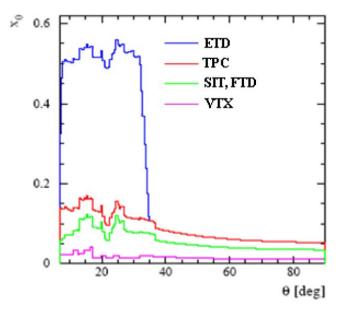
Both GLD and LDC rely on TPC for large volume tracking

differences are small

hardware developments are already done together

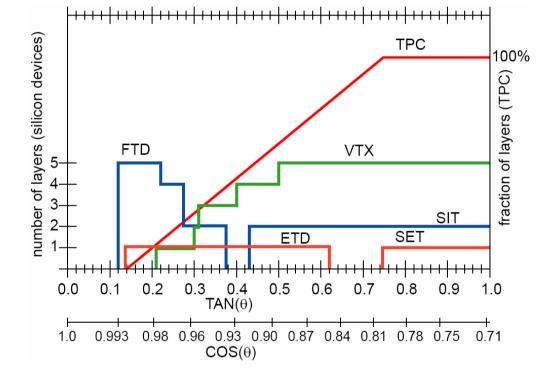
Performance goals seem within reach

biggest question remaining is material:



# **Tracking Configuration**

Coverage of subdetectors:



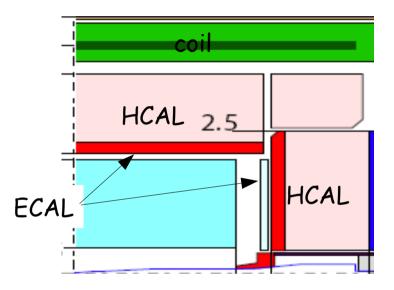
- Role of additional detectors?
- External Si tracker?
- SI detector behind the TPC endplate?

LDC coverage

# Calorimetry: Layout

Basic layout is the same:

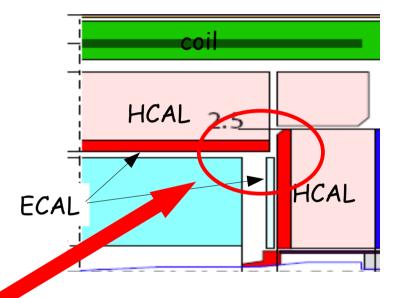
ECAL, HCAL both within the coil Separation into barrel and endcap



# Calorimetry: Layout

Basic layout is the same:

ECAL, HCAL both within the coil Separation into barrel and endcap

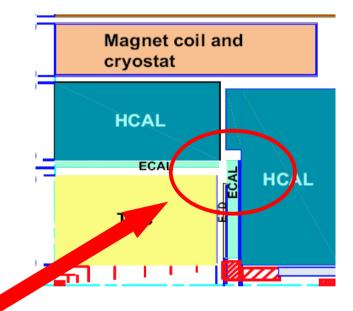


Layout of the corner is not well enough studied and different in detail

# Calorimetry: Layout

Basic layout is the same:

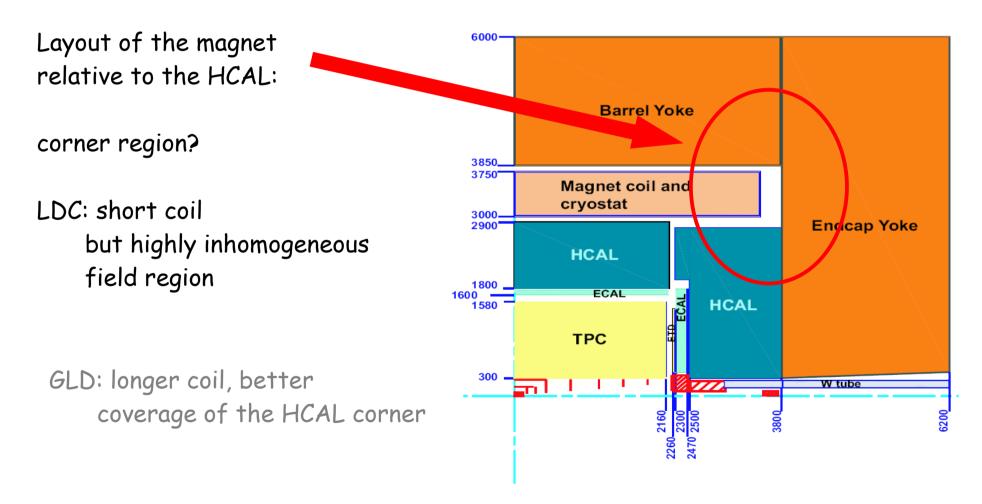
ECAL, HCAL both within the coil Separation into barrel and endcap



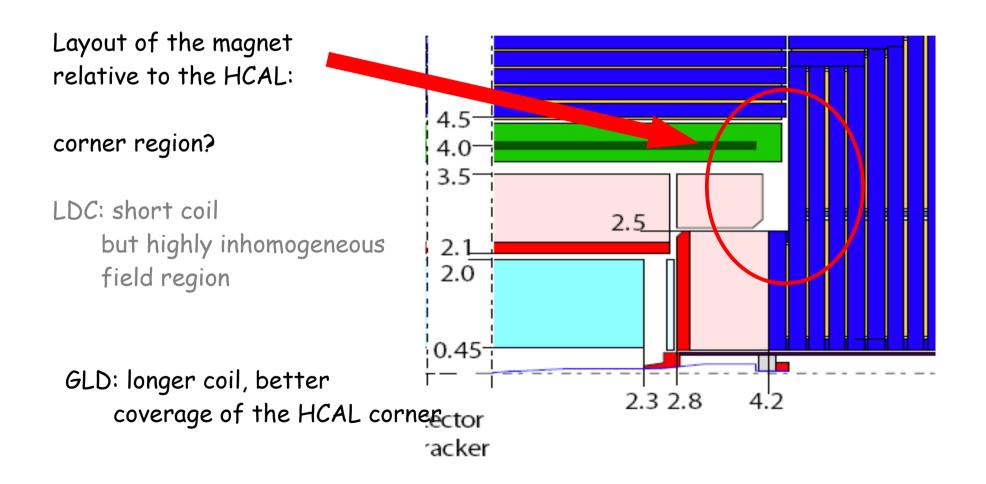
Layout of the corner is not well enough studied and different in detail

GLD and LDC

# **Calorimetery: Layout**



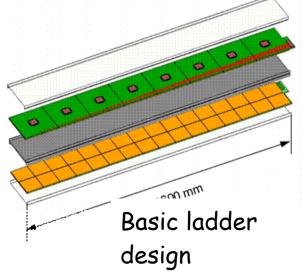
# **Calorimetery: Layout**

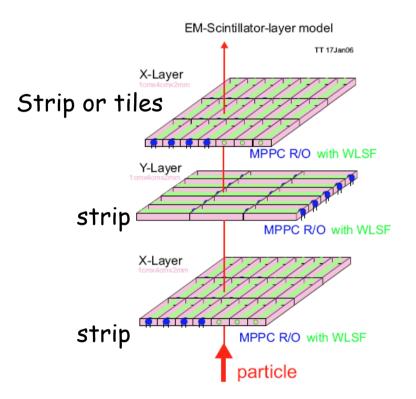


# ECAL: technology

Particle flow calorimetry: small cells, small Moliere radius

LDC: Si-W sampling calorimeter

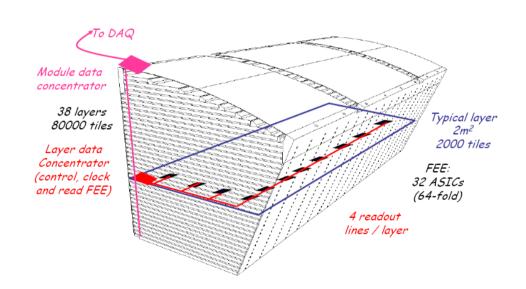


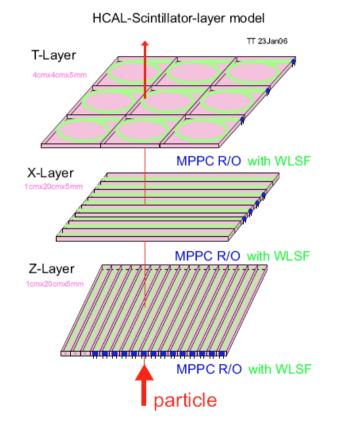


GLD: Scintillator-Pb sampling calorimeter

# HCAL

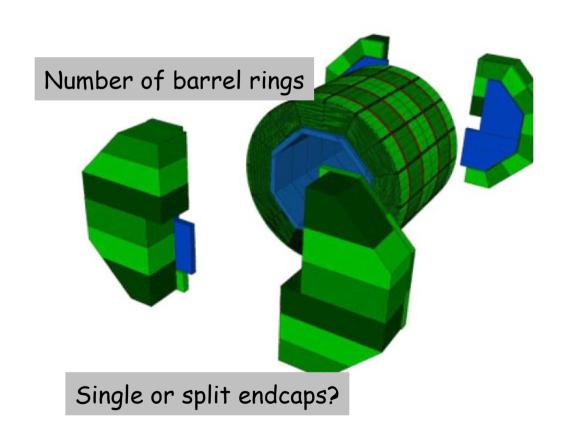
LDC: Analogue Scintillator tile – Fe sampling digital Fe-sampling





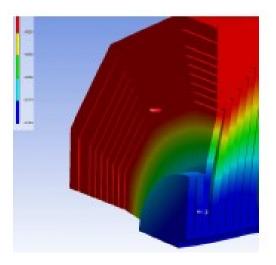
GLD: Analogue Scinitillator tile - Pb sampling (maybe Fe)

# Calorimeter: System design



Overall design depends on many factors:

stability magnetic forces integration aspects opening and closing etc



GLD and LDC

## Calorimeter conclusion

Conceptually there are no (or little) differences between LDC and GLD

Technologically there are differences

The final choice of technology will depend critically on the performance evaluation, and possibly on cost

Open questions (same for all options)

- Optimal sampling
- Optimal granularity
- Thickness (in particular HCAL)
- Barrel-endcap transition

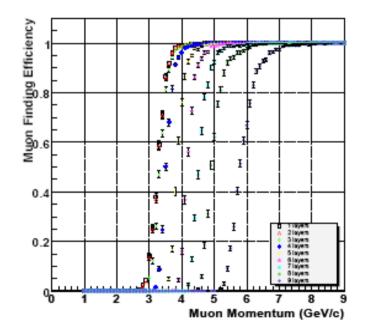
**)** ....

(see Marks talk later today)

## **Outer Detectors**

Muon system: instrumented iron return yoke

Options are Scintillator strip or large area RPC



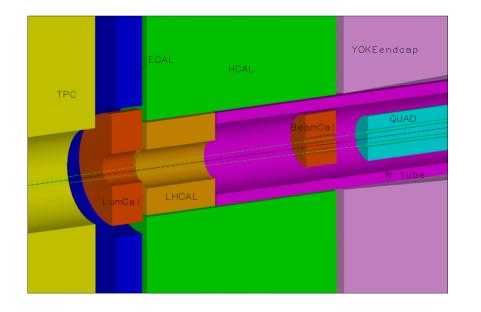
Number and spacing of layers need to be optimized

Role of Muon detector in a PFLOW detector needs to be understood

# Very forward detectors

Layout of GLD and LDC are different in detail,

but similar in principle



MDI working group is already studying this in detail

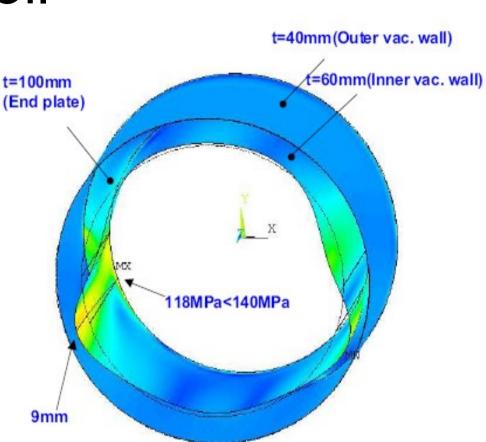
see tomorrows morning session

## Coil

Designs for coils exist for both LDC and GLD

> They differ in some details but not in principle

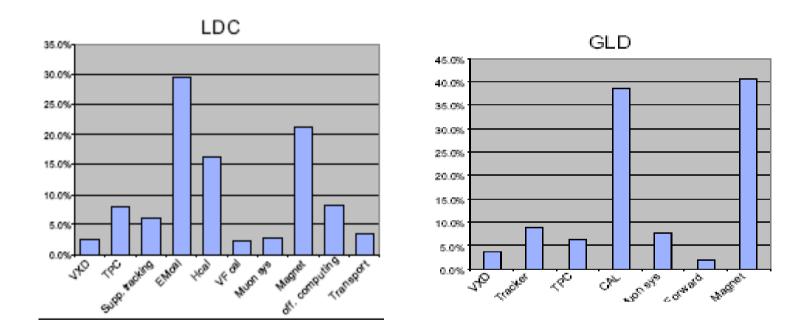
Most relevant question:



what is the optimal field value (closely related to size optimization discussed at beginning)

## Cost

### Costs have been evaluated for both LDC and GLD



Cost will play a crucial role in the definition and optimization procedure We have to understand the costing methodology.

# Conclusion

GLD and LDC start from similar assumptions

Solutions found are similar in principle, but different in detail

To define ILD we need

- Understand the arguments for a particular solution
- Explore the available phase space (optimization)
- Understand the cost impact
- Define a baseline configuration with a (hopefully small) number of options

This workshop will show us how to proceed towards ILD