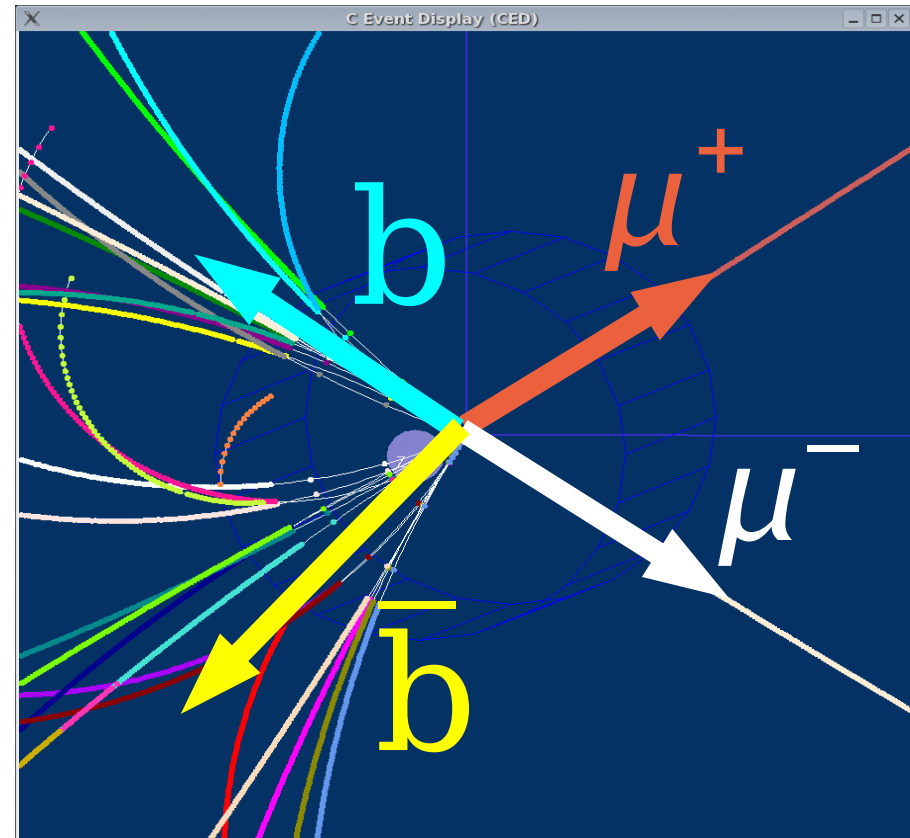


# Status of Tracking Software & ILD Tracking Performance

Alexei Raspereza, Steven Aplin  
*ECFA Workshop, Warsaw 10/06/2008*

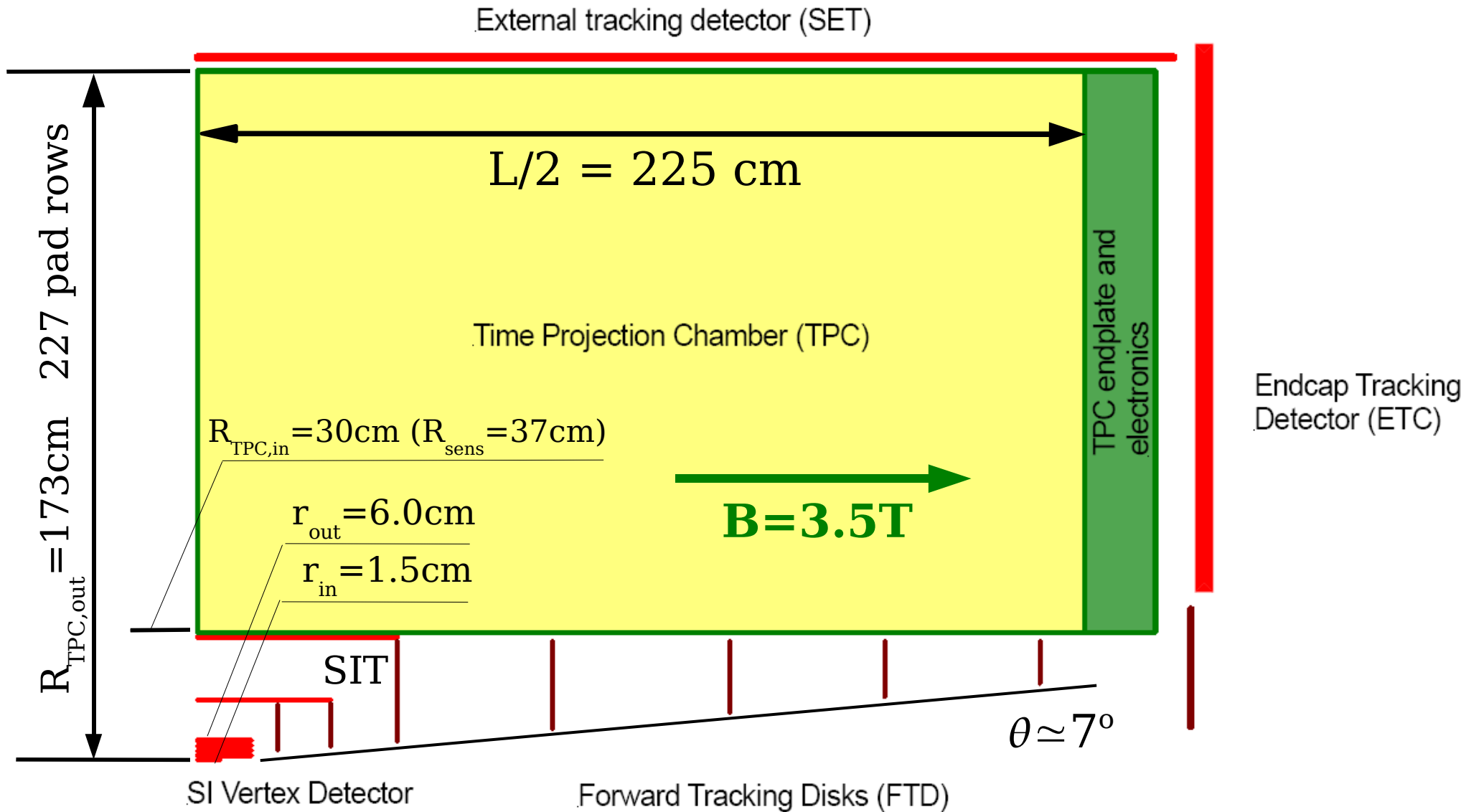
## Outline

- Overview of ILD Tracking System
- Tracking Software Updates
- Performance of ILD Tracking
  - × Resolution on track parameters
  - ×  $V^0$  reconstruction
  - × Track finding efficiency
  - × PFA – related performance
- Summary

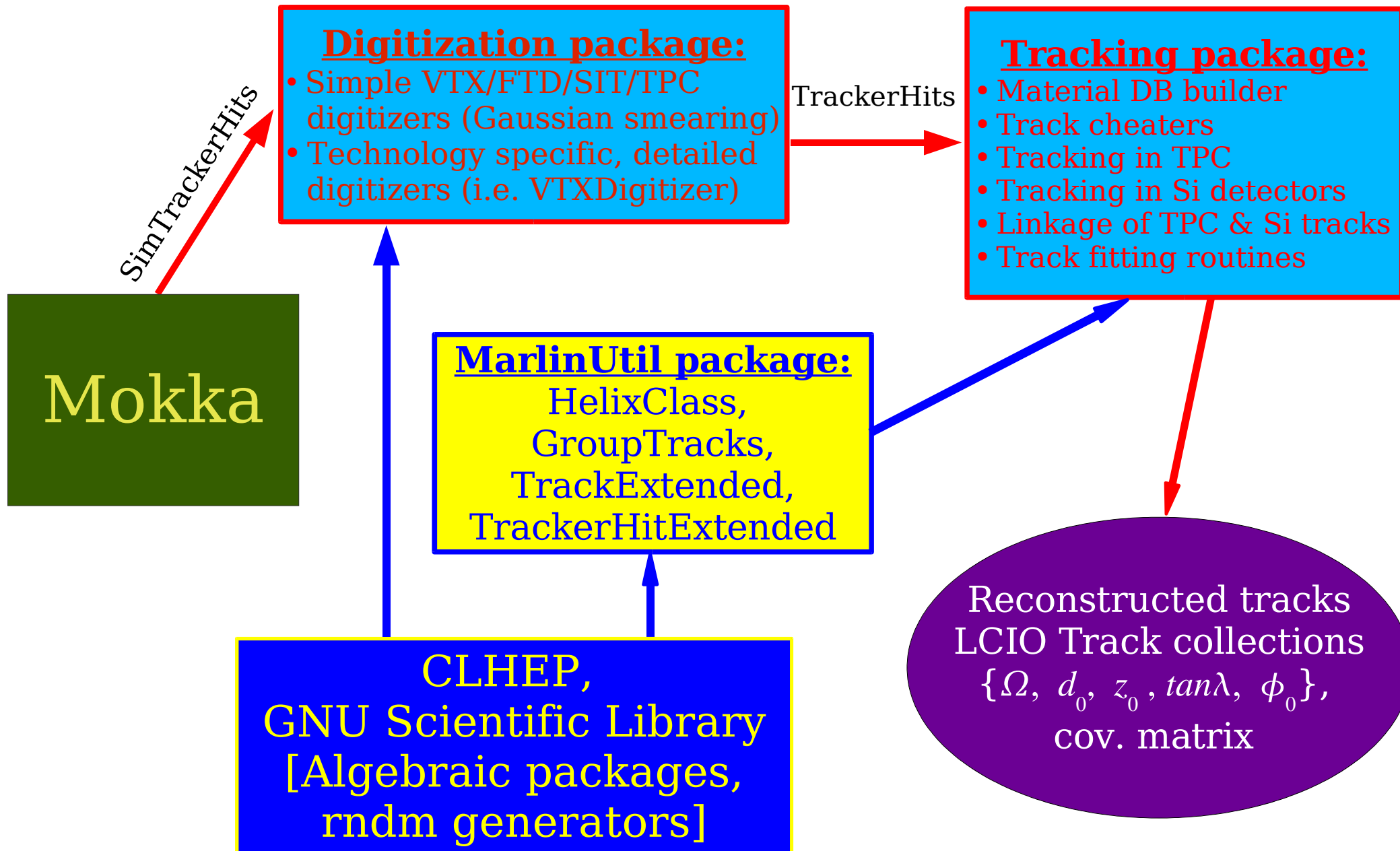


# ILD Tracking System

Mokka Model LDCPrime\_02Sc



# Structure of Tracking Package



# Updates of Tracking package

- **Digitization**

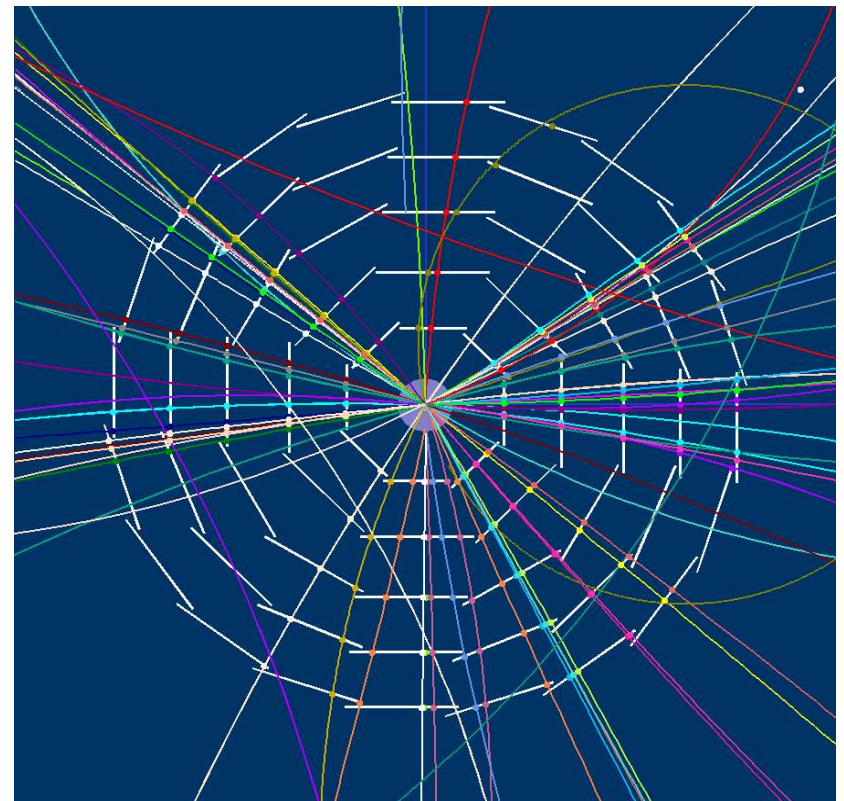
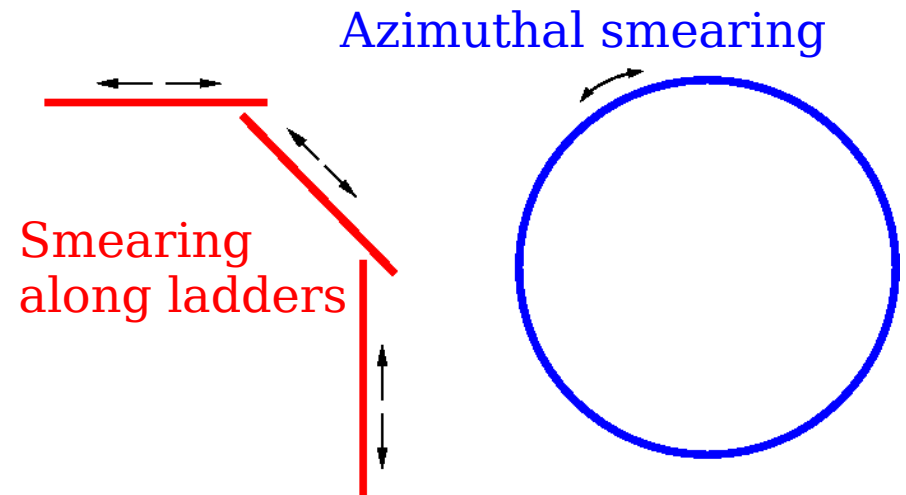
- Hit smearing along ladders in the laddered structures of VTX (C.Lynch)

- **Tracking**

- Implementation of realistic shapes describing VTX ladders in MaterialDB processor for Kalman fitter (A. Moll)
- Gear steerings and MaterialDB processor are made consistent with recent Mokka models (S. Aplin)
- Inclusion of SET and ETD in pattern recognition
- Dedicated  $V^0$  finder processor (in development stage)

- **Visualization**

- Marlin processor **VertexViewer**  $\Rightarrow$  visualization of tracks (useful debugging tool)



# Digitization Procedure & Spatial Point Resolutions

- Simple digitization : Gaussian smearing of **SimTrackerHits** positions  $\Rightarrow$  **TrackerHits**

- **TPC** :

Realistic parametrization of the TPC resolutions provided by LCTPC group (Ron Settles) [implemented by Steve]

$$\sigma(r-\phi)^2 = \sigma_0^2 + D^2 \cdot L_{drift} / N_{eff}$$

$$\sigma_0 = (50\mu m)^2 + (900\mu m \cdot \sin\phi_{local})^2$$

$$N_{eff} = 22 / (\sin\theta \cdot pad\_height[mm] / 6)$$

$$D = 25\mu m / cm^{1/2}$$

$$\sigma(z)^2 = (400\mu m)^2 + L_{drift}[cm] \cdot (80\mu m)^2 / cm$$

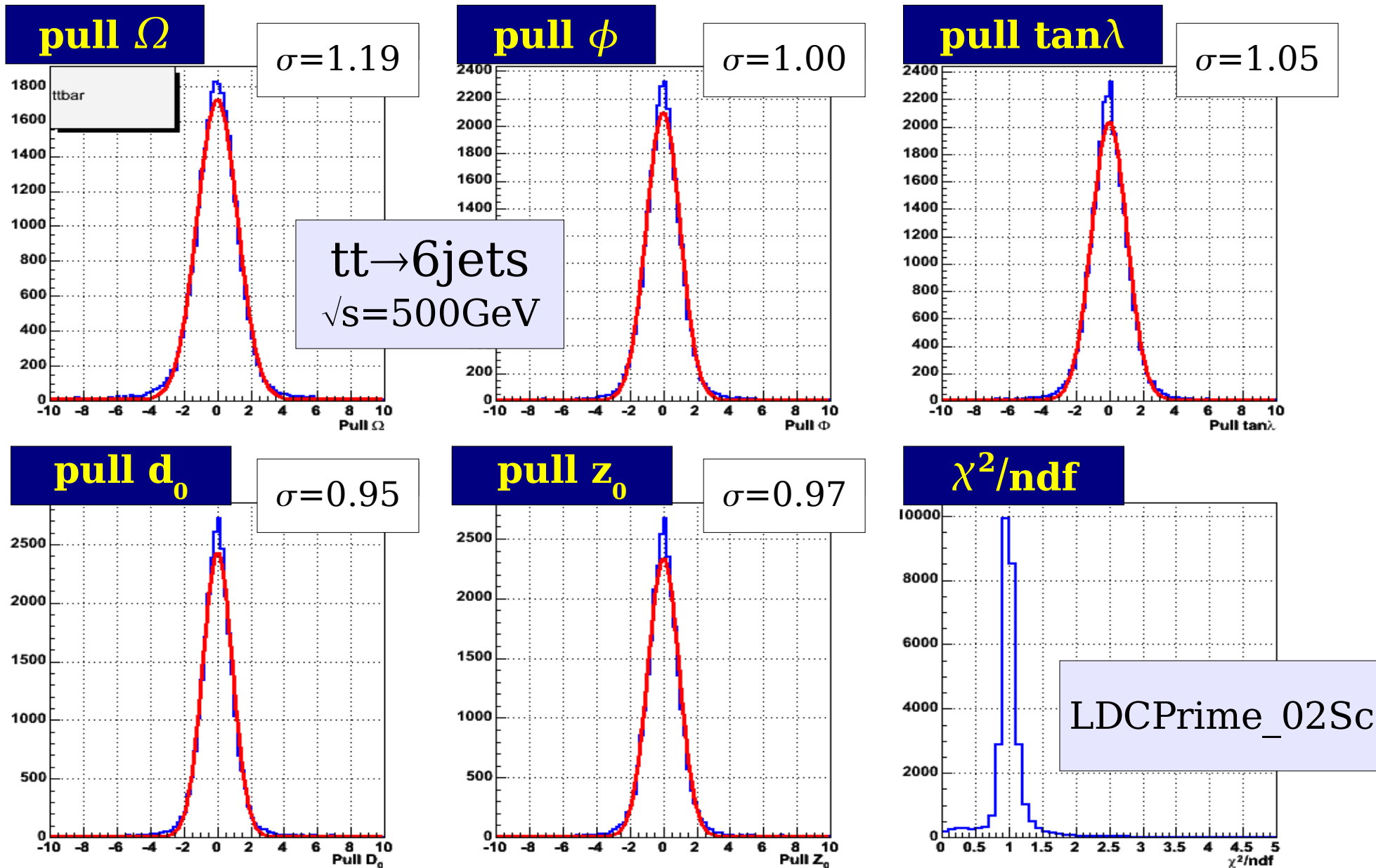
- **VTX** :  $\sigma(z) = \sigma(r-\phi) = 4\mu m$
- **SIT, SET** :  $\sigma(z) = \sigma(r-\phi) = 10\mu m$
- **FTD, ETD** :  $\sigma(r-\phi) = \sigma(r) = 10\mu m$

$\theta$  dependence of spatial point resolution of Si detectors has been neglected

# Tracking in MarlinReco

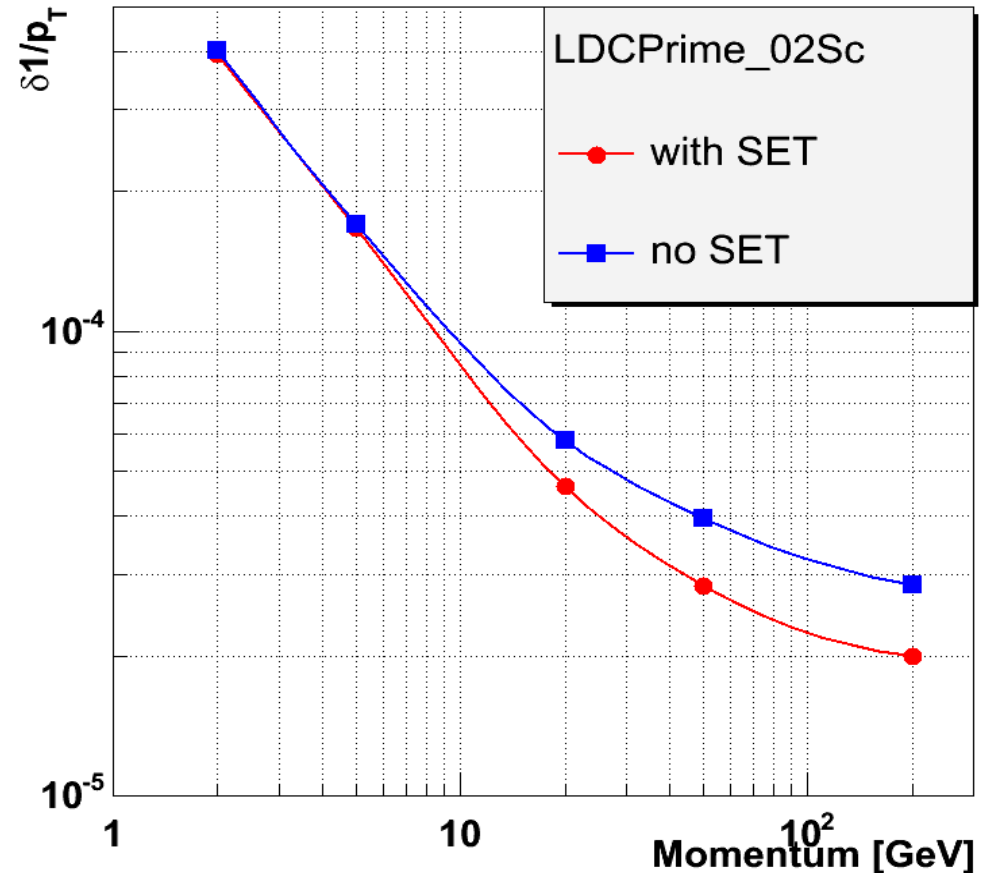
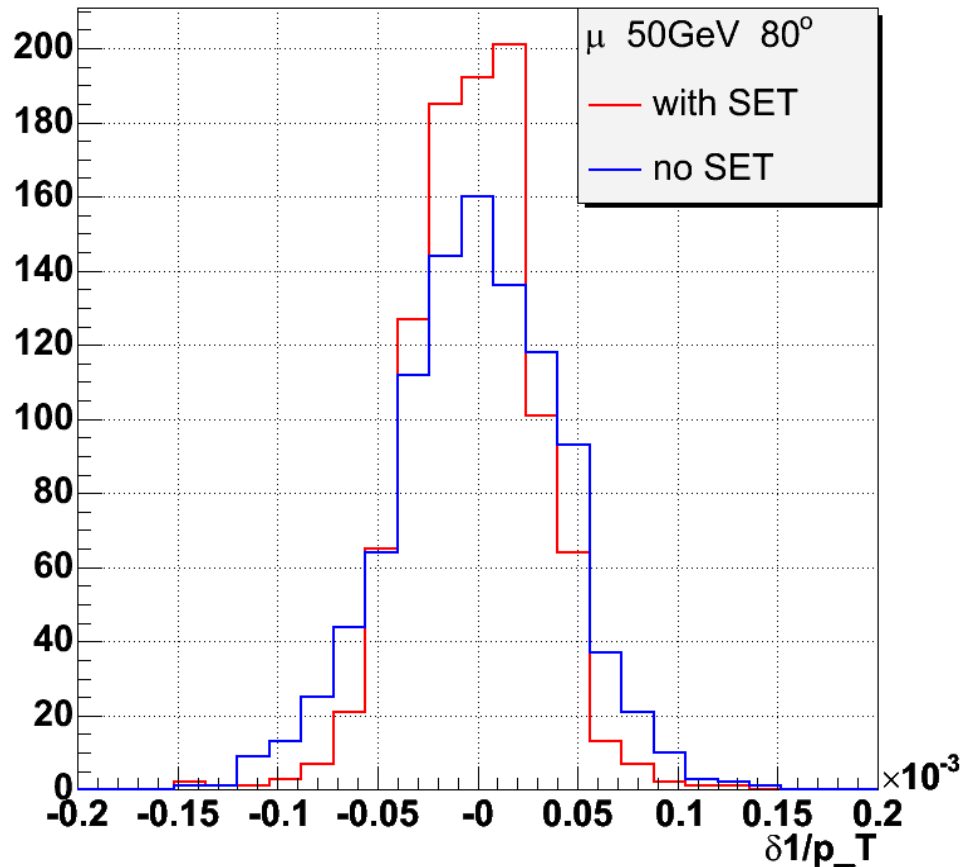
- **Tracking in TPC : LEPTrackingProcessor**  
(C++ wrappers of DELPHI code, author : S.Aplin )
  - Inward search for continuous track segments. Kalman track fit
  - Input : collection of TPC hits. Output : collection of TPC tracks
- **Tracking in Si detectors : SiliconTracking processor**
  - Search for hit patterns compatible with the helix model. Kalman track fit
  - Input : collection of VTX, FTD & SIT hits. Output : collection of Si tracks
- **FullLDCTracking processor**
  - Association of Si & TPC track segments. Assignment of left-over hits to found tracks  $\Rightarrow$  full track recovery (loopers). Kalman track fit. Extrapolation of tracks to ECAL
  - Input : collections of VTX, FTD, SIT & TPC hits + Si & TPC tracks.  
Output : Full LDC tracks + cov. matrices

# Diagnositics of Tracking Pulls & $\chi^2$ Distributions



# Impact of SET on $p_T$ Resolution

$\delta(P_T)/P_T^2$  LDC Tracks

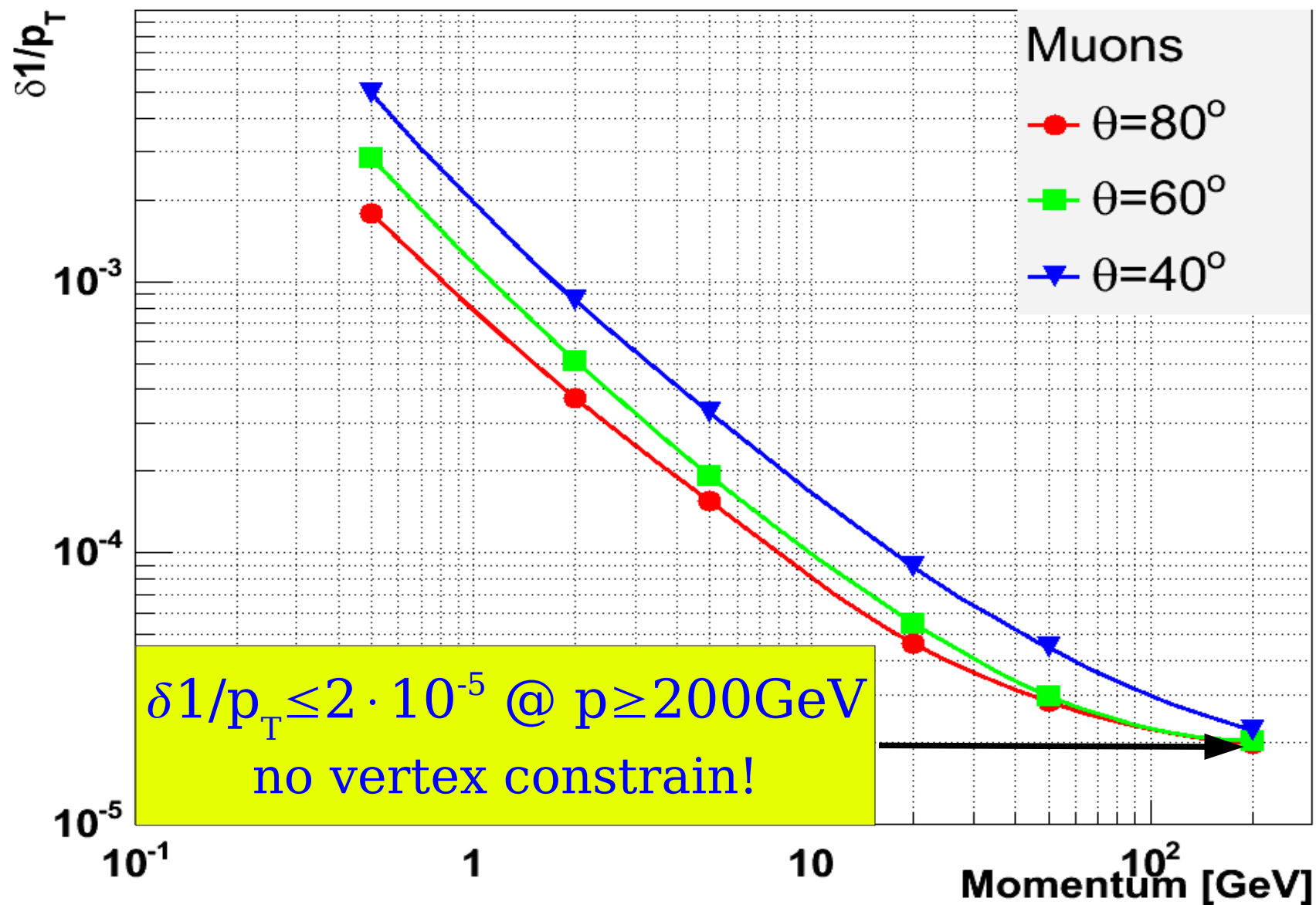


~40% improvement in  $1/p_T$  resolution at **high p**  
perhaps too aggressive assumption on  $\sigma(r-\phi)_{\text{SET}} = 10\mu\text{m}$



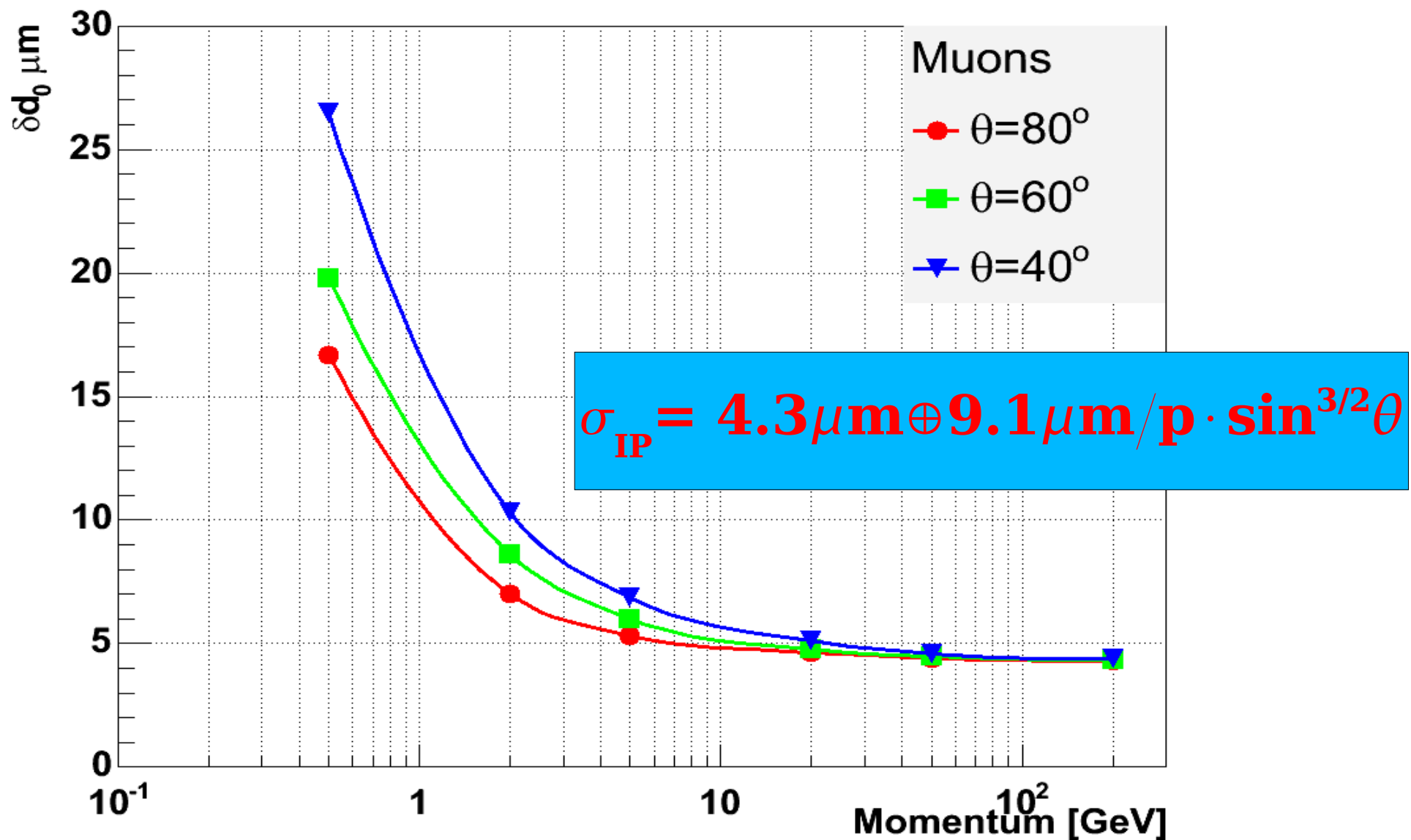
# Momentum Resolution

Central Tracks. Model LDCPrime\_02Sc



# Impact Parameter Resolution

Central Tracks. Model LDCPrime\_02Sc



# Track Parameter Resolutions

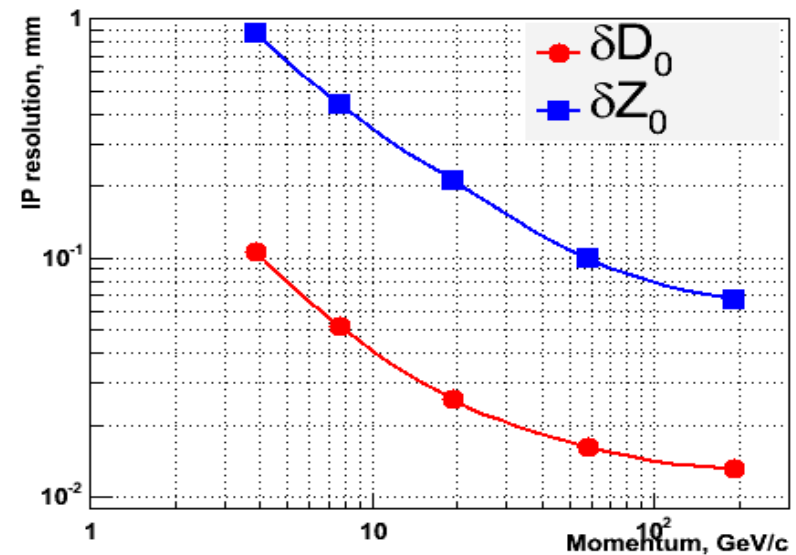
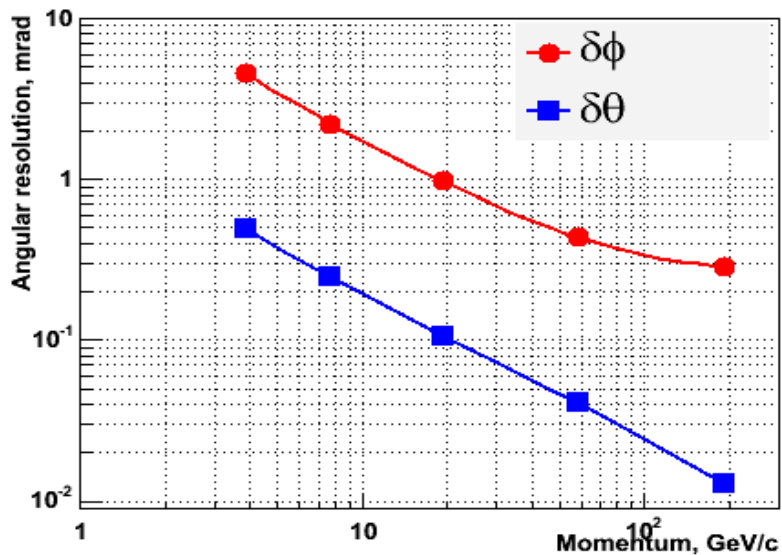
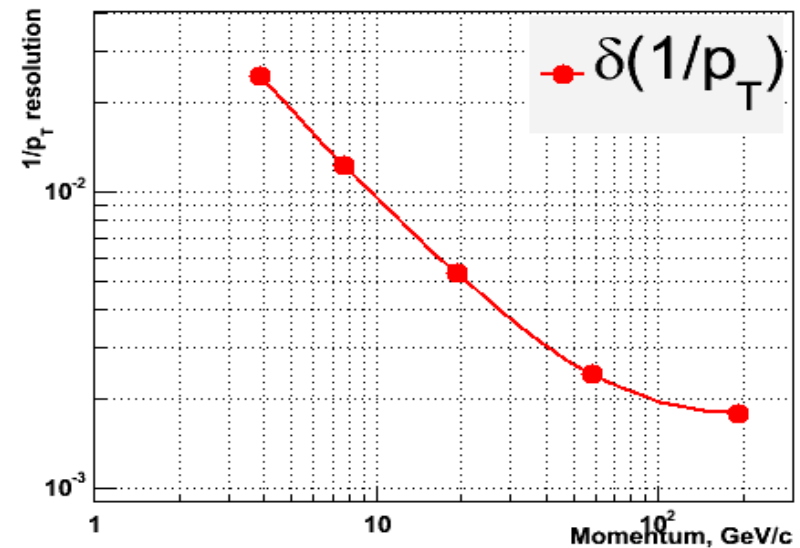
Forward Region. Model LDCPrime\_02Sc

Forward region [ $10^\circ \leq \theta \leq 20^\circ$ ]  $\Rightarrow$   
Tracks reconstructed with FTD

Planar z-Discs  $\Rightarrow$

$$\sigma_\phi \propto \sigma_\theta / \sin\theta$$

$$\sigma_{z0} \propto \sigma_{d0} / \tan\theta$$



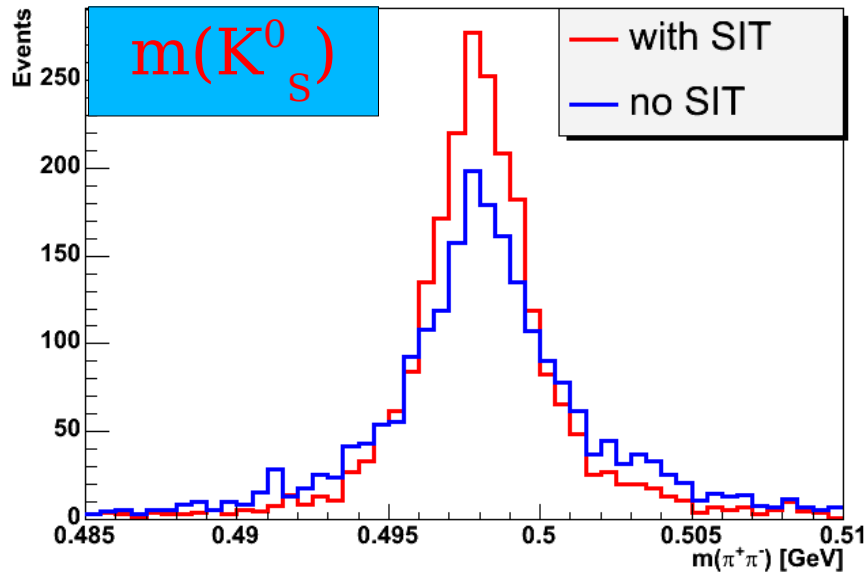
# Reconstruction of $V^0$

- Dedicated  $V^0$  reconstruction procedure implemented as separate Marlin processor **V0FinderProcessor**
- Signature :
  - two tracks with opposite charges (track charged is defined by the sign of the track parameter  $\Omega$ )
  - consistent with coming from single point
  - tracks do not originate from primary interaction vertex
- Reconstructed 4-vectors of vertices are stored in collection of type **ReconstructedParticle**
- Three mass hypotheses ( $K_s^0$ ,  $\Lambda^0$ ,  $\gamma$ ) and vertex positions are stored in additional collection of type **LCFloatVec**  
( **6 elements in vector :**  
**3 mass hypotheses + 3 coordinates of vertex** )

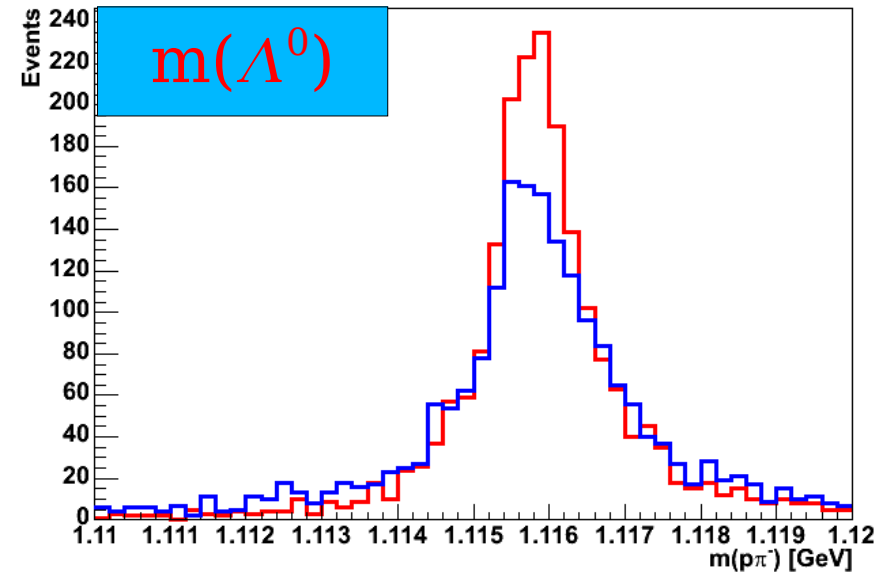
# Importance of SIT for $V^0$ ID

$e^+e^- \rightarrow Z^0 \rightarrow s\bar{s}$  sample @ 91.2 GeV

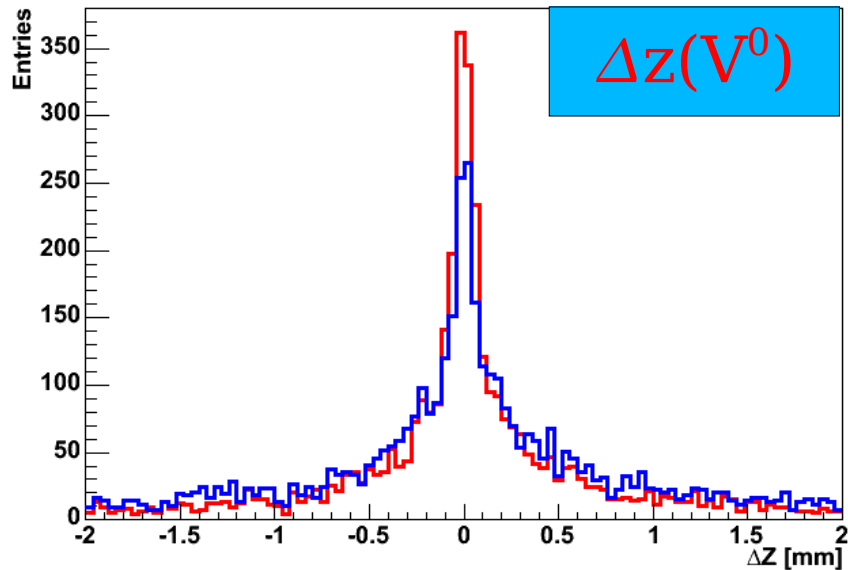
$K_S^0$  mass



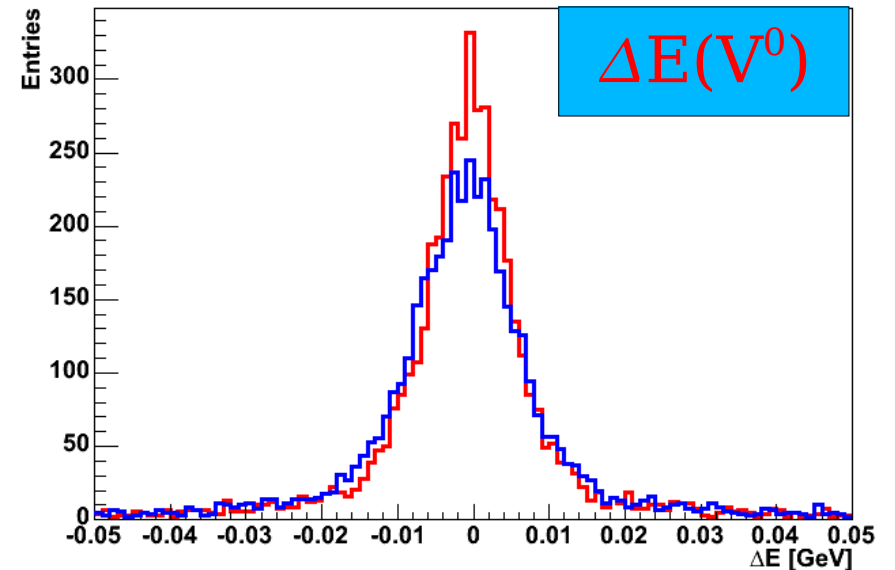
$\Lambda^0$  mass



$\Delta Z_{V^0}$



$\Delta E_{V^0}$

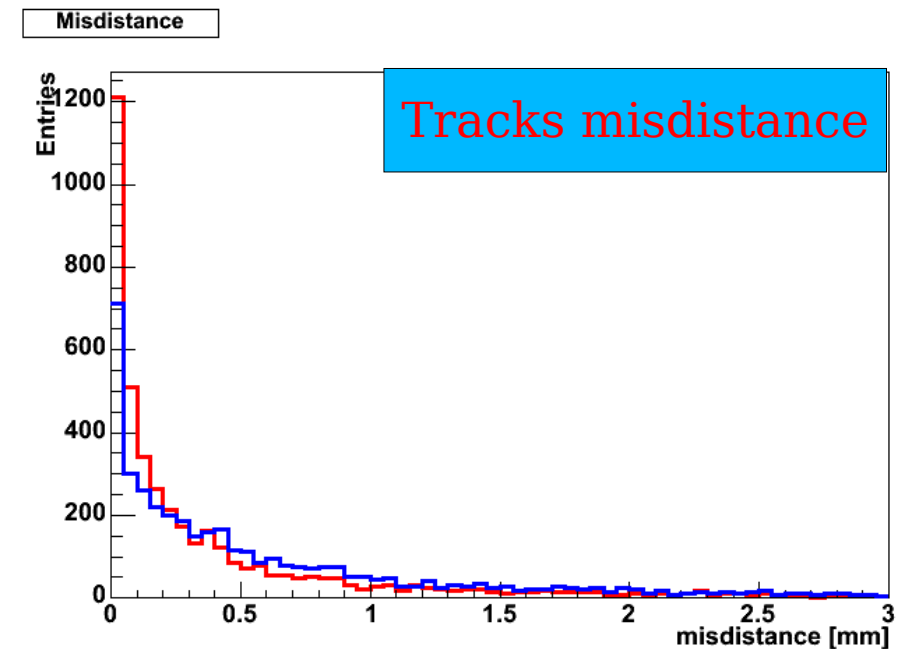
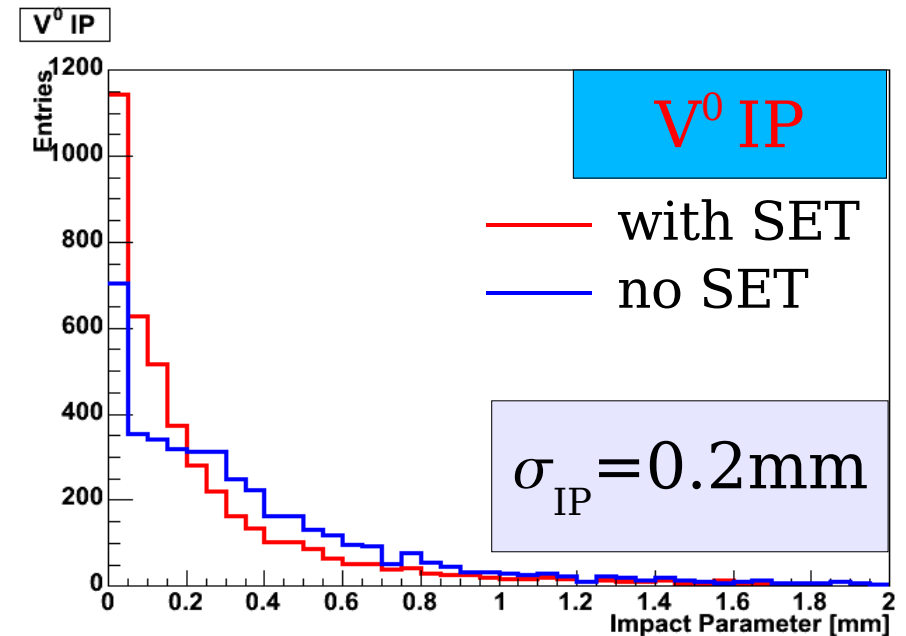


# Performance of $V^0$ Identification

- Good impact parameter resolution  $\Rightarrow$  sensitivity to neutral particles originating from secondary vertices
- Two parameters steer  $V^0$  finding :
  - cut on tracks misdistance  $\Delta \mathbf{d}$
  - cut on vertex radius  $\mathbf{r}_{V^0}$
- Default cuts :  $\mathbf{r}_{V^0} > 2\text{cm}$   $\Delta \mathbf{d} < 2\text{mm}$ 
  - $\Rightarrow V^0$  finding efficiency = 93% ,  
fake rate < 0.1%

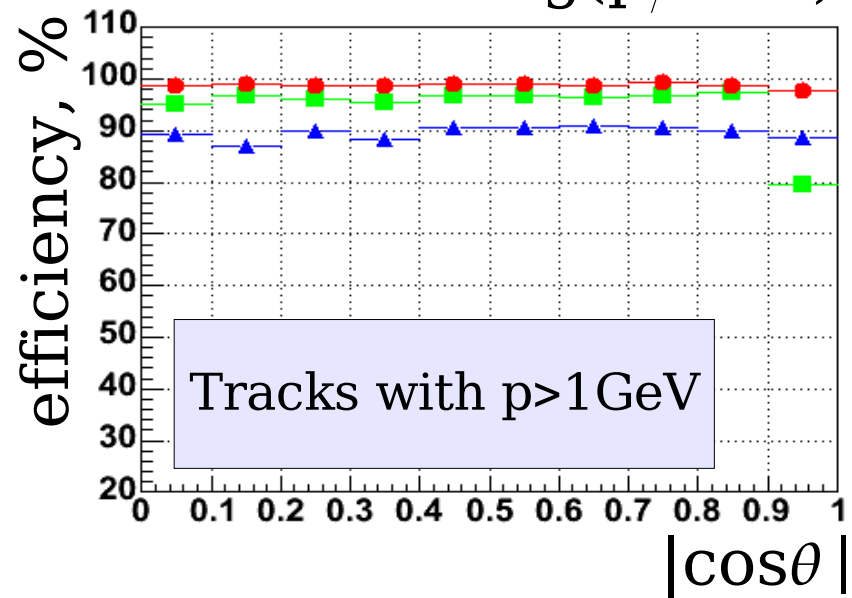
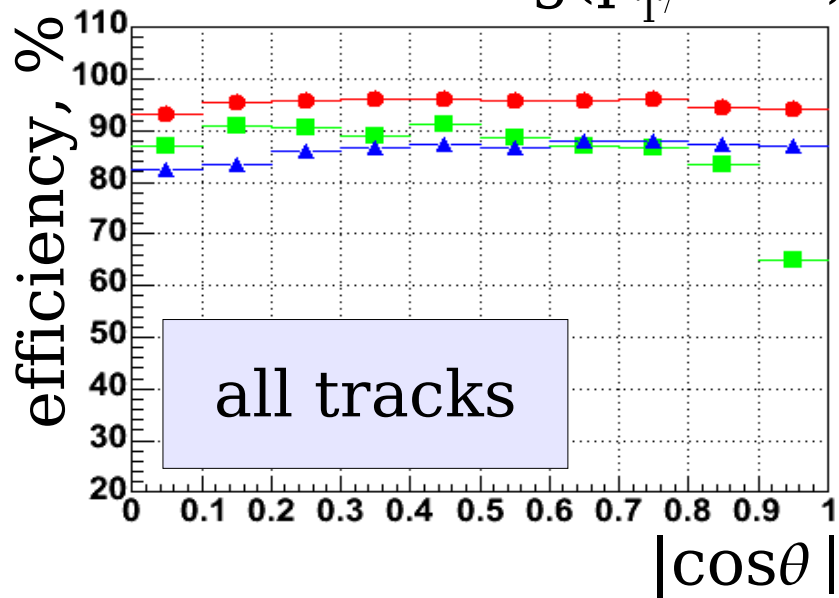
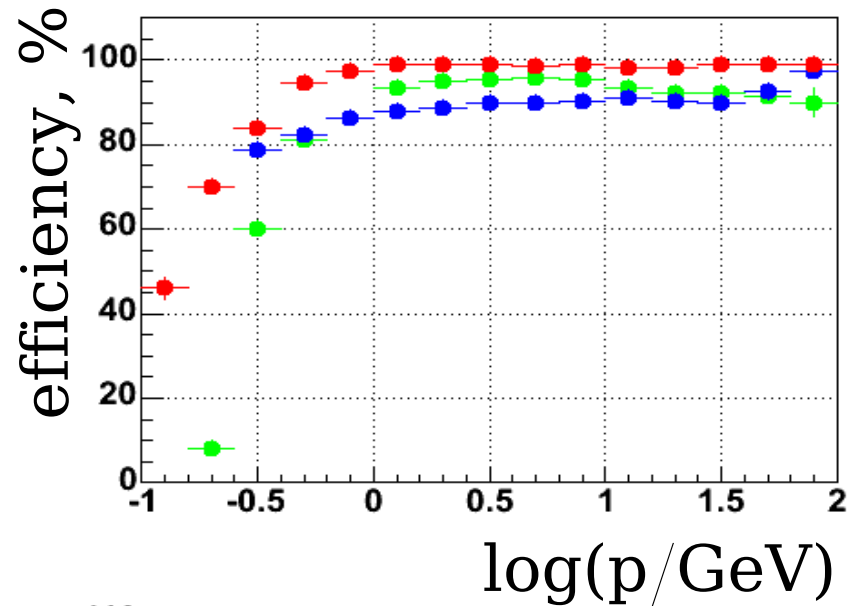
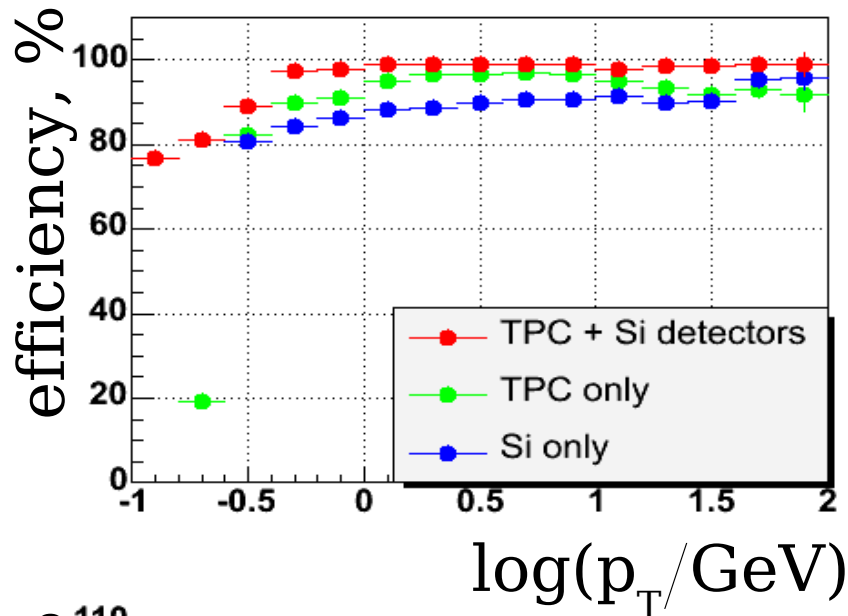
**$V^0$  finding : input for heavy flavor tagging!**

**(Rejection of  $K_s^0$  &  $\gamma$ -conversions)**



# Track Finding Efficiency

$tt \rightarrow 6\text{jets}$  @ 500GeV. LDCPrime\_02Sc



# PFA Related Performance

## Resolution on charge energy in $tt \rightarrow 6\text{jet}$

### Visible energy resolution

$$\sigma_E = \sigma_{\gamma\text{'s}} \oplus \sigma_{h0\text{'s}} \oplus \sigma_{\text{tracks}} \oplus \sigma_{\text{conf.}}$$

### Evaluation of $\sigma_{\text{tracks}} \Rightarrow$

energy contained in the reconstructed tracks

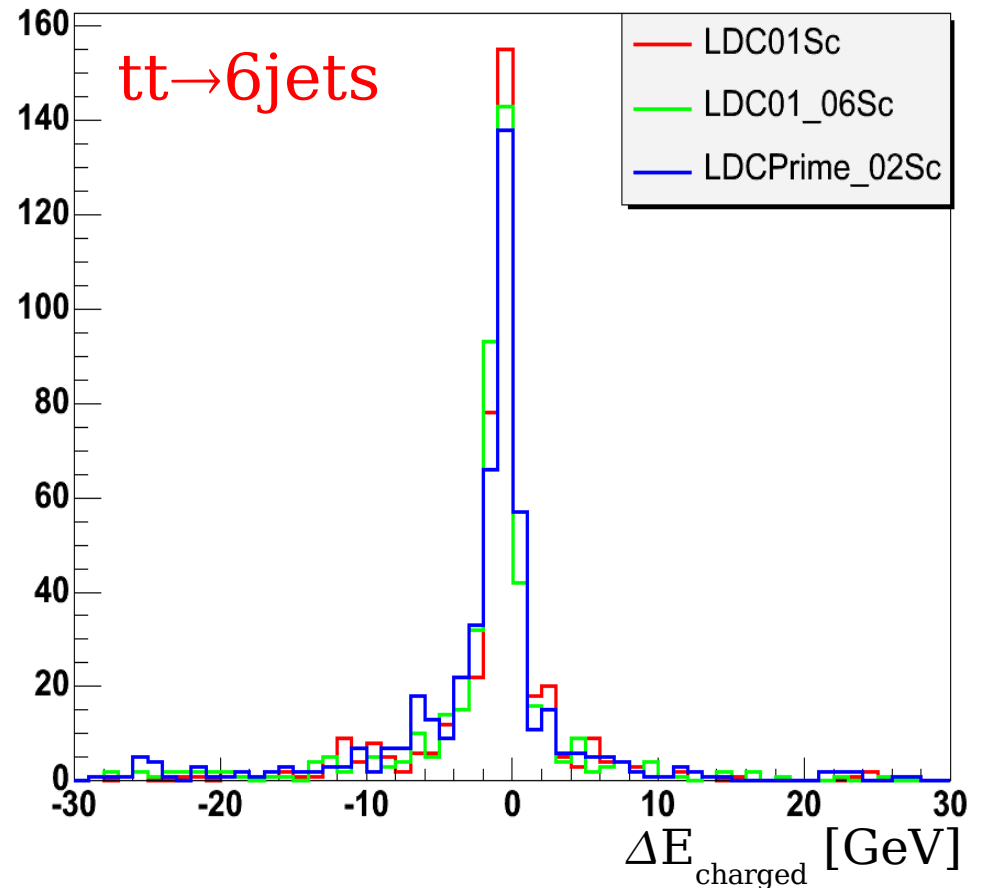
vs.

energy of charged particles at the generator level

- $V^0$  and kinks are properly taken into account in reconstruction
- albedo tracks removed

FWHM=3.5-3.9GeV

Reco - True energy, GeV



Left tail due to missing tracks (finite track finding efficiency)



# Summary

- Recent developments of tracking package closely followed updates of tracking system in Mokka
  - SET & ETD included in pattern recognition
  - Gear steerings and MaterialDB processor appropriately modified to account for a more realistic models of tracking devices in Mokka
- Tracking package is brought into consistency with the recent Mokka models to be used for the mass MC production
- Tracking package extended  $\Rightarrow$  dedicated  $V^0$  finder implemented (inclusion in MarlinReco shortly after ECFA Meeting)
  - code can be used in heavy flavour tagging ( $K^0$ 's and  $\gamma$ -conversions rejection)
- Tracking performance of the baseline ILD model LDCPrime\_02Sc meets ILC requirements
  - $\delta(1/\mathbf{p}_T) = 2 \cdot 10^{-5}$  (with SET)       $\sigma(\text{IP}) = 4.3\mu\text{m} \oplus 9.1\mu\text{m}/\mathbf{p} \cdot \sin^{3/2}\theta$
  - tracking efficiency : **98.4%** (  $\mathbf{p}_{\text{track}} > 0.5\text{GeV}$  ) ; **99%** (  $\mathbf{p}_{\text{track}} > 1\text{GeV}$  )  
@ low fake rate of  $\simeq 0.4\%$  [  $t\bar{t} \rightarrow 6\text{jets}$  events @  $\sqrt{s}=500\text{GeV}$  ]
- Code is ready to be used in physics studies and has been already successfully applied in a few analyses