



JRA1: EUTelescope SW

Philipp Roloff (DESY) for the JRA1 analysis group



Outlook:

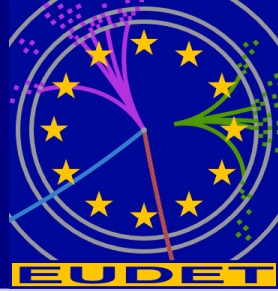
- Reminder
- Usability
- New features



EUDET Annual Meeting 2008, NA2 Session
NIKHEF Amsterdam, 06/10/2008



Reminder: EU Telescope



- Set of **Marlin processors**: Every step of the analysis chain is implemented as a separate processor

Advantages:

- If the behaviour of a given telescope setup is well understood, several steps can be merged together
- Storing intermediate data can reduce processing time

- User integration possible at different levels of the analysis

- Based on the existing **ILC software framework** (Marlin, LCIO, GEAR, (R)AIDA, CED, ...)

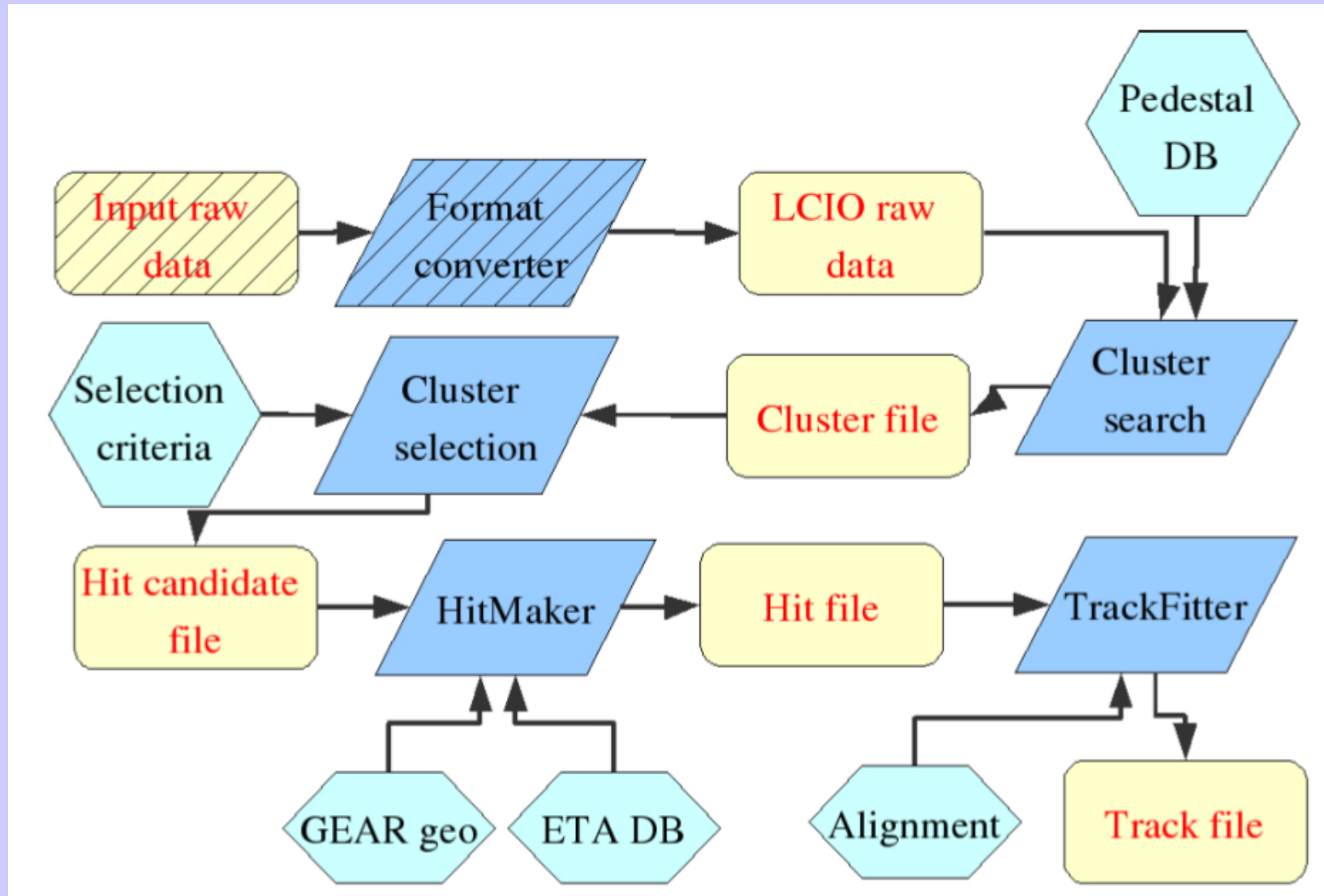
- Good experience with running on the GRID

- CVS and documentation:

http://ilcsoft.desy.de/portal/software_packages/eutelescope



Reminder: analysis scheme





Usability



An **increased number of detector R&D groups** is adopting the EU Telescope package!

Several issues have been addressed to **ease the installation and usage** of EU Telescope:

- **Installation procedure:**

- Encourage usage of ilcinstall

- *Dependencies:* Marlin and LCIO

Optional: MarlinUtil, GEAR, AIDA, ROOT, LCCD, CED, eudaq
(it is possible to compile without these for minimal features)

- install.cfg files are provided for minimal and complete installations

- **Keep documentation updated**

- **A tutorial was held in May 2008** (available on the JRA1 webpage)



Usability II



- **Preparing the transition from CVS to SVN:**
 - **R/W access to the repository can be provided by the project leader(s)** and not anymore by the CVS responsible in Zeuthen
 - R/W access will be based on personal SSL certificates (like for the GRID)
 - Users can create their own branches and when their code is mature enough it can be merged into the main trunk
- **GRID operation:**
 - The submission scripts were rewritten to use the new ILCSoft installation on the CE
 - In the future we aim for a unique submission script for execution on the local machine as well as on the GRID
- **Stability:** In general the package is stable and runs without crashes



New feature: universal reader



Most common scenarios for user integration in the DAQ system:

- *Integration at DAQ SW level*: The user provides own DAQ hardware, but the data are treated by the EUDAQ software
- *Integration at trigger level*

In the first case EUDAQ allows to **include DUT data in the native output file** → safest possible synchronisation

Universal native reader:

- Very **general data reading and conversion processor**
- Automatically detects from the native EUDAQ files which sensors were used and converts the information from the native format to LCIO
- Users are invited to provide a small piece of code to read their sensors

Alternative: EUDAQ now able to write LCIO files



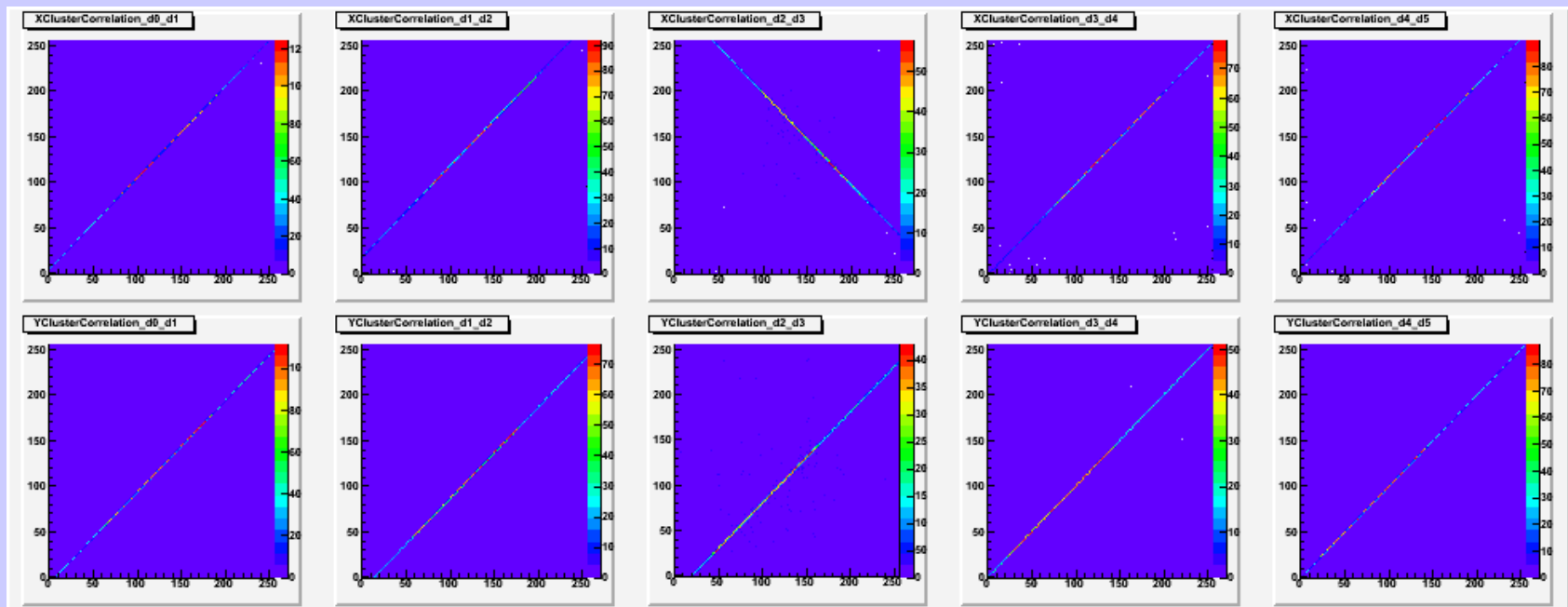
New features: Correlator



New simple processor to display correlations of hits and clusters in different telescope planes

- Useful to:
- Monitor the data quality
 - Verify the geometry description
 - Check alignment

Next step:
Correlate telescope planes with the DUT





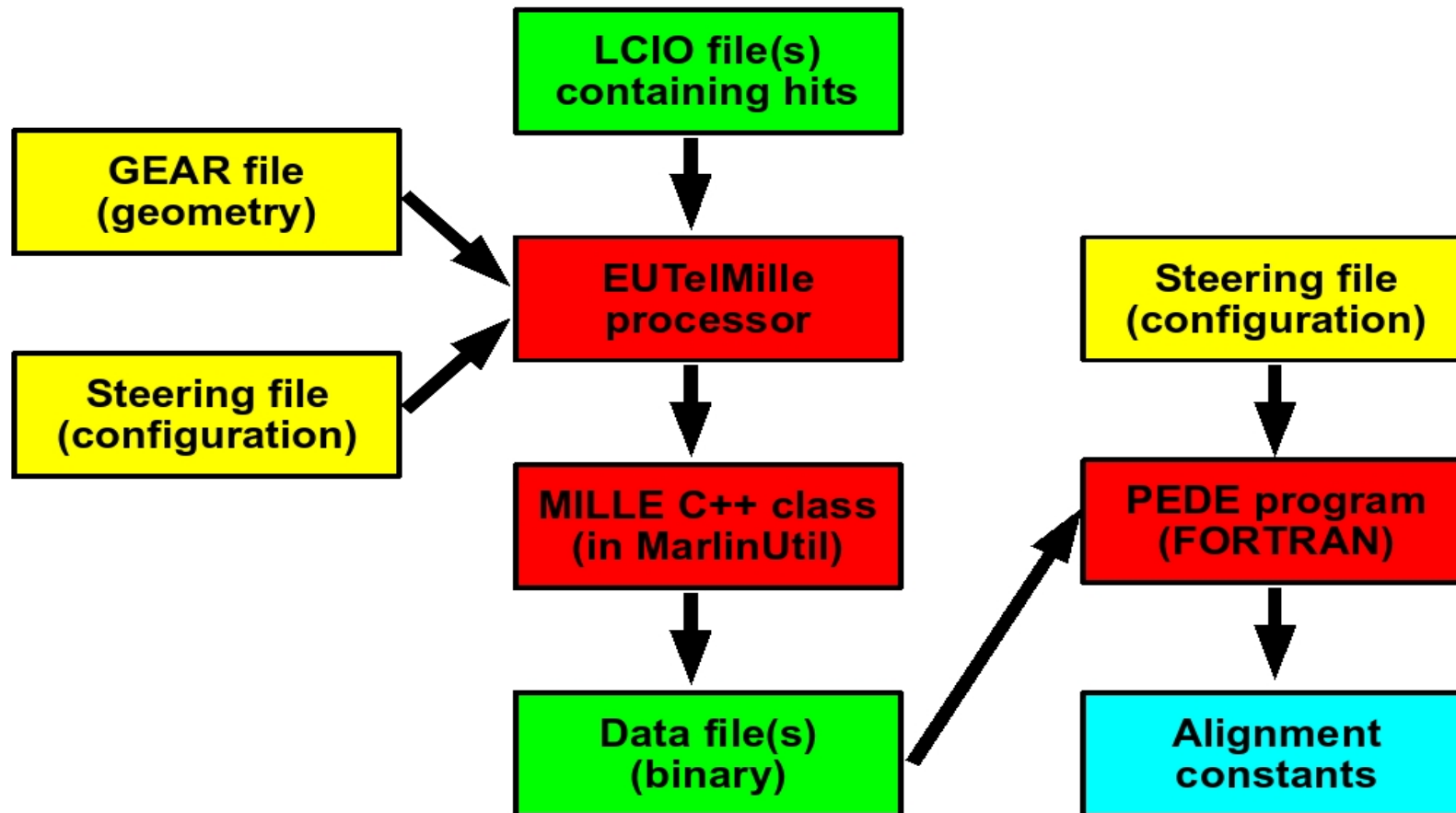
New feature: Alignment



- The new alignment procedure is based on the **Millepede II** package by V. Blobel
- A simultaneous fit using **full tracks** is performed to derive the alignment constants
- Modular implementation:
 - The **Mille** class has been included in MarlinUtil
 - It is used by the **EUTelMille** processor to generate binary files
 - The actual minimisation is done by the **pede** program (Fortran)
- EUTelMille can execute pede and generate the needed steering file
→ **The alignment can be fully controlled in the Marlin XML-File**
- It is possible to redirect the output of pede into a condition that can be stored in LCCD and read by Marlin using a conditions processor



Alignment scheme



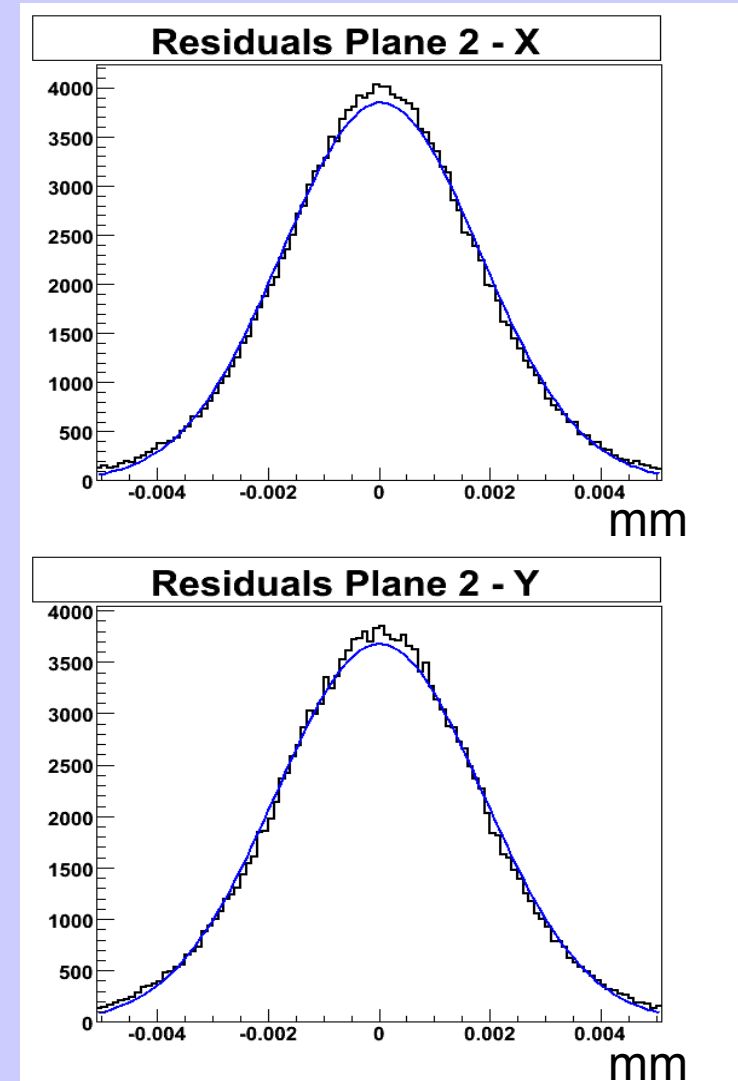


Example alignment



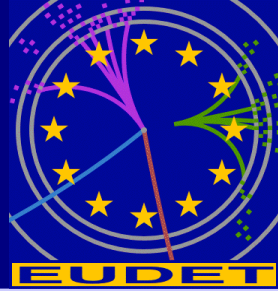
- 3 GeV electron data recorded at DESY
- Typical values of the Alignment constants:
 - shifts in X and Y: **a few hundred μm**
 - Rotation around the beam axis: **a few mrad**

Sensor	Residuals X Mean [μm]	Residuals Y Mean [μm]
0	-0.003 ± 0.002	-0.023 ± 0.002
1	-0.012 ± 0.004	0.036 ± 0.005
2	0.032 ± 0.004	0.005 ± 0.005
3	-0.020 ± 0.004	-0.005 ± 0.005
4	0.001 ± 0.002	-0.002 ± 0.002

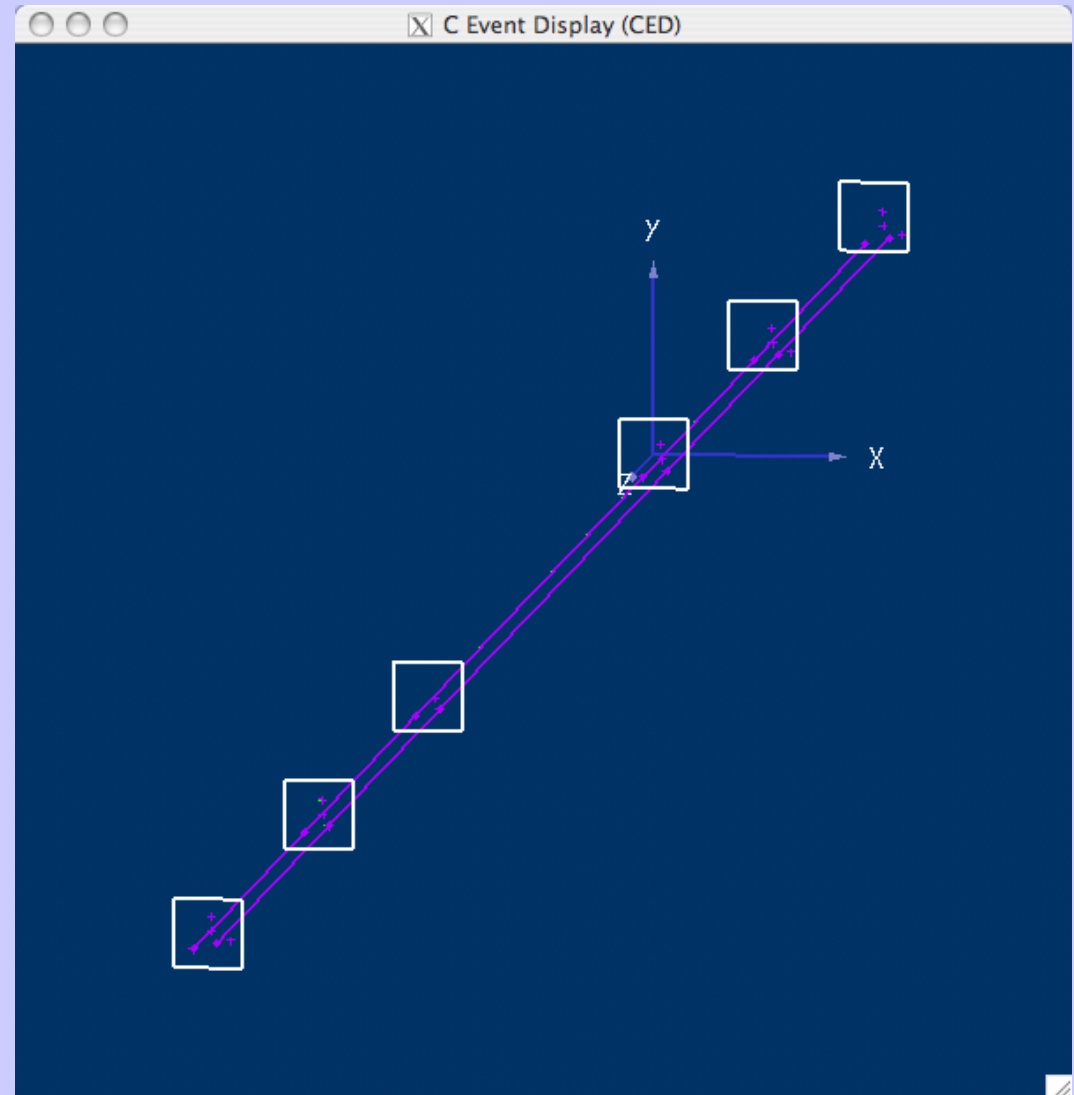




Improved event viewer



- Based on CED and CEDViewer
- Allows to display any set of hits (before / after alignment)
- New feature: **draw tracks** and impact positions of tracks in the telescope planes





Summary



- The package EUTelescope is in good shape and is utilised by an increasing number of groups
- During the last year lot of effort to increase the usability
- New features:
 - Universal reader
 - Correlator
 - Alignment
 - Improved event viewer