

ILD Vertex Detector for the Lol

Marc Winter (IPHC/Strasbourg)

OUTLINE

- **Introductory remarks :**
 - ⊕ *VXD requirements*
 - ⊕ *R&D questions related to the Lol*
- **Status of sensor and system integration R&D** ▷ **”state-of-the-art” detector :**
 - ⊕ *achieved performances* → *”s.o.t.a.” VXD*
 - ⊕ *continuation of the R&D*
- **The issue of alignment**
- **Accounting for beam background in Lol studies**
- **Towards the Lol :**
 - ⊕ *which VXD parameters to vary*
 - ⊕ *sharing of tasks*
- **Summary**

▶ Aim for several very ambitious (realistic ?) goals :

- ◇ excellent impact parameter resolution
- ◇ distinguish impacts from close tracks (inside jets)
- ◇ reconstruct soft tracks
- ◇ minimal m.s. \mapsto pattern confusions, $\Delta p/p$, part.flow, jet flavour (e^- vs ν_e), ...

▶ Constraints mainly driven by $\sigma_{ip} = a \oplus b/p \cdot \sin^{3/2} \theta$

small $a \mapsto$ high granularity (pixels) and small R_{in}

small $b \mapsto$ small R_{in} ($b \sim R_{in}$),

reduced mat. budget ($b \sim (X/X_0)^{1/2}$) \mapsto low P_{diss}

Accelerator	a (μm)	b ($\mu m \cdot GeV$)
LEP	25	70
SLD	8	33
LHC	12	70
RHIC-II	13	19
ILC	< 5	< 10

▶ Accommodate running conditions (e.g. event pile-up, background from e_{BS}^{\pm} , photon gas ?, etc.)

- ◇ occupancy \mapsto high r.o. speed (or extreme granularity) \mapsto power dissipation
- ◇ irradiation \mapsto radiation tolerant detectors

▶ Accommodate requirements from other sub-detectors :

- ◇ ex : relatively low B for PFA optimisation \Rightarrow occupancy in VXD \nearrow

▶ Accommodate & optimise VXD design consistently with neighbouring sub-det. (SIT, FW/BW trackers)

■ **How realistic is the vertex detector description used for the Lol physics studies ?**

- ◇ *how far are we from achieving the Lol detector performance ?*
- ◇ *what could actually be achieved within 2–3 years with the accumulated R&D experience and outcome ?*
- ◇ *could these achievements already suit the least demanding part of the detector, i.e. the 3 outer layers ?*
- ◇ *what is still needed to also satisfy the requirements of the two inner layers ?*
- ◇ *meanwhile, could we imagine a SAFE / CONSERVATIVE version of the vertex detector allowing to assess the needs for further R&D and to spot where it is most necessary ?*

■ **Beyond the Lol :**

- ◇ *why do we need several R&D lines in parallel ?*
- ◇ *how are sensor technologies and architectures connected to integration issues and detector geometry ?*
- ◇ *what is the advantage of pursuing the Lol studies with 2 different (but complementary) VXD concepts ?*

■ **How to optimise the goals of further R&D ?**

- **R&D groups expect guidance from detector performance studies in order to know :**
 - ◇ *how far each R&D direction should be pursued*
 - ◇ *which compromise between conflicting R&D directions is best suited to ILC physics goals*
 - ⇒ *where to put most effort ?*

- **Physics studies need ABSOLUTELY to account for dominant backgrounds !!!**
(e.g. beamstrahlung e^{\pm})

Pixel sensors :

- ◇ *pixel technologies developed : CCD, CMOS sensors, DEPFETS, 3D-PS (\supset Sol)*
- ◇ *read-out architectures : \rightleftharpoons continuous r.o. (during train) vs delayed r.o. (inbetween trains)*
 \rightleftharpoons *various degrees of signal processing inside pixels (time stamping, discri., ...)*
- ◇ *R&D goals : r.o. speed, power consumption (power cycling), radiation tolerance, EMI, material budget*
- ◇ *CCD: UK (LCFI), Japan – DEPFET: Germany – CMOS: France, Italy, US ? – 3DPS: US, France, Italy*

Ladder design \rightsquigarrow mat. budget \sim 0.1–0.2 % X_0 :

- ◇ *LCFI coll.: supports made of SiC foam*
- ◇ *KEK: FPCCD sandwiching an RVC (+epoxy) support*
- ◇ *DEPFET: monolithic Si slab incorporating sensors and mechanical support in a single piece*
- ◇ *CMOS: extrapolate from STAR-HFT (0.3 % X_0)*

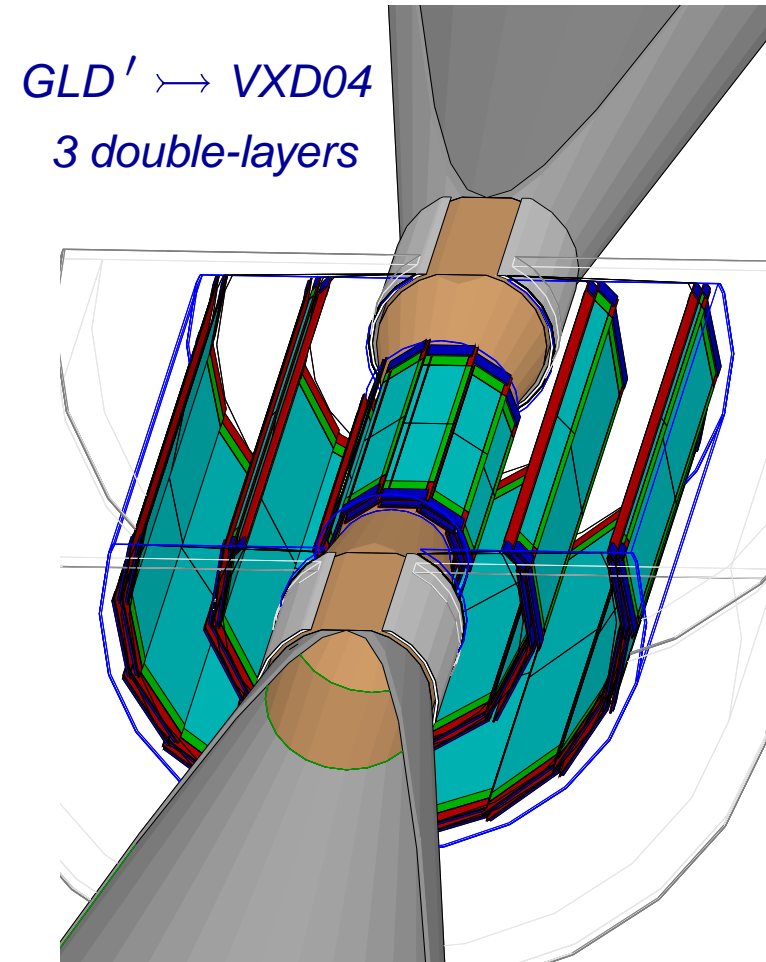
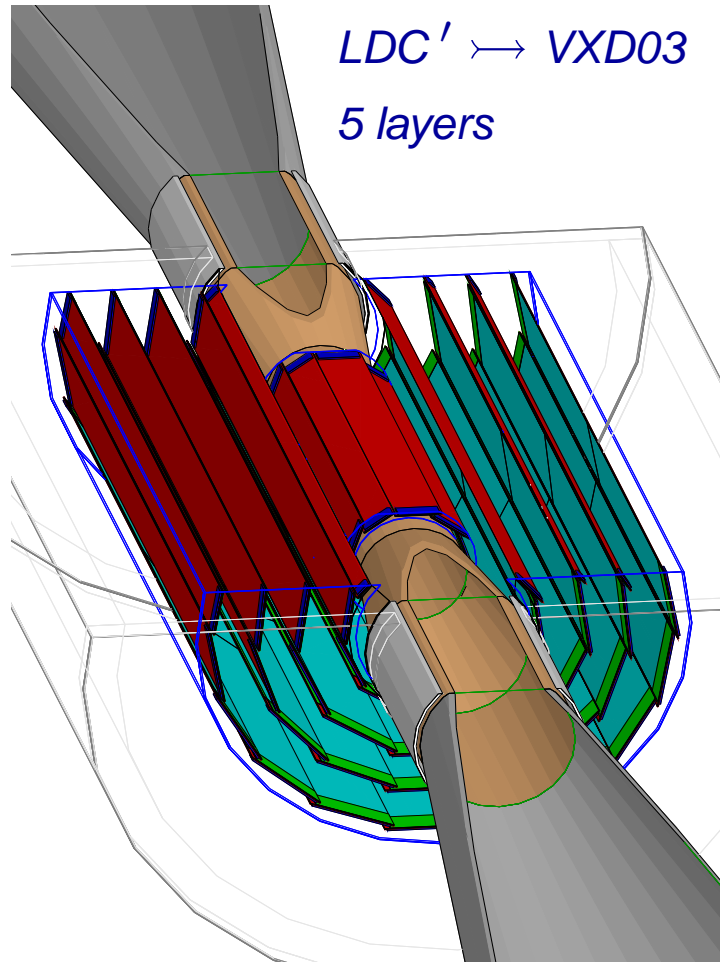
Global detector design \rightsquigarrow 2 approaches :

- ◇ *extrapolated from SLD vertex detector* ◇ *FNAL based studies (W.Cooper)*
- ▷ ▷ ▷ *who cares about Be beam pipe near I.P.: 0.25 \rightsquigarrow 0.50 mm thickness ?*

Comprehensive reviews on <http://ilcagenda.linearcollider.org/conferenceDisplay.py?confId=2564>

(ILC Vertex Detector Workshop, Villa Vigoni, Menaggio, Italy, 21-24 April 2008)

- Maintain 2 alternative long-barrel approaches :



- Two read-out modes considered :

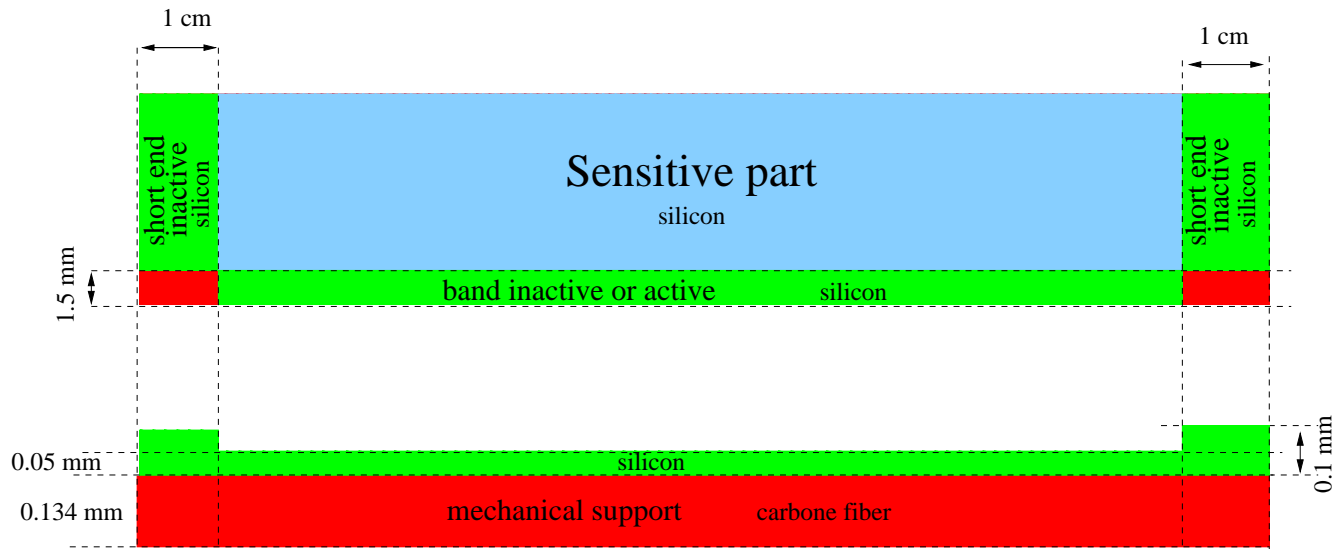
⊕ **continuous** read-out

⊕ **read-out delayed** after bunch-train \rightarrow 3 double layers expected to help

\Rightarrow mini-vectors

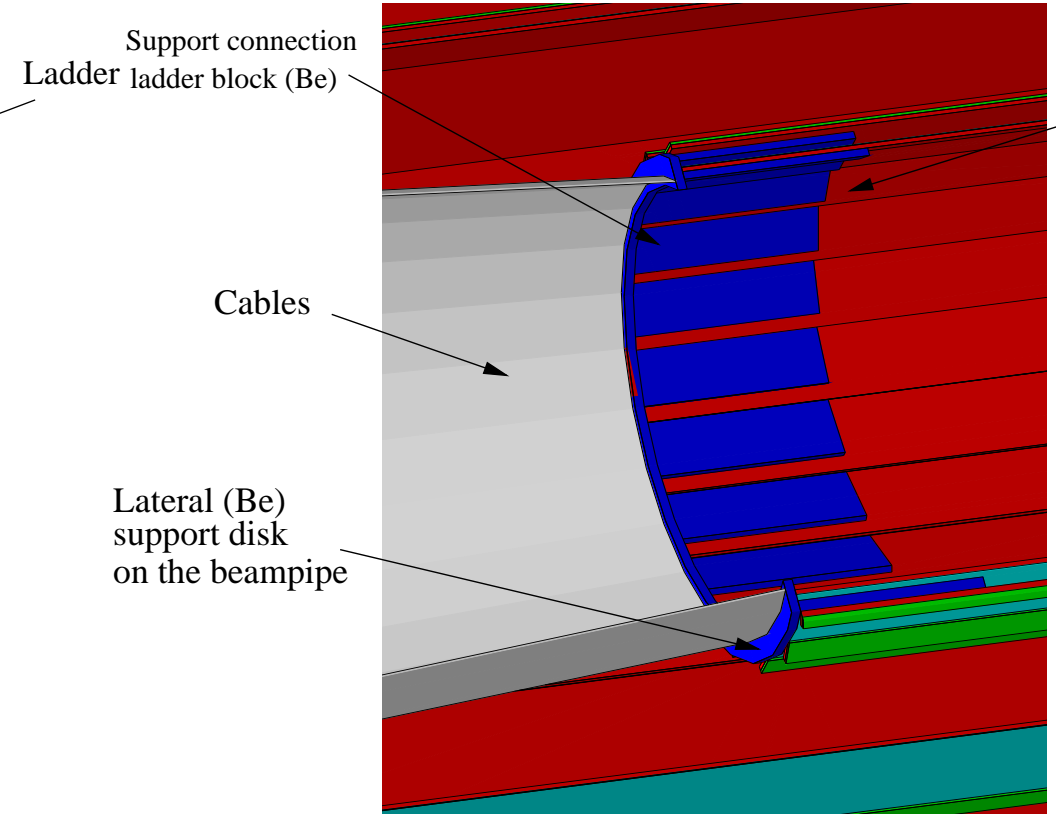
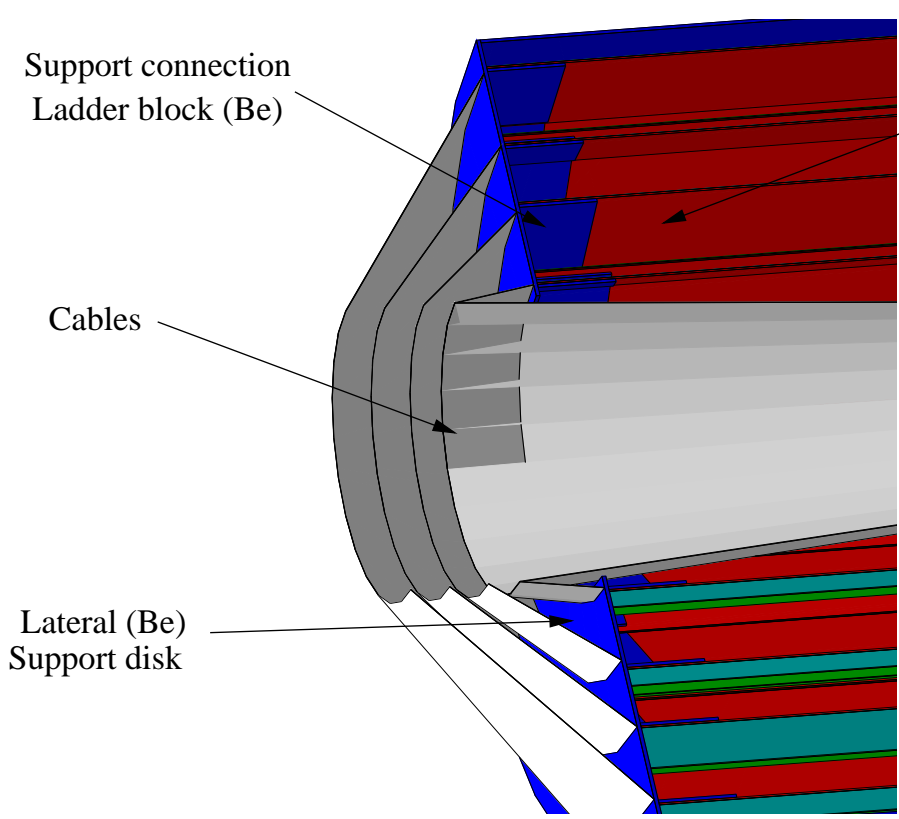
■ Ladder geometry \rightarrow accommodate simultaneously different sensor technologies :

- *Steering and r.o. electronics foreseen along the edges and at the ladder ends*
- *Ladder material budget :* ✱ $VXD03 : 0.11 \% X_0$ ✱ $VXD04 : 0.16 \% X_0$

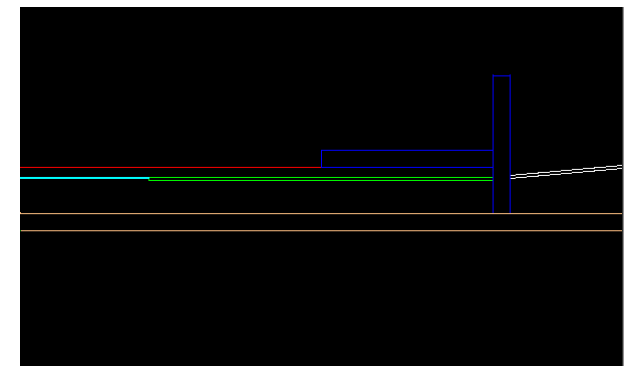


■ Will be studied extensively by VD groups working on diff. sensor technologies

■ "Realistic" ladder fixture on "gasket" → combine with beam pipe geometry study



Ladder fixture ▷▷▷



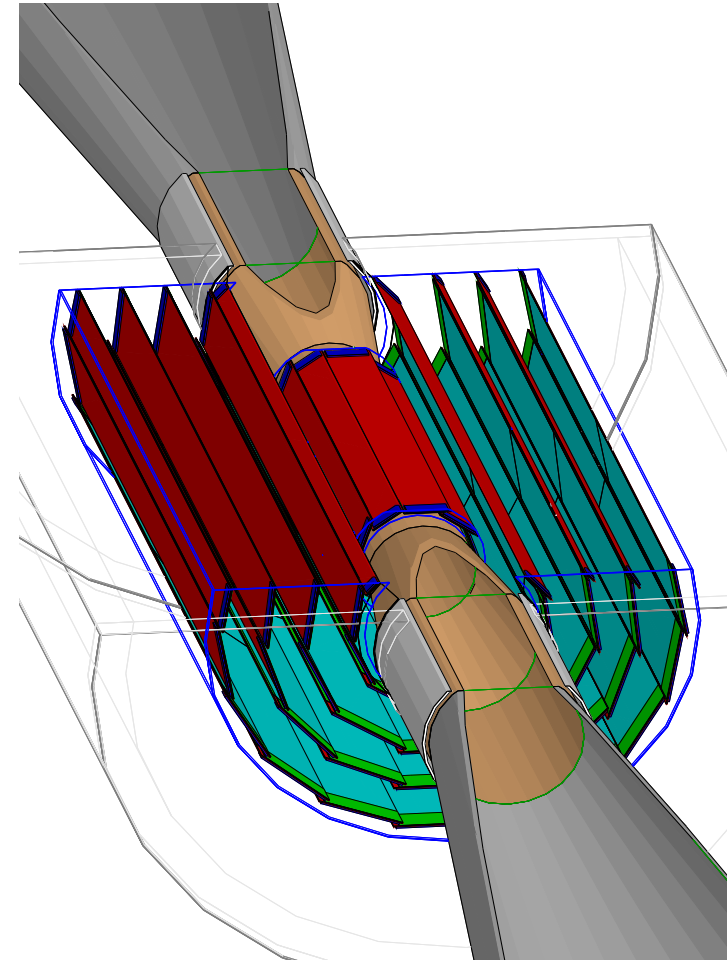
Vertex Detector parameters which seem achievable within short term, based on present R&D outcome :

- **Single point resolution : $3.5 \mu m$ (Lol : $2.8 \mu m$)**
 $\hookrightarrow a \sim 5 - 6 \mu m$
 $\triangleright Lol : a < 5 \mu m$
- **Ladder material budget : $0.25 - 0.3 \%$ (Lol : 0.1%)**
 $\hookrightarrow b \sim 10 - 12 \mu m \cdot GeV$
 $\triangleright Lol : b < 10 \mu m \cdot GeV$

- **Read-out speed :**

Layer	L1	L2	L3 - L5
Lol (μs)	≤ 50	≤ 100	≤ 200
State-of-the-art (μs)	60	120	240

- **Power dissipation : (Lol : $\ll 100 W$ in average)**
 - instantaneous : $\sim 1 kW$
 - average (1/50 duty cycle) : $\sim 20 W$



▷▷▷ Most decisive Lol assumptions for the VXD seem reachable

Pixel sensors :

- ◇ *improve on read-out speed (as much as possible ...) and radiation tolerance*
 - ↳ *magnitude of simulated beam background is a challenge, but reality may still be worse ... ⇒ account for it !*
- ◇ *pursue R&D on delayed read-out architecture to avoid reading out during trains (EMI, consumption ?)*
- ◇ *explore emerging technology variants offering better performances:*
 - ⊖ *the best we have today may not be sufficient to face the real beam background*
 - ⊖ *better performing technologies will be beneficial for higher \sqrt{s} (luminosity, double hit separation)*

Detector design :

- ◇ *pursue ladder design studies in order to approach a global material budget of ~ 0.1 %*
- ◇ *pursue detector design in order to prove realism of Lol detector geometry*
- ◇ *investigate double sided ladder geometry*
- ◇ *investigate alternative design based on short barrel with disks at small angle*
 - ⇒ *manpower missing on system integration aspects*

▷▷▷ **The continuation of the R&D needs to be guided by physics simulations**

■ The critical issue is the INTERNAL alignment

▷ need to control ladder (& sensor) position within a few μm (LHC experiments manage $\sim 10 \mu m$)

■ Alignment requirements will probably impact the vertex detector design (material budget ?) :

◇ rigidity of gasket and ladder support

◇ necessity to implement position sensors ?

◇ effect of air flow and power cycling (Lorentz forces ...) ▷ effort to minimise it ?

◇ make active areas of neighbouring ladders overlap sufficiently

◇ squeeze σ_{sp} (**a** and **b** !) in order to "leave room" for additional missalignment uncertainty

■ Impact on/from neighbouring tracking detectors ?

■ Running at Z^0 peak mandatory ($\gtrsim 1$ week/yr ?)

▷▷▷ System study not yet started

- **Critical issue : beamstrahlung e^\pm hitting the 2 inner layers**
 - ◇ *GuineaPig, "standard" optics, 14 mrad Xing, anti-DID, $R_{in} = 15$ mm, 3.5 T, 15 μ m thick sensitive vol.,*
 - ◇ *inner layer rate $\gtrsim 5 e_{BS}^\pm/cm^2/BX \rightsquigarrow \gtrsim 800 e_{BS}^\pm/cm^2/50 \mu s \rightsquigarrow \gtrsim 2000$ "seed" pix/cm²/50 μ s*
 \Rightarrow *25 μ m pitch $\rightsquigarrow \gtrsim 1$ % occupancy ($\cong 100$ kRad & 10^{11} $n_{eq}/cm^2/yr$)*
 - ◇ *2nd layer background ($R = 26$ mm) only 6–8 times less than innermost layer*
 - ◇ *not accounted for :*
 - $\hat{=}$ *cluster size (only seed pixels)* $\hat{=}$ *thicker sensitive volume (e.g. 50 μ m)*
 - $\hat{=}$ *MC uncertainties (safety factor)* $\hat{=}$ *other backgrounds (photons, photon coll., ...)*
 - $\hat{=}$ *ϕ -dependence (if any ?)*

- ▷▷▷ **Physics studies ought to include beamstrahlung effects**
 - ◇ *we need to know which occupancy is acceptable for (which ?) physics*
 - ◇ *potential impact on VXD design (radius and read-out speed of inner layers, technology,)*
 - ◇ *potential impact on neighbouring tracker design*

- ▷▷▷ **How should we proceed ?**

- **Strategy : studies based on central production with baseline geometry**
 - *outcome will be used by VD groups for refined studies*

- **Basic VXD parameters to vary in order to evaluate impact on physics performance :**
 - *innermost layer radius : $14 \text{ mm} \lesssim R_{in} \lesssim 20 \text{ mm}$*
 - *single point resolution : $2 \text{ } \mu\text{m} \lesssim \sigma_{sp} \lesssim 3 \text{ } \mu\text{m}$*
 - *ladder material budget : $0.1 \% X_0 \lesssim t \lesssim 0.2 \% X_0$*
 - *magnetic field strength : $3 \text{ T} \leq B \leq 4 \text{ T}$*

- **How to deal with the beam background vs VXD read-out frequency ?**
 - *depends on layer : $5 \rightarrow 40 \text{ frames / train}$*
 - *depends on read-out architecture : continuous read-out vs delayed read-out*

- Several specific aspects of the VXD will be studied by vertex detector community :
 - *optimal pixel pitch and read-out time for each layer*
 - *mini-vector efficiency for BG rejection (layer-pair geometry)*
 - *optimal number of ladders per layer, etc.*
 - *influence of electronics on ladder edge and ends (mat. budget)*
 - *consequence of low P optics : shorter innermost layer*
 - *influence of SIT : track matching \rightarrow time stamping , low P reconstruction, ...*
 - *track matching (& time stamping) with fw/bw trackers \rightarrow how long should the barrel be ?*
 - ▷ *for which fw/bw material budget does a geometry based on short barrel + end-cap disks start to be more attractive than long barrel ?*
 - *effect of Be beam pipe material budget (0.25 ... 0.50 mm thick)*

- Work organisation ▷ Connecting VXD community studies with Global physics performance studies :
 - *consider **a** and **b** in $\sigma_{ip} = \mathbf{a} \oplus \mathbf{b}/p \cdot \sin^{3/2} \theta$ as the reference indicators of the benefits or disadvantages of variants of the VXD geometries used in the central detector performance studies*
 - *input from central detector performance studies towards VXD groups :*
 - ≍ *values of **a** and **b** corresponding to nominal detector studies*
 - ≍ *correspondance between $\sigma_{ip}(\mathbf{a}, \mathbf{b})$ and flavour tagging efficiency★purity*

■ VXD geometry in Lol :

- ⇒ *VXD geometry in MOKKA expected to be detailed enough for Lol*
- ⇒ *present R&D achievements support the realism of Lol VXD descriptions*
- ⇒ *guidance expected from detector performance group to orient next R&D steps*

■ Alignment :

- ⇒ *internal alignment is a serious challenge : few μm precision required*
- ⇒ *may impact VXD requirements (σ_{sp}), geometry and operation (power cycling, cooling)*
- ⇒ *need substantial running time at Z^0 (how much ?)*

■ Organisation of VXD related studies for the Lol :

- ⇒ *connection between detector performance group & VXD community could consist in evaluating impact of VXD variations on parameter **a** and **b** entering σ_{iP} (relation with efficiency***purity** ?)*
- ⇒ *define sharing of VXD related studies between detector performance group & VXD community*

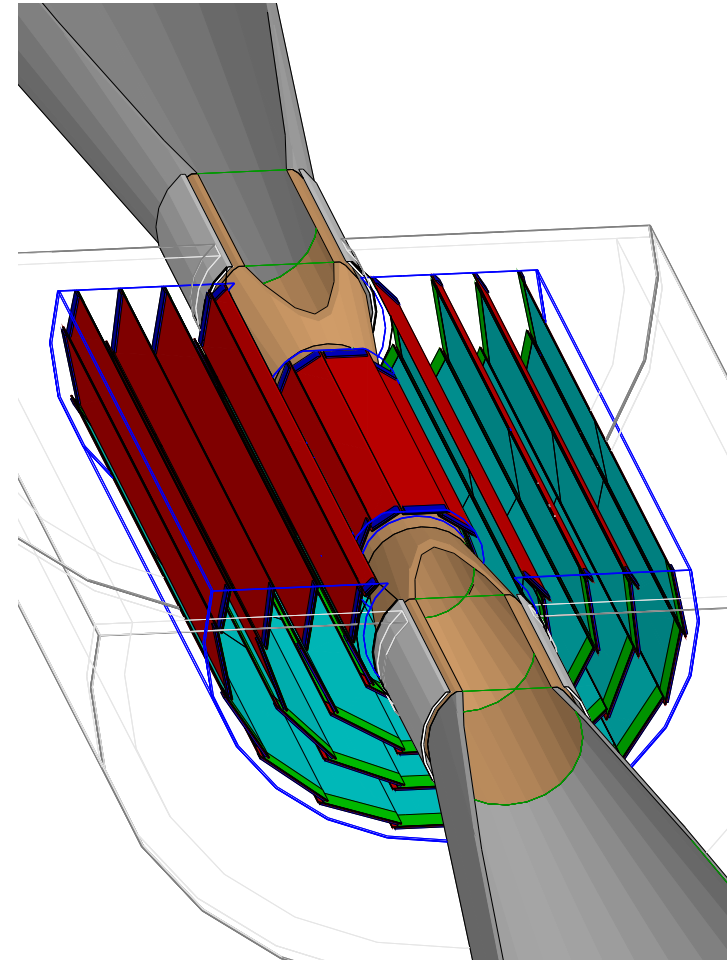
▷ ▷ ▷ **Studies ought to incorporate dominant beam background !**

▷ ▷ ▷ *mailing list for discussions on ILD vertex detector: ild-subsystem-vtx@desy.de*

people interested may subscribe to the mailing list from <https://lists.desy.de/sympa/info/ild-subsystem-vtx>

BACK-UP SLIDES

- 5 layers intercepting angles down to $\|\cos \theta\| \simeq 0.97$:
- Layer radii : 15, 26, 37, 48, 60 mm
- Nb of ladders per layer : 10 (in) / 11 / 12 / 16 / 20 (out)
- Ladder lengths : 125 mm (inner), 250 mm (outer)
- Ladder support structure : carbon fiber (100 μm thick)
- Ladder sensitive part width on each layer :
 - inner : 11 mm - second : 15 mm - outer : 22 mm
 - 50 μm thick silicon
- Electronics at ladder end :
 - 10 mm long
 - 100 μm thick silicon
- Insensitive ladder edge :
 - 1.5 mm wide
 - 50 μm thick silicon
 - can be activated



■ 3 pairs of layers intercepting angles down to $\|\cos \theta\| \simeq 0.97$:

- **Double-layer radii (inner/outer) :** 16/18, 37/39, 58/60 mm
- **Nb of ladders per layer :** 10 (in) / 12 / 20 (out)
- **Ladder lengths :** 125 mm (inner), 250 mm (outer)
- **Ladder support structure :** carbon fiber (100 μm thick)
- **Ladder sensitive part width on each layer :**
 - inner : 11 mm - outer : 22 mm
 - 50 μm thick silicon
- **Electronics at ladder end :**
 - 10 mm long
 - 100 μm thick silicon
- **Insensitive ladder edge :**
 - 0.5 mm wide
 - 50 μm thick silicon
 - can be activated

