Extraction line orbit correction / Feedback

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Outline

- EXT line Orbit correction Feedback Task
- 2 My results
- 3 Antony Scarfe's results
- Omparison of results
- 5 Orbit reconstruction
- 6 Conclusion and prospects



Outline



EXT line Orbit correction - Feedback Task



Description of the task

It is needed to :

- Simulate ATF2 with agreed errors (e.g. list by G. White).
- Analyze the effects on the stability and the size of the beam.
- Development of several algorithms (from various contributors).
- Compare the results of all.
- Implementation in the Flight Simulator.
- Explicit reconstruction and control of the orbit.
- Make GUI and User's guide.
- Study the FB implementation, interactions with others.

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People involved

Current contributors :

- Y. Renier LAL (task leader)
- J.R. Lopez Oxford University
- G. White SLAC
- A. Scarfe Manchester & Cocroft Institute
- K. Kubo KEK

If someone else is interested, please contact me.



EXT line Orbit correction - Feedback Task

Agreed errors (thanks to Glen)

Relevant Error Parameter for EXT section

Error Type				
x/y/z Post-Survey				
Roll Post-Survey				
BPM - Magnet field center alignment (initial install) (x, y)				
BPM - Magnet alignment (post-BBA, if BBA not simulated) (x, y)				
Relative Magnetic field strength (dB/B) (systematic)				
Relative Magnetic field strength (dB/B) (random)				
C/S - band BPM nominal resolution (x, y)				
Stripline BPM nominal resolution (x, y)				
IP BPM nominal resolution (x, y)				
EXT magnet power-supply resolution				
FFS magnet power-supply resolution				
Corrector magnet pulse-pulse relative field jitter				



Status of the work

General status

- All agreed errors were implemented in each simulations.
- "1 to 1" methods were implemented.
- Now let's present the results to compare.
- Relative orbit reconstruction performed in ATF EXT line on may shifts data, unsuccessful due to missing data.
- Attempt to make relative and maybe absolute orbit reconstruction in EXT during FS shift tomorrow.



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X steering in EXT for nominal misalignments







X steering in EXT for nominal misalignments

rms X after 1-to-1 correction





Y steering in EXT for nominal misalignments





Y steering in EXT for nominal misalignments

rms Y after 1-to-1 correction





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Number of iterations for nominal misalignments

number of iterations





Comments

Precisions

- 1 iteration is an average of 10 measurements.
- 7/100 seeds could not be simulated due to too large errors, beam loss problem must be solved.
- Present correction between 10 and 15 min ? Can be quicker, but result are worse.



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Extraction line orbit correction / Feedback Antony Scarfe's results

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Antony Scarfe's results

X steering in EXT for nominal misalignments





Antony Scarfe's results

Y steering in EXT for nominal misalignments





Antony Scarfe's results

Number of iterations for nominal misalignments





Extraction line orbit correction / Feedback

Antony Scarfe's results



Precisions

- 1 iteration is an average of 10 BPM measurements.
- Beam jitter simulated.



Extraction line orbit correction / Feedback

Comparison of results

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Comparison of results

Summary of steering results in FFS

quantity	resluts				
	mine	Antony's	Glen's	Javier's	Kubo-san's
rms X (EXT) [mm]	0.7 ± 0.3	2 ± 2			
rms Y (EXT) [mm]	0.5 ± 0.2	1.5 ± 1			
rms X (EXT+FF) [mm]	2 ± 1	1 ± 1			
rms Y (EXT+FF) [mm]	3 ± 3	5 ± 5			
BPM measurements	1000 < <i>n</i> < 1500	70 ± 50			

legend

- rms (EXT) : standard deviation of EXT BPM readings after EXT steering.
- rms (EXT+FF) : standard deviation of EXT+FF BPM readings after EXT steering.
- BPM measurements : number of measurements to obtain previous results.



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Orbit reconstruction

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Orbit reconstruction

Relative reconstruction

Principles

- any ΔE , $\Delta B \Rightarrow \Delta X(BPMs)$.
- if elem is downstream, knowing all R(elem → BPM_m), one can reconstruct Δx(elem), Δx'(elem), Δ<u>E</u>(elem) using SVD.
- Tested during bumps in QM7 during last may shift.
- *x* and *x'* was not reconstructed due to missing information.
- $\frac{\Delta E}{E}$ reconstruction looked good, special using ring's BPM.

$$\begin{pmatrix} R_{11}(\rightarrow BPM_1) & R_{12}(\rightarrow BPM_1) & R_{16}(\rightarrow BPM_1) \\ R_{11}(\rightarrow BPM_2) & R_{12}(\rightarrow BPM_2) & R_{16}(\rightarrow BPM_2) \\ \vdots & \vdots \\ R_{11}(\rightarrow BPM_M) & R_{12}(\rightarrow BPM_M) & R_{16}(\rightarrow BPM_M) \end{pmatrix} \times \begin{pmatrix} \Delta x(elem) \\ \Delta x'(elem) \\ \frac{\Delta E}{E}(elem) \end{pmatrix} = \begin{pmatrix} \Delta x(BPM_1) \\ \Delta x(BPM_2) \\ \vdots \\ \vdots \\ \Delta x(BPM_M) \end{pmatrix}$$

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Conclusion

- Steering algorithms in EXT give good results with all errors included.
- Need results from all.
- Need performance function of iterations number.
- Relative orbit reconstruction will be tested tomorrow with FS.



Prospects

- Look at beam jitter influence.
- Meeting of all collaborators in January to chose an algorithm.
- Implement it in FS.
- Implement orbit monitoring in FS.
- Implement absolute orbit reconstruction.
- Tests in early next year.
- Couple orbit reconstruction and steering for faster results.



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X steering for nominal misalignments in EXT+FF

rms X bpm readings before and after 1-to-1 correction





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X steering for nominal misalignments in EXT+FF

rms X after 1-to-1 correction





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Y steering for nominal misalignments in EXT+FF





Y steering for nominal misalignments in EXT+FF

rms Y after 1-to-1 correction





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X steering in EXT+FF for nominal misalignments





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Y steering in EXT+FF for nominal misalignments





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