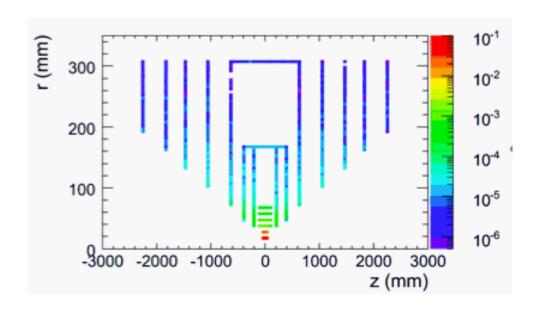
Background studies in the VXD: status and future plans



R. De Masi, S. Aplin, F. Gaede, M. Winter, ...

Present status

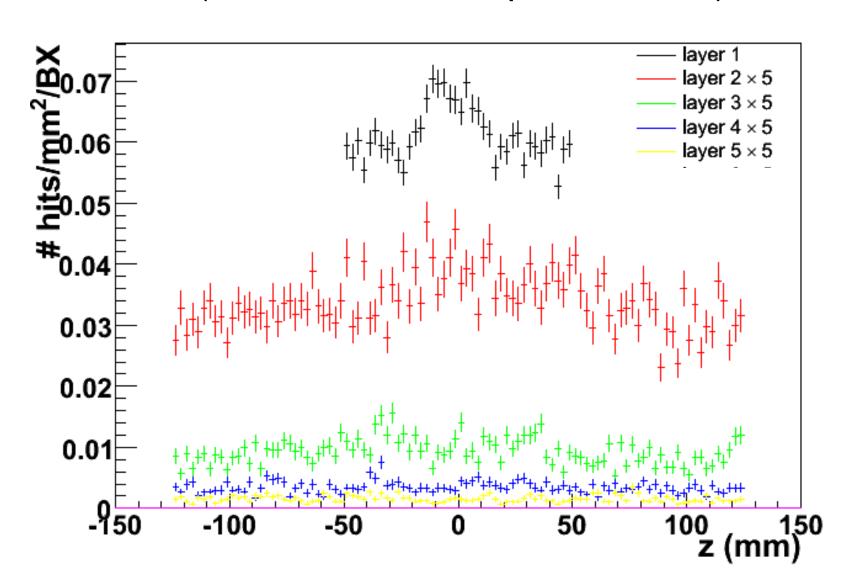
Several studies from DESY, Strasbourg, Warsaw, ...
 on the expected hit rate.

First estimate of occupancy for two sensor types.

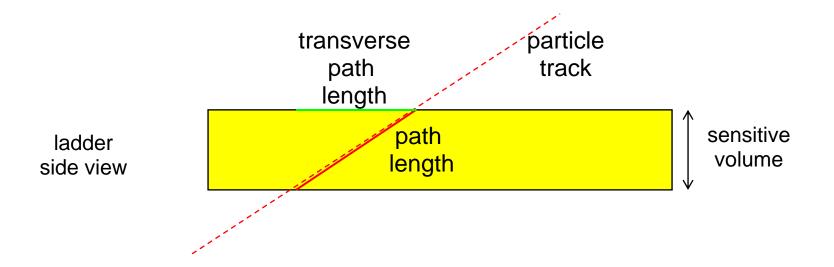
Development of a detailed digitizer (Warsaw).

Hit rates

(LDCPrime_02Sc_p01 VXD-SL)



How to get to the occupancy...



seed pixels = pl_T / pitch size
pixels in cluster = 2 x #seed pixels + 4



... with two different options

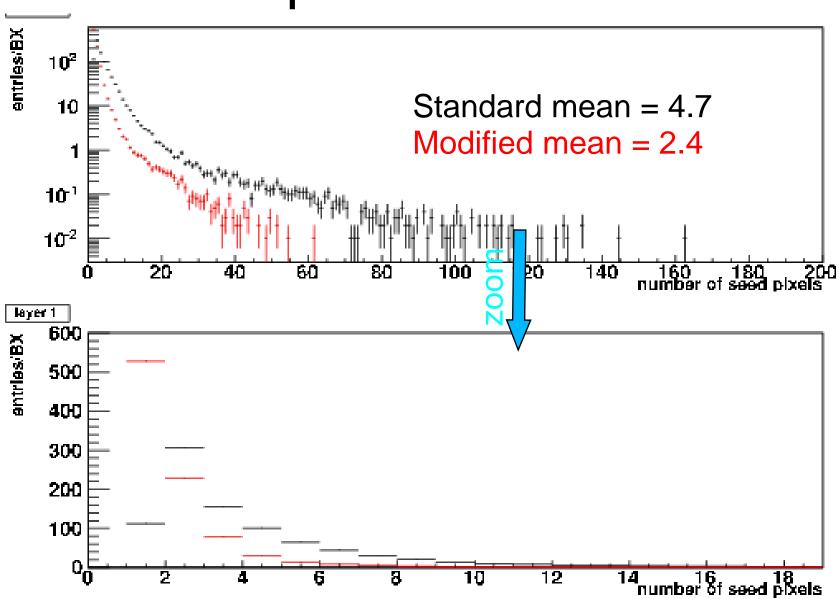
Standard parameters 50 µm epi

Modified parameters
15 μm epi larger clusters

Layer	pitch (μm)	integration	time(μs) pitch (μm)	integration time(μs)
1	25	50	20	25
2	25	200	25	50
3	25	200	33	100
4	25	200	33	100
5	25	200	33	100

Layer	occupancy	occupancy
1	0.059	0.015
2	0.027	0.005
3	0.007	0.004
4	0.003	0.002
5	0.001	0.001

Seed pixel distributions



This implies ...

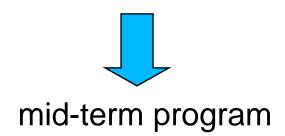
- Occupancy ranges from ~6% to 1.5% (with anti-DID) not accounting for any safety factor.
- Its impact on the tracking efficiency needs to be investigated according to the IDAG request for June (and on heavy-flavour tagging later).
- The present status of reconstruction software does not allow for a complete treatment of the bkg in a straight way.



Address tracking issues and vertexing issues separately

Next steps

- Optimisation of tracking algorithm (ghost tracks).
- Hit to cluster conversion.
- BKG-physics clusters discrimination.
- Cluster-track association.
- Consequences on impact parameter resolution.
- Tagging.
- lowP,



For the IDAG meeting

STEP0:

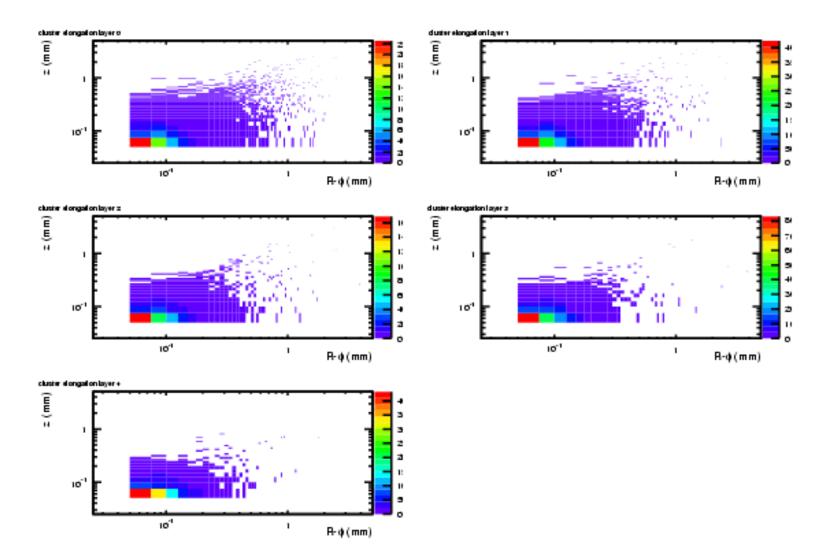
- Use of salt&pepper bkg hit distribution convoluted with realistic cluster dimensions.
- Preliminary study based on bkg clusters only in the innermost layer (against ghost tracks).

STEP1

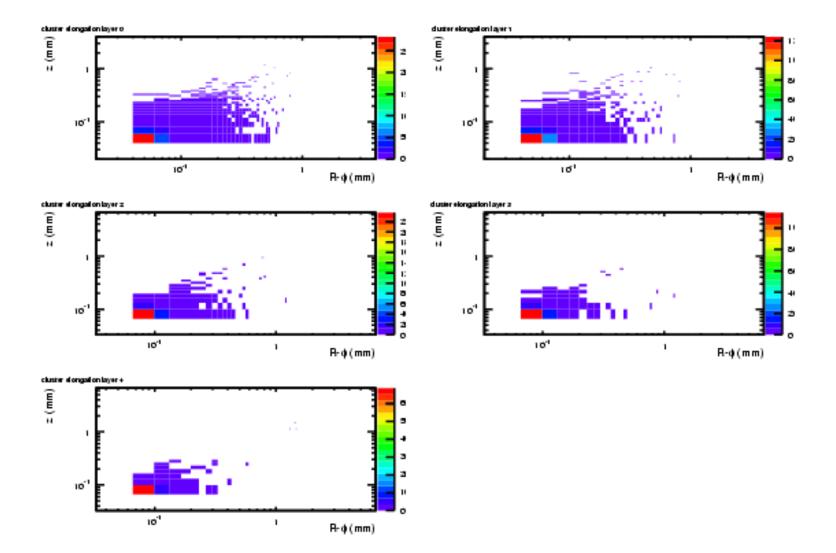
• Overlay GuineaPig hit with realistic cluster dimensions.

SL or DL geometry?

Cluster dimensions (standard)



Cluster dimensions (modified)



To be discussed

- Goals & timelines.
- Task sharing.