# **Cavity Integration**

H. Hayano

#### (A) Cavity Integration Work Packages

ID	Title	Description
1.2.1	Tuner	Development of slow tuner for resonance stabilization and fast tuner for Lorentz detuning compensation
1.2.2	Input Coupler	Development of coupler designs, including evaluation of fixed/variable coupling, port diameter, heat load, etc.
1.2.3	Magnetic Shield & He-Vessel	Determination and test of magnetic shielding method, inside/outside He-vessel.  Vessel material, bi-metallic junctions, Pressure Vessel regulation, and alignment method.
1.2.4	Integration/Test	system integration into cryomodule and performance test
1.2.5	Cost & Industrialization	Cost estimate and pre-industrialization value engineering

#### (B) Plug-compatibility concept development

Specifications for plug-compatibility
Definitions of boundary for plug-compatibility

(A) Cavity Integration Work Packages

# 1.2.1 Tuner development status

(1) Blade-tuner results

# **Blade Tuner "Slim" Prototype**



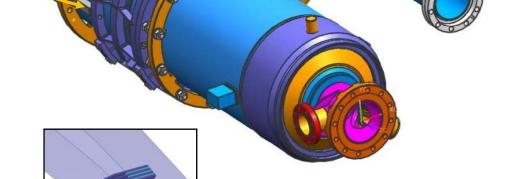
The bending system consists of **three different rings**: one of the external rings is rigidly connected to the helium tank, while the central one is divided in **two halves**. The **rings are connected by thin plates, the blades**, that by means of an imposed azimuthally rotation bend and elastically change the cavity length.

#### The Piezo Actuators

**2 piezo actuators in parallel** provide fast tuning capabilities needed for **Lorentz Force Detuning** (LFD) compensation and **microphonics** stabilization.

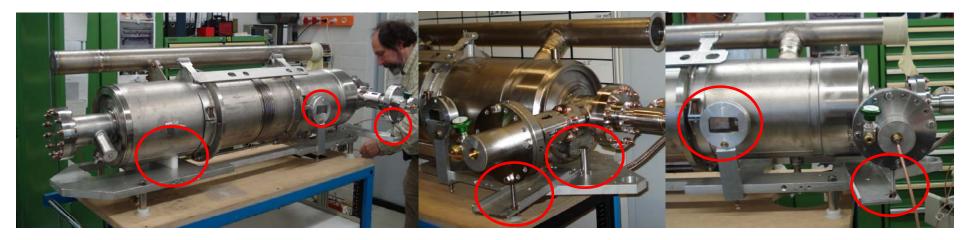
#### The movement system

The **stepping motor**, with its **harmonic drive** and a **CuBe screw** rotates the central ring



Lighter,
Cheaper,
New driving mechanism,
Wider tuning range,
Ready for future SS tank

#### **Test setup at CHECHIA - DESY**



The cavity package is installed on a table

- 2 pads fixed by supporting clamps
- helium tank sliding on a Teflon support,
- beam pipe and coupler supported

The table hosting the cavity and its ancillaries is then moved into the CHECHIA cryostat

The Stainless Steel + INCONEL prototype has been tested at cold:

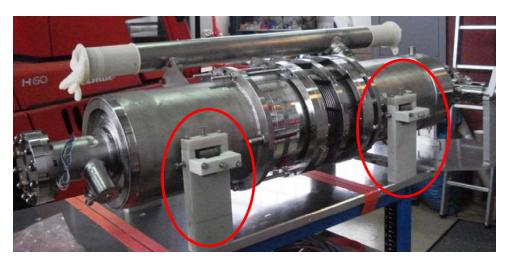
Sept. 2007 in the CHECHIA horizontal cryostat, DESY

Installed on the **Z86 TESLA cavity** equipped with a standard modified He vessel Equipped with a standard TTF unit: **Sanyo stepper motor + Harmonic Drive gear 2 Noliac 40 mm** standard piezoelectric actuator installed



- Blade Tuner cold tests on September 2007
  - Stainless steel + Inconel Blade Tuner
  - 40 mm Noliac piezo (10 x10 mm²)
  - Sanyo-Denki stepper motor, 200 steps/turn
  - HD drive unit, 1:88 reduction ratio
  - therefore 17600 steps each spindle turn (CuBe spindle screw, 1.5 mm/turn)

### Test setup at HoBiCat - BESSY





The cavity package is installed on a table

 Each pad is clamped in a Teflon pillar that can slide on the SS table

The table hosting the cavity and its ancillaries is then moved into the HoBiCat cryostat

Feb. 2008 in the HoBiCaT horizontal cryostat, BESSY

The same assembly but equipped with a prototype of a possible alternative driving unit: Phytron stepper motor + Planetary Gear





- Blade Tuner cold tests, February and April 2008
  - Stainless steel + Inconel Blade Tuner (same as CHECHIA test)
  - 40 mm Noliac piezo (same as CHECHIA test)
  - Phytron stepper motor, 200 steps/turn
  - Phytron VGPL planetary gear, 1:100 reduction ration nm/step
  - therefore 20000 steps each spindle turn (CuBe spindle screw,
     1.5 mm/turn)

#### **Considerations about friction**

#### **Superstructure Test setup**

Ti pad on rolling needles (Cry 3), 40 kg preload force, T = 77 K:

- Static friction coefficient: 0.0043
- Dynamic friction coefficient : 0.0022

D. Barni, M. Castelnuovo, M. Fusetti, C. Pagani and G. Varisco FRICTION MEASUREMENTS FOR SC CAVITY SLIDING FIXTURES IN LONG CRYOSTATS Advances in Cryogenic Engineering, Vol. 45A, Plenum Publishers, 2000, 905-911

#### **CHECHIA** setup

#### PTFF Teflon on Titanium

Static friction coefficient: 0.17 (40 times larger than Type 3)

Friction Data Guide (Linden, NJ: General Magnaplate Corp., 1988

#### **HoBiCat setup**

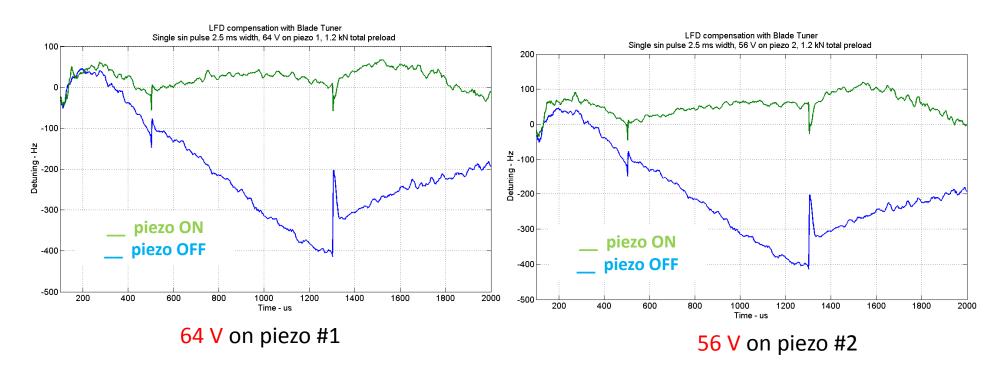
#### PTFF Teflon on Steel

Static friction coefficient: 0.04 (9 times larger than Type 3)

Friction Data Guide (Linden, NJ: General Magnaplate Corp., 1988

#### **Blade Tuner tests at CHECHIA – Results**

- LFD exhibited by Z86 cavity, about 300 Hz, has been compensated:
  - Actuating each piezo alone (see plots)
  - Actuating both piezo in parallel



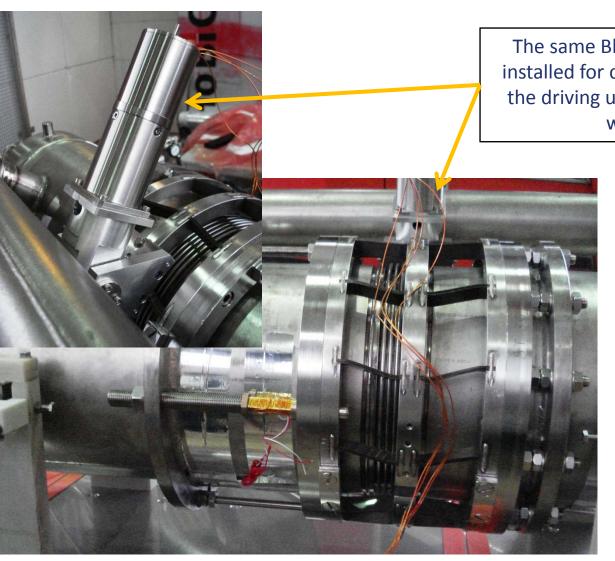
Nominal piezo pulse amplitude for this level of LFD is 60 V +/- 7%

#### **Blade Tuner tests at CHECHIA**

The piezo assisted blade tuner performed as expected Simulations are confirmed by experimental data

	Only one piezo acting	
Nominal RT stroke at 200 V (max voltage)	60 μm	
Stroke at 60 V	12 μm	
Residual stroke at 25 K	3 μm	
Blade Tuner efficiency	40 % +/-10%	
Static-to-Dynamic ratio	1.2	
Resulting stroke at the cavity	1 μm +/- 10%	
Expected resulting dynamic cavity frequency variation	280 - 350 Hz	
Measured resulting dynamic cavity frequency variation	300 Hz	

# Blade tuner installation in HoBiCaT, BESSY



The same Blade Tuner assembly has been installed for cold testing at BESSY, except for the driving unit, a stepper motor equipped with planetary gear

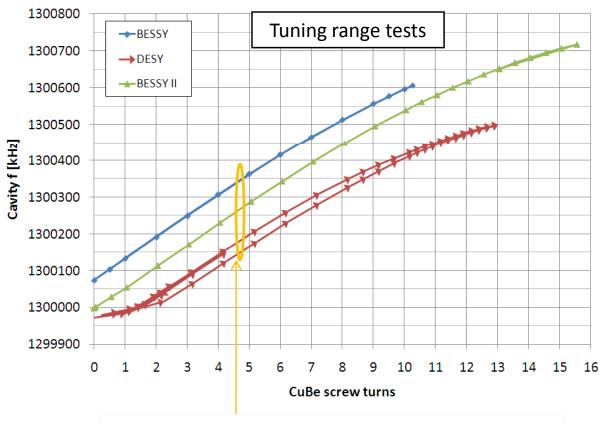


**HoBiCaT at BESSY** 

# **HoBiCaT Tests – full tuning range**

600 kHz tuning range has been confirmed with margin.

The hysteresis has been almost cancelled.



Mechanical hysteresis almost cancelled over the full range after a few cycling

Tests were performed with different piezo preloads.

The correct value cancels the piezo unloading effect and enhances tuning sensitivity.

Tuning resolution met expectations, about

1.5 Hz/half-step confirmed.

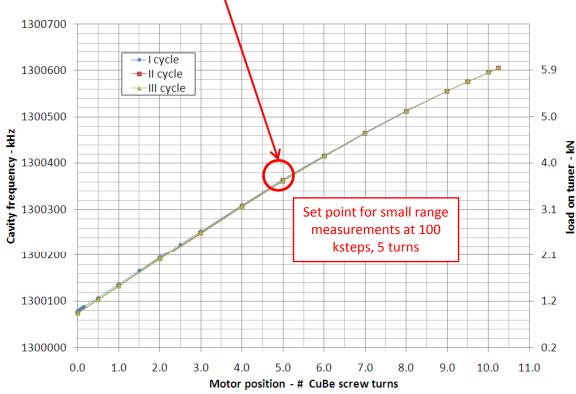
# **HoBiCaT** tests – small tuning range

Data about frequency tuning on a  $\mu$ m-scale come from:

Piezo actuators static tuning range measurements. Piezo are driven with DC voltage

Drive unit small range measurements. Stepper motor is driven in a small range around a

working point

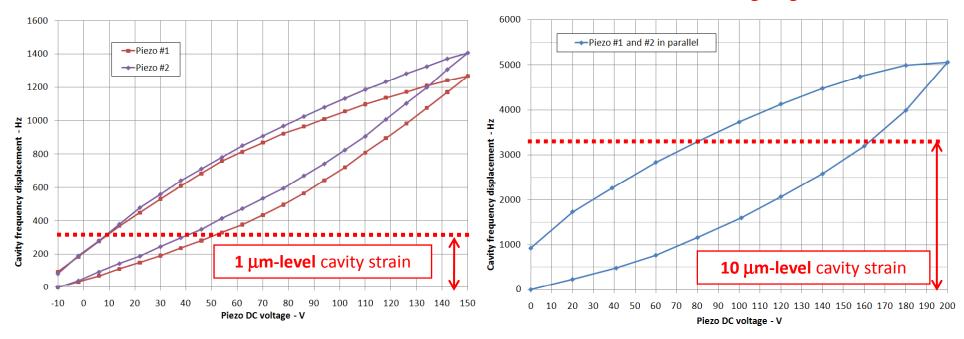


# Blade Tuner piezo tests at HoBiCaT

- Each piezo actuator alone and also both in parallel have been driven with a DC voltage, the cavity frequency is locked by a PLL and measured.
- No deviation observed from the hysteresis curves expected from piezoelectric properties:
   no obstacles to the movement of piezo.
- Looking at plots a sub-micron resolution can be observed: 10 V step in piezo driving voltage corresponds to about 0.1 μm at low absolute voltage (where slope is lower)

# Each piezo alone up to 150 V: 1.3 kHz +/- 10 % tuning range

Both piezo together up to 200 V: 5 kHz tuning range



# Blade Tuner piezo tests at HoBiCaT

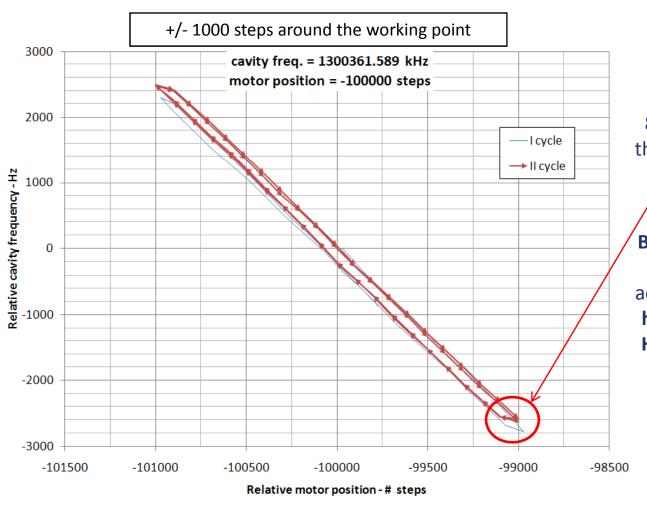
The HoBiCaT piezo tests confirm that the entire stroke expected to be transmitted to the cavity by piezo actuators is achieved:

Consider for example the test with both piezo operated in parallel up to 200 V (table):

	Both piezo acting	
Nominal RT stroke at 200 V (max voltage)	60 μm	
Residual stroke at working T (25%)	15 μm	
Blade Tuner efficiency	83 %	
Resulting stroke at the cavity	13 μm	
Expected resulting static cavity frequency variation	4.1 – 5.2 kHz	
Measured static cavity frequency variation	5 kHz	

### **HoBiCaT** motor Tests – close to the working point

#### tuning characteristics around a specific working point



The frequency positioning behavior and the amount of backlash, about

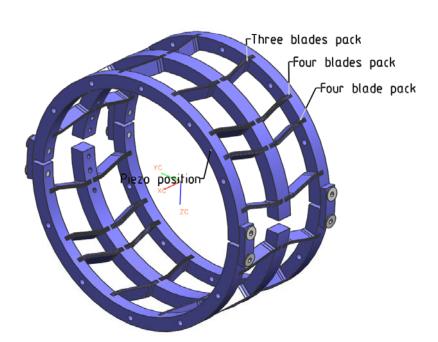
85 steps, is slightly higher than the one usually experienced with TTF tuner.

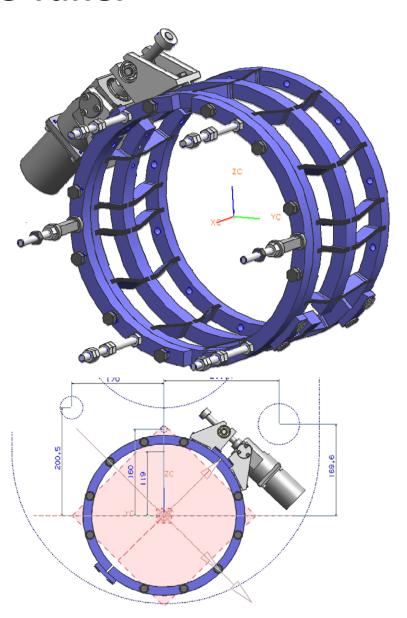
But the planetary gear installed, here tested for the first time, actually introduces a significantly higher backlash if compared to HD gear, about 20 times higher

#### The ILC Blade Tuner

On the basis of the test results here presented the ILC Blade Tuner prototype is already close to fulfill all the XFEL and ILC specifications.

The experience gained with the cold tests on the prototype has been used for the final revision of the Blade Tuner.





# **Design analysis - conclusions**

Tuner under construction (3.9.4)	Tuner characteristics	Required value	Margin factor
Tuning range - nominal (no hysteresis)	0 – 500 kHz		
Tuning range – max. (some hysteresis <sup>1</sup> )	0 – 600 kHz		
Max compression strength <sup>2</sup>	7800 + 3100 N	7800 + 1.1 * 2840 N	1.0
Max traction strength	16000 N	13771 N	1.16
Compression stiffness	15 – 100 kN/mm		
Moon from conditivity	1.5 Hz/half-step - XFEL standard drive unit -	~ 0.75 Hz/half-step - actual TTF I tuner sensitivity -	
Mean freq. sensitivity	0.75 Hz/half-step - devoted 1:200 gear -		
Max. torque at the CuBe screw	12.5 Nm - XFEL standard drive unit -	2.4 Nm	5.2
max. torque at the oube screw	25 Nm - devoted 1:200 gear -		10.4

<sup>1</sup> With some plastic deformations at worm, limited to the blade packs near the motor

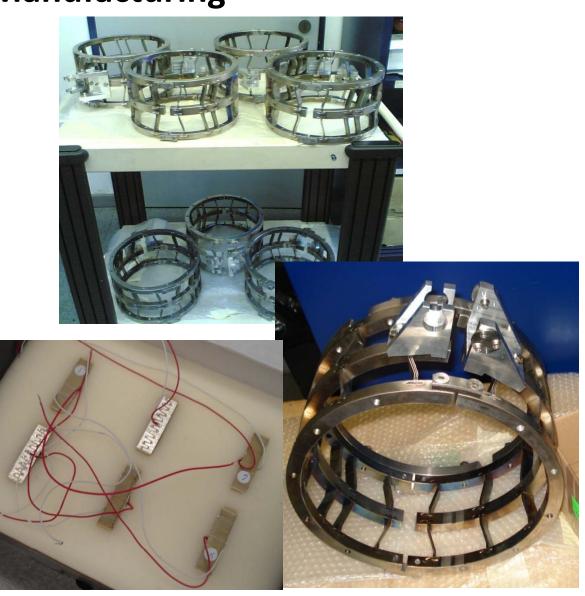
<sup>2</sup> This is composed of the fixed part due to the cavity deformation and a variable part due to external pressure

### Manufacturing

The first 8 units of revised
Blade Tuner have been
already manufactured. Two
more units are under
production.

Currently two complete systems, including piezo actuators, are under shipment to Fermilab.

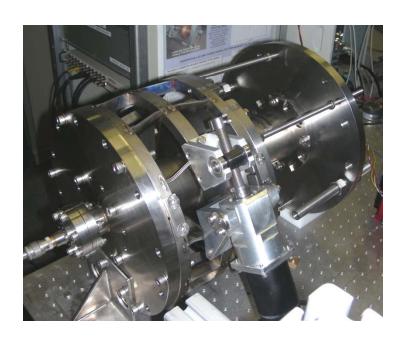
These revised Blade Tuners will fully equip the second criomodule of ILC\_NML test facility.

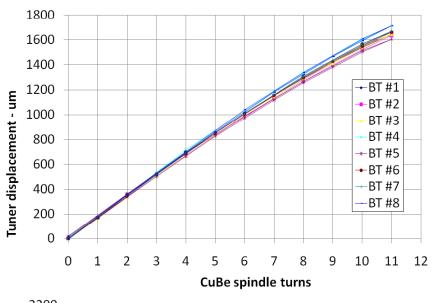


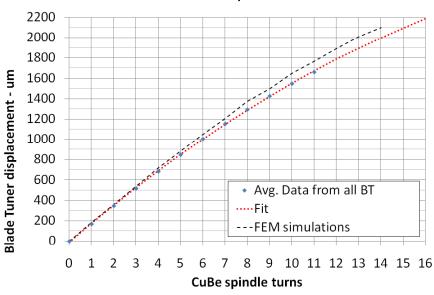
### **Room Temperature Qualification**

The first 8 units produced have been tested for qualification at room temperature on a devoted single cell test facility

Results meet expectations in terms of homogeneity and predictions (tolerable 5 % full-scale discrepancy )







#### **Revised Blade Tuner - conclusions**

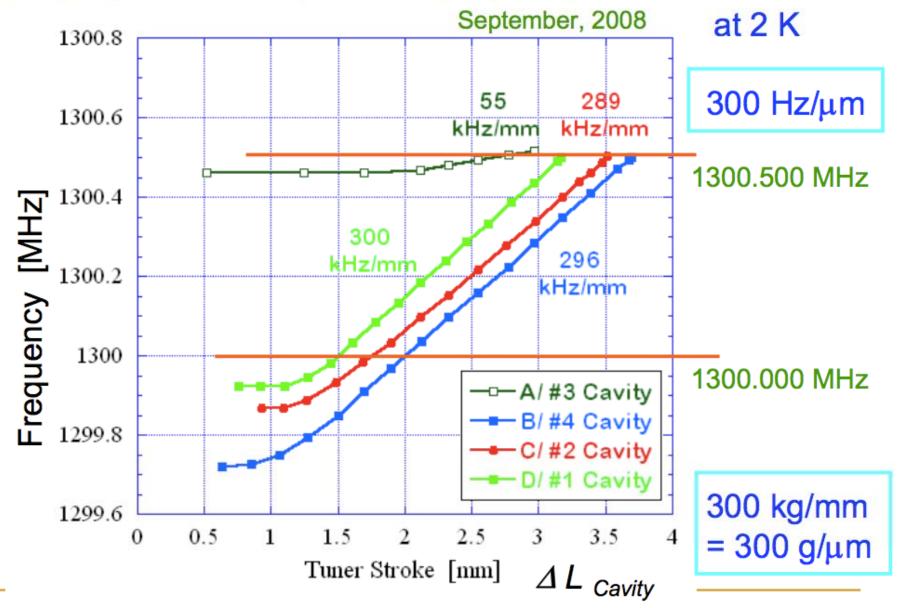
- Production and room temperature qualification of first 8 units of revised Blade Tuner satisfactorily completed.
  - 2 complete tuner system now shipping to Fermilab. INFN group will now join FNAL team for installation and cold test of first units in horizontal cryostat.
  - Shipment of remaining 6 assemblies will shortly follow in view of the CM2 commissioning.
  - 4 additional Blade Tuner units have already been required by Fermilab. Production expected by this year.
- The revised Blade Tuner will be also involved in the existing collaboration with BESSY
  - Several research topics related CW and small BW application of SC cavities (ERL etc.): microphonics active compensation, ultra-small fast tuning range improvement (nm level)
  - Further horizontal cold tests planned from March 2009.

(A) Cavity Integration Work Packages

# 1.2.1 Tuner development status

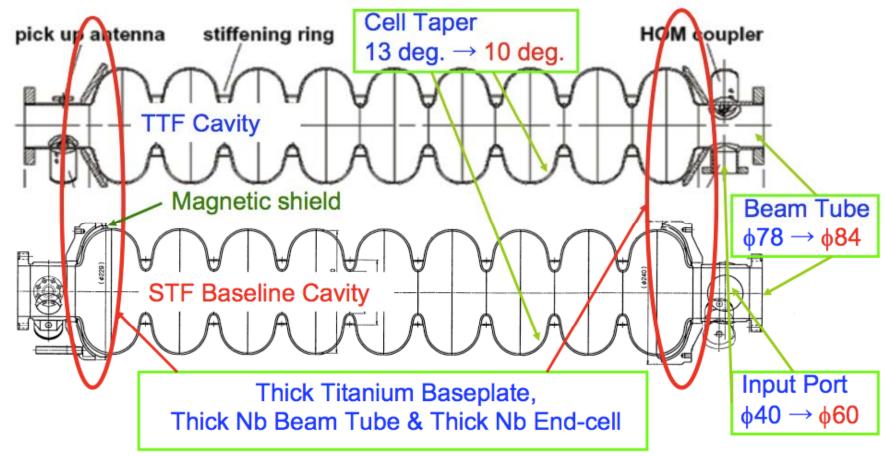
(2) Slide-jack tuner results

# Tuner Stroke in STF Phase-1.0



TTC at India, 200 8, Oct. 22

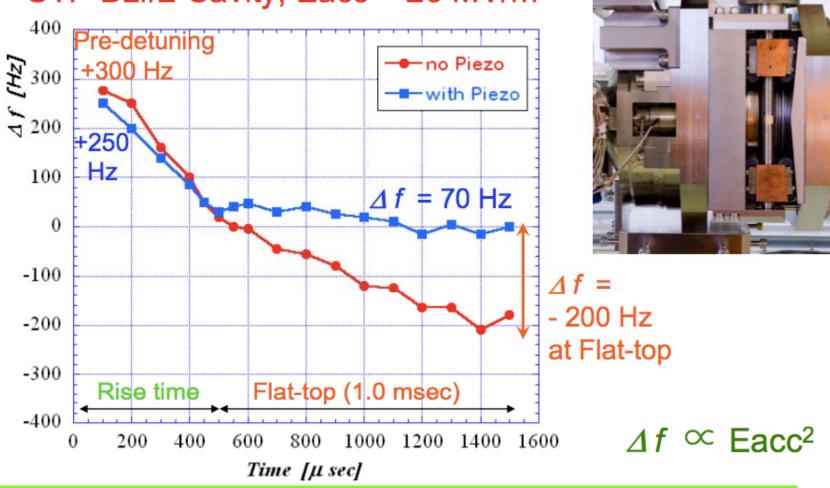
# STF Baseline Cavity; Improved Stiffness



	STF Baseline Cavity	TTF Cavity	
Stiffness of Cavity Sys.	72 kN/mm	22 kN/mm	
Lorentz Detuning	$\Delta f = -150 \text{ Hz}$	$\Delta f = -500 \text{ Hz}$	Estimation
at flat-top	TTC at India,	2 0 0	at 31.5 MV/m

# Lorentz force detuning in STF Phase-1.0





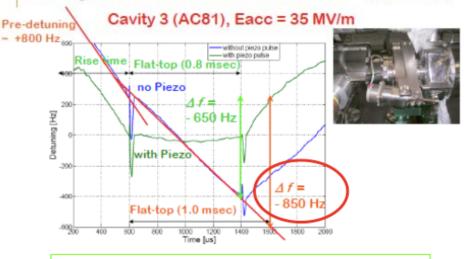
 $\Delta f = -300 \text{ Hz}$  (Eacc = 31.5 MV/m, Flat-top = 1.0 msec)

# Lorentz force detuning in TTF Cavities with a different tuner system

∆ f at Eacc = 31.5 MV/m, Flat-top = 1.0 msec

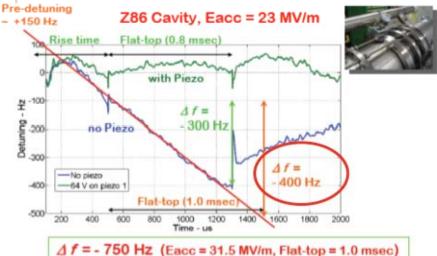
# Saclay Tuner tests for XFEL Z107 Cavity, Eacc = 35 MV/m Pre-detucing +700 Hz Rise time Flat-top (0.8 msec) no Piezo with Piezo With Piezo Af = -800 Hz Af = -810 Hz (Eacc = 31.5 MV/m, Flat-top = 1.0 msec)

#### Saclay Tuner tested in Module 6 (by L. Lilje)



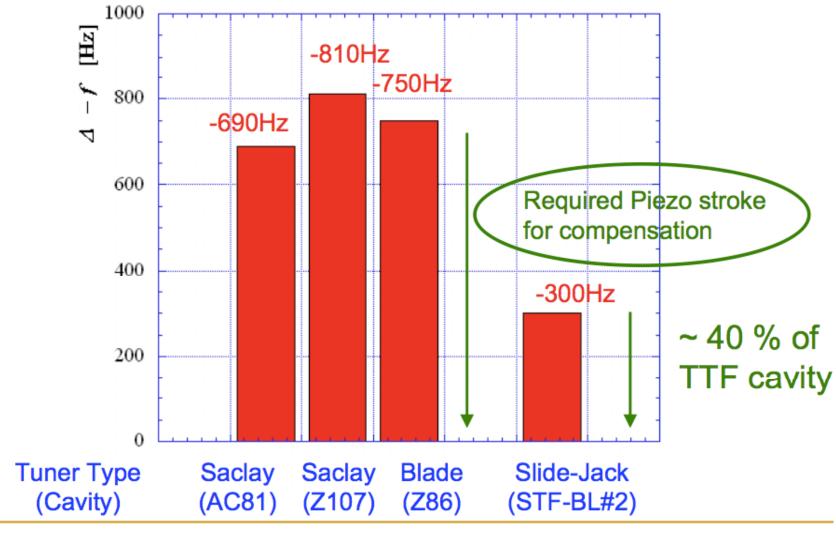
 $\Delta f = -690 \text{ Hz}$  (Eacc = 31.5 MV/m, Flat-top = 1.0 msec)



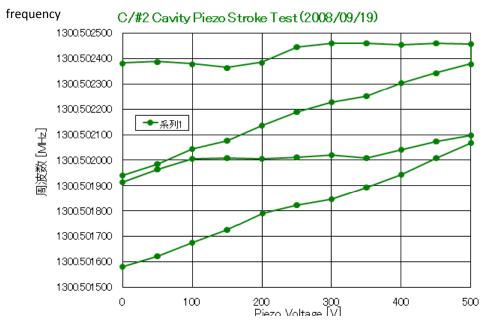


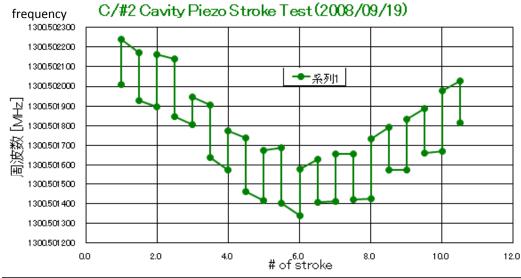
# Comparison of Lorentz force detuning

 $\Delta f$  at Eacc = 31.5 MV/m and Flat-top = 1.0 msec



#### No repeatability for piezo response (STF1.0 experiment)





support tab friction for piezo drive??→ confirmation by room-temp meas.consideration of tuner design change.

(A) Cavity Integration Work Packages

# 1.2.2 Input Coupler development status

(1) TTF-III coupler industrialization study results







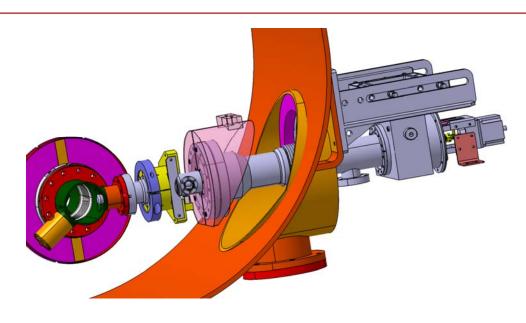




# Status report on "Industrialization studies" at LAL on power couplers for XFEL

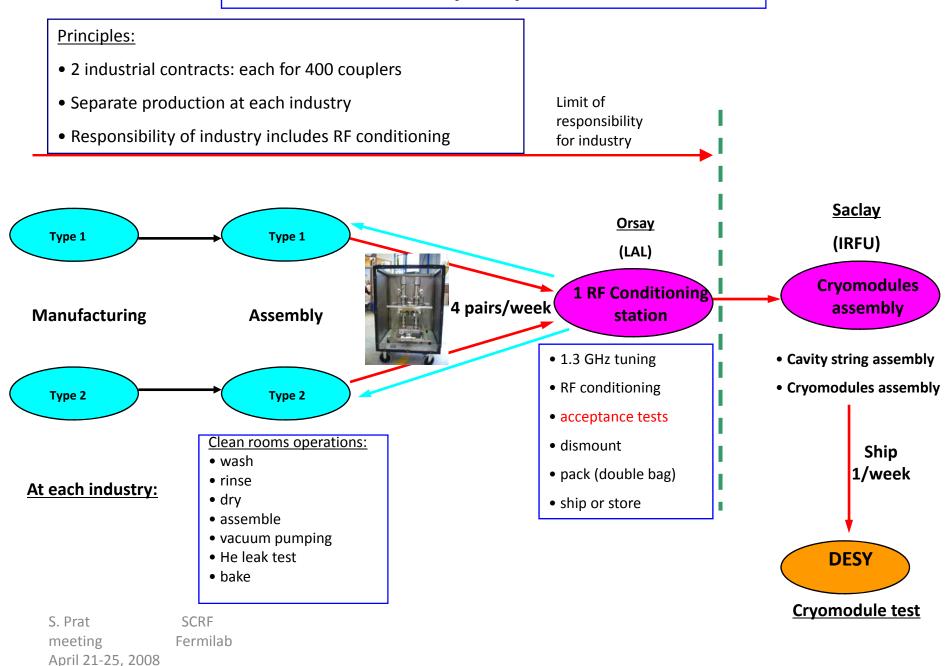
**SCRF Meeting** 

**Fermi Lab** 21-25 April 2008



S. Prat meeting April 21-25, 2008 SCRF Fermilab

#### Scenario for couplers production – XFEL



#### **Example of systems engineering result**

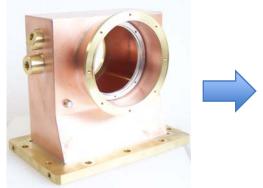


Prototype design for motorized tuning

<u>Industrial design</u>



Design to minimize assembly time (chain clamp)



Copper + stainless steel + brass: 13 parts

brazed and soldered

S. Prat SC meeting Fer April 21-25, 2008

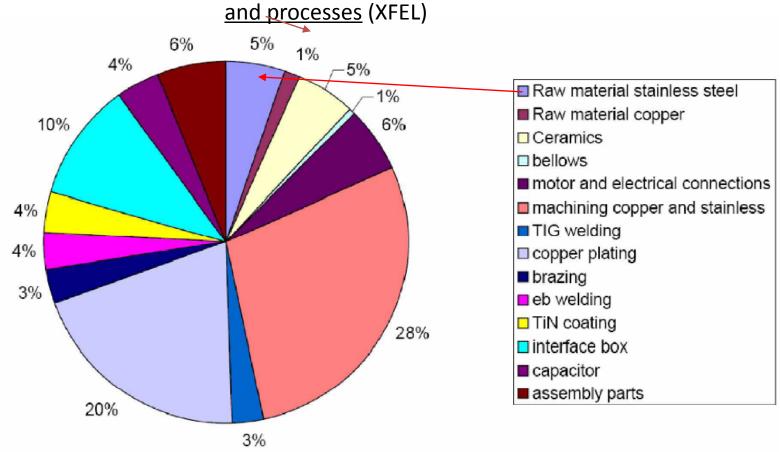
SCRF Fermilab



Al alloy: 1 single part

- Prototypes: machined from single block
- Mass production: casting

#### Manufacturing cost breakdown for materials

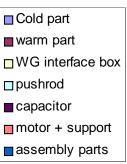


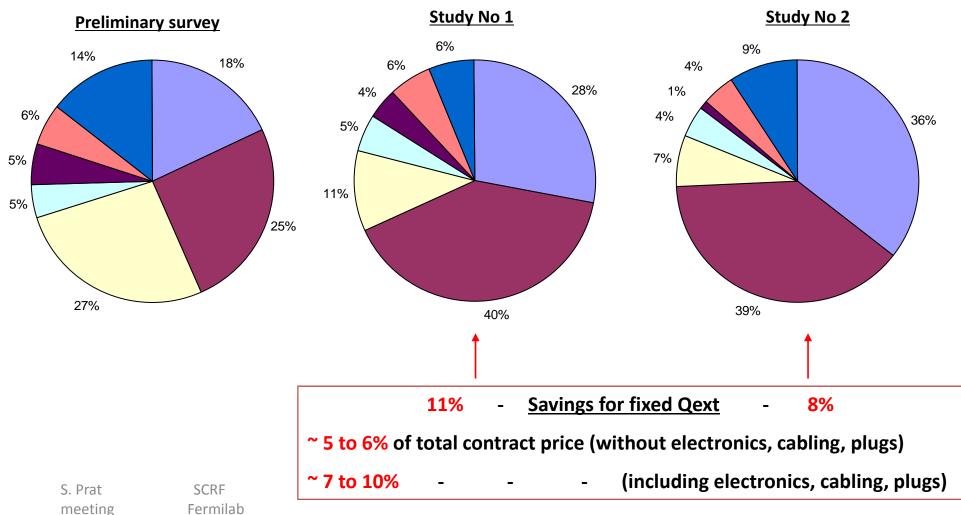
Total raw material cost ~ 20 %

S. Prat SCRF meeting Fermilab April 21-25, 2008

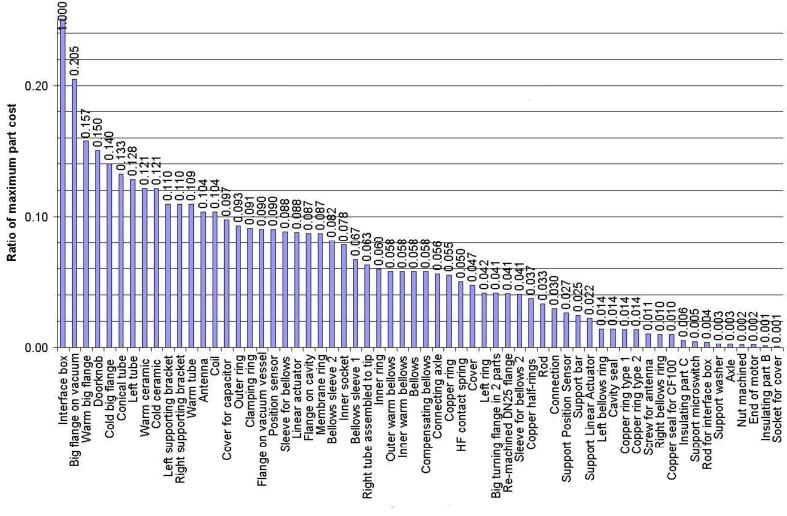
#### <u>Cost breakdown for</u> <u>subassemblies</u> (XFEL)

April 21-25, 2008





#### Bar chart for each part



This is the basis for future round of cost reduction: → concentrate efforts on expensive items

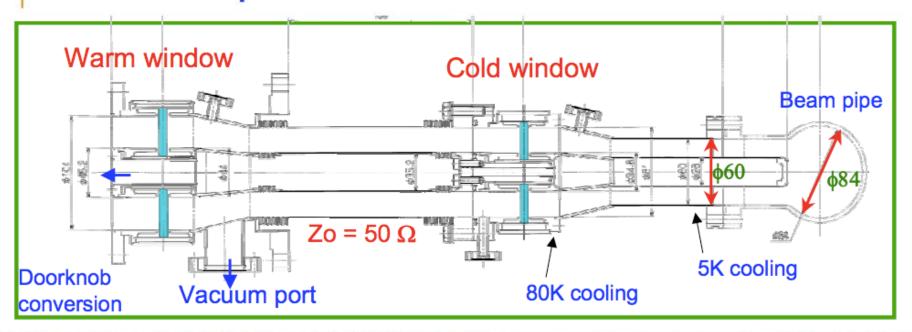
S. Prat SCRF meeting Fermilab April 21-25, 2008

(A) Cavity Integration Work Packages

# 1.2.2 Input Coupler development status

(2) STF fixed coupler study results

# Fixed Coupler for STF Phase-1.0











# Installation of Warm Couplers and Doorknobs into Cryomodule



Coaxial - N Transition

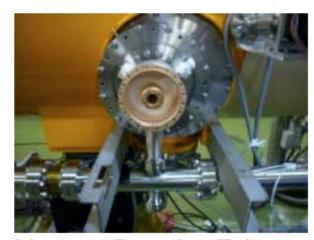


Warm Coupler



June, 2008

Connection of Inner Conductor



Vacuum Pumping Tube

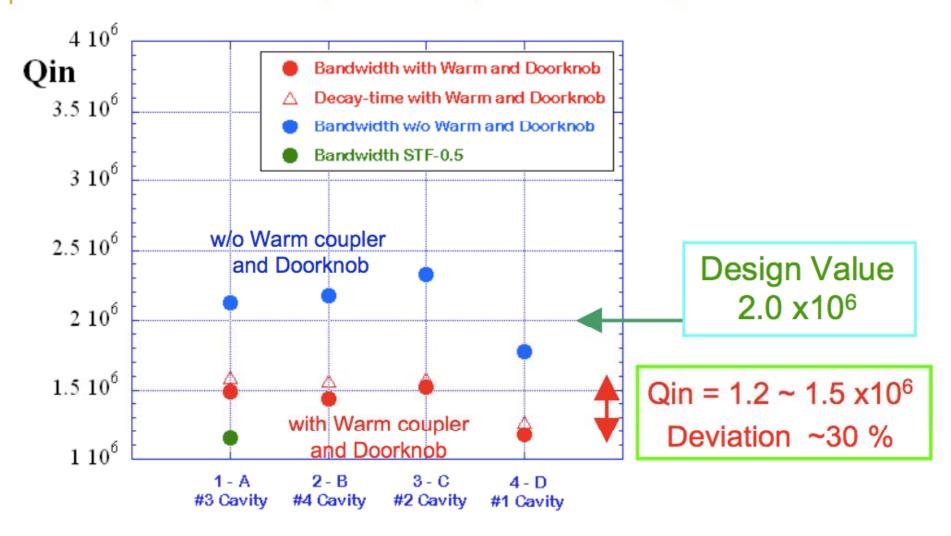


Clean Booth for Assembly



**Doorknob-type Transition** 

## Qin of Fixed Input Couplers in Cryomodule



Large difference of Qin between with / without Warm & Doorknob

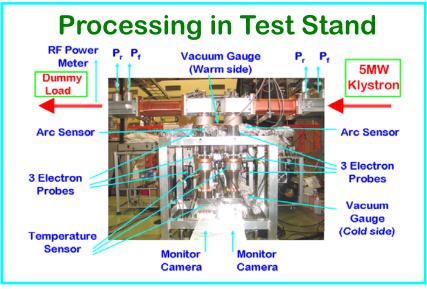
## **Component Test; Input Couplers**

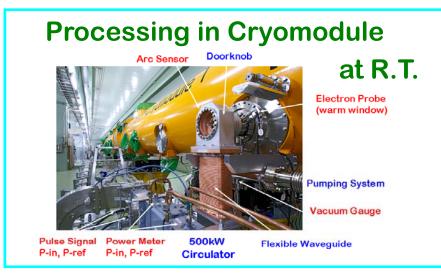


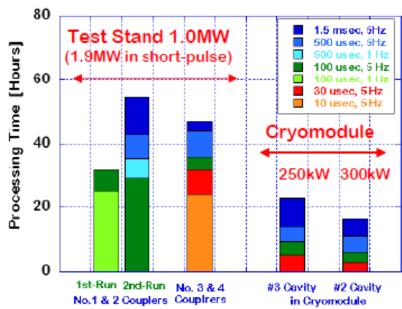










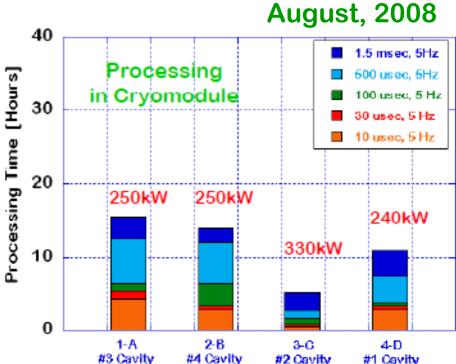


**Processing of Input Couplers** 

in Cryomodule; STF Phase-1.0

**Four STF-BL Cavities** 





Processing time up to 240~330 kW for 5 ~ 15 hours

# New Variable Input Coupler for S1 Global and STF Phase-2

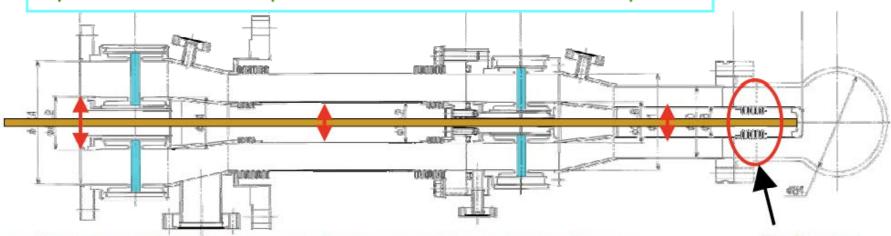
Present Fixed Input Coupler



φ 35.2

 $Zo = 50 \Omega$ 

φ 26



Large diameter of an inner conductor and Low impedance

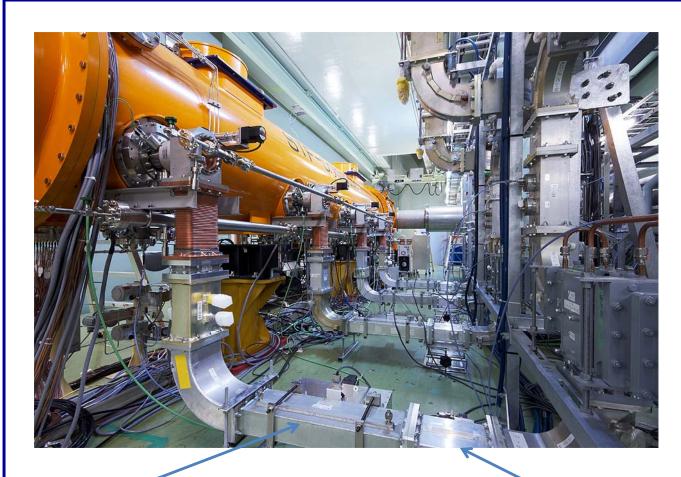
New

$$Z_0 = 41.5 Ω$$

Variable Antenna Length → +/- 2.5 mm

Tune-ability of Qin → +/- 30 %

### QL control test by WG phase shifter and reflector



phase shifter

reflector

high power test, 4 cavities combined, using external phase shifters and variable reflectors. QL can be set +/- 15%.

### (A) Cavity Integration Work Packages

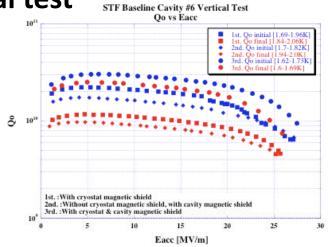
## 1.2.3 Magnetic Shield study status

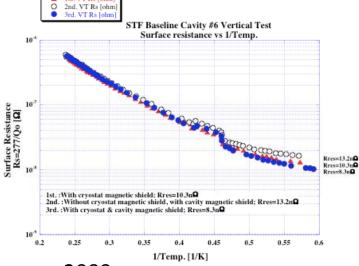
STF studies for magnetic shield

### Magnetic shield evaluation in vertical test



magnetic shield (same as for cryomodule installation)





MHI-06 cavity were vertical tested in December 2008, January 2009.

MHI-06 : no cavity mag-shield, cryostat mag-shield: Rs=10.3n $\Omega$  usual vertical test cavity mag-shield, no cryostat mag-shield: Rs=13.2n $\Omega$  cryomodule installation cavity mag-shield, and cryostat mag-shield: Rs=8.3n $\Omega$ 

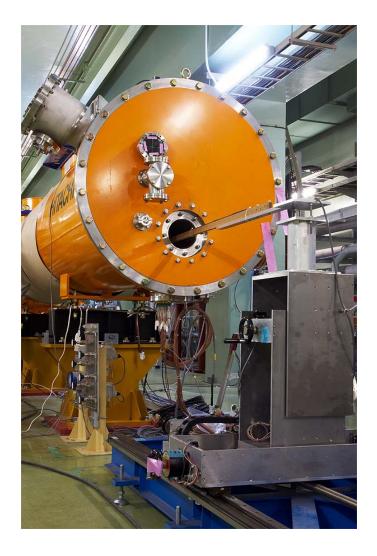
### Magnetic shield evaluation in STF cryomodule



cavity magnetic shield (one end is open for probe scan)

direct magnetic field measurement inside of the cavity magnetic shield, in the cold state.

Measurement is scheduled in April 2009.



magnetic probe is inserted from outside and the mapped field can be measured.

### (B) Plug-compatibility concept development

(1) Specifications for plug-compatibility

(2) Definitions of boundary for plug-compatibility

### (1) Specification Profile Tables

### The purpose of table:

to understand specification of function, specification of physical dimensions. to understand what is fixed, what is not fixed, for item by item. to facilitate 'Plug compatibility' concept.

### Tables visualize the specifications for;

Cavity Tuner Coupler

#### We had the discussion

at Cavity Kick-off meeting in DESY (Sep. 2007), at ML-SCRF meeting in DESY (Jan. 2008), at GDE meeting in Sendai (Mar. 2008), at ML-SCRF meeting in FNAL (Apr. 2008)

Updated tables are followings;

cavity	specification item	specification	unit and comments	further comments
RF properties	Frequency	1.30	GHz	
	Number of cells	9.00	cells	
	Gradient	31.50	MV/m	operational
	Gradient	35.00	MV/m	Vertical test
	Q0	0.80	10^10	at 35
	QU	1.00	10^10	at 31.5
	HOM damping		Q	decide later
	HOW Gamping		R/Q	decide later
	Short range wake			decide later
	Operating			
	temperature	2.00	K	
	Length	1247	mm	TESLA-short length
				must be compatible with
	Aperture		mm	beam dynamics
	Alignment accuray	300.00	um	rms
	Material	Niobium		
	Wall thickness	2.80	mm	
	Stiffness			decide later
	Flange/Seal system		Material	decide later
	Maximum			
Physical properties	overpressure			
		2	bar	
	Lorentz force			
	detuning over Flat-			
	top at 35 MV/m	1.00	kHz	maximum
				Mag shield outside,
	Outer diameter He vessel	220.00	(:	decide later for precise
		230.00	mm(inner diameter)	number
	AC99GI			KEK Mag shield inside, decide later for precise
		230 00	mm(inner diameter)	number
	Magnetic shielding	230.00	inside/outside	decide later
1	magnetic sineranig		miside/Outside	שבטועב ומנכו

<sup>\*</sup> yellow boxes indicate 'not fixed'

specification item	specification	unit and comments	further comments
Tuning range	>600 kHz		
Hysteresis in Slow tuning	<10	μm	
Motor requirement	step-motor use, Power-off Holding, magnetic shielding		
Motor specification	ex) 5 phase, xxA/phase,	match to driver unit, match to connector pin asignment,	decide later
Motor location	insdie 4K? / outside 300K? / inside 300K accessible from outside?	need availability discussion, MTBF	decide later
Magnetic shielding	<20	mG at Cavity surface, average on equater	
Heat Load by motor	<50	mW at 2K	
Physical envelope	do not conflict with GRP, 2-phase line, vessel support, alignment references, Invar rod, flange connection,		cable connection, Mag shield
Survive Frequency Change in Lifetime of machine	~20 Mio. steps	could be total number of steps in 20 years,	
	Tuning range Hysteresis in Slow tuning  Motor requirement  Motor specification  Motor location  Magnetic shielding Heat Load by motor  Physical envelope  Survive Frequency Change in Lifetime	Tuning range Hysteresis in Slow tuning  Motor requirement  Motor specification  Motor location  Motor location  Magnetic shielding  Magnetic shielding  Heat Load by motor  Physical envelope  Physical envelope  Survive Frequency Change in Lifetime  Survive Frequency  Change in Lifetime  Step-motor  Alto  step-motor use, Power-off Holding, magnetic shielding  ex) 5 phase, xxA/phase,  insdie 4K? / outside 300K? / inside 300K accessible from outside?  Alto  Alto	Tuning range

<sup>\*</sup> yellow boxes indicate 'not fixed'

	Tuning range	>1	kHz over flat-top at 2K	
Fast tuner	Lorentz detuning residuals	<50	Hz at 31.5MV/m flat- top	(LD and microphinics? or LD only?) :decide later
	Actuator specification	ex) low voltage piezo 0-1000V,	match to driver unit, match to connector pin asignment,	decide later
	Actuator location	insdie 4K?/inside 4K accessible/inside 100K? accesible / inside 300K accessible from outside?		decide later
	Magnetic shielding	<20	mG at Cavity surface average	
	Heat Load in operation	<50	mW	
	Physical envelope	do not conflict with GRP, 2-phase line, vessel support, alignment references, Invarrod, flange connection,		
	Survive Frequency Change in Lifetime of machine	>10 <sup>10</sup>	number of pulses over 20 years, (2x10 <sup>9</sup> :operational number)	

<sup>\*</sup> yellow boxes indicate 'not fixed'

Coupler	condition	specification unit and comments	further comments
	Operation	>400 kW for 1600 us	
Power requirements	Processing	>1200 <mark>kW upto 400 us</mark>	need after vac break, cool-down
		>600 kW larger than 400 us	need after vac break, cool-down
	Processing with reflection		
	mode	>600 kW for 1600us	in Test stand
Processing time	warm	<50hours	after installation,definition of power/pulse_width target are the same as 'Power Requirement' above.
	cold	<30hours	after installation, definition of power/pulse_width target are the same as 'Power Requirement' above.
	2K static	< 0.063 W	
	5K static	< 0.171 W	depend on tunability
lleet leede <i>l</i> eeuwlen	40 K static	< 1.79W	
Heat loads /coupler	2K dynamic	< 0.018 W	
	5K dynamic	< 0.152W	
	40K dynamic	< 6.93 W	
Cavity vacuum	# of windows	2	
integrety	bias capablity	yes	
DE Proportios	Qext	Yes/No <mark>tunable</mark>	decide later
RF Properties	Tuning range	1-10 10^6 if tunable	
Physical envelope	Position	compatible to TTF-III	decide later
	Flange	compatible to TTF-III	decide later (to cavity, to cryostat)
	waveguide	compatible to TTF-III	decide later
	support	compatible to TTF-III	decide later
Instrumentation	vacuum level	>= 1	
	spark detection	0at window	
	electron current detection	>= 1 at coax	
	temperature	>= 1 at window	

<sup>\*</sup> yellow boxes indicate 'not fixed'

### (2) Definitions of boundary for plug-compatibility

# Cavity and Cryomodule Plug-Compatibility

To Reach Consensus

Akira Yamamoto

ILC-08, Chicago, Nov. 17, 2008

## Why and How Plug-compatibility?

### Cavity

- Necessary "extended research" to improve field gradient,
- Keep "room" to improve field gradient,
- Establish common interface conditions,

### Cryomodule

- Nearly ready for "system engineering"
- Establish unified interface conditions,
- Intend nearly unified engineering design
- Need to adapt to each regional feature and industrial constraint

# Plug-compatibility in R&D and Construction Phases

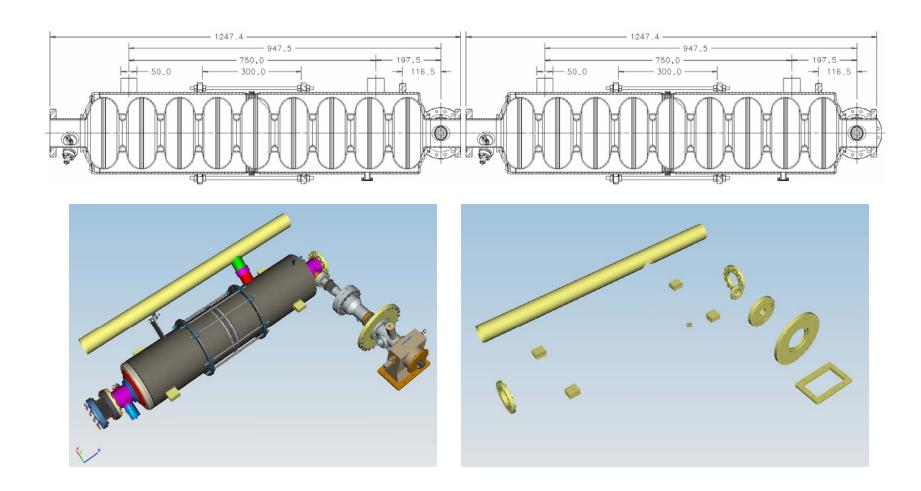
### R&D Phase

- Creative work for further improvement with keeping replaceable condition,
- Global cooperation and share for intellectual engagement

### Construction Phase

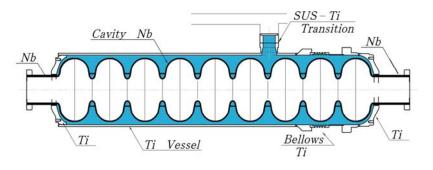
- Keep competition with free market/multiple-suppliers, and effort for const-reduction, (with insurance)
- Maintain "intellectual" regional expertise base
- Encourage regional centers for fabrication/test facilities with accepting regional features/constraints

# **Plug-compatible Development**



Plug-compatible interface to be established

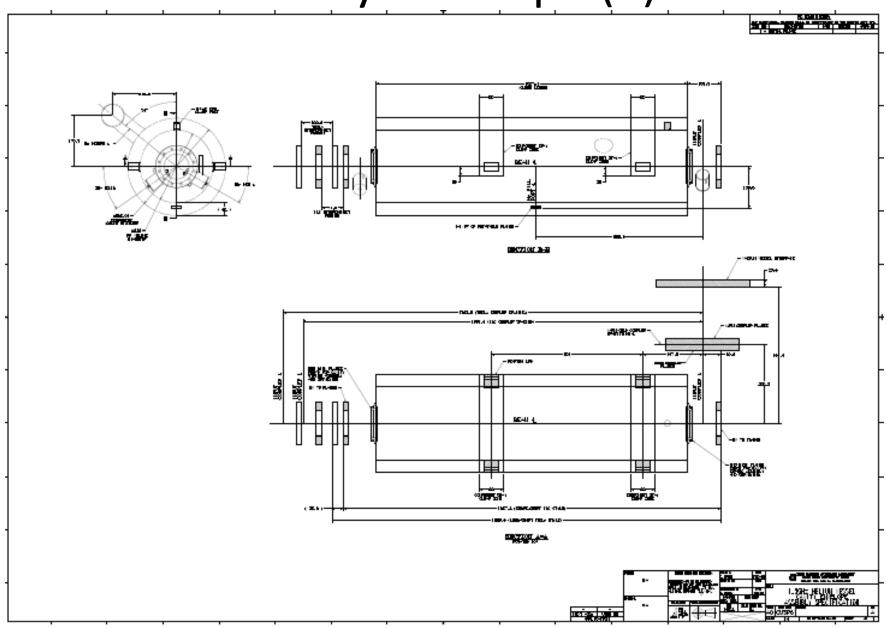
# Plug compatible conditions at Cavity package (in progress)



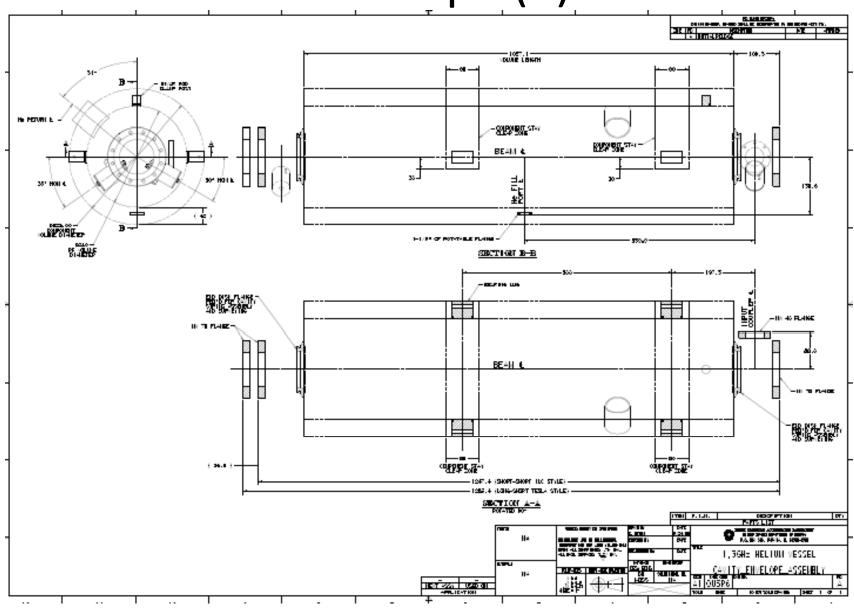


Item	Can be flexible	Plug- compatibl e
Cavity shape	TeSLA/L L/RE	
Length		Required
Beam pipe dia		Reuuired
Flange		Required
Tuner	TBD	
Coupler flange		Required
He –in-line joint		Required
Input coupler	TBD	TBD

# Cavity Envelope (1)



# Envelope (2)



### Summary of 'Cavity Integration Work package'

### (A) Work Package progress

- (1) Blade tuner study is well in advance. 8 units will be installed FNAL CM2.
- (2) Slide-jack tuner was demonstrated of small LD. Further study is necessary.
- (3) TTF3 coupler is going into the mass production.
- (4) STF fixed coupler is going to install variable coupling capability.
- (5) QL control was also demonstrated by using external WG components, phase shifter and reflector.
- (6) magnetic shield evaluations are in progress.

\*system integrations into cryomodule: FNAL and KEK has integration experience. (This is not yet mentioned in this talk.)

### (B) Plug-compatibility concept development

Specifications profile for plug-compatibility are on a way (still several are not fixed). Definitions of boundary for plug-compatibility are almost done.