

ILC Software

Reconstruction

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DESY

Vancouver Linear Collider Workshop

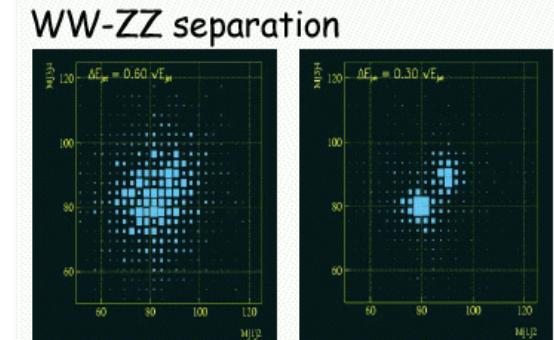
Vancouver, July 19 - 22, 2006

Outline

- Introduction
- Reconstruction Software Tools
 - **LCIO** – data model & persistency
 - Frameworks: **Marlin** vs **org.lcsim**
 - Reconstruction **org.lcsim Reconstruction** vs **MarlinReco**
 - Conditions data: **LCCD** vs **org.lcsim Conditions**
 - Geometry description: **GEAR** vs **Compact Geometry description**
 - Event viewer: **Wired4** (**org.lcsim**) vs **CED viewer** (**Marlin**)
 - Interoperability
- Summary & conclusion

Demands on Reconstruction

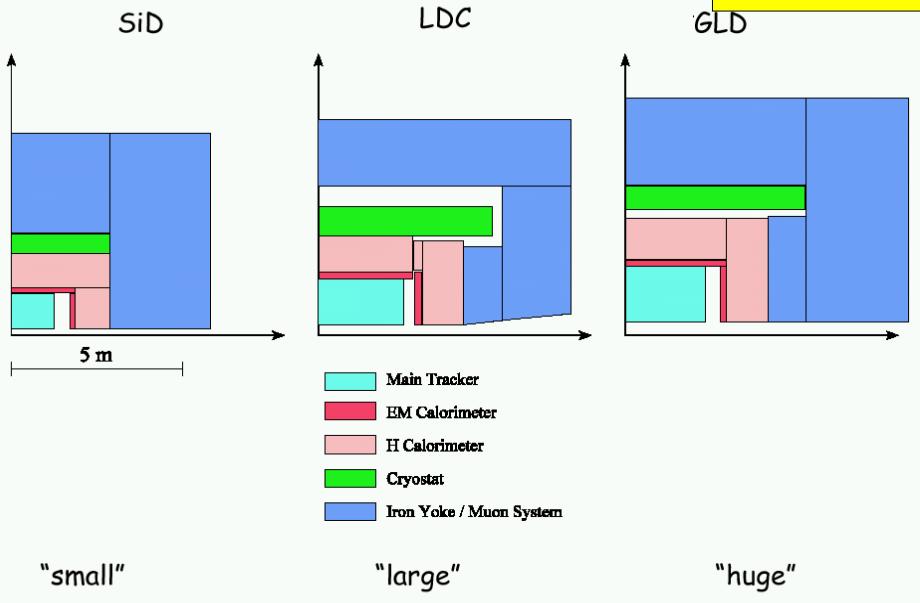
- precision tracking and vertexing
- take advantage of the high granularity in calorimeters
- very high jet-mass resolution needed** $\sim 30\%/\text{sqrt}(E/\text{GeV})$:



Particle Flow

- reconstruct all single particles
- use tracker for charged particles
- use Ecal for photons
- use Hcal for neutral hadrons

- reconstruction algorithms (pflow) determine the overall detector performance
- need full reconstruction to choose and optimize detector concepts

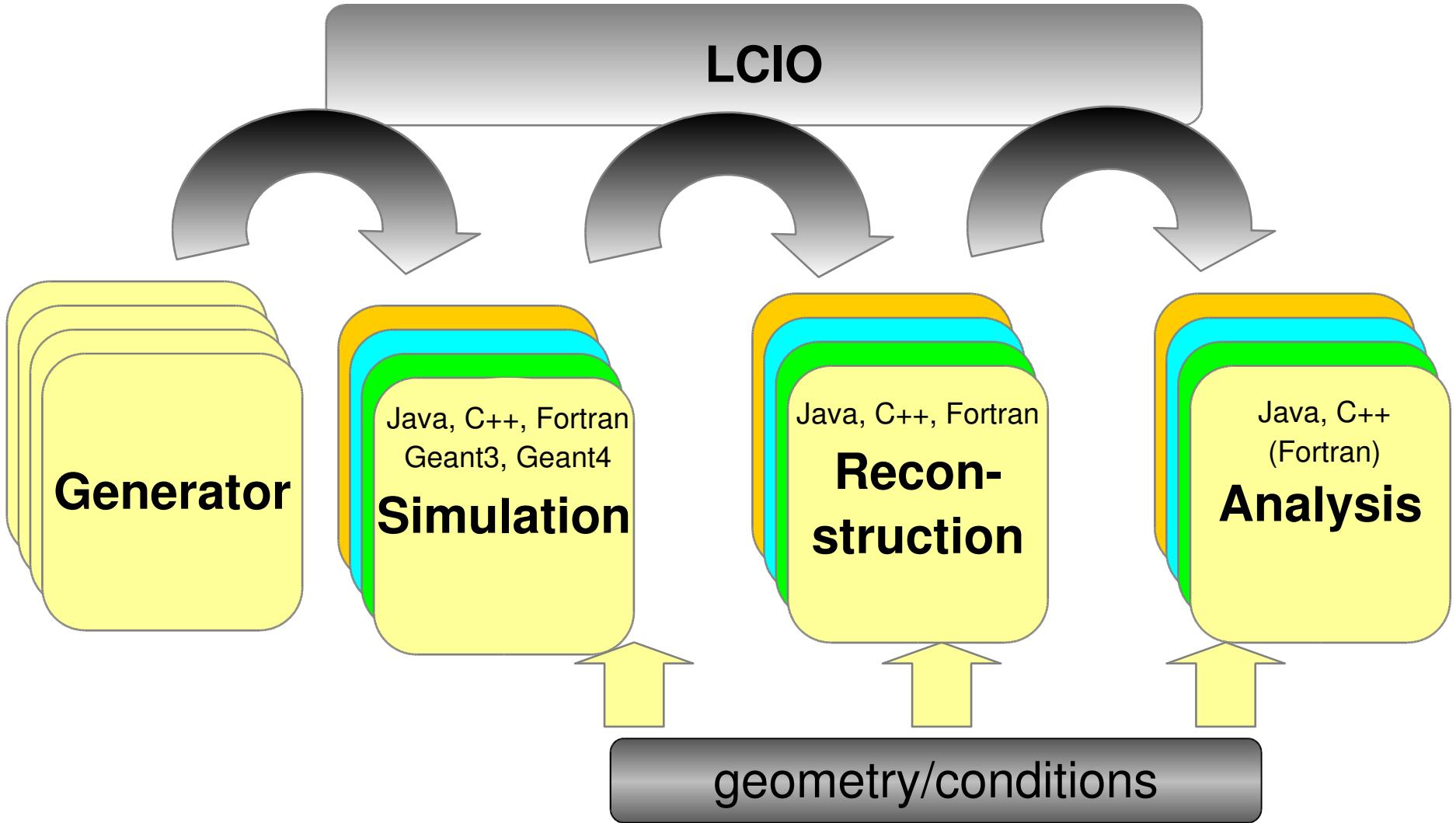


four **interregional**
detector concept
studies ongoing

ILC software packages

	Description	Detector	Language	IO-Format	Region
Simdet	fast Monte Carlo	TeslaTDR	Fortran	StdHep/LCIO	EU
SGV	fast Monte Carlo	simple Geometry, flexible	Fortran	None (LCIO)	EU
Lelaps	fast Monte Carlo	SiD, flexible	C++	SIO, LCIO	US
Mokka	full simulation – Geant4	TeslaTDR, LDC, flexible	C++	ASCI, LCIO	EU
Brahms-Sim	Geant3 – full simulation	TeslaTDR	Fortran	LCIO	EU
SLIC	full simulation – Geant4	SiD, flexible	C++	LCIO	US
LCDG4	full simulation – Geant4	SiD, flexible	C++	SIO, LCIO	US
Jupiter	full simulation – Geant4	JLD (GDL)	C++	Root (LCIO)	AS
Brahms-Reco	reconstruction framework (most complete)	TeslaTDR	Fortran	LCIO	EU
Marlin	reconstruction and analysis application framework	Flexible	C++	LCIO	EU
hep.lcd	reconstruction framework	SiD (flexible)	Java	SIO	US
org.lcsim	reconstruction framework (under development)	SiD (flexible)	Java	LCIO	US
Jupiter-Satelite	reconstruction and analysis	JLD (GDL)	C++	Root	AS
LCCD	Conditions Data Toolkit	All	C++	MySQL, LCIO	EU
GEAR	Geometry description	Flexible	C++ (Java?)	XML	EU
LCIO	Persistency and datamodel	All	Java, C++, Fortran	-	AS,EU,US
JAS3/WIRED	Analysis Tool / Event Display	All	Java	xml,stdhep, heprep,LCIO,	US,EU

ILC software chain



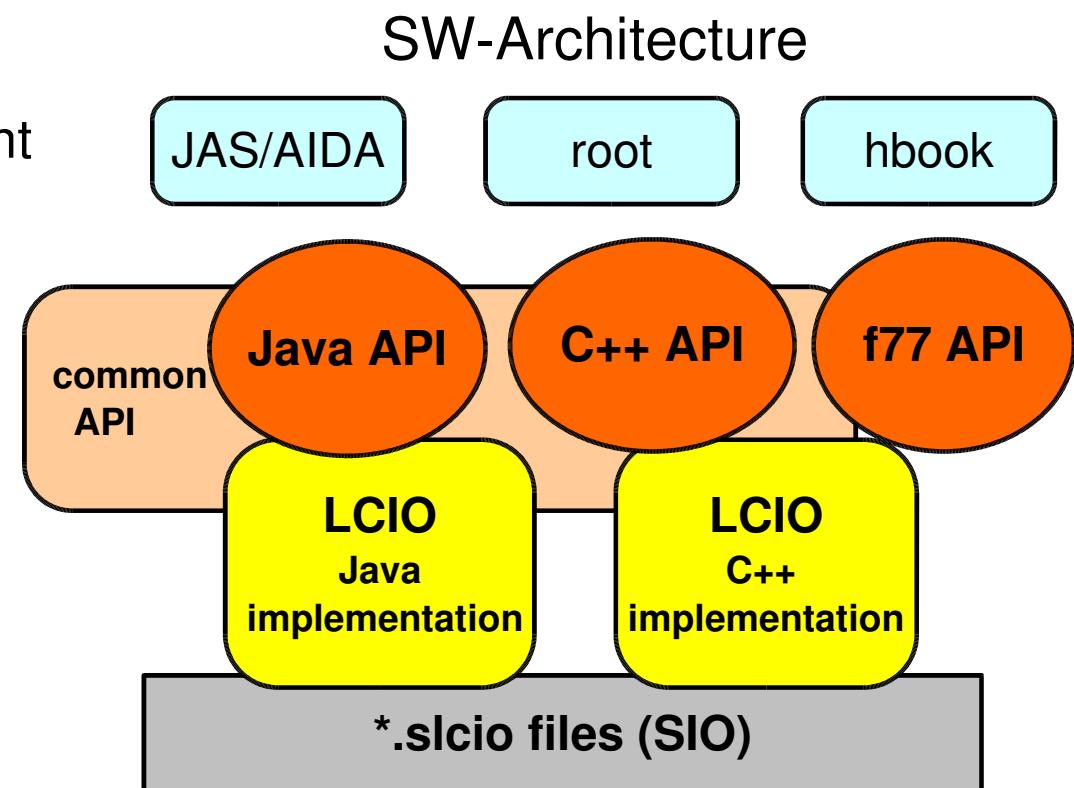
LCIO Overview

- DESY and SLAC joint project:
 - provide a common basis for ILC software
- Features:
 - Java, C++ and f77 (!) API
 - extensible data model for current and future simulation and testbeam studies
 - user code separated from concrete data format
 - no dependence on other frameworks

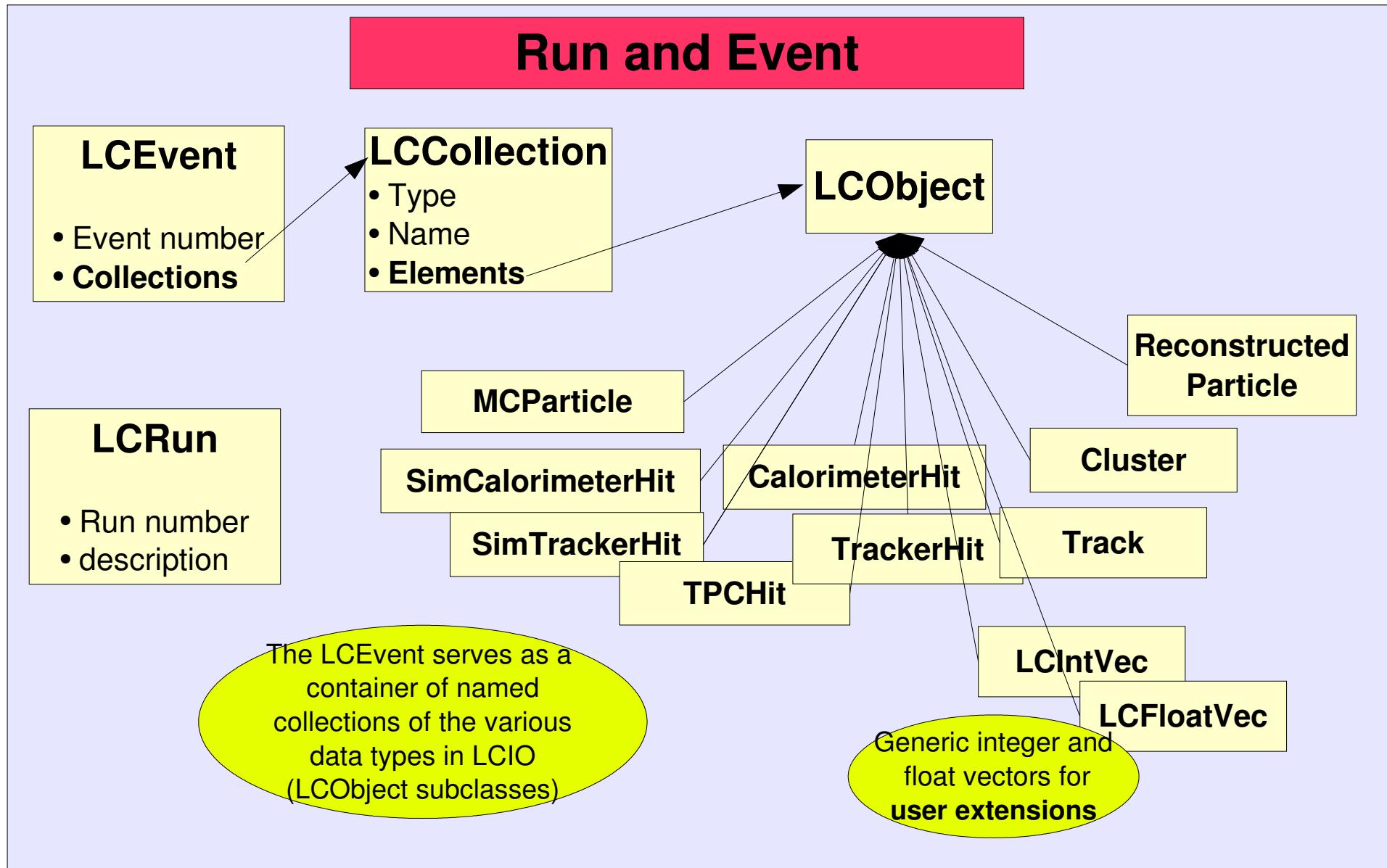
simple & lightweight

new release: **v01-07**

now de facto standard
persistency & data
model for ILC software



LCIO Event Data Model



LCIO Event Data Model

- the LCIO event data model is fairly complete, nevertheless flexible for future extensions
- thus, it has been adapted and can be extended as needed by the community
 - maintaining downward compatibility
 - with international discussion and agreement

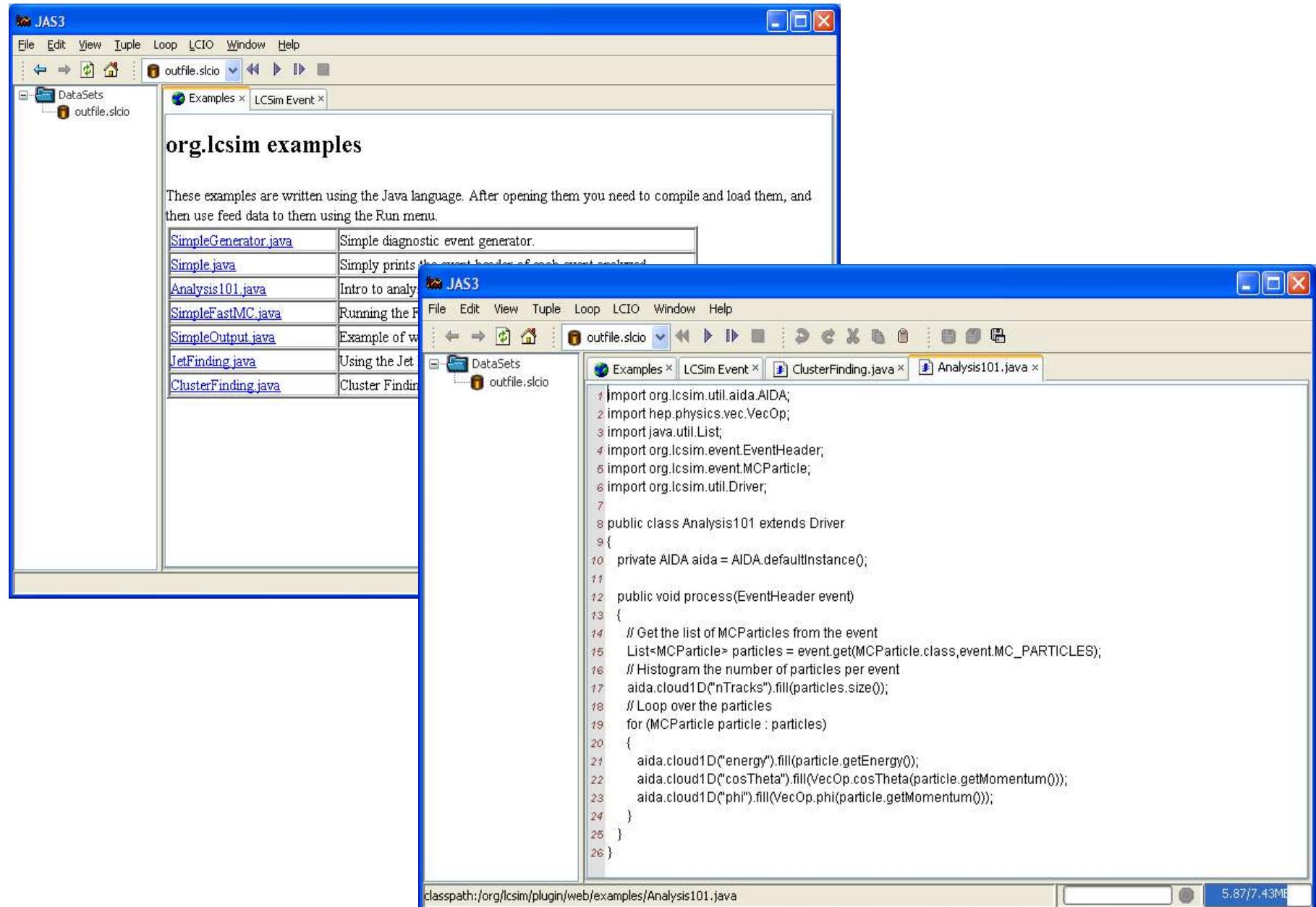
Framework I: org.lcsim

- “Second generation” ILC reconstruction/analysis framework
 - Builds on hep.lcd framework used since 1999
 - Full suite of reconstruction and analysis tools
- Uses LCIO for IO and as basis for simulation, raw data and reconstruction event formats
 - Isolate users from raw LCIO structures
 - Maintain full interoperability with other LCIO based packages
- Detector Independence
 - Make package independent of detector, geometry assumptions so can work with any detector
 - Read properties of detectors at runtime
- Written using Java (1.5)
 - High-performance but simple, easy to learn, OO language
 - Enables us last 10 years of software developments in the “real world”
- Ability to run standalone (command line or batch) or in JAS3 or IDE such as Netbeans, Eclipse

org.lcsim with JAS3

- ❑ JAS3 org.lcsim plugin adds:
 - Example Analysis Code
 - org.lcsim Event browser
- ❑ The org.lcsim can be used standalone, within IDE, or inside JAS3. Same code can be used in all modes, so it's easy to move back and forth
 - E.g. develop in IDE and run in JAS3
 - E.g. develop in JAS3 and run in batch
 - Easy viewing of analysis plots
 - WIRED event display integration

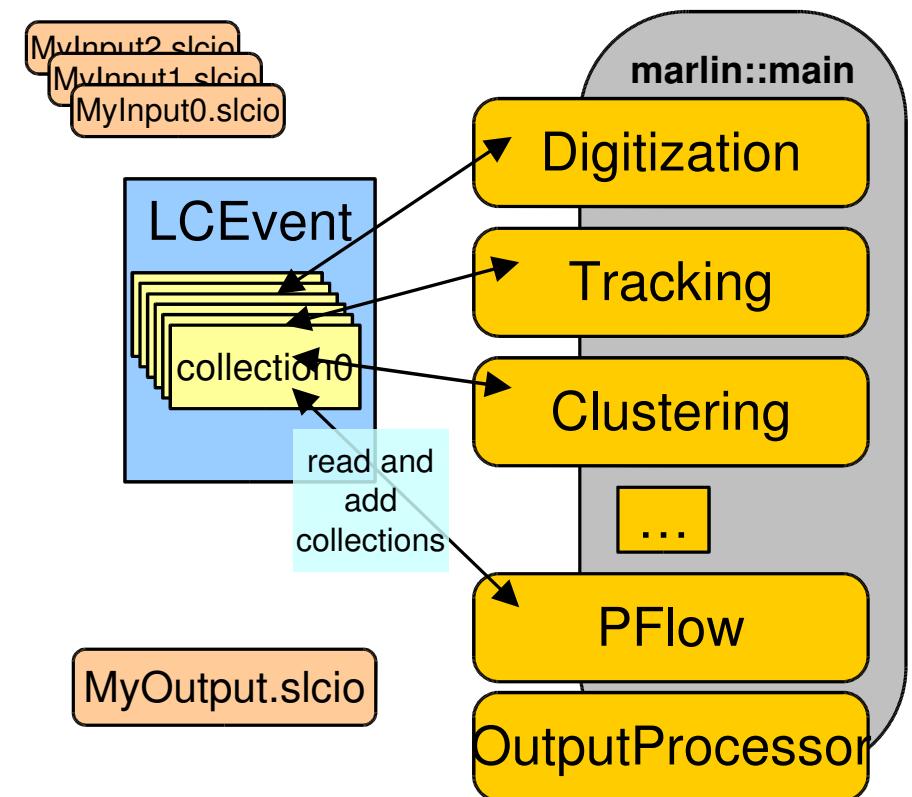
org.lcsim: Examples



Framework II: Marlin

Modular Analysis & Reconstruction for the L⁺I⁻Near Collider

- modular C++ **application framework** for the analysis and reconstruction of LCIO data
- uses **LCIO** as data model
- software modules called Processors
- provides the main program
- provides simple user steering (XML):
 - program flow (active processors)
 - user defined variables
 - per processor and global
 - input/output files



Marlin features

- fully configurable through steering files:
 - program flow
 - input parameters (processor based and global)
- self-documenting:
 - `./bin/Marlin -x`
prints example steering file for all available processors
with their parameters and example/default values
- AIDA interface for histogramming
 - easy creation of histograms through abstract interface
 - AIDAJNI/JAIDA, RAIDA (root based), ...
- configurable output
 - drop collections by name/type
- simple examples
 - user processor template, GNUmakefile,...
- easily extensible
 - makefiles 'automatically' include user packages with processors

Marlin: XML steering files

```

- <marlin>
  - <execute>
    <processor name="MyAIDAProcessor"/>
    <processor name="MyEventSelection"/>
  - <if condition="MyEventSelection">
    <group name="Tracking"/>
    <processor name="MyClustering"/>
    <processor name="MyPFlow"/>
    <processor name="MyLCIOOutputProcessor"/>
  </if>
</execute>
- <global>
  <parameter name="LCIOInputFiles"> simjob.slcio </parameter>
  <parameter name="MaxRecordNumber" value="5001"/>
  <parameter name="SupressCheck" value="false"/>
</global>
- <processor name="MyLCIOOutputProcessor" type="LCIOOutputProcessor">
  <parameter name="LCIOOutputFile" type="string">outputfile.slcio </parameter>
  <parameter name="LCIOWriteMode" type="string">WRITE_NEW</parameter>
</processor>
- <group name="Tracking">
  <parameter name="NTPCLayers" value="200"/>
  <processor name="MyTrackfinder" type="Trackfinder"/>
  - <processor name="MyTrackfitter" type="Trackfitter">
    <parameter name="Algorithm" value="DAF"/>
  </processor>
</group>
<!-- ... -->
</marlin>
```

- Program flow defined in `<execute>...</execute>` section
- logical conditions from parameters evaluated at runtime

- global Parameters defined in `<global/>` section

- local Parameters defined in mandatory `<parameter/>` section

- Processors can be enclosed by `<group/>` tag
- Parameters in `<group/>` joined by all processors

a Marlin application is fully configured through the steering files
(no user main program) !!

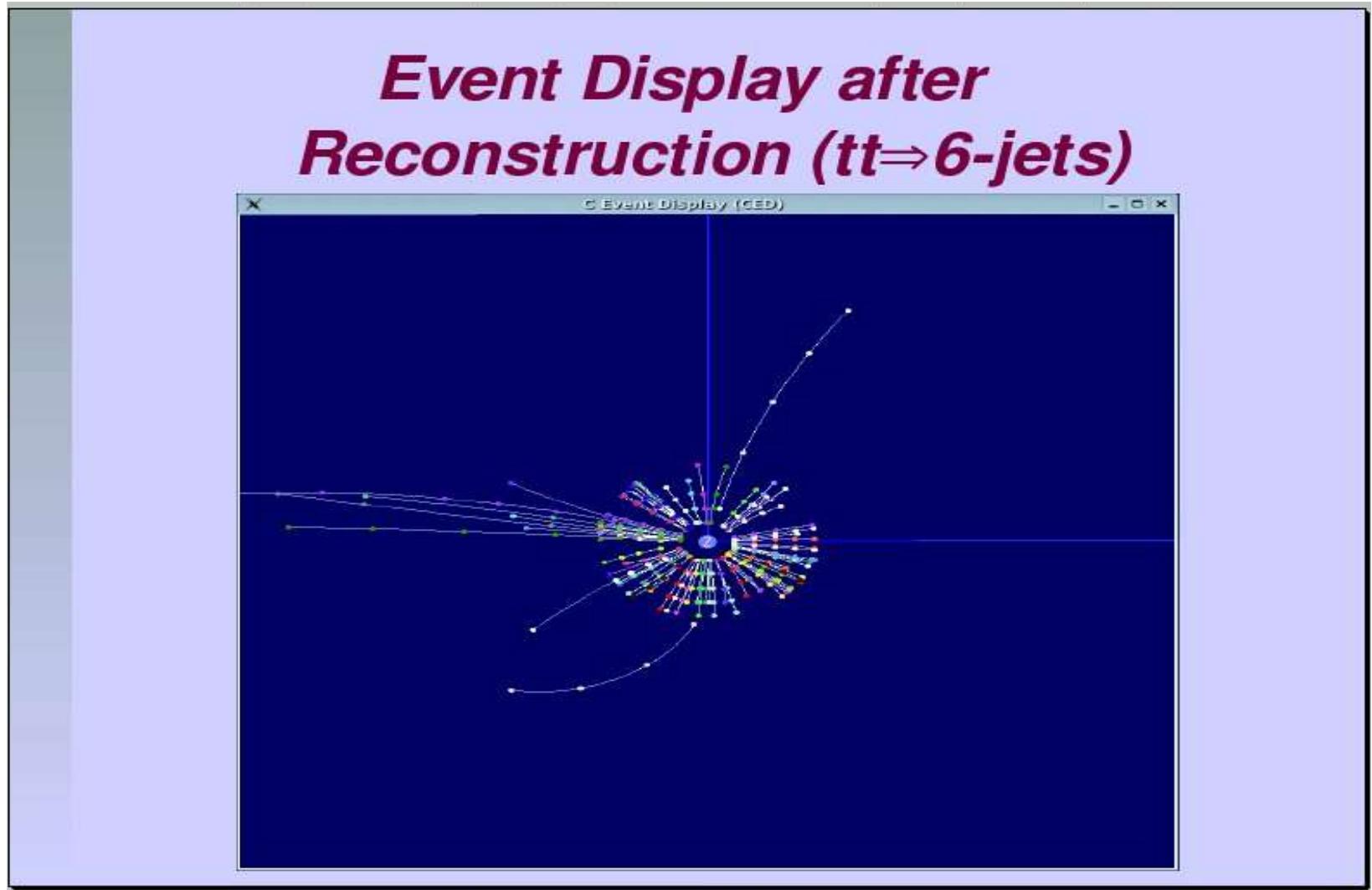
MarlinReco packages

- **TrackDigi**
 - TPCDigi
 - **new** ■ VTXDigi
- **CaloDigi**
 - LDCCaloDigi
- **Tracking**
 - LEPTracking
 - **new** ■ VTXTracking
 - TrackCheater
- **Clustering**
 - TrackwiseClustering
 - ClusterCheater
- **Particle flow**
 - ... next talk
- **Analysis**
 - EventShapes
 - SatoruJetFinder

most MarlinReco processors (algorithms) are **geometry independent**
→ they can be applied to **all detector concepts** (via Gear file)

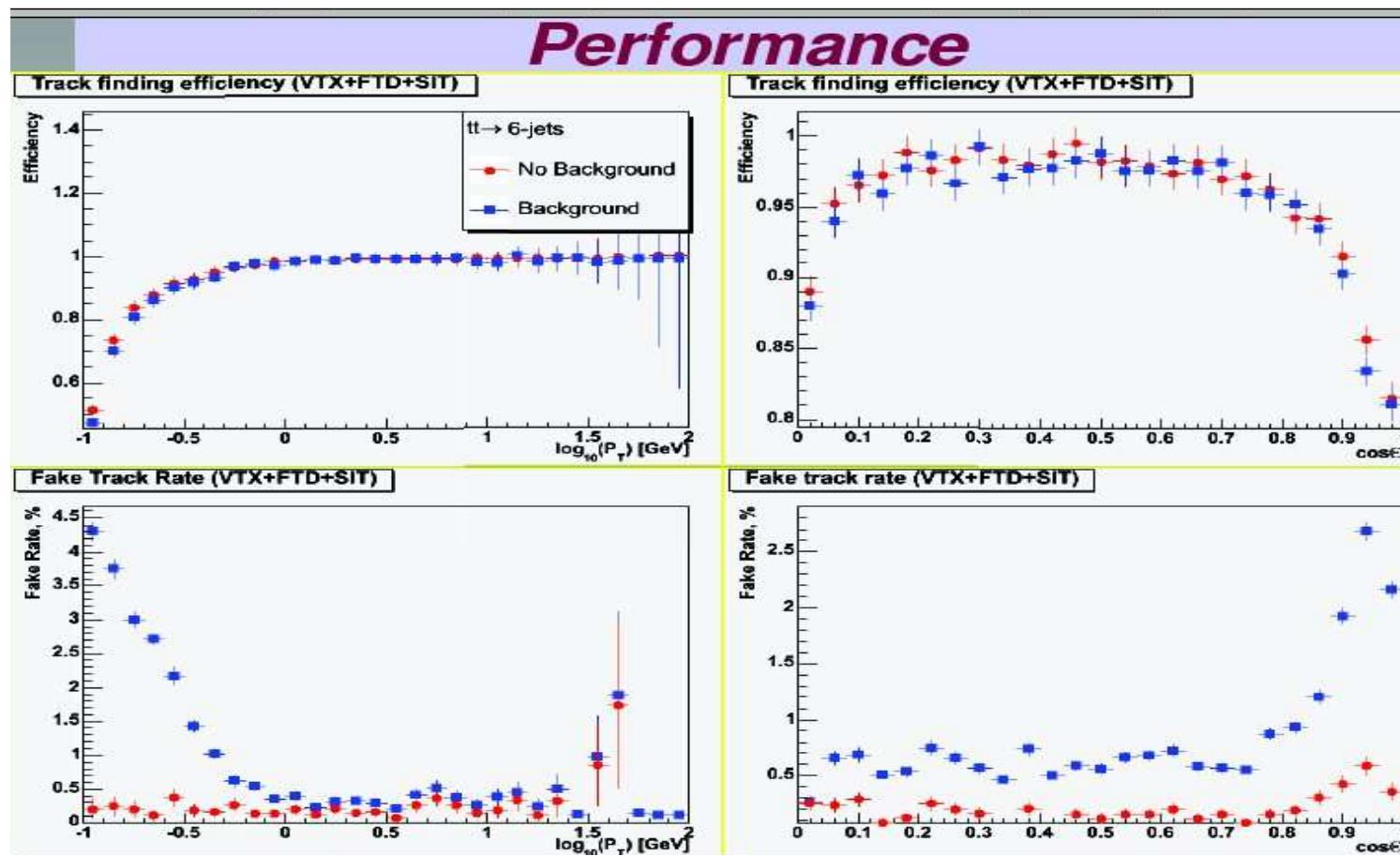
MarlinReco: Si Tracking (LDC)

Track finder & fitter with Kalman filtering:



Si Tracking for the LDC

- Track finder & fitter with Kalman filtering:



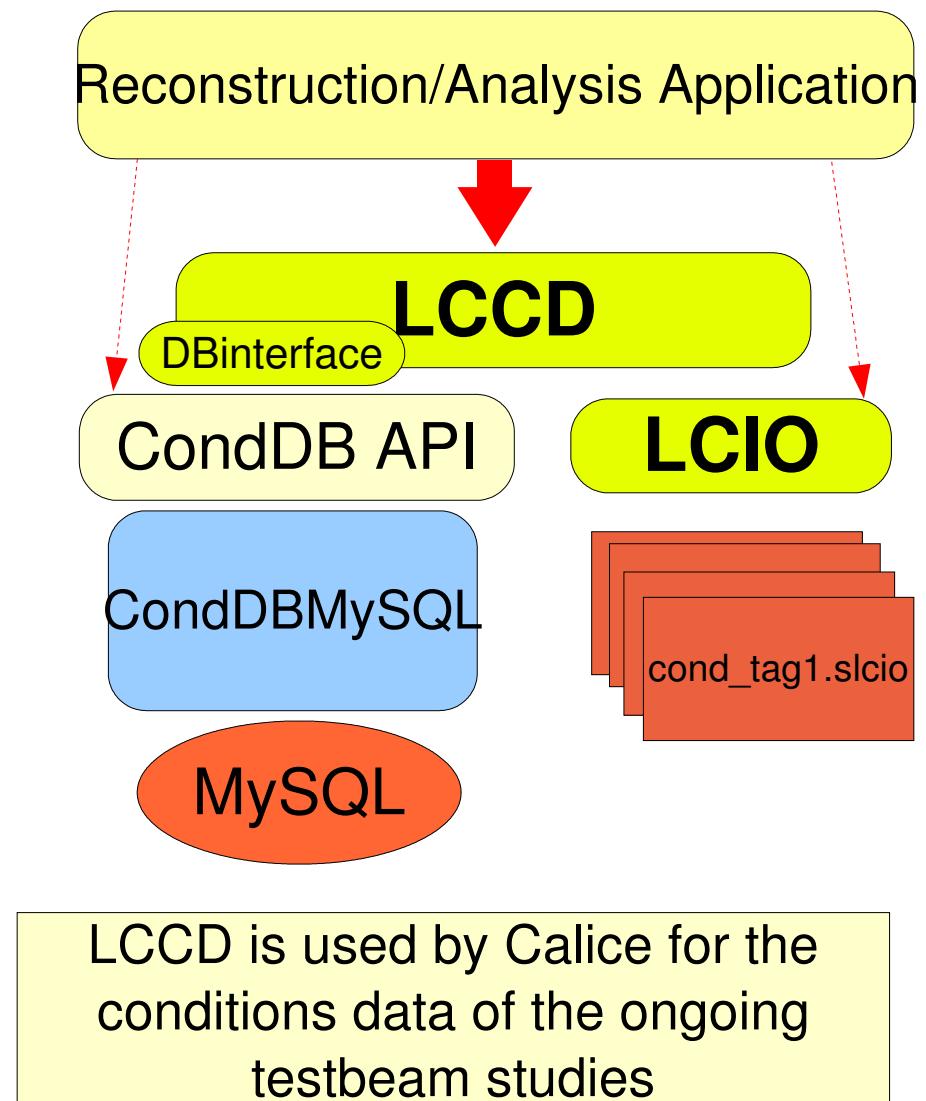
org.lcsim Reconstruction

- Reconstruction package includes:
 - Physics utilities:
 - Jet finders, event shape routines
 - Diagnostic event generator, stdhep reader/translator
 - Histogramming/Fitting/Plotting (AIDA based)
 - Event Display
 - Processor/Driver infrastructure
 - Fast MC
 - Track/Cluster smearing
 - Reconstruction
 - Cheaters (perfect reconstruction)
 - Detector Response
 - CCDSim, Digisim
 - Clustering Algorithms
 - Cheater, DirectedTree, NearestNeighbour, Cone
 - Tracking Finding/Fitting Algorithms
 - TRF,
 - Muon Finding, Swimming
 - Vertex Finding (ZvTop)

MarlinReco: LCCD

Linear **C**ollider **C**onditions **D**ata Toolkit

- Reading conditions data
 - from conditions database
 - from simple LCIO file
 - from LCIO data stream
 - from dedicated LCIO-DB file
- Writing conditions data
 - tag conditions data
 - Browse the conditions database
 - through creation of LCIO files
 - vertically (all versions for a timestamp)
 - horizontally (all versions for a tag)



org.lcsim Conditions Data

- Provide access to a extensible set of conditions for each detector including:
 - Detector Geometry
 - Algorithm Specific Constants
 - E.g. FastMC smearing parameters
 - Doesn't make assumptions about format of data
 - Doesn't rely on internet access, or local database installation
 - Detector Constants stored in .zip file
 - Typically contains:
 - Compact geometry file
 - Set of (ascii) constants for standard algorithms
 - Can additionally contain:
 - Arbitrary files (xml, ascii, binary) needed by other algorithms
 - Other geometry formats (HepRep, LCDD)
 - Full fieldmap
 - To define a new detector just create a new .zip file.

Detector Geometry

Different sets of detector geometry descriptions are needed for:

- cad – not discussed here
- detector simulation (Geant)
- reconstruction / analysis

For each application, more, less, or different details are needed

Aim: One common source from which the descriptions for Geant, reconstruction, and analysis can be derived.

Two different solutions:

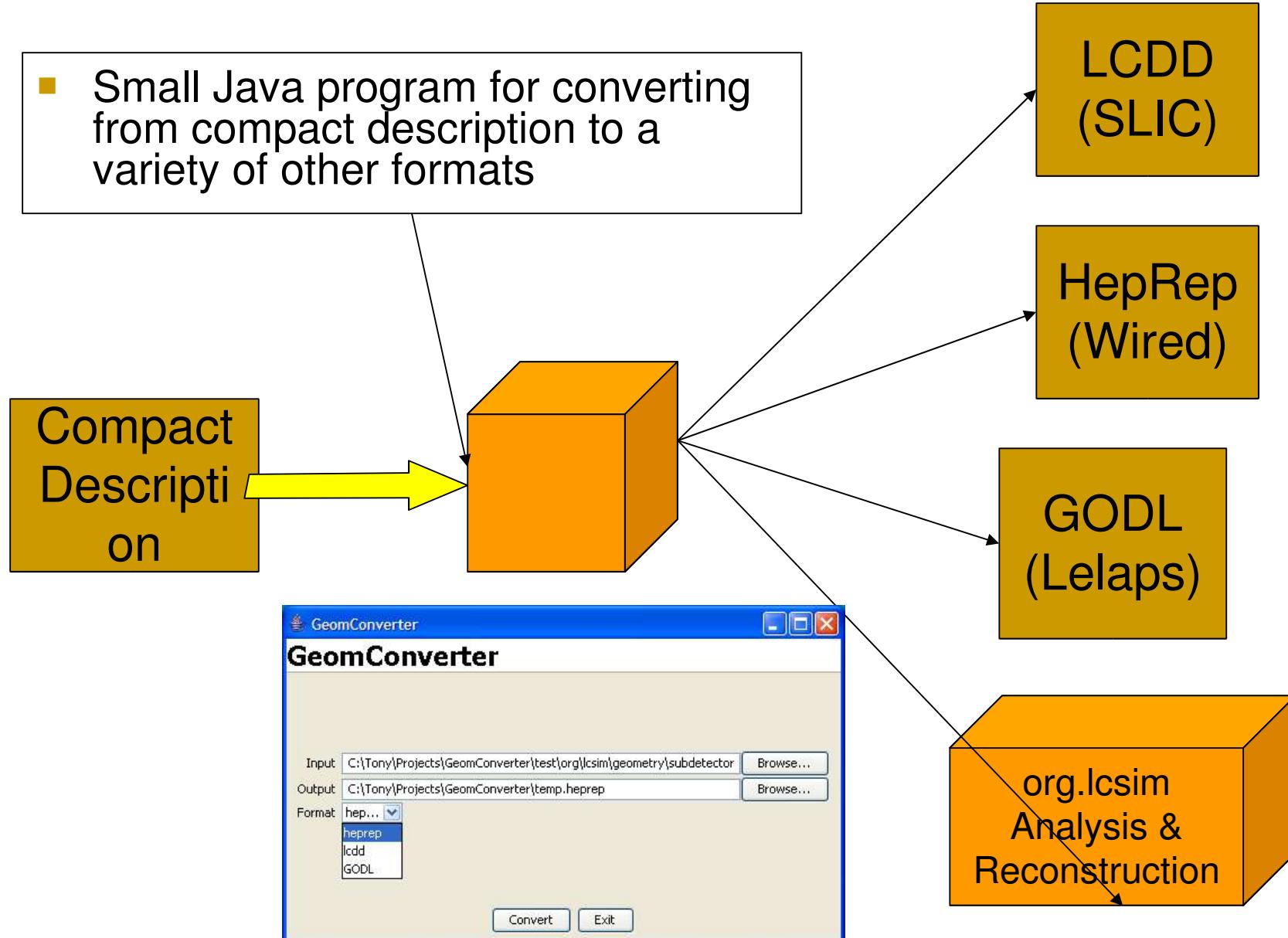
- org.lcsim: [Compact geometry description](#)
- MarlinReco: [Gear](#)

org.lcsim: Compact Geometry Description

- ❑ org.lcsim uses the “Compact Geometry Description” to define detectors
 - Simple XML format for describing ILC detectors
 - Handles typical ILC detector geometries
 - ❑ Range of detectors handled is extensible (by writing Java modules)
- ❑ Allows rapid prototyping of new detector geometries
- ❑ Does not require network access or installation of database software to run
- ❑ Automatic generation of full Geant4 LCDD geometry for full compatibility with SLIC

org.lcsim: Geometry Converter

- Small Java program for converting from compact description to a variety of other formats



Gear

```

<gear>
  <!--
    Example XML file for GEAR describing the LDC detector
  -->
  <detectors>
    - <detector id="0" name="TPCTest" geartype="TPCParameters" type="TPC">
      <maxDriftLength value="2500."/>
      <driftVelocity value="" />
      <readoutFrequency value="10."/>
      <PadRowLayout2D type="FixedPadSizeDiskLayout" rMin="386.0"
        maxRow="200" padGap="0.0"/>
      <parameter name="tpcRPhiResMax" type="double"> 0.16 </parameter>
      <parameter name="tpcZRes" type="double"> 1.0 </parameter>
      <parameter name="tpcPixRP" type="double"> 1.0 </parameter>
      <parameter name="tpcPixZ" type="double"> 1.4 </parameter>
      <parameter name="tpcIonPotential" type="double"> 0.00000003
    </detector>
    - <detector name="EcalBarrel" geartype="CalorimeterParameters">
      <layout type="Barrel" symmetry="8" phi0="0.0"/>
      <dimensions inner_r="1698.85" outer_z="2750.0"/>
      <layer repeat="30" thickness="3.9" absorberThickness="2.5"/>
      <layer repeat="10" thickness="6.7" absorberThickness="5.3"/>
    </detector>
    - <detector name="EcalEndcap" geartype="CalorimeterParameters">
      <layout type="Endcap" symmetry="2" phi0="0.0"/>
      <dimensions inner_r="320.0" outer_r="1882.85" inner_z="2820.0"/>
      <layer repeat="30" thickness="3.9" absorberThickness="2.5"/>
      <layer repeat="10" thickness="6.7" absorberThickness="5.3"/>
    </detector>
  </detectors>
</gear>

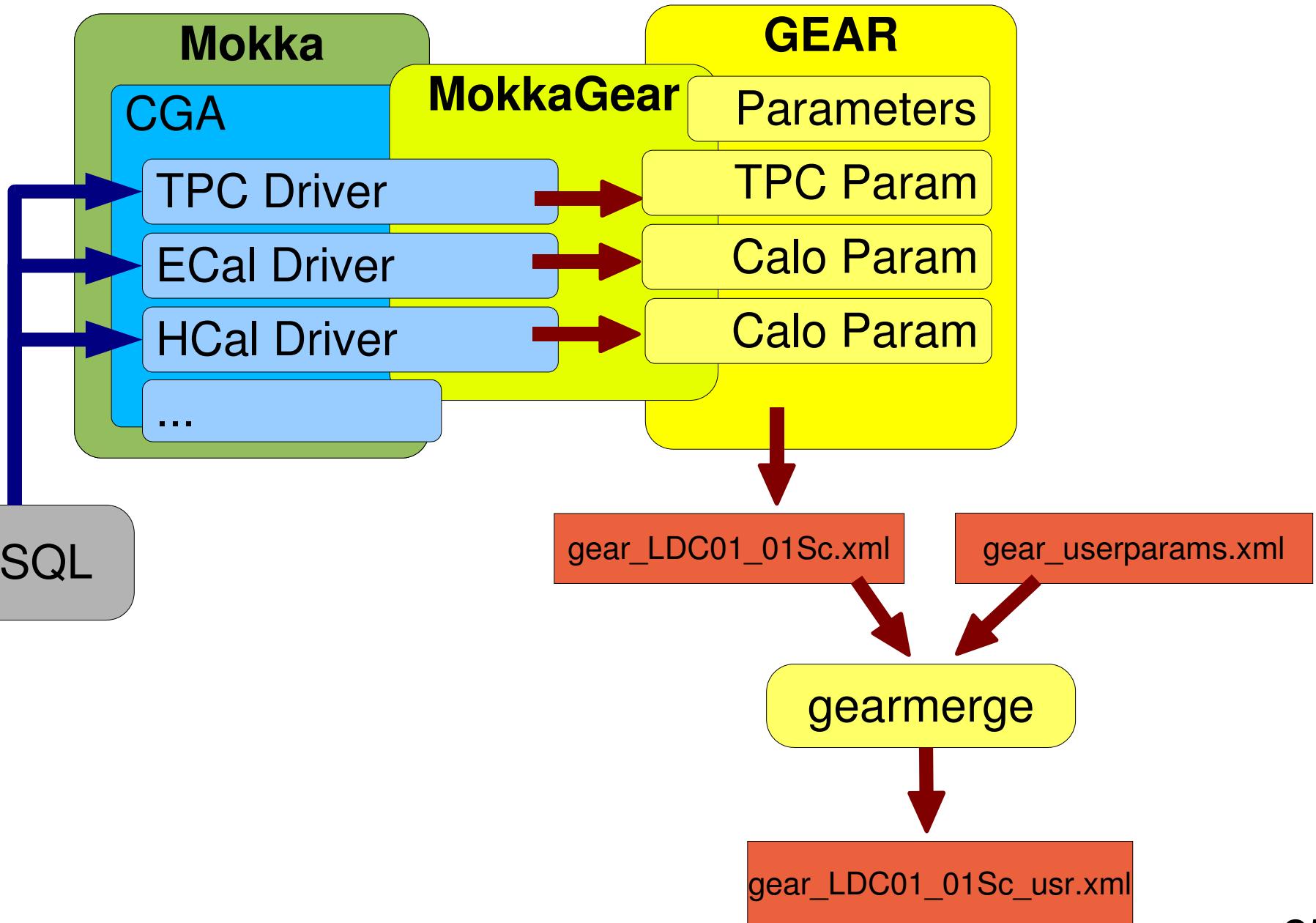
```

GEometry API for R econstruction

compatible with US – compact format

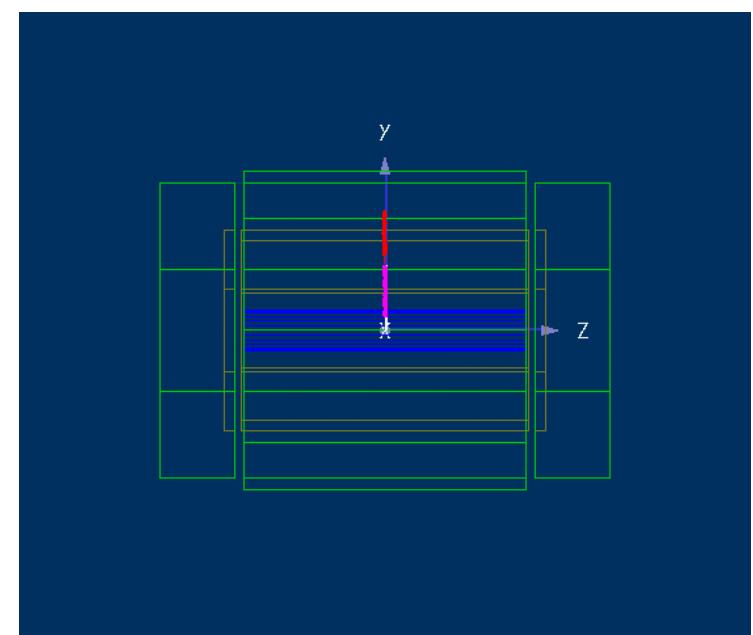
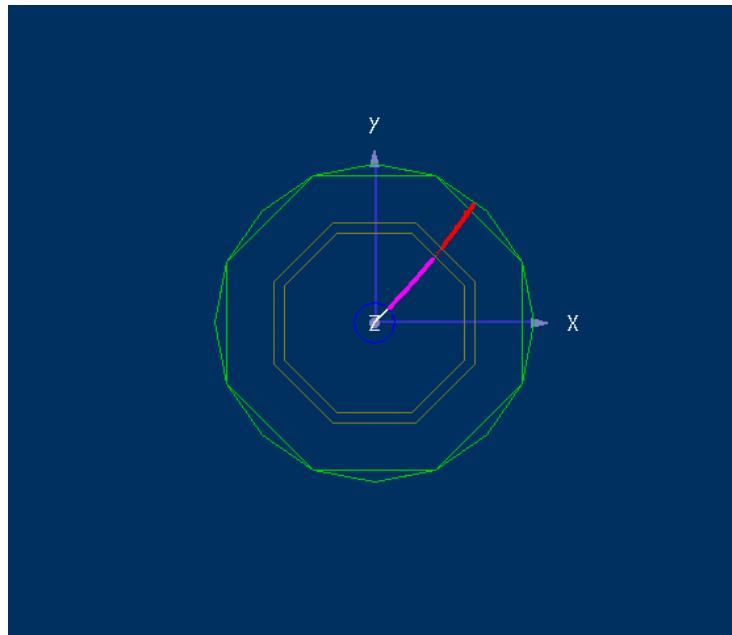
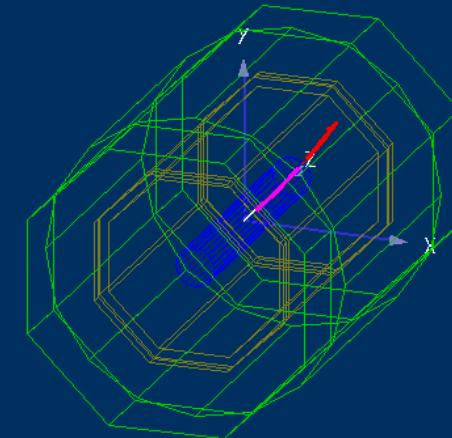
- well defined geometry definition for reconstruction that
 - is flexible w.r.t different detector concepts
 - contains all information needed for reconstruction and analysis
 - provides access to material properties (under development)
- abstract interface (a la LCIO)
- concrete implementation based on XML files
- and Mokka-CGA

MokkaGear

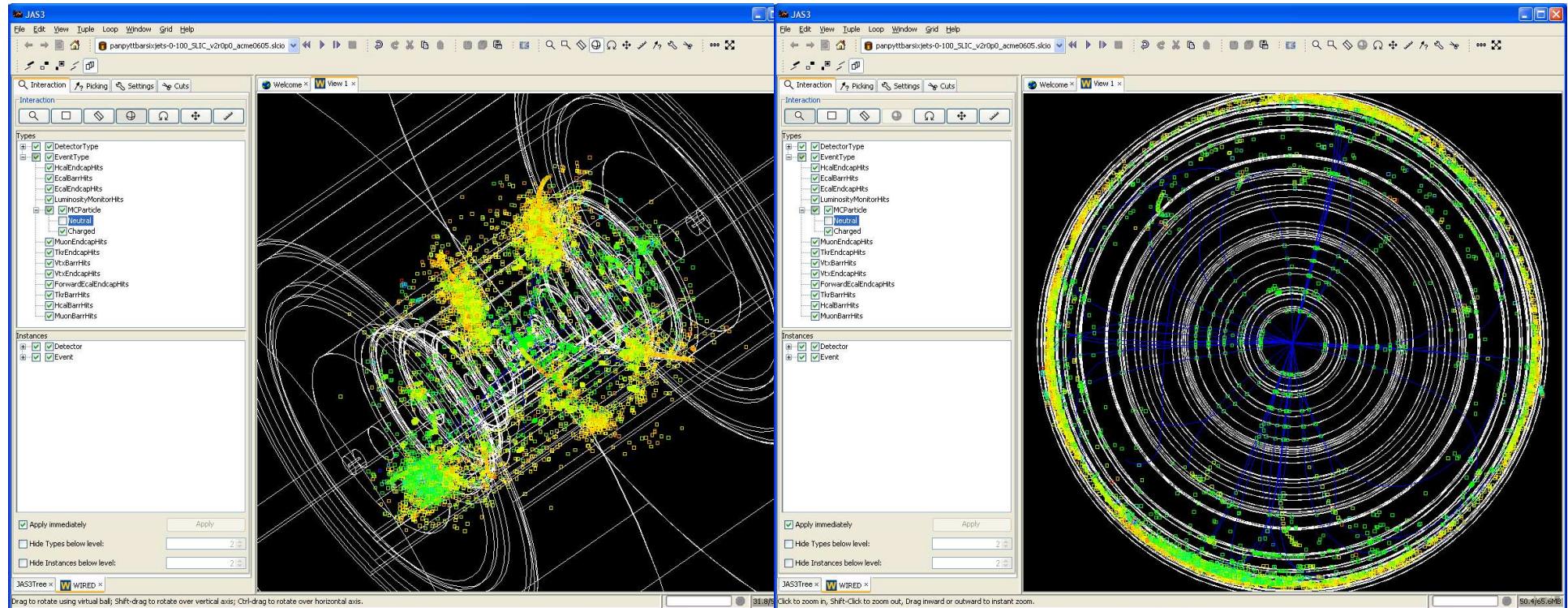


Marlin: CEDViewer

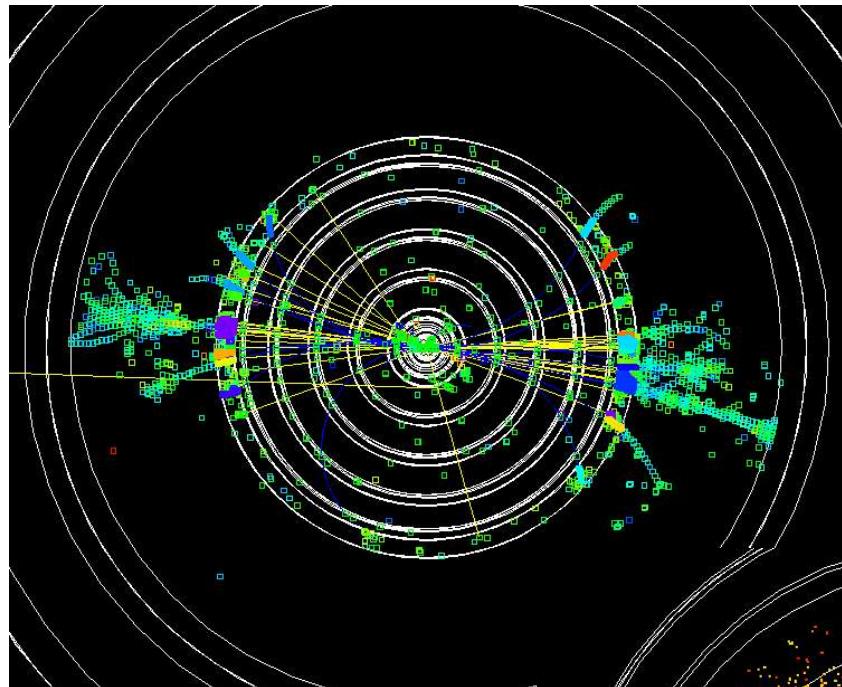
simple example taken from
\$MarlinReco/examples/LDC
steer_ldc.xml
gear_ldc.xml



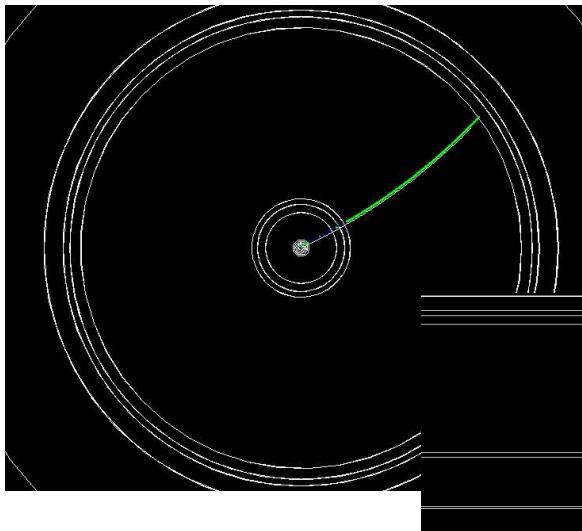
org.lcsim with WIRED



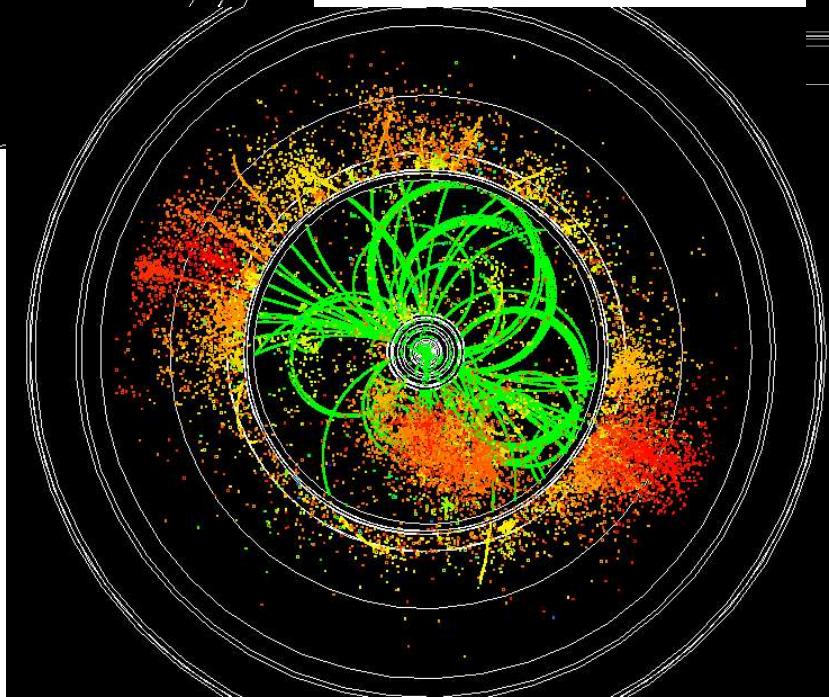
Interoperability: org.lcsim



SiD

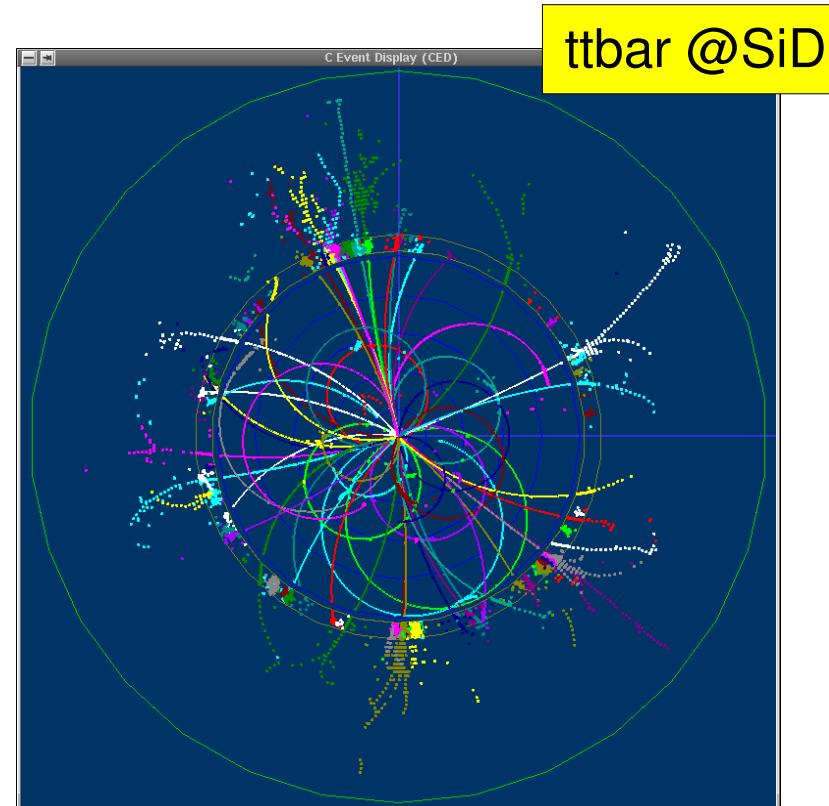
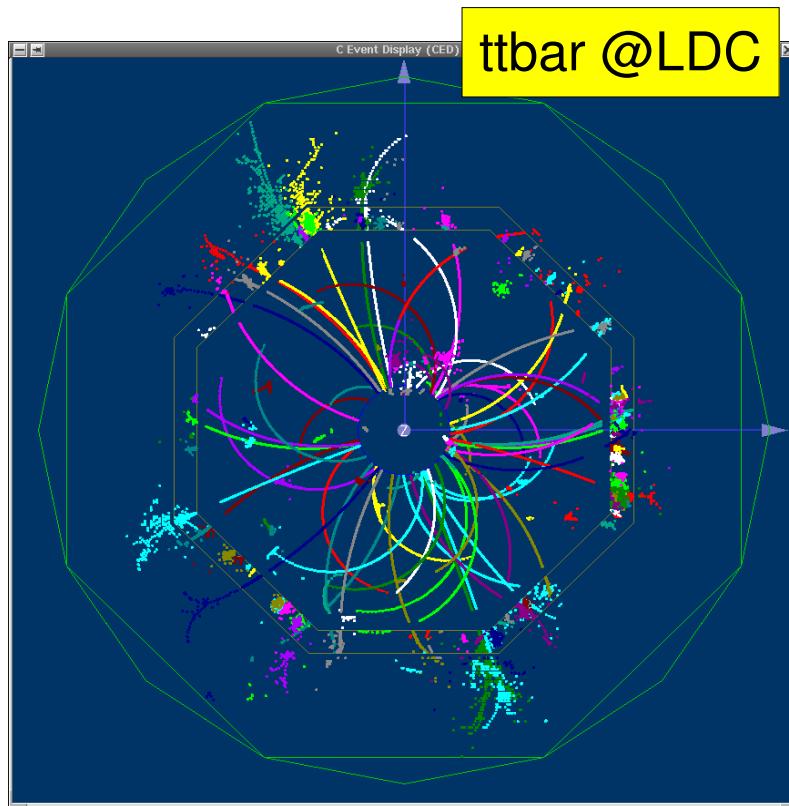


LDC



GLD

Interoperability: Marlin



ILC grid - “mass production”

- detector optimization – vary
 - B,R_TPC,L_TPC,...
- need considerable number of events with detector parameter variations for benchmark reactions
- produced these files on the grid for VO ILC – 450 kevts:
 - Z0 and uds, ccbb , ttbar, WW, ZH @ 500 GeV
 - 4 detector variants, 3 T and 4 T field
- database with available data files
- use grid tools to distribute/download the data !**

The screenshot shows a Firefox browser window with the URL <http://www-ilc.desy.de/simulation/database/>. The page title is "International Linear Collider MC Production Navigation Bar". It features a "Search Database" form with fields for Run Number, Date of Production [yyyy-mm-dd], Process, Event Generator, Simulation, Detector Model (set to LDC00Sc), B Field [T] (set to 4), and Center of Mass Energy [GeV]. Below the form is a note from "Oliver Wendt" stating "Last modified: Wed Nov 09 11:22:33 MEST 2005".

The screenshot shows a Firefox browser window with the same URL as the top screenshot. The page title is "International Linear Collider MC Production Navigation Bar". It displays a table titled "MC data-files matching your query:" with columns for Run Number, Event Generator, Simulation, Detector Model, B Field [T], and Center of Mass Energy [GeV]. The table lists numerous entries for "zpole_noisr_LDC00Sc" files across various parameters.

Run Number	Event Generator	Simulation	Detector Model	B Field [T]	Center of Mass Energy [GeV]	
zpole_noisr_LDC00Sc_6.0T_r1690_l2730_LCPhs_5	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2	
zpole_noisr_LDC00Sc_6.0T_r1690_l2730_LCPhs_4	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2	
zpole_noisr_LDC00Sc_6.0T_r1690_l2730_LCPhs_3	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2	
zpole_noisr_LDC00Sc_6.0T_r1690_l2730_LCPhs_2	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2	
zpole_noisr_LDC00Sc_4.0T_r1690_l2730_LCPhs_1	Pythia 6.321	Mokka 5.03pre	LDC00Sc	6	91.2	
zpole_noisr_LDC00Sc_4.0T_r1690_l2730_LCPhs_5	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2	
zpole_noisr_LDC00Sc_4.0T_r1690_l2730_LCPhs_4	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2	
zpole_noisr_LDC00Sc_4.0T_r1690_l2730_LCPhs_3	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2	
zpole_noisr_LDC00Sc_4.0T_r1690_l2730_LCPhs_2	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2	
zpole_noisr_LDC00Sc_4.0T_r1690_l2730_LCPhs_1	Pythia 6.321	Mokka 5.03pre	LDC00Sc	4	91.2	
zpole_noisr_LDC00Sc_2.0T_r1690_l2730_LCPhs_5	Pythia 6.321	Mokka 5.03pre	LDC00Sc	2	91.2	
zpole_noisr_LDC00Sc_2.0T_r1690_l2730_LCPhs_4	Pythia 6.321	Mokka 5.03pre	LDC00Sc	2	91.2	
zpole_noisr_LDC00Sc_2.0T_r1690_l2730_LCPhs_3	Pythia 6.321	Mokka 5.03pre	LDC00Sc	2	91.2	
zpole_noisr_LDC00Sc_2.0T_r1690_l2730_LCPhs_2	Pythia 6.321	Mokka 5.03pre	LDC00Sc	2	91.2	
zpole_noisr_LDC00Sc_2.0T_r1690_l2730_LCPhs_1	Pythia 6.321	Mokka 5.03pre	LDC00Sc	2	91.2	
			Mokka 5.03pre	LDC00Sc	4	500
			Mokka 5.03pre	LDC00Sc	4	500
			Mokka 5.03pre	LDC00Sc	4	500
			Mokka 5.03pre	LDC00Sc	4	500

- provide the simulated data that's needed
- exercise the software & computing infrastructure

Summary

- **LCIO**: Standard for ILC.

Controversial solutions on different sides of the Atlantic:

- **Conditions data**: Differences between **LCCD** and **org.lcsim** are of technical, not at all of philosophical nature.
- **Common source for the geometry**: Contradictory approaches. I don't dare to make any recommendation. Is there any convincing solution in other experiments?
- **Event viewer**: Many experiments use a variety of event viewers.
- **Framework**: **org.lcsim** vs **Marlin**: Unfortunate duplication of work ... but: an infinite amount of frameworks conceivably may meet our needs perfectly.
- **Choice of language**: Java or C++?
Every decent framework is requested to support both of them!

Conclusion

About religious wars

In Germany, we have quite some experience with them. Example: The War of Thirty Years (1618 – 1648) between catholic and protestant parties.

At the end, there were only losers, and the population decreased by 30% (in some areas by 100%). It was ended by a treaty called “Peace of Westphalia”.

And what was the outcome of this treaty? Religious freedom?

Conclusion

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The War of Thirty Years (1618 – 1648) between catholic and protestant parties.

At the end, there were only losers, and the population decreased by 30% (in some areas by 100%). It was ended by a treaty called “Peace of Westphalia”.

And what was the outcome of this treaty? Religious freedom?
Absolutely wrong!

The outcome was:

“The regional authorities decree the religion of their dependent subjects”

Let's avoid religious wars!

Save the manpower to work on real issues like PFA