

# **ILD Software**

## **Status and Plans – towards the TDR 2012**

Frank Gaede

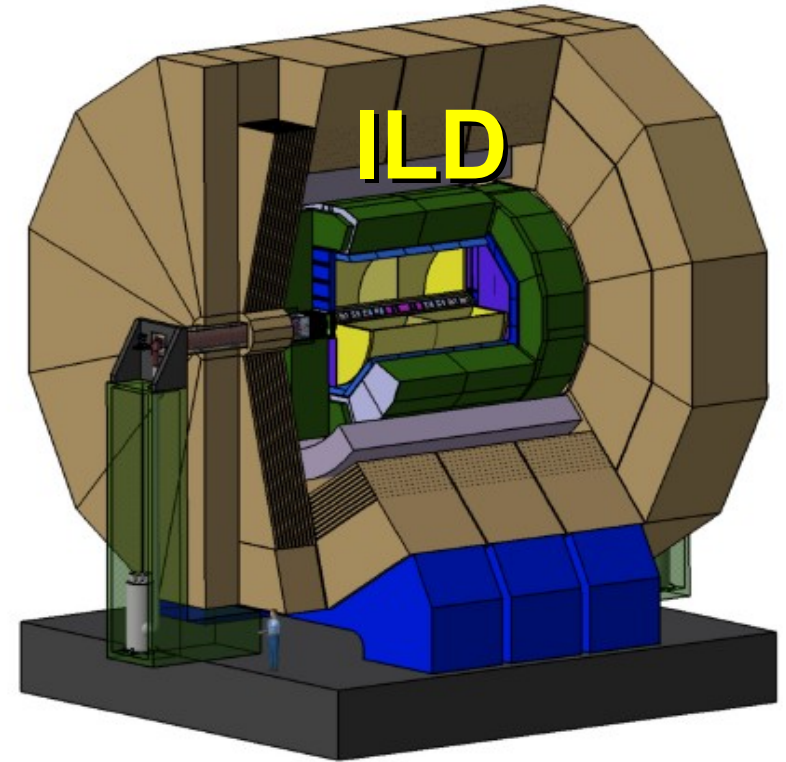
DESY

ILD Meeting

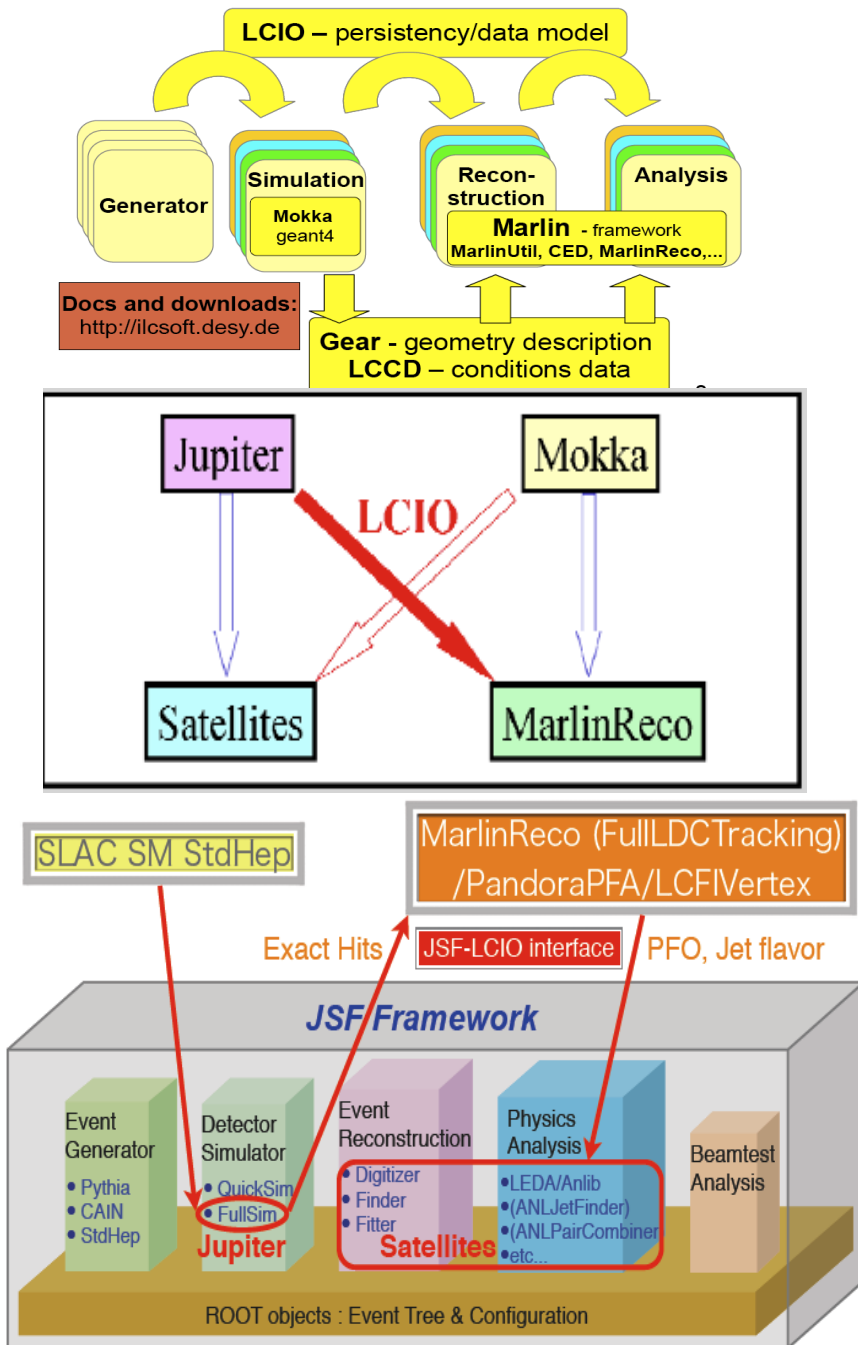
Albuquerque, October 1, 2009

# Outline

- Overview & Status
- Plans
  - framework
  - simulation, geometry, reconstruction
  - LCIOv2
- Timeline
- Summary & Outlook



# ILD Software Introduction



- ILD had two frameworks at beginning of LOI phase
- both frameworks 'battle proven' in massive Monte Carlo production
- interoperability provided by common usage of LCIO
- started to move towards a common ILD software framework – based on Marlin, LCIO with 'Goddies from Jupiter&Satellites

# ILD Core Software Tools

<http://ilcsoft.desy.de>

- **Mokka** (LLR)

- geant4 simulation application

- **LCIO** (DESY/SLAC)

- international standard for persistency format / event data model

- **Marlin**

- core application framework for reconstruction & data analysis

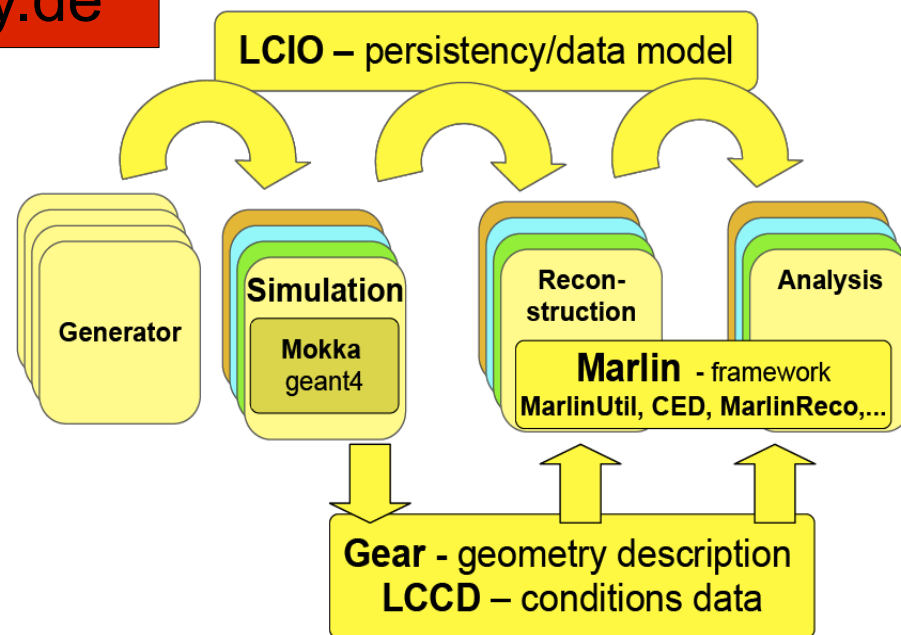
- **GEAR** geometry package f. reconstruction

- **LCCD**

- conditions
- data toolkit (DB)

- **CED**

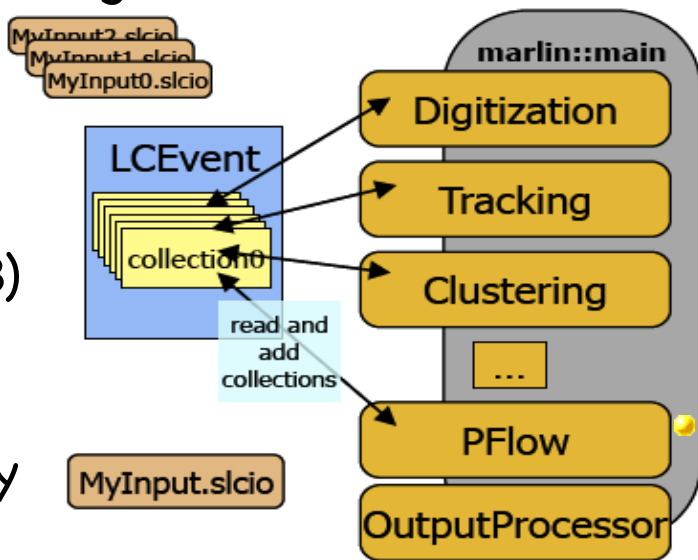
- 3d event display



- complete framework used in Monte Carlo & 'real experiments':

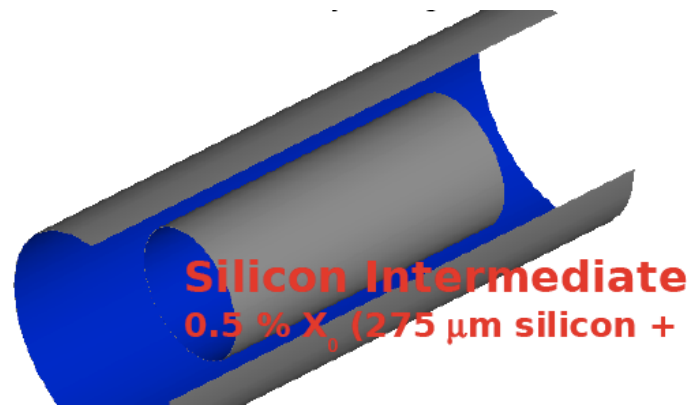
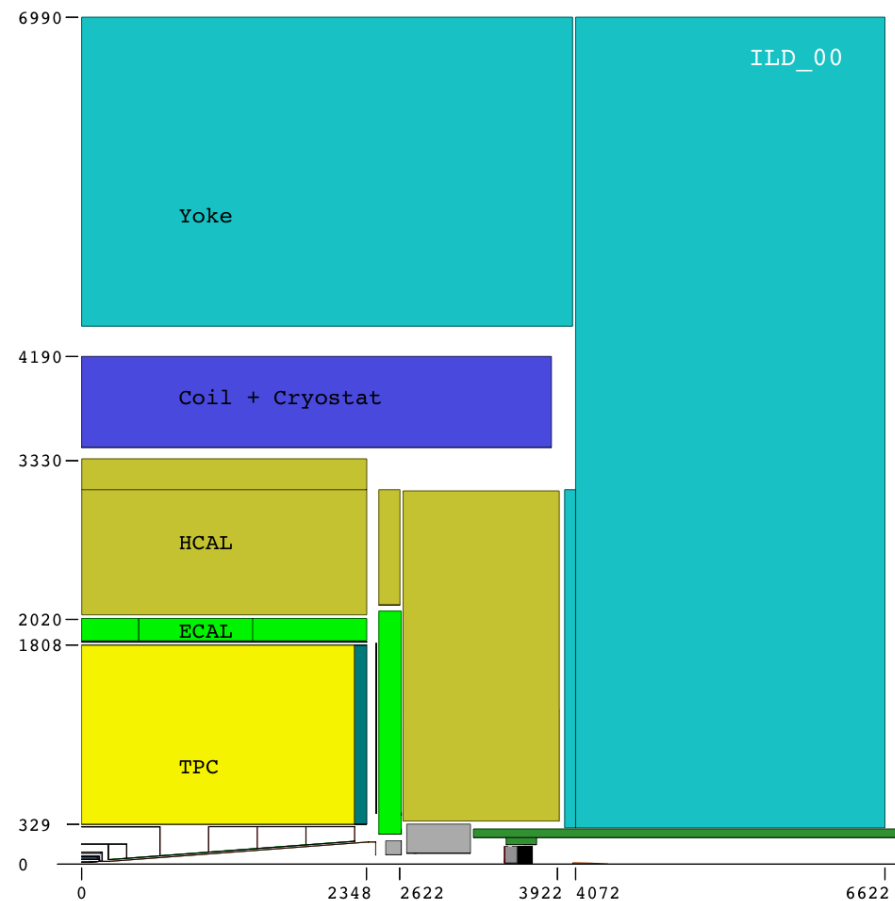
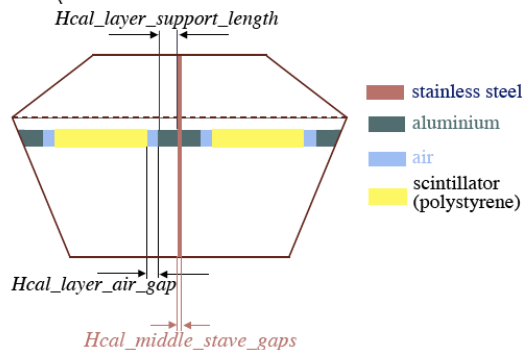
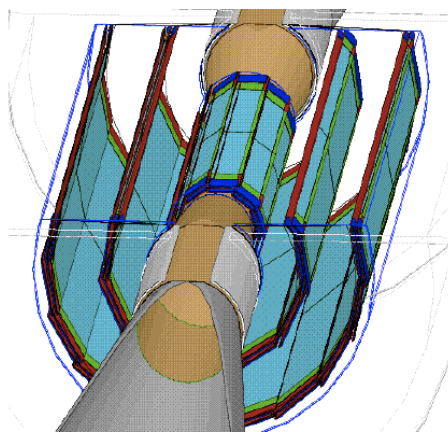
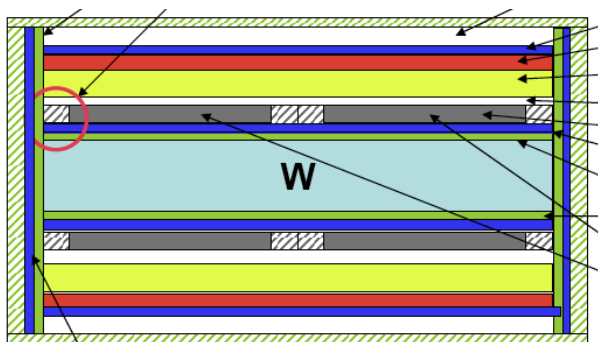
- **ILD detector concept** studies
- **Calice** calo testbeam
- **LC-TPC** testbeam
- EUDET - **Pixel Telescope**

- **synergies between testbeam and global detector optimization**



# Mokka Simulation

- defined 'ILD simulation reference model' after LOI optimization process LDC and GLD
- engineering level of detail for most subdetectors:
  - support structures
  - dead material (cabling, cooling)
  - cracks



# Marlin based Reconstruction

- Tracking
  - standalone tracking in Silicon detectors and TPC
  - Kalman filtering: wrapped f77 code from LEP
- Particle Flow Algorithm
  - PandoraPFA: best PFA to date
- JetFinder
  - Durham jet finder (run for 2-6 jets)
- Flavour Tagging
  - LCFIVertex package: ZVTop, ZVRes + Neural Network Fl.Tag
  - now maintained and improved by japanese groups !
- DST Maker
  - ReconstructedParticles, Jets, Tracks and Clusters (25k/evt)
- Overlay
  - overlay of fully simulated background events of N bunch crossings

- software was used quite successfully for the LOI:

*“The ILD efforts on simulating the physics benchmark processes have been impressive.”*  
**IDAG Report on the Validation of Letters of Intent for ILC detectors**

- however,  
after the LOI is only before the TDR ...

# preparing the ild software for the TDR

## Guideline for the Plan of the detector groups

1. Continue R&Ds on critical components to demonstrate proof of principle
2. Define a feasible baseline design  
(Options may also be considered. But one of them should be proven to be feasible.)
3. Complete basic mechanical integration of the baseline design accounting for insensitive zone  
(such as support structure, pipes, power lines etc.)

4. Develop a realistic simulation model of the baseline design, including faults and limitations

## Guideline (cont'ed)

5. Develop a push-pull mechanism working with relevant groups
6. Develop a realistic concept of integration with the accelerator including the IR design  
5&6: with GDE's BDS group through the MDI group
7. Simulate and analyze benchmark reactions, which can be updated
8. Simulate and analyze some reactions at 1 TeV, including realistic higher energy backgrounds demonstrating the detector performance.

8&9: Based on the work of the Physics Group and Software group.

The reaction will be chosen to show the strength of ILC compared to other facilities.



# Plans for ILD software

- at Cambridge decided to move towards common ILD software framework – developed plans in
- (bi)weekly ild-sw-mgmt meetings
- dedicated ILD software workshop in Tsukuba 2009
- bi-weekly software WG meetings:
  - merge goodies from JSF into framework
  - develop a test system
  - develop new GRID production system
  - improve the geometry description
  - improve the reconstruction (tracking & PFA)
  - develop LCIOv2
  - improve the simulation

# Merge goodies from JSF in to ildsoft

- port useful features of the core framework such as command line options to Marlin
- adopt selected JSF modules to be run as Marlin processors, e.g. the **QuickSim fast simulator**
- port subdetector simulation code from Jupiter to Mokka for technologies that are not present in Mokka, such as the **Scint. ECal**
- make existing analysis code from JSF available and compatible with LCIO (possibly via ROOT dictionaries)

# Test system for ILD software

- develop test system for ILD software including:
  - unit tests
    - 'technical' software tests on class/function level
  - integration tests
    - technical tests of packages and their interplay
  - physics quality
    - check algorithms, physics performances, hit maps,...
  - comment: such a test systems would probably have saved us some hassle in the past – and will make future development more efficient !
  - need to be pragmatic about this: look into existing testing tools and/or extend our installation toolkit

# new GRID production system

- during LOI Monte Carlo production realized that current system needed quite some manual interference and 'baby sitting'
- in order to save manpower with next major production started development of new GRID production system:
  - properly design data base schema (performance)
  - based on python scripts (flexibility & maintainability)
  - better robustness and error handling
  - easy to use (share work of production)

# develop a generic geometry Toolkit

- description of complex shapes, materials and sensitive detectors
  - with interfaces to:
  - full simulation programs (geant4, fluka?)
  - fast simulation programs
  - reconstruction algorithms
    - high level interface a la GEAR
    - questions that need to be answered during reconstruction tracking and clustering/PFA
  - visualization tools (ROOT, VRML, etc.)
- allow for **misalignment** of detector components
- small memory footprint
- efficient tracking in geometry hierarchy and fields
- ...

ideally collaborate with other HEP groups on that !

# Improve Reconstruction Tools

- **digitization:**
  - improve description of spacial resolution (R&D groups)
  - introduce ghost hits for strip detectors
- **tracking:**
  - **develop modern tracking and pattern recognition software to replace f77 LEPTracking**
    - proper treatment of strip detectors
    - tracking in non-uniform B field (anti-DID)
- **clustering/PFA**
  - modularize and improve PandoraPFA

needed for  
proper background  
studies !

# LCIOv2

- improve LCIO -> LCIOv2
- event data model
  - 1d, 2d hits
  - Track class - multiple fits per track
- Improve I/O
  - splitting of files
  - direct access
  - partial reading of events
- investigate the use of ROOT with LCIO
  - LCEvent in ROOT macros
  - look into optional ROOT I/O for LCIO

continue successful horizontal collaboration with SID on LCIO

# ROOT I/O for LCIO

- started to investigate optional ROOT I/O for LCIO
  - created **dictionary** with rootcint for LCIO classes
    - thanks to ROOT team for their help and for adding some features to ROOT 5.24.00 needed for LCIO
    - => write and read LCEvents transparently to/from ROOT files
      - no change in user code !
    - => use LCEvents in ROOT macros
      - rapid development of analysis code based with LCIO in ROOT !
  - issues:
    - no branches due to pointers between object
    - no partial reading and splitting of events over files
    - need proper interface to ROOT I/O for java implementation
- > need to work with ROOT team to resolve these issues...



# Extend and Improve Simulation

- need 'baseline detector' in simulation, with
  - proven subdetector technology
  - including realistic description of 'faults and imperfections'
- need to develop additional technology subdetector drivers for Mokka, such as:
  - SciEcal and DHCAL options (ongoing)
  - FPCCD vertex detector
- need to improve realism for some subdetectors wrt. LOI model ILD\_00, eg.
  - silicon trackers: SIT, SET, ETD, FTD (currently cylinder and disks w/ parameterized support material)

# improving the simulation

- almost all of the Mokka subdetector drivers have been written by experts from the R&D groups
- this is of course the right approach as it ensures that 'state of the art' sub detector description is used
- ideally it should also be the detector R&D groups that maintain the simulation code, ie. test, debug and further improve it
- would like to have one name per subdetector that is responsible for the simulation and serves as contact to the core software group !

# what level of realism is needed ?

- Mokka simulation already quite realistic for some detectors - clearly need to improve for others ?
- how **realistic** do we have to be ?
  - describing every cable and every nut and bolt is neither feasible nor necessary
  - need to be realistic with cracks and clearances (for cable channels etc.)
  - need to get good estimate from R&D groups/ MDI group on cable/support material budget
- in any case what eventually can be done depends on the effort in terms of manpower
- and the discussion within ILD !

# timeline for ILD software development

t0	hand in TDR	13 month
5 month	Analysis and Writing	
t0 - 5m	Monte Carlo production finished	
5 month	Grid Production	
t0 -10m	start Monte Carlo production	
3 month	Test, Debug and release ILDsoft	
t0-13m	freeze ILDsoft development	14-26 month
>1 month	implement baseline in simulation	
t0-x	ILD baseline defined	
	evaluate technology options develop tracking package develop geometry LCIOv2 improve simulation realism improve reconstruction study machine backgrounds ...	

13 month prior to hand in of TDR are **fixed**

depending on actual t0 we have ~1-2 years for software developments...  
 e.g. t0=Oct 2012  
 => 23 months from now !

# Summary

- ILD has a complete software framework that is battle proven in LOI mass production for detector optimization and physics analyses
- now entered new phase:
  - merging the two frameworks into one common ILD framework
  - further improve the tools to get ready for the TDR 2012
- already have quite ambitious plans for software development – clearly need support from ILD
- in the end what can be done realistically depends on the TDR-t0 and on the effort that we put into the software development