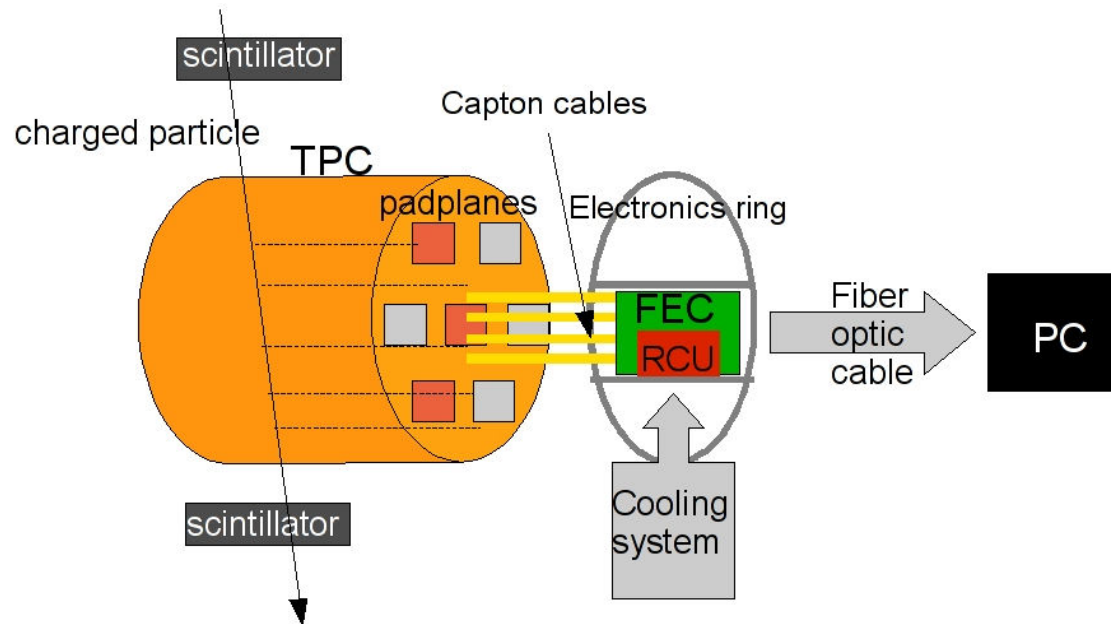
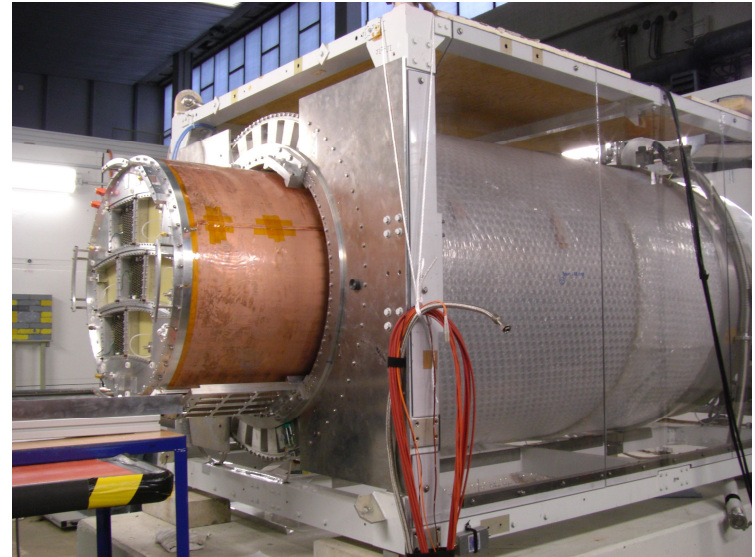
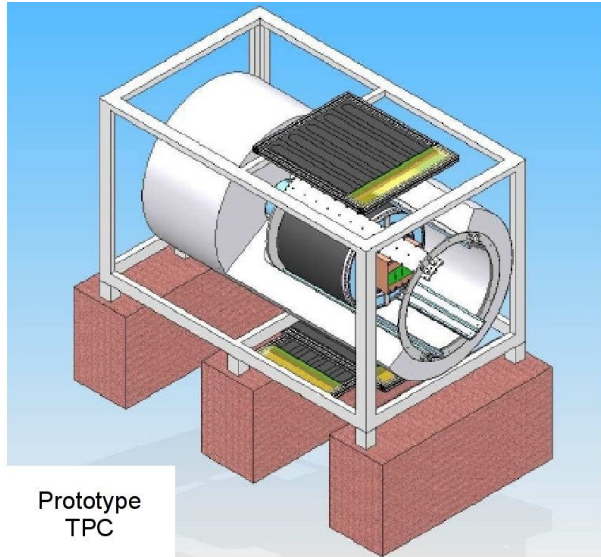


Track analysis
from the beam tests
with the Japanese GEM's
and the Altro electronics

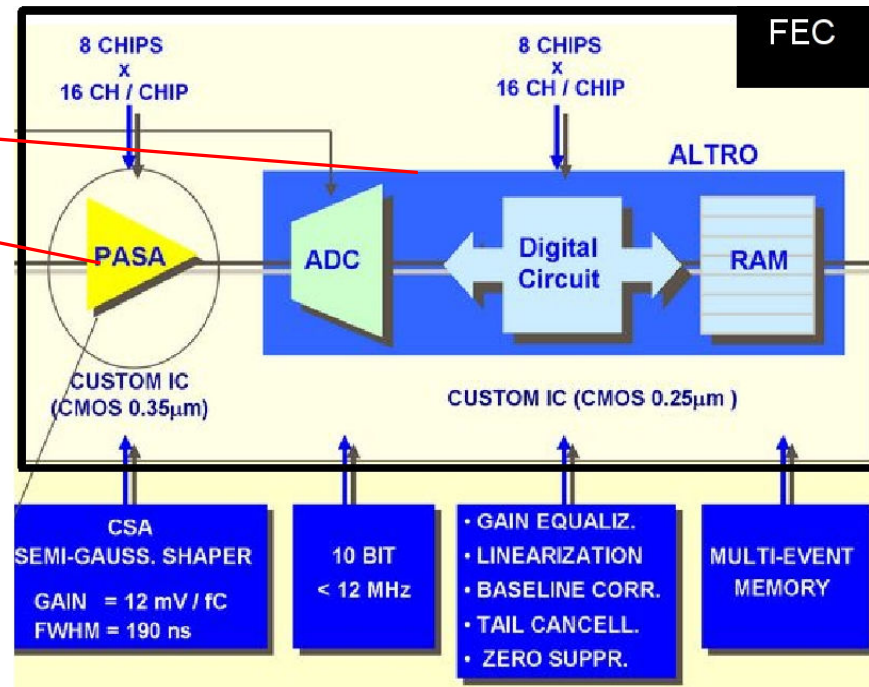
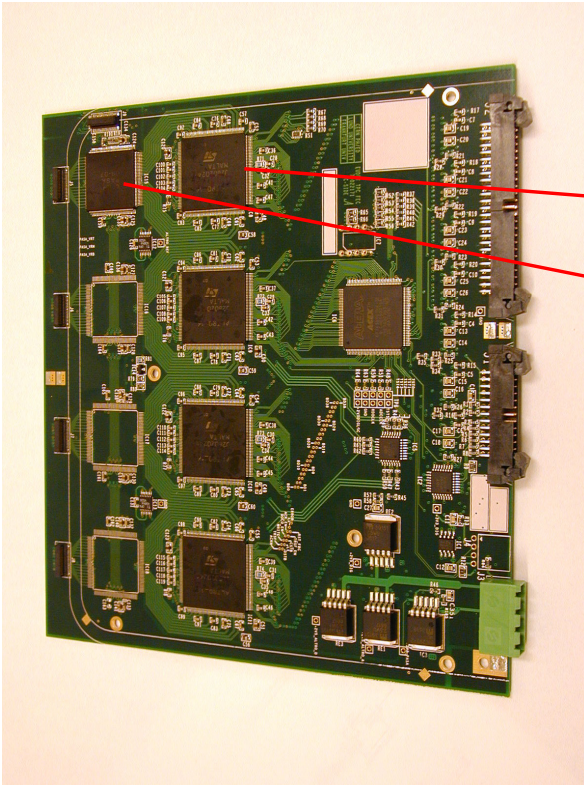
(Performed by Tuva Richert and Lene Bryngemark)

(Presented by Leif Jönsson)

The set-up



The front end card



PCA16: Charge sensitive amplifier

Parameter choice:

Gain: 12, 15, 19, 27 mV/fC

Shaping time: 30, 60, 90, 120 ns

Can also be run in non-shaping mode
with variable decay time

Altro:

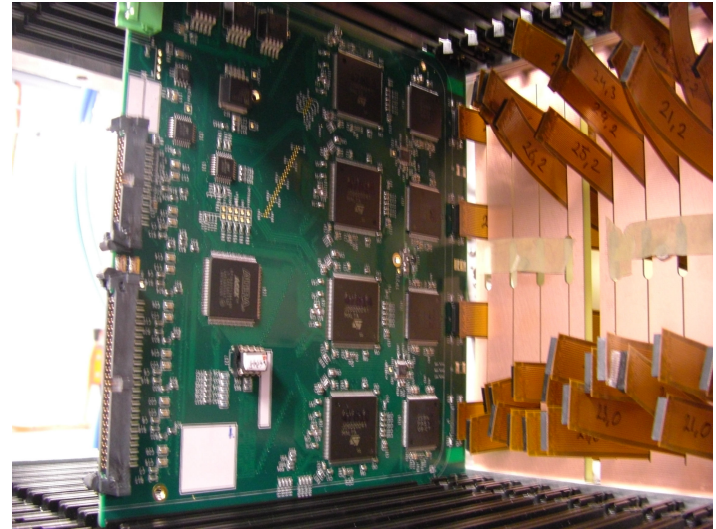
ADC digitizes the PCA16 analogue signal
of 1.2 V to a 10 bit digital value

Sampling frequency: 20 MHz (40 MHz)

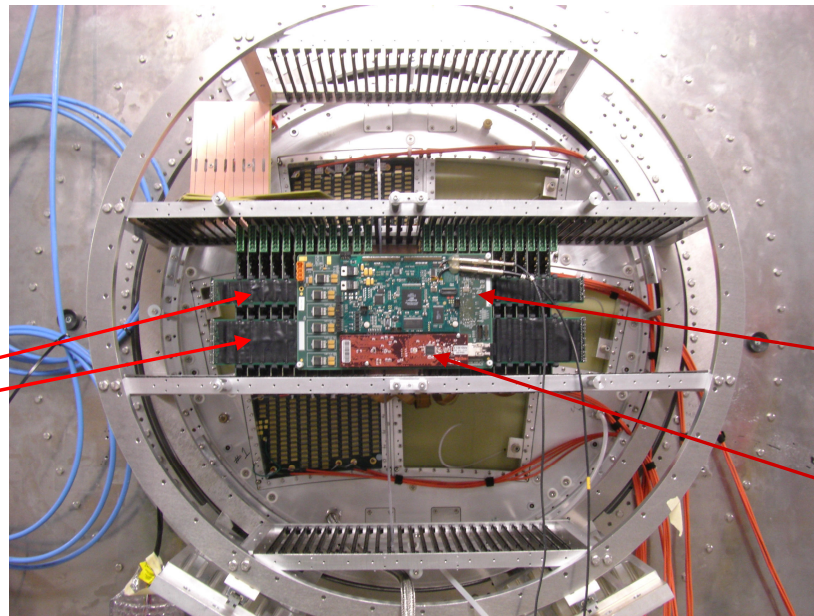
Buffers data while waiting for store/discard
decision

Perform pedestal subtraction and zero
suppression

What it looks like in real life



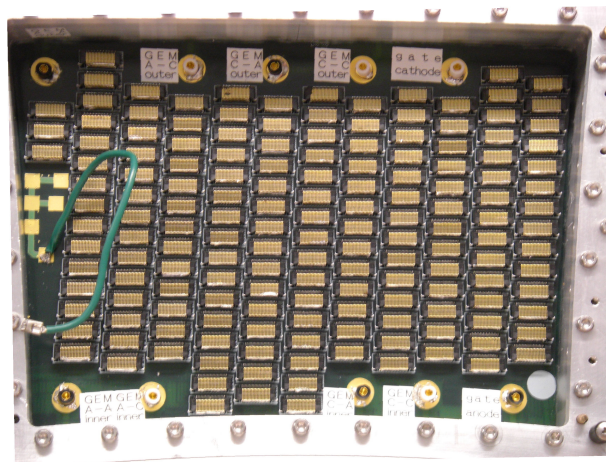
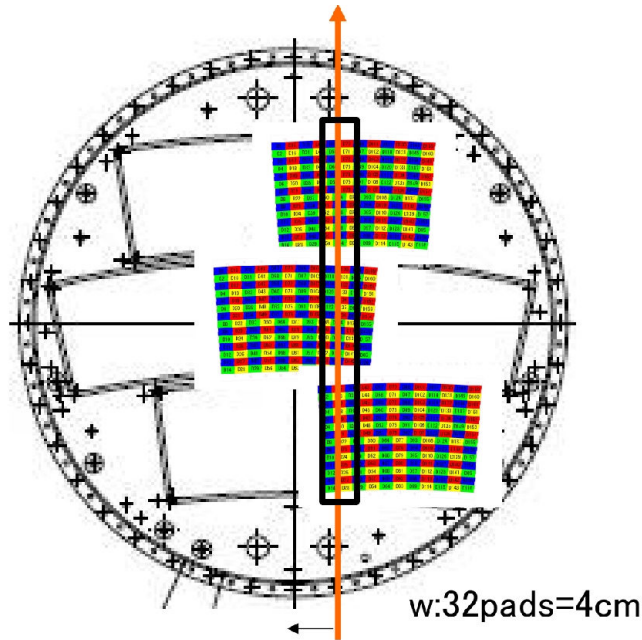
Backplanes



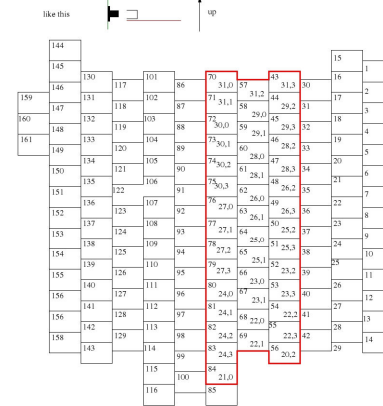
RCU
(Readout Control Unit)

SIU
(Source Interface Unit)

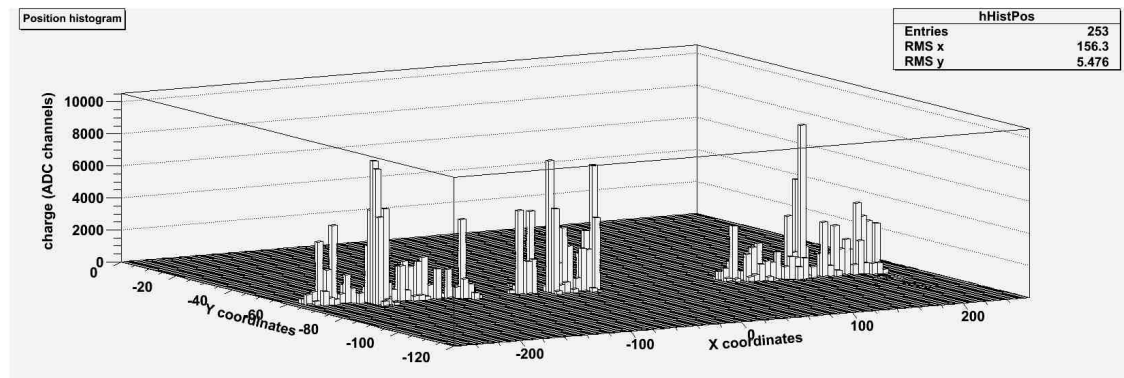
Modules and pad arrangement



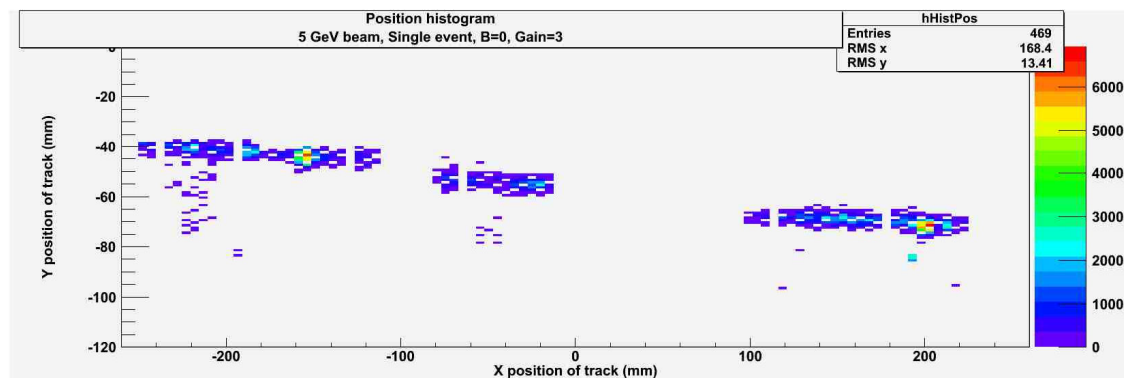
Final connection of cables at DESY Feb 22/09, seen from outside the TPC.
Connectors placed with the flat cable on the below side of the connector



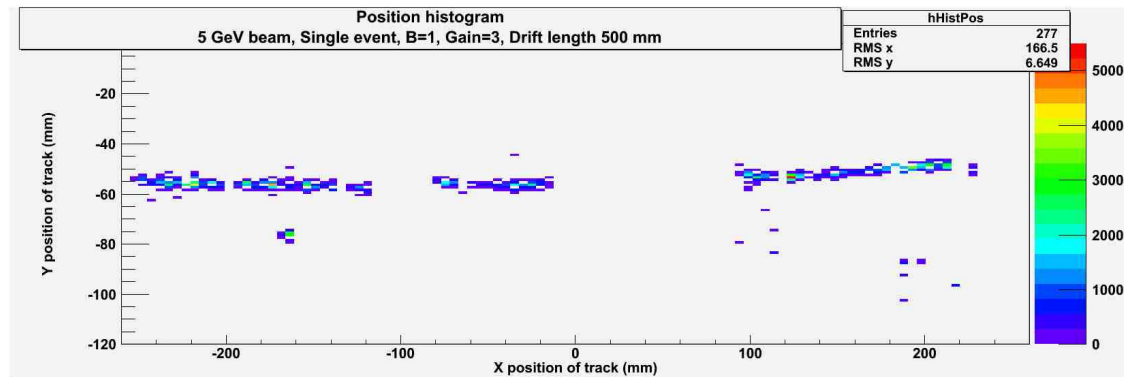
Track visualization



5 GeV electrons
B=0 Tesla
Drift length 200mm



5 GeV electrons
B=1 Tesla
Drift length 200 mm

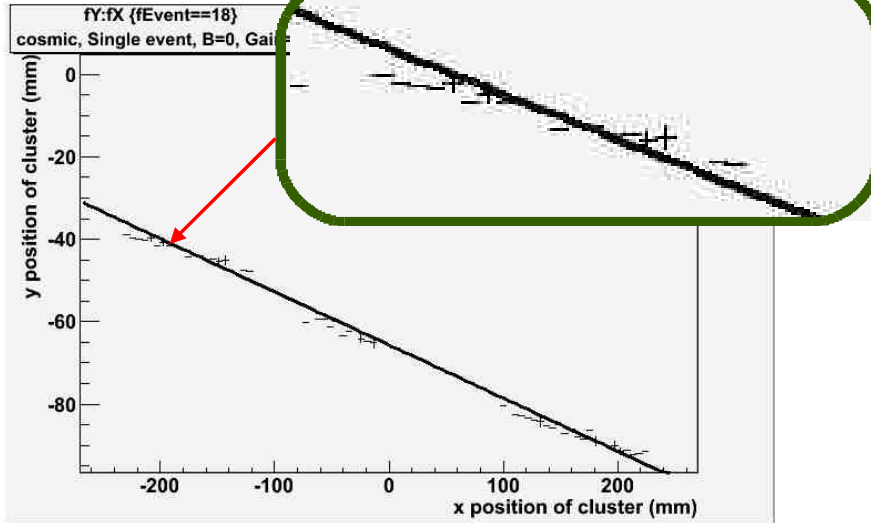


Cluster finding and track reconstruction

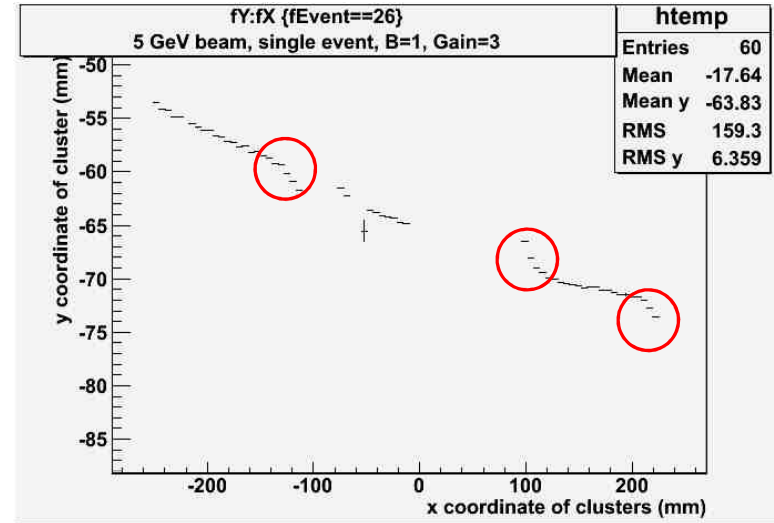
- Find peak of charge distribution for each pad row \Rightarrow cluster
- Calculate the weighted mean position of the cluster;
 $\langle y \rangle = \Sigma Q_i y_i / \Sigma Q_i$ where y_i is the pad position and Q_i is the charge on pad i
- Translate position to space coordinates
- Fit a polynomial \Rightarrow distance from the "real track" to reconstructed track
 $= \Delta Y$ (residual)
- Histogram the residuals
- Fit a Gaussian
- The standard deviation corresponds to the position resolution

Track studies

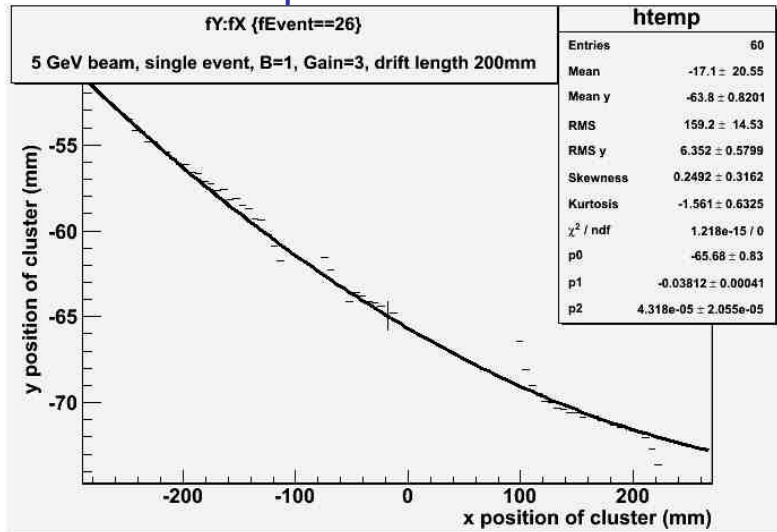
B=0



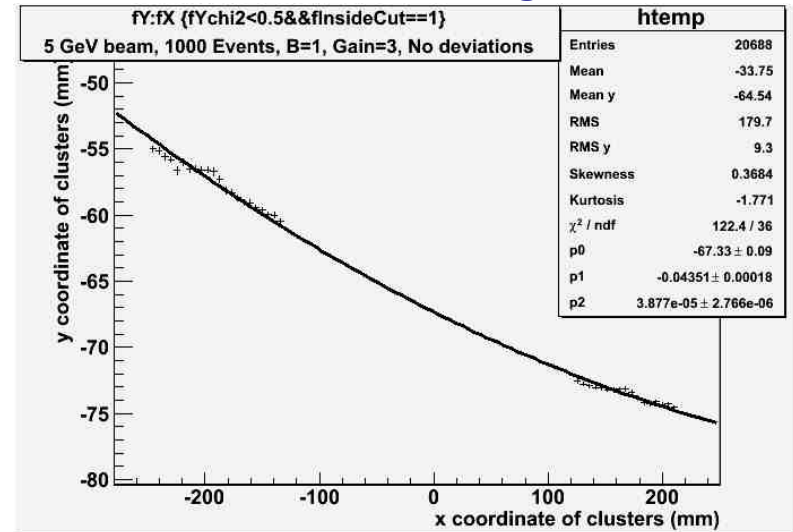
B=1



B=1 fit to all points

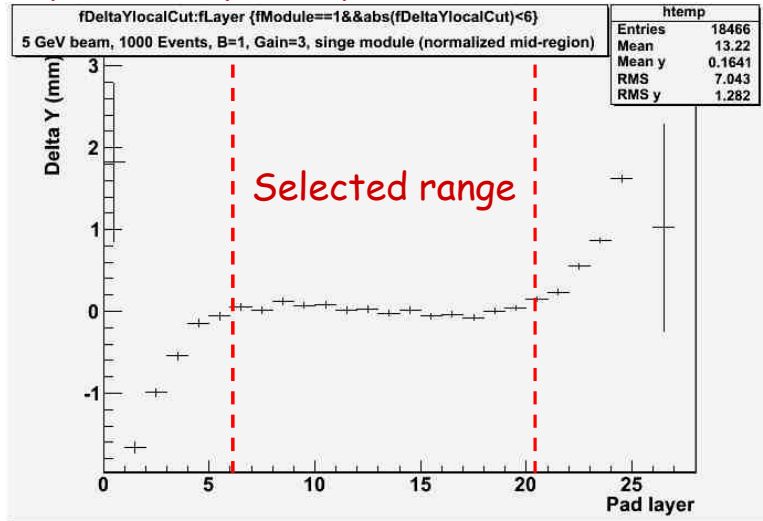


B=1 fit with distorted regions removed

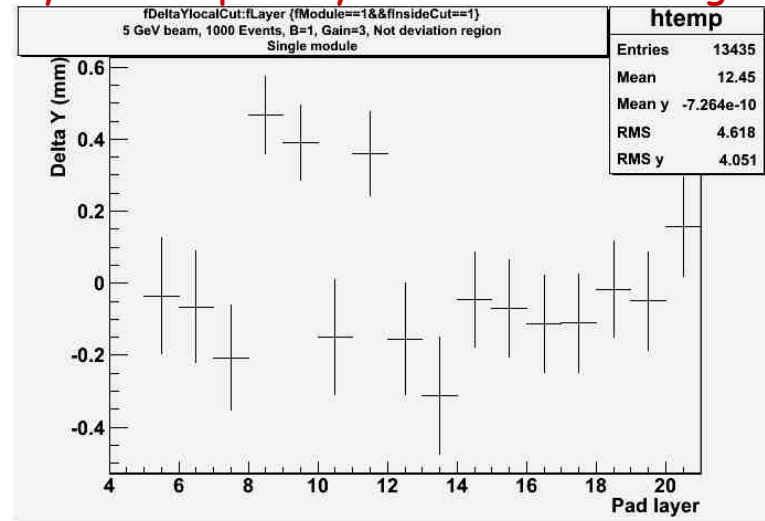


Position resolution

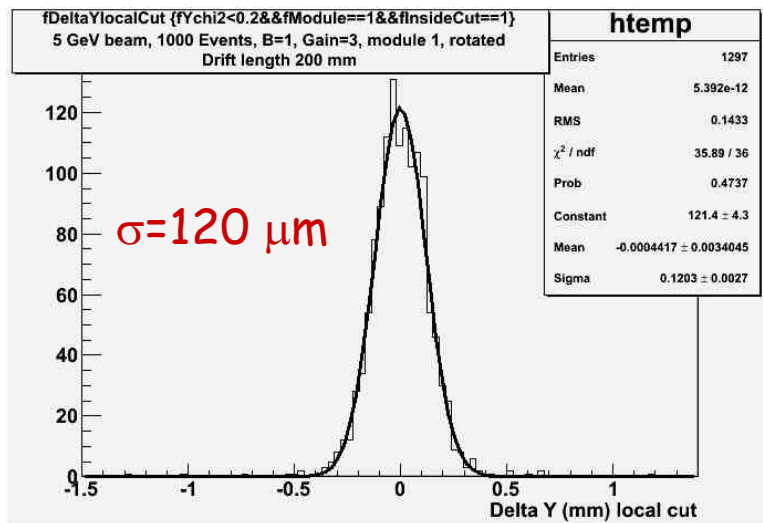
Δy versus pad layer



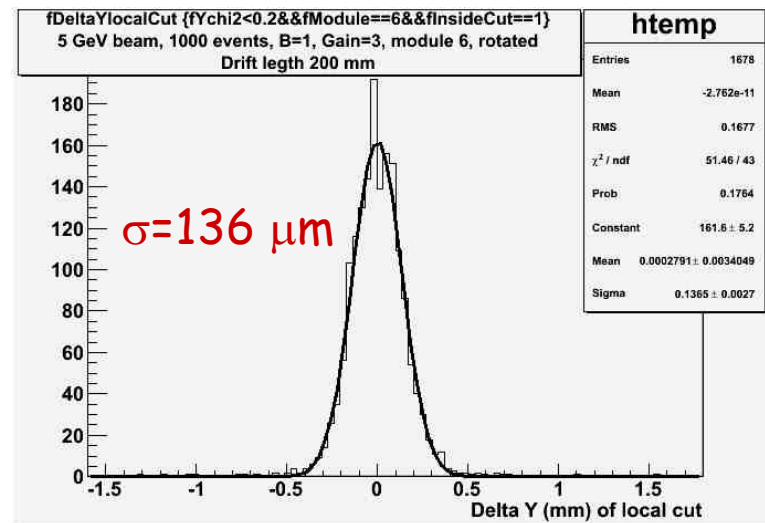
Δy versus pad layer in selected range



Distribution of residuals; module 1



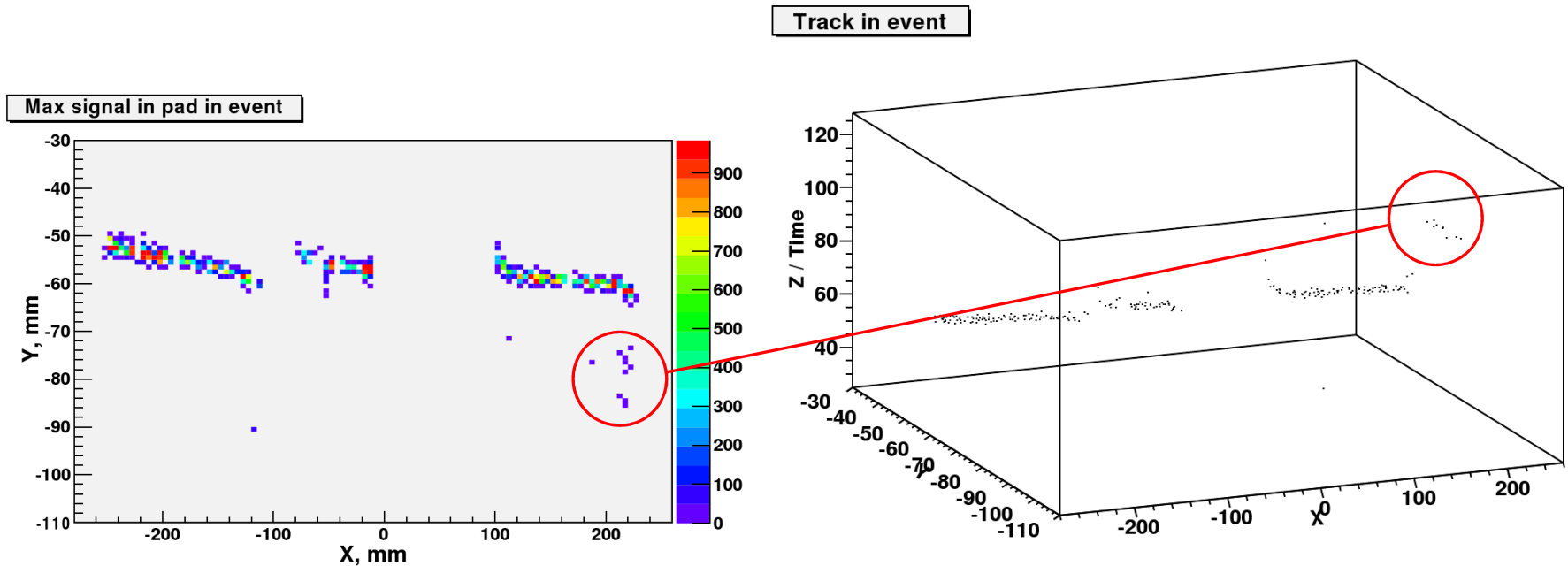
Distribution of residuals, module 3



Drift time (z-coordinate)

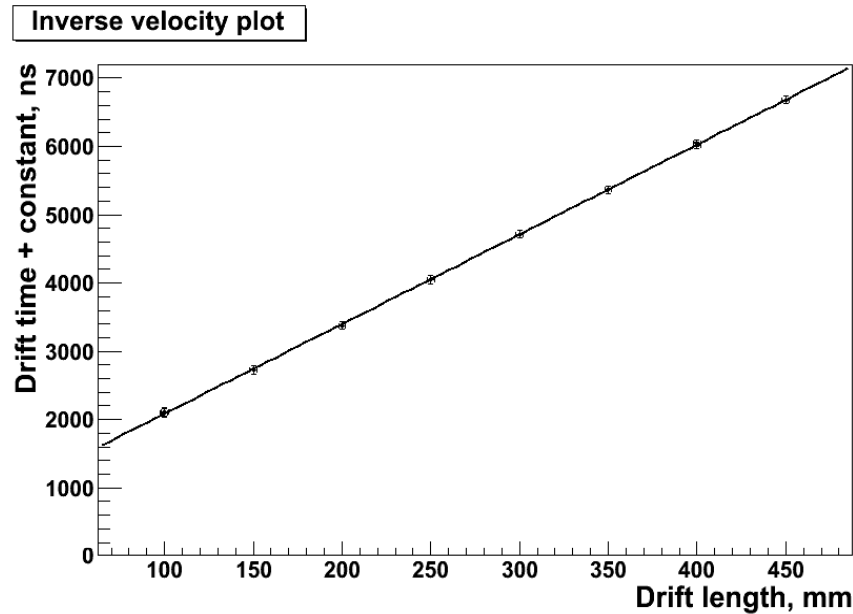
5 GeV electrons
B=1 Tesla

The z-axis is given in time bins of
50 ns/bin



The noise region can be removed by applying a cut in time (or z)

Drift time measurement



The drift time is taken to be the mean of a Gaussian distribution in the z-direction fitted to the first non-zero sample of every readout channel in a run

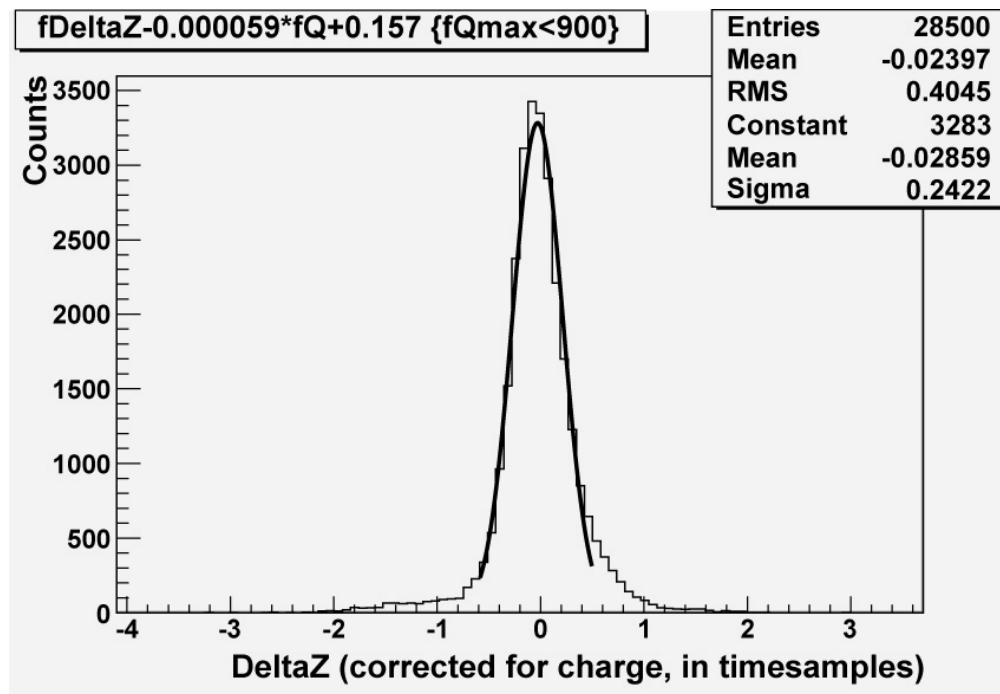
The offset is due to the time it takes for the electrons to travel from the trigger telescope to the TPC and for the electronics to respond to a trigger signal

⇒ drift velocity: 7.62 ± 0.09 cm/ μ s

⇒ drift length of 3.8 mm per time sample (at 20 MHz readout)

The z-resolution

- Fit a first order polynomial to the cluster coordinates in the z direction
- Histogram deviations of cluster times to the fitted line \Rightarrow distribution in Δz
- Fit a gaussian to the Δz distribution
- The standard deviation (σ) gives the resolution



Result: 0.242 ± 0.002 time samples $\Rightarrow 0.920 \pm 0.007$ mm

Conclusions

- Tracks read out by GEM's and the Altro electronics have been studied.
- Results on position resolution in the x-y plane of $120\text{-}130\text{ }\mu\text{m}$ was obtained
- The drift velocity was measured to $7.62\pm0.09\text{ cm}/\mu\text{s}$ and the resolution in the z-direction was determined to $0.920\pm0.007\text{ mm}$
- For B=0 Tesla, some deviations from a straight track is observed, which might indicate misalignment or rotations of the modules with respect to each other
- For B=1 Tesla, distortion of the tracks are observed at the edges of the modules. This might be due to the influence of the GEM support structure on the electric field.