

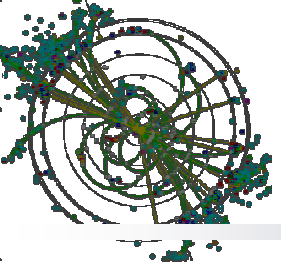
# Chronopixe first prototype tests



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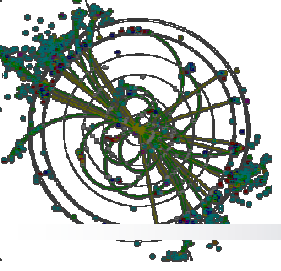
EE work is contracted to Sarnoff Corporation



# Outline of the talk



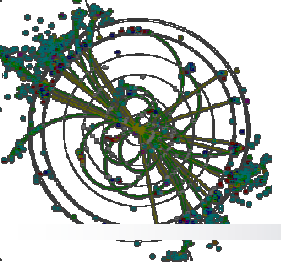
- **Recall how chronopixel works**
- **Milestones**
- **Test stand design and software**
- **Test results**
  - ↪ **Problem with power distribution found**
  - ↪ **Performance parameters**
  - ↪ **Noise level**
  - ↪ **Comparators offsets spread**
  - ↪ **Fe55 source test**
  - ↪ **Leakage currents.**
- **Conclusions**
- **Next steps**



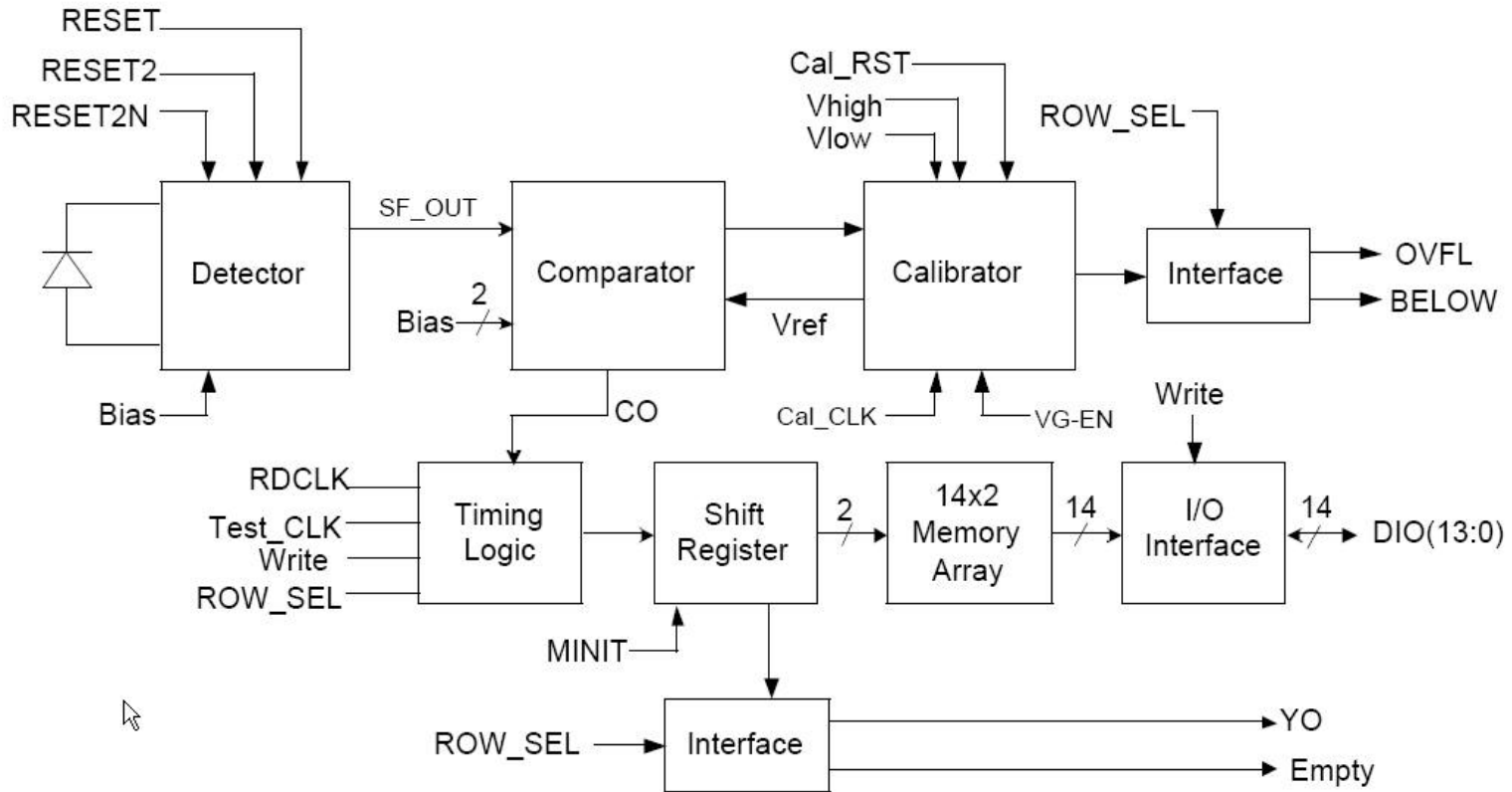
# How Chronopixel works



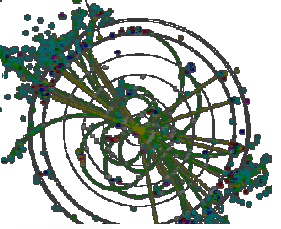
- When **signal** generated by particle crossing sensitive layer **exceeds threshold**, snapshot of the **time stamp**, provided by 14 bits bus is **recorded** into pixel memory, and **memory pointer is advanced**.
- If **another particle** hits the same pixel during the same bunch train, **second memory cell is used** for this event time stamp.
- During readout, which happens between bunch trains, **pixels which do not** have any time stamp **records**, generate **EMPTY** signal, which **advances IO-MUX circuit to next** pixel without wasting any time. **This speeds up readout** by factor of about **100**.
- **Comparator offsets** of individual pixels are determined in the **calibration cycle**, and reference voltage, which sets the comparator threshold, is shifted to **adjust thresholds** in all pixels to the **same signal level**.
- To achieve required noise level (about **25 e r.m.s.**) **special reset circuit (soft reset with feedback)** was developed by **Sarnoff designers**. They claim it reduces reset noise by **factor of 2**.



# Simplified Chronopixel Schematic



**Essential features: Calibrator, special reset circuit**



# Calibration procedure

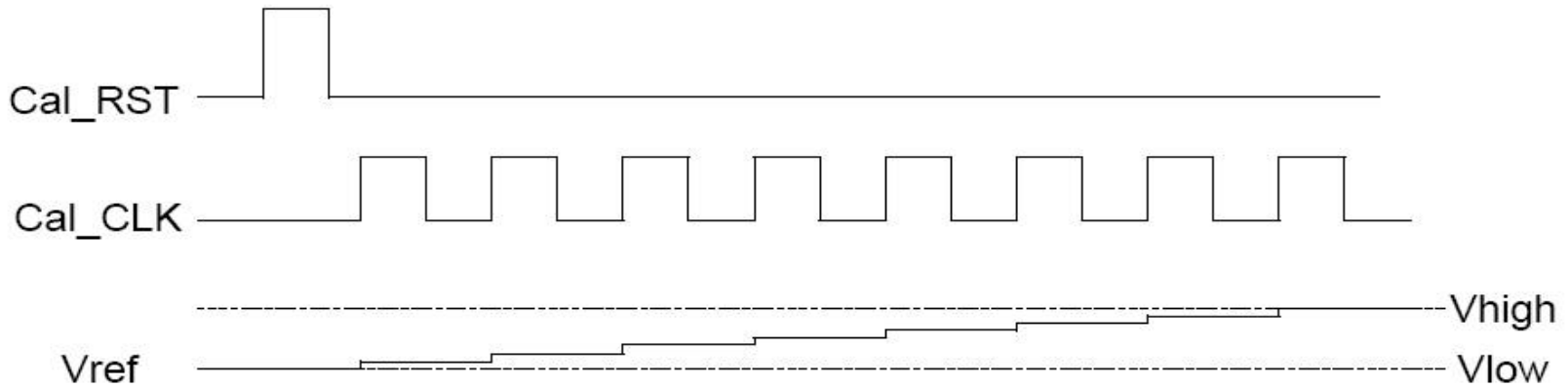
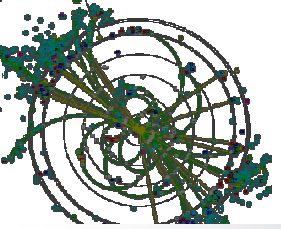


Figure 10.3 Timing diagram showing the calibrator operation

- During calibration, comparator **reference** voltage **changes** from  **$V_{low}$  to  $V_{high}$  in 8 steps**, controlled by **Cal\_CLK** clock pulses. As soon as it **reaches** the value when **comparator flips**, state of the clock counter is **recorded** into **calibration register** – individual for each pixel. During normal operation this **register** is **used** to set comparator **offset** for a given pixel.



# Sensor design

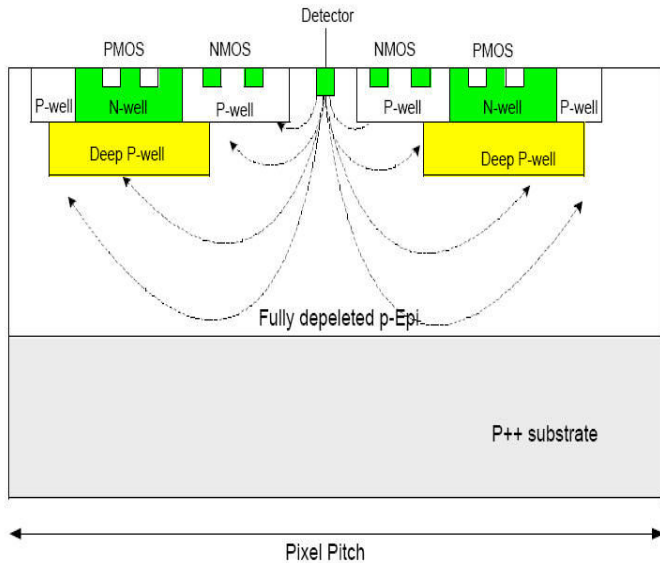


Figure 11.1 Proposed pixel architecture employing the deep p-well layer

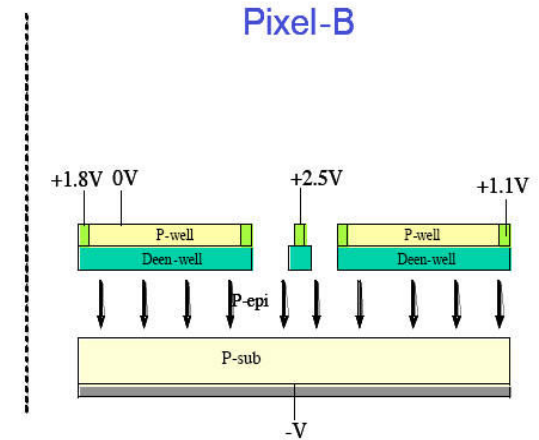
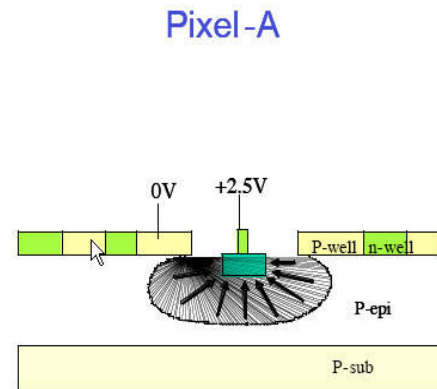
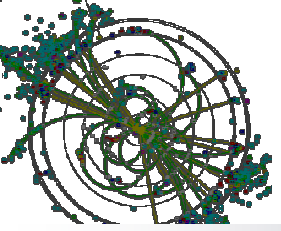


Figure 6.3 Comparison of the vertical cross section views of two pixels

## Ultimate design, as envisioned

## Two sensor options in the fabricated chips

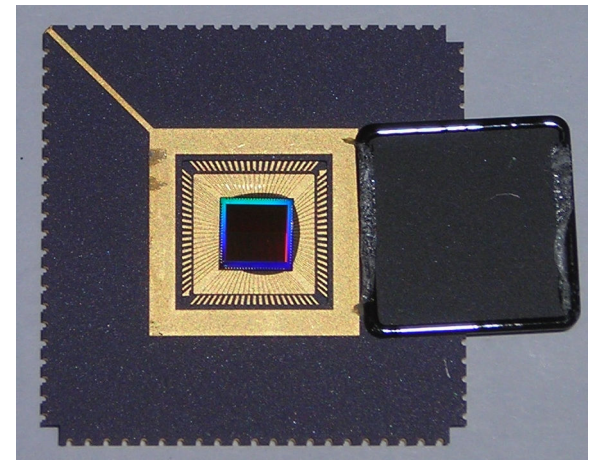
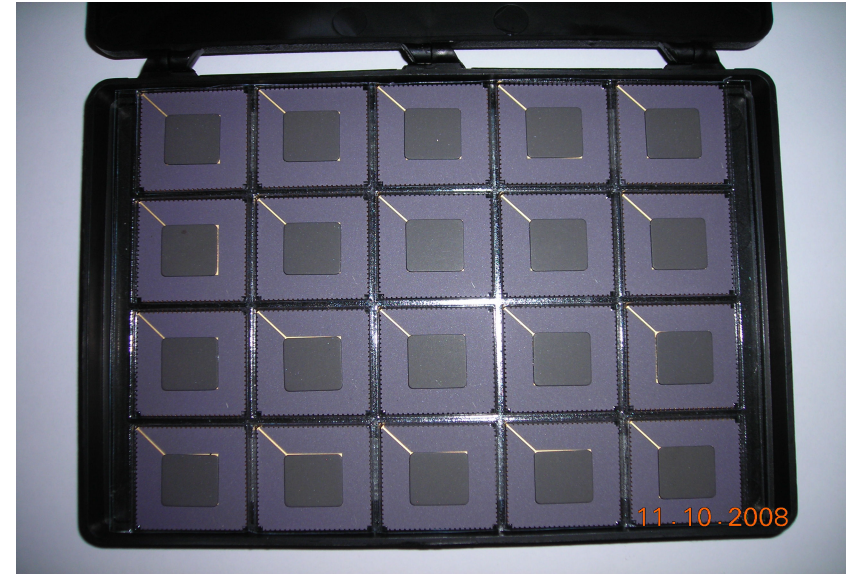
- TSMC process **does not** allow for creation of **deep P-wells**. Moreover, the test chronopixel devices were **fabricated** using **low resistivity** ( $\sim 10 \text{ ohm}\cdot\text{cm}$ ) epi layer. To be able to achieve comfortable depletion depth, Pixel-B employs **deep n-well**, **encapsulating** all **p-wells** in the NMOS gates. This allow **application of negative** (up to **-10 V**) bias on **substrate**.



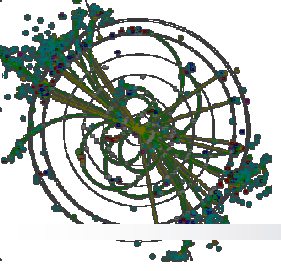
# Milestones



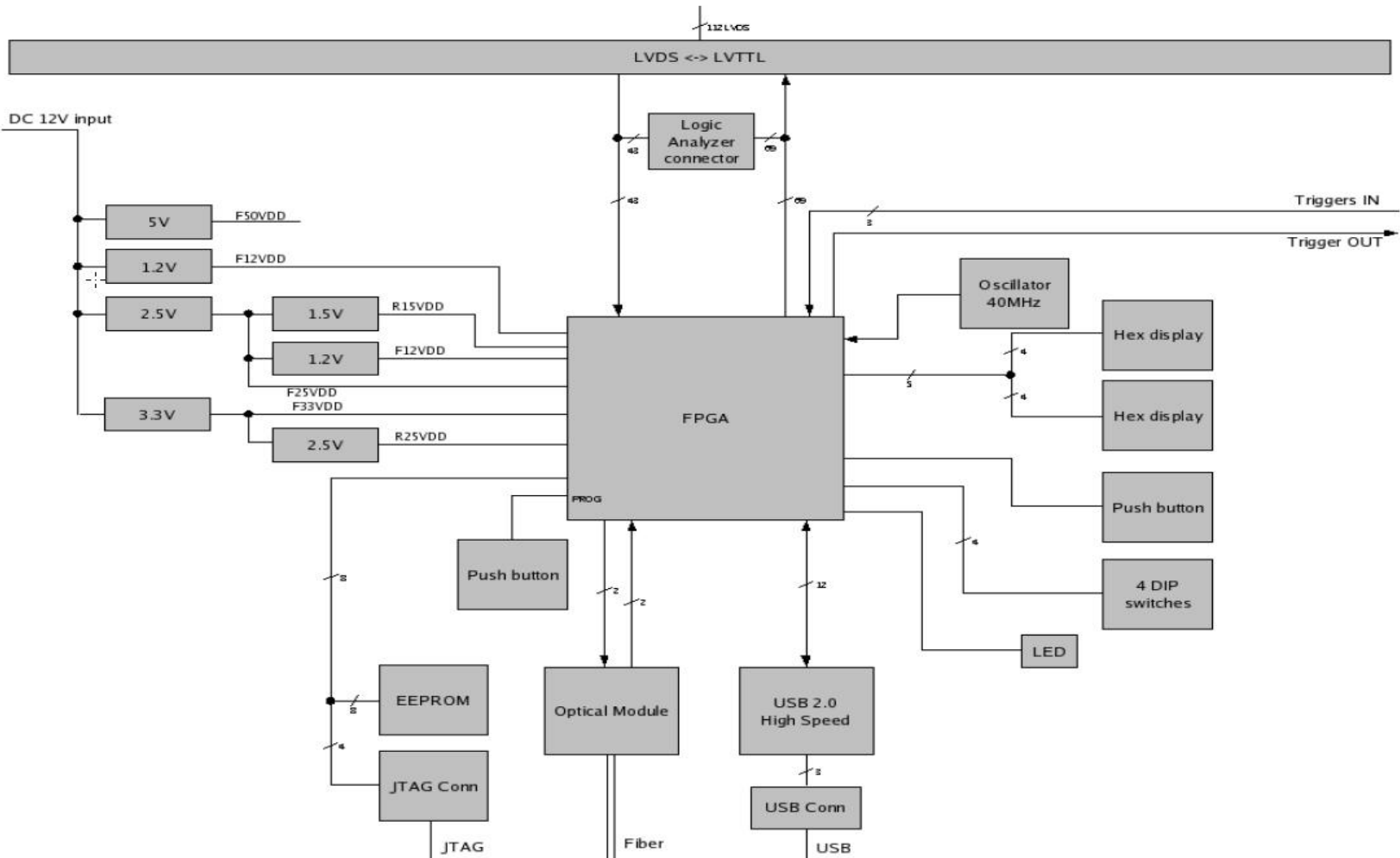
- January, 2007
  - ✧ Completed design – Chronopixel
    - ❖ **2 buffers, with calibration**
- May 2008
  - ✧ Fabricated 80 5x5 mm chips, containing 80x80 50  $\mu\text{m}$  Chronopixels array (+ 2 single pixels) each
  - ✧ TSMC 0.18  $\mu\text{m}$   $\Rightarrow$  ~50  $\mu\text{m}$  pixel
    - ❖ Epi-layer only 7  $\mu\text{m}$
    - ❖ Low resistivity (~10 ohm\*cm) silicon
    - ❖ Talking to JAZZ (15  $\mu\text{m}$  epi-layer)
- October 2008
  - ✧ Design of test boards started at SLAC
- June 2009
  - ✧ Test boards fabrication. FPGA code development started.
- August 2009
  - ✧ Debugging and calibration of test boards
- September 2009
  - ✧ Chronopixel chip tests started
- February 2010
  - ✧ Chronopixel chip tests completed



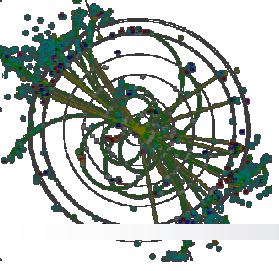




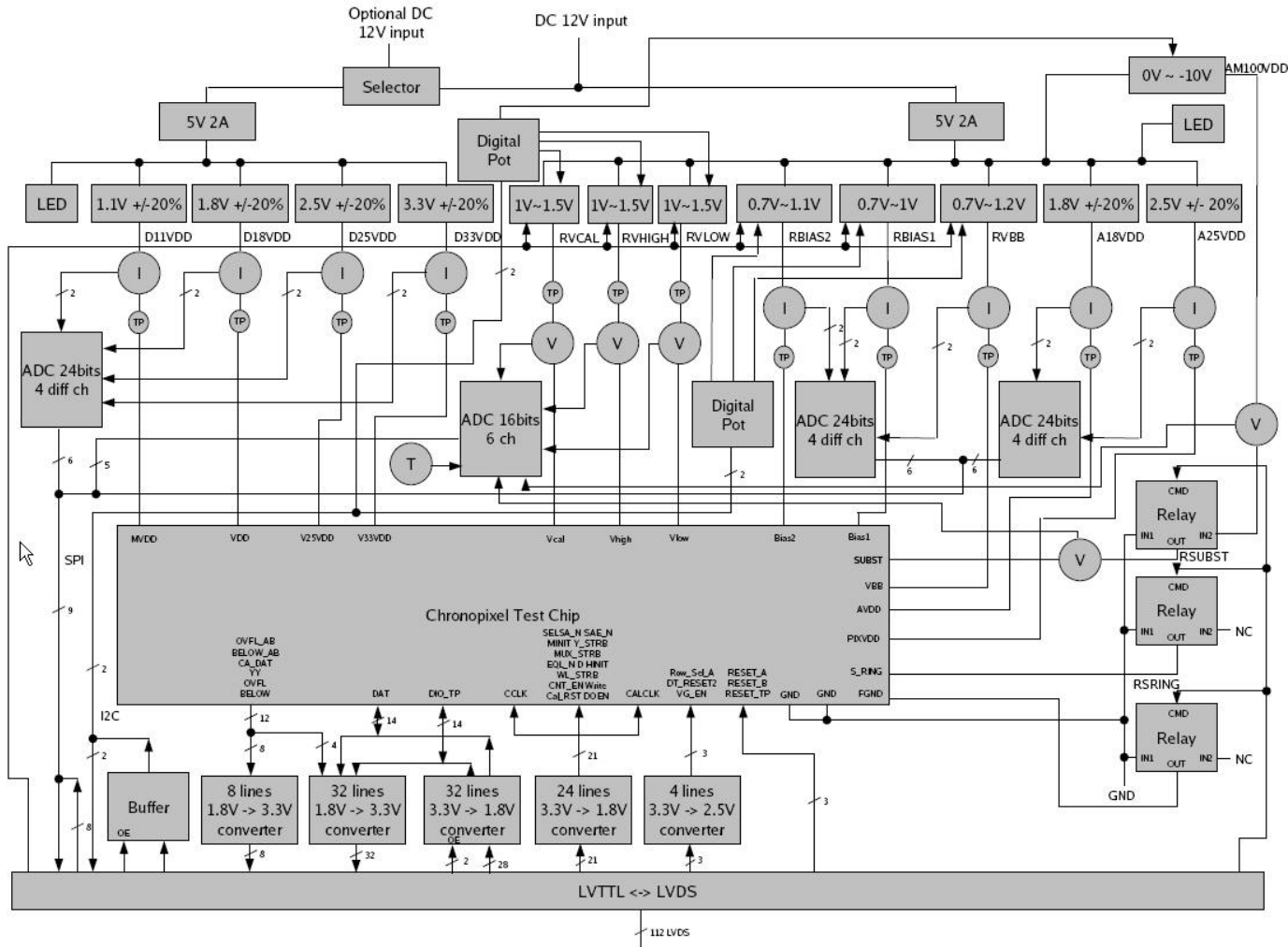
# Test stand design. Block-diagram of FPGA board

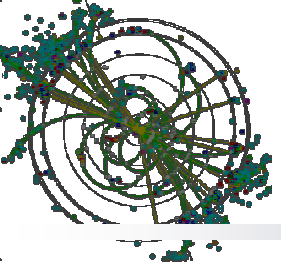






# Block-diagram of chronopixel test board

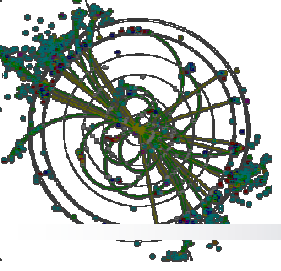




# Test stand software



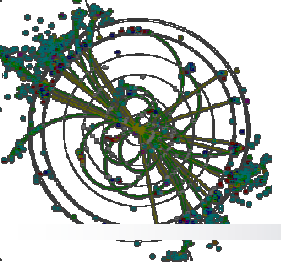
- **Since May 2008 I started development of test stand software.**
- **Graphical User Interface was developed on the basis of Motiff library for Unix.**
- **Main idea of how to provide large number of different control signal waveforms was to use very fast waveform memory in the Xilinx FPGA. Memory has 32 bit wide words, and its capacity is 4096 such words. Each bit of the memory output register is connected to some of chronopix control signal wire. Memory address is increasing with 80 MHz rate. So control signals have time bin width of 12.5 ns.**
- **There is another, larger memory (24 bits wide 16 kwords) for storing read back data from chrono pixels.**
- **Everything in test stand software is configured by set of text files in configuration directory. These text files contain all voltage settings, all waveforms information and list of all monitored voltages and currents together with calibration constants.**



## Test stand software - continue



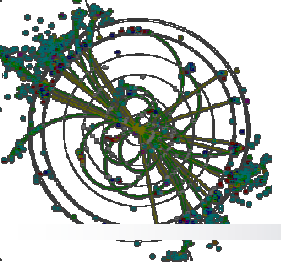
- **Configuration directory also contains list of commands, which are assigned to buttons on the GUI. This list can be changed, and command buttons number and assigned commands will change without need of any code recompiling.**
- **All commands (performed by button clicks), are automatically saved in log files. Log files are named by current date, and each day will have only one log file, even if you restart GUI many times. Log file contains also all voltage settings.**
- **Another file, automatically created and filled is the monitored values records.**
- **Yet another files, created automatically by some of the tests – KUMAC files for use with PAW**
- **For every KUMAC file, record in the testcond.txt file is created, containing specific settings for the test and operator comments.**



# Test Stand GUI



Exit										Plot monitors										Plot waveforms										HELP									
date:	Feb 16 2010			time:	11:23:40			Power:	ON			Sensors:	OFF			mon.int(ms):	2000																						
V33Vdd	3.2797			I33Vdd	1.9722			V25Vdd	2.5098			I25Vdd	3.0330			V18Vdd	1.8146																						
I18Vdd	19.4180			VMVdd	1.2295			IMVdd	2.8224			VPixVdd	2.1684			IPixVdd	0.0000																						
VA18Vdd	1.8189			IA18Vdd	0.0000			VCAL	1.3036			IVCAL	0.0062			VHIGH	0.8180																						
IVHIGH	0.0052			VLOW	0.8187			IVLOW	0.0453			Vvbb	1.1934			IVbb	20.3019																						
VBias1	0.5890			IBias1	1.0035			VBias2	0.7896			IBias2	3.8722			VSwitch	0.0006																						
VSubst	0.0057			Temp1	33.3944																																		
TstVctA:	0x0			TstVctB:	0x1fff			AltClkF:	7			Pixels:	Array			Crnt mode:	memrd2																						
V33Vdd	3.3000		V25Vdd	2.5000		V18Vdd	1.8000		Connect	SetVhV1	MemRst	SetRowOffs	ShowROI	SlectRow																									
VMVdd	1.2000		VPixVdd	2.2000		VA18Vdd	1.8000		PowerON	SetVhVIDif	MemWrite	Probe	ShowRead	TestPx1																									
VCAL	1.3000		VHIGH	0.8170		VLOW	0.8170		StartMon	ReadCSR	MemRead1	ProbeRun	RefreshWF	SFon/off																									
Vvbb	1.2000		VBias1	0.6000		VBias2	0.8000		StopMon	ChangePar	MemRead2	DoSng1	ShowHisto	AquireHits																									
VSubst	0.0000		MonInt	10.0000										PowerOFF	Calibr	SetROIa	Run	WFModif	AqHitsRun																				
																SetAllV	MemInit	SetROIb	Stop	SetIdleV	closeUSB																		
IdleVec:	0x14c839			InitVec:	0x14c839			RowToSh:	5			RowOffs:	123			Clk speed:	High																						

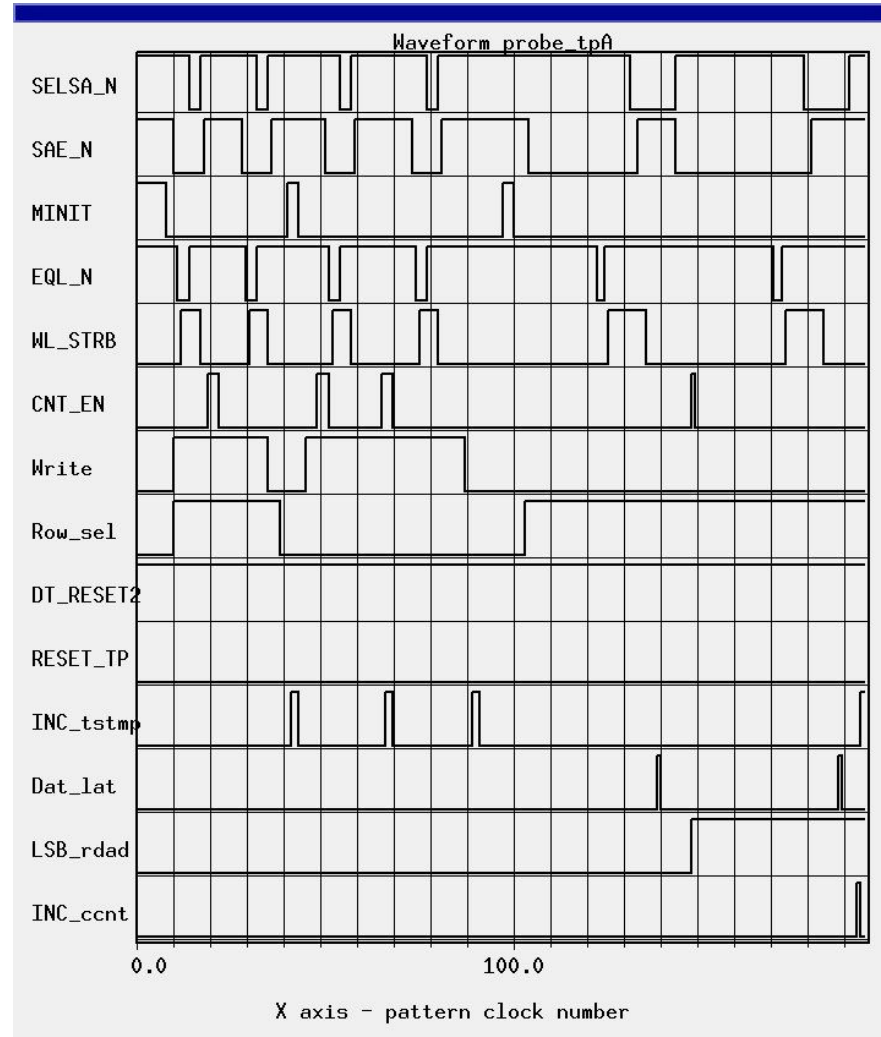


# Waveform Display Example

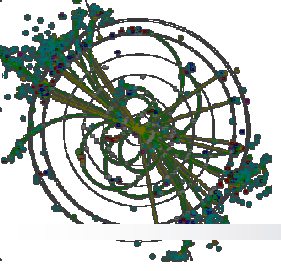


**Test Stand GUI has a button for displaying waveforms. You can select (from drop down menus) which waveforms to display, the mode of operation to display, and clocks range – as some waveform may be too long to be shown on the display from start to the end.**

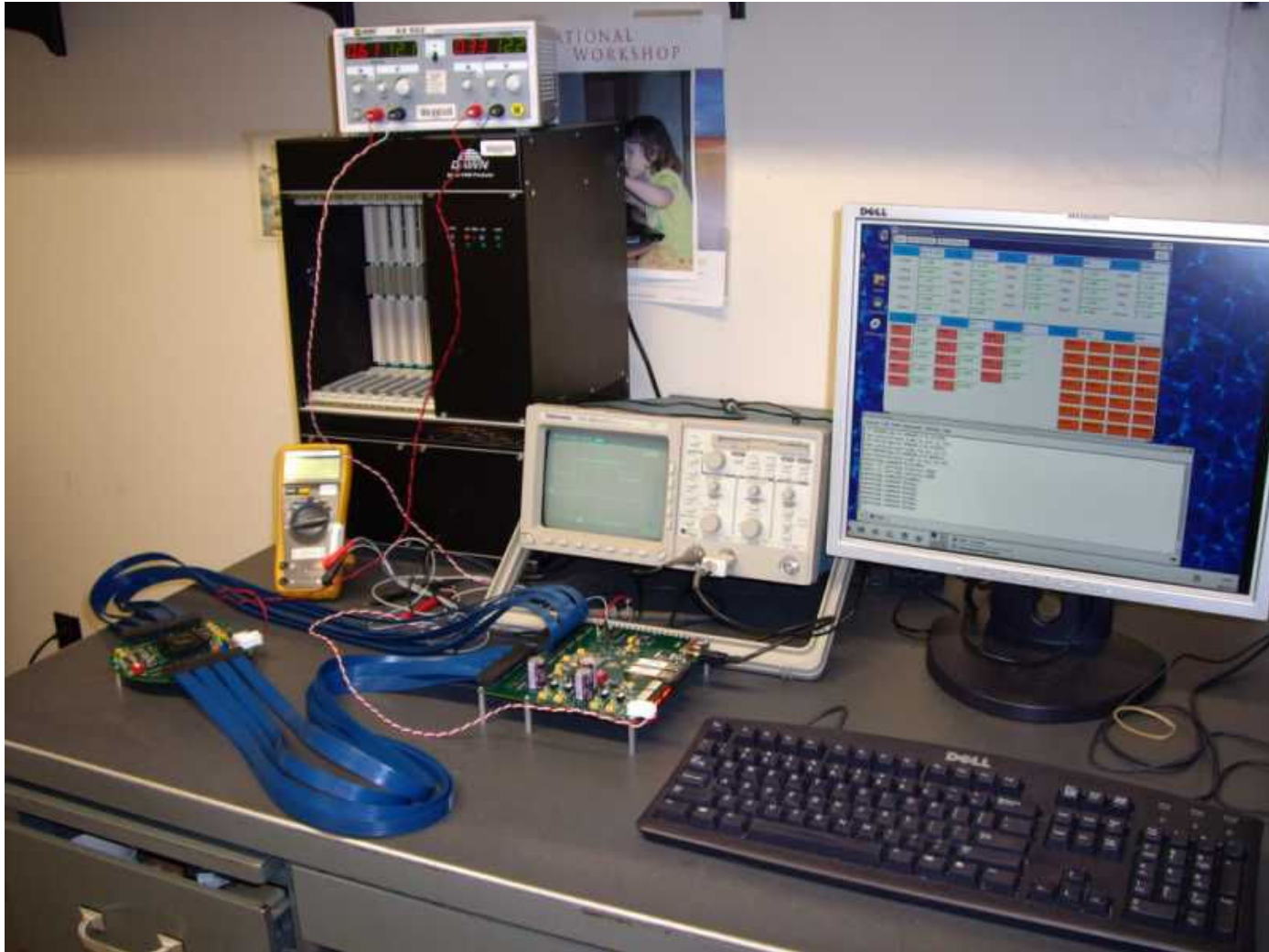
**Example at right – waveforms used in most noise measurements with Test Pixel A. They provide initial reset memory to 0, then manipulations to record comparator status, and then reading out results. As soon as file, describing WF is modified, new waveforms immediately can be displayed, no need to restart GUI.**

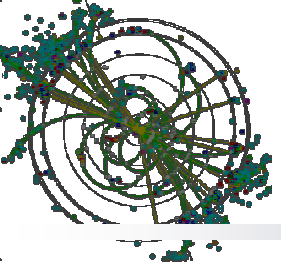






# Teststand is working !



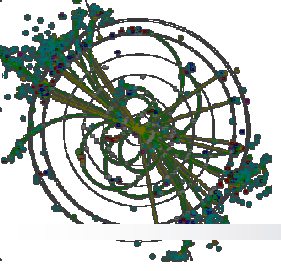


# Tests plan

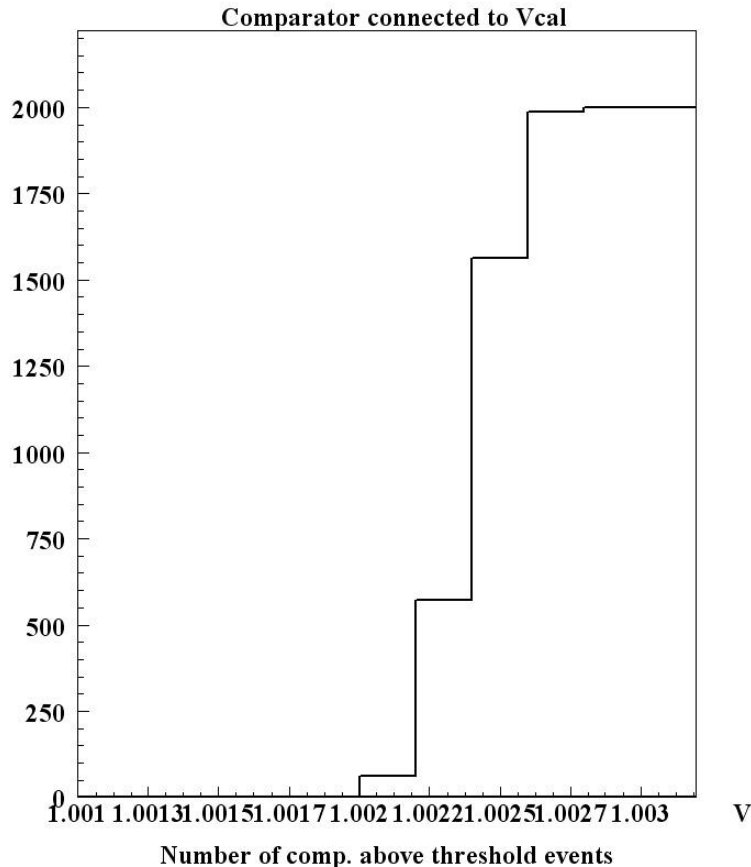


- First tests will be done with single pixels (Test pixel A and B) to learn how everything works.
- The most important part of the tests is to check, if **calibration** procedure **works**, and is **2 mV** range **enough** to cover offsets in all pixels.
- Next test will be to check **memory** operations. In principle, writing into time stamps memory is only done by pixel comparator, sensing signal. But **for testing** of memory proper operation, external **write** signal can be used to **record any value** into all memory cells simultaneously and when **read it back** cell by cell.
- After memory operations established, we can do the whole bunch of tests – noise measurements, the range of comparator offsets, pixel leakage currents and so on.
- If **everything goes smooth**, even for some part of the pixels, **Fe55** source can be used to determine **sensitivity** (expected  $10 \mu\text{V}/e$  – depend on pixel capacitance) .
- Of course, **power consumption**, and all questions concerning 3MHz time stamp bus (crosstalk, recording errors) operation should be investigated.

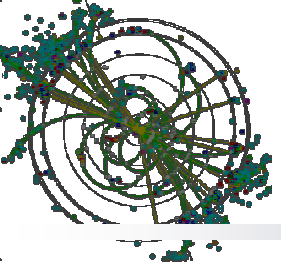




# Method of noise measurements – threshold scan



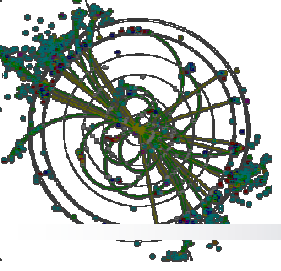
- Horizontal axis on the plot at left shows **comparator threshold** (set by connecting reference input of comparator to calibration selected tap of resistive ladder and setting voltages **Vlow and Vhigh**, on the ends of the ladder. (These voltages **differ only by 2 mV !**). Values shown on x axis are Vhigh. Vlow is always by 2 mV lower.
- Vertical axis shows number of cases than comparator **at the sampling moment appeared fired** (which means it sensed input voltage as lower than reference – remember we expect negative signals). Notice, entire range of x axis values is only 2 mV on this plot!



## Test results for test pixels



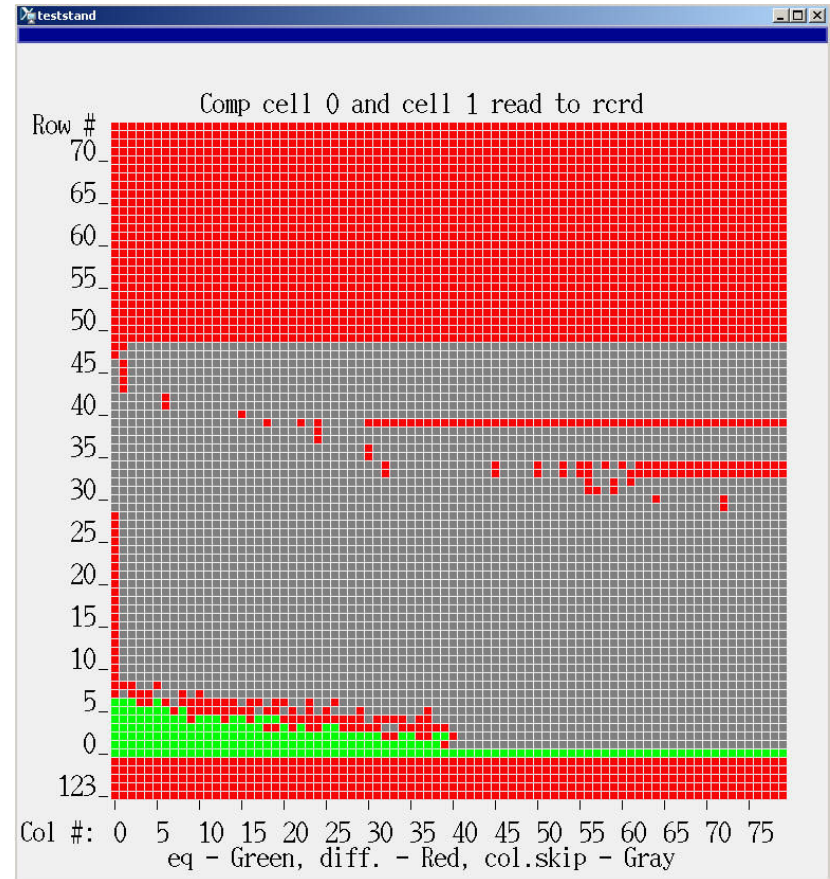
- As was mentioned earlier, in addition of array of 6400 pixels, each chip contains 2 test pixels, which could be accessed without involving addressing logics. This pixels were tested first, and it was found:
  - ↪ Memory operations are working as designed. Maximum timestamp recording speed – **7.27 MHz** (we need at least 3 MHz).
  - ↪ Calibration circuit operates properly.
  - ↪ Noise level looks like higher than expected. However, because it is difficult to make test with Fe55 source with single pixel (too small area), we can't express noise in the units of charge. From the estimation of sensor capacitance ( $\sim 7.5$  fF) we expect reset noise at the level of 800  $\mu\text{V}$ , measured value  $\sim$  **1.3 mV**. If our estimation of capacitance is correct, the sensitivity is  $21.3 \mu\text{V}/e$ , so noise level is about 61 e. In fact, from Fe55 signal in pixel array, sensor capacitance is rather 4.5 fF, so measured noise is 36.4 e. Specification is 25 e. For single pixel we can't implement "soft reset", which, by designers claim should reduce noise by factor of 2. So final noise figures will be discussed in pixel array test results.

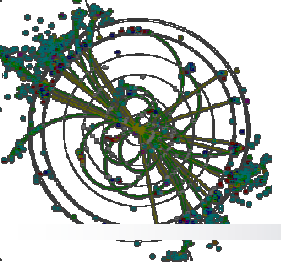


# Pixel array: Problems with power distribution

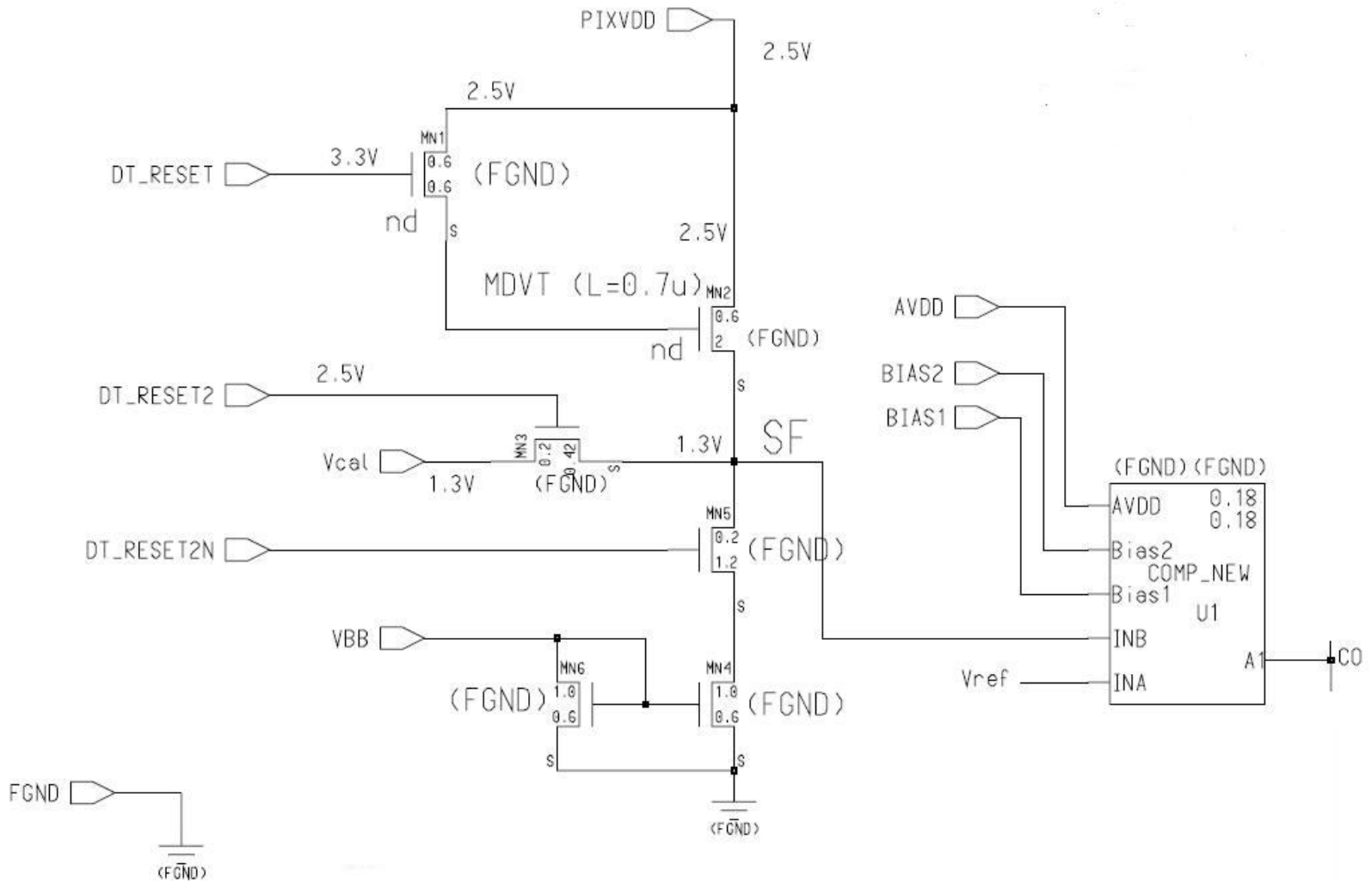


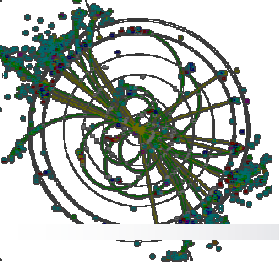
- Correct memory operation for array of 6400 pixels is shown with green color. Readout starts from non-existing row 123 to make sure correct operation of row 0 is not correlated with it to be first in readout sequence.
- As we can see, **only 3 first rows of pixels A (columns 0-40) and 1 row of pixels B** shows correct memory operations.
- Gray color corresponds to pixels, claiming they are “empty”, do not have anything recorded.
- Red color corresponds to pixels, which have different read back value from the written to memory value.



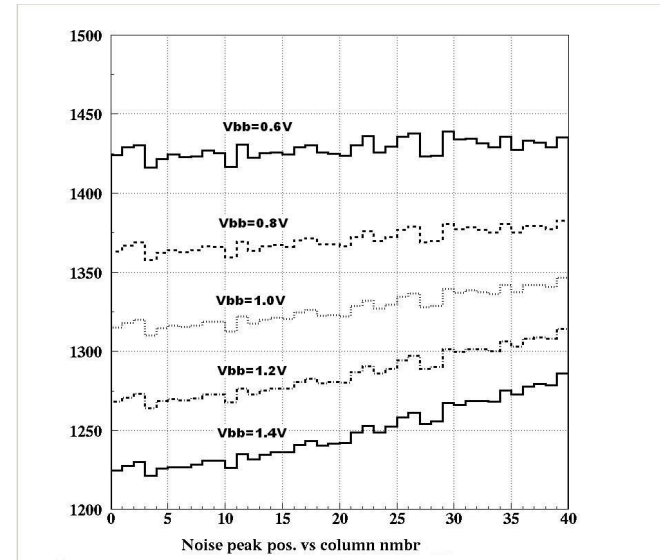
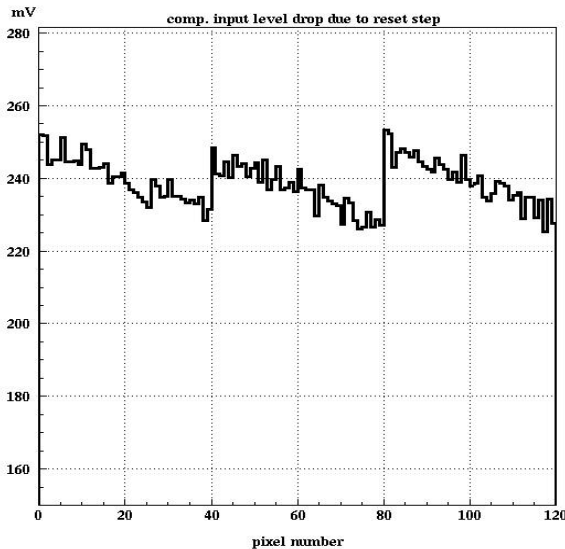


# Around sensor schematics

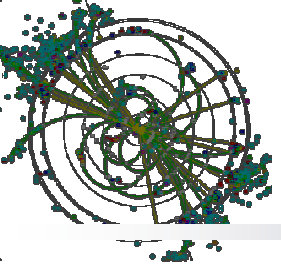




# Power distribution problem



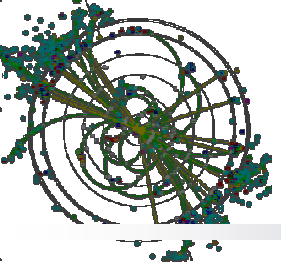
- On the left you can see the value of crosstalk in individual pixels for 3 rows of pixels A from pixel reset signal. This signal is formed in each pixel and has amplitude equal to 3.3V supply. We can see, that signal is larger at the start of the row. This tells us, that **3.3V drops as it reaches farther along row.**
- Same can be seen from right plot. It shows source follower output level for different pixels depending on the Vbb bias. This bias control current through source follower, and higher bias value leads to lower output level. **So, Vbb also drops along row.**



## Power distribution problem (why?)



- The resistivity of most metal layers in TSMC 0.18 process is 80 mohm/□. So, with trace width 0.23  $\mu\text{m}$  1 cm trace would have resistivity of **3.5 Kohm**. Middle of the row is 2 mm from the edge, so current **0.6 mA** will create **0.3 V** voltage drop. From the total current for all rows for 3.3 V (~5 mA) I expect only 0.0625 mA/row but I can't be sure that current is distributed evenly. It is reasonably to suppose that current drops in higher rows, as voltage drops not only along row, but also from row to row. So, trace resistivity is a realistic explanation of observed effects.
- And result of it is, that in the fabricated prototypes **only few first rows are working** (in fact, only one first row for pixels B, and 3 rows for A) . It was found, that most critical is the drop of 1.8 V supply (may be just because it is highest current circuit). And we can slightly increase number of operating rows by boosting 1.8 V supply to 2.1 V.

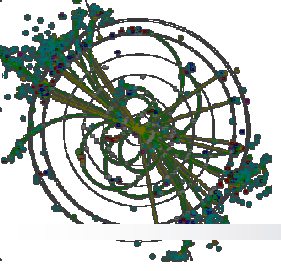


# Noise measurements



- It is expected, that major noise contributor is so-called “reset noise” or “**kTC**” noise – the thermal noise on the RC circuit. **It does not depend on R**, but if R is low, the bandwidth of the comparator may be not enough to see high frequency components. We can adjust the reset gate resistance by changing 3.3V supply and see that noise reaches reset noise values. This is **most clean** method, as it does not involve pulse on reset gate, which can lead to additional noise from cross talks. From calculations, noise level is  $\sim 2000 \mu\text{V}/\sqrt{C(\text{fF})}$ . For pixels A observed noise is **1.13 mV**, which corresponds to **C=3.1 fF**. Another method – measurement after reset gives **1.2 mV**.
- If we try to estimate sensor capacitance from sensor area and depletion depth for 10 ohm·cm silicon, we should expect **C ~7.5 fF**.
- So, may be resistivity of our silicon is a bit higher. Also, chip is certainly hotter, than room temperature. Anyway, estimation of the sensor capacitance, made from Fe55 signal indicates sensor capacitance value of about **4.5 fF** - almost consistent with noise figure.

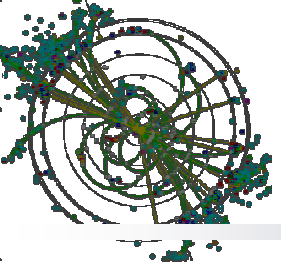




## Soft reset works ?



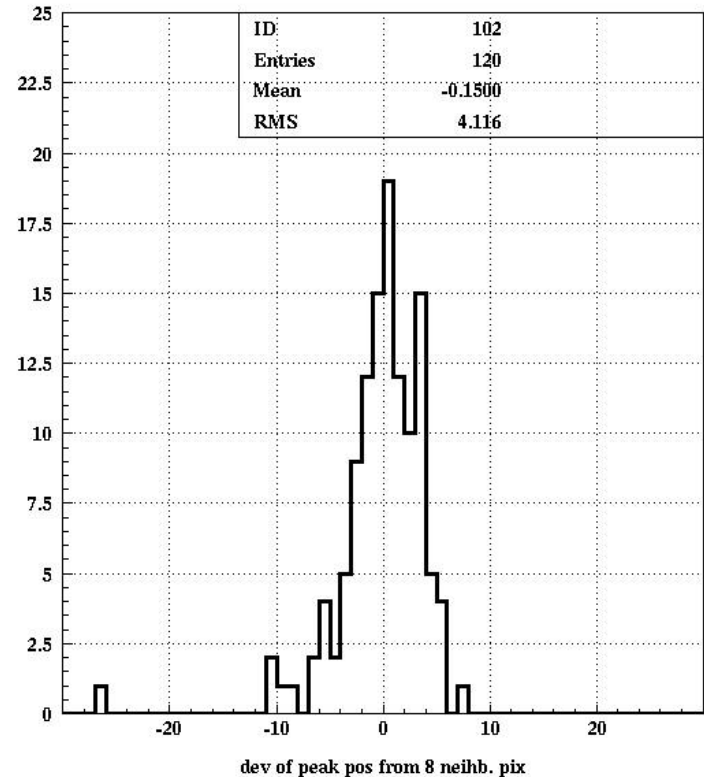
- Varying reset pulse parameters, I was able to achieve noise distribution with  $\sigma=0.86 \text{ mV}$ . This is better than noise measured with high resistivity of reset transistor ( $1.13 \text{ mV}$ ). So, may be special forming of reset pulse really helps. I did not have enough time to investigate this in details. And for pixels B I could not find such parameters that would noticeably improve noise compare to high resistivity measurements. Pixels B in general have much worse performance, but I don't know if it is because of deep n-well employed here, or just because they are farther on the power bus.

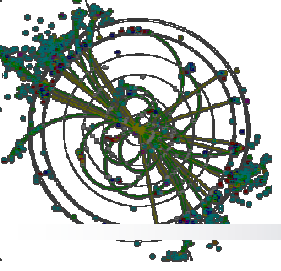


# Comparator thresholds spread



- We need the ability to set thresholds in all pixels at the level of about  $5\sigma$  of noise with accuracy of about  $1\sigma$ . With specified sensors sensitivity of  $10\ \mu\text{V}/e$  and specified noise of  $25\ e$ , that means that after calibration threshold accuracy should be  $250\ \mu\text{V}$ , and from the fact that calibrator has  $10\ \text{steps}$ , total spread of comparator offsets before calibration should not be larger than  $2.5\ \text{mV}$ . From plot at right (after correction for systematic shift due to power problems) spread  $\sigma=4.1\ \text{mV}$ , and full spread is  $6\sigma$ ,  $24.6\ \text{mV}$  –  $10\ \text{times we want}$ . However, situation is a little better if we take into account that our real sensitivity is about  $3.5\ \text{times higher}$  than specified (see Fe55 test results).

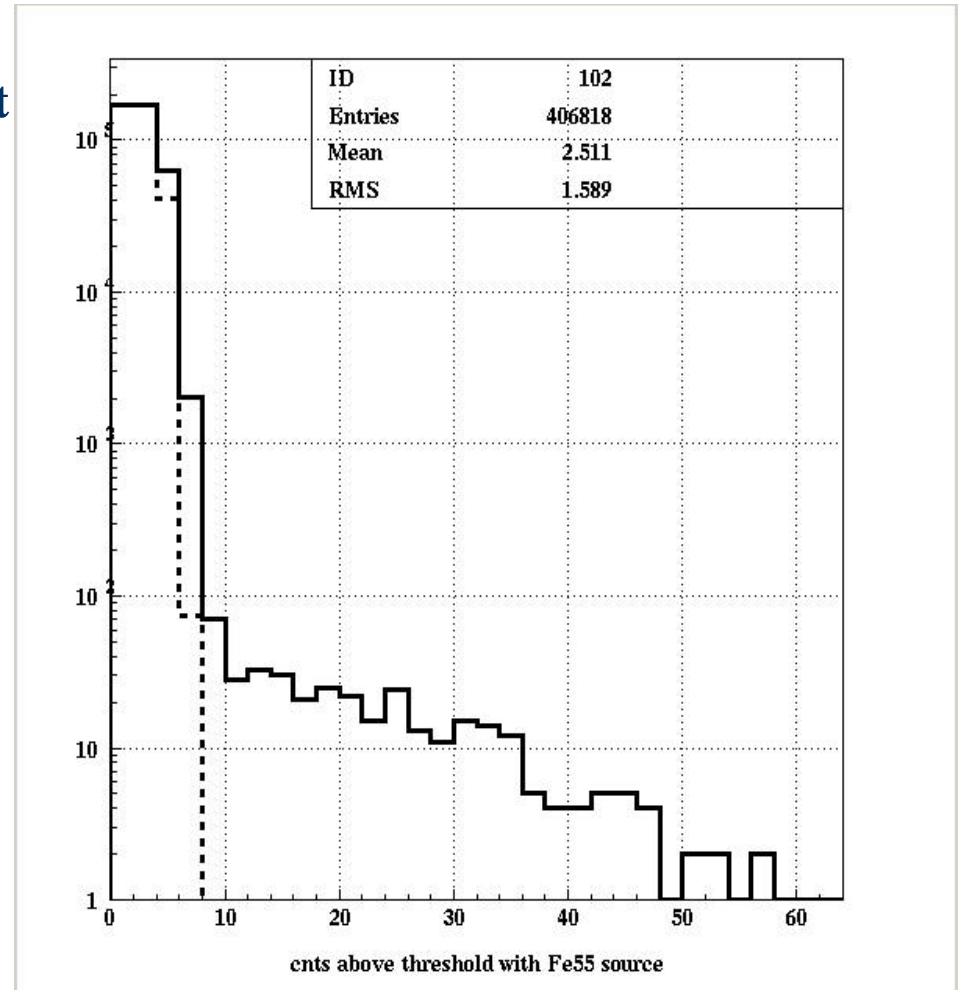


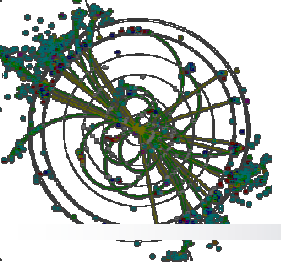


# Test with Fe55 source



- Distributions of number of hits above threshold with and without Fe55 source placed above chronopixel device are shown at right (without source – dashed line). Maximum signal seen is about 50 mV, and it corresponds to ~1400 e generated by Fe55 X-rays of 5.9 KeV. So, sensor sensitivity is ~**35.7  $\mu\text{V}/\text{e}$** , exceeding specified 10  $\mu\text{V}/\text{e}$ .
- This sensitivity tells us, that sensor capacitance is ~**4.48 fF** (compare to estimation of **3.3 fF** from noise measurement and **7.5 fF** from sensor area and calculated depletion depth).

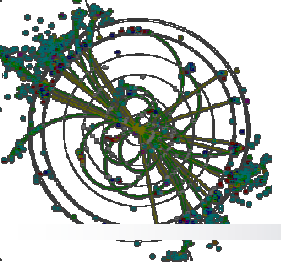




## Leakage currents measurement.



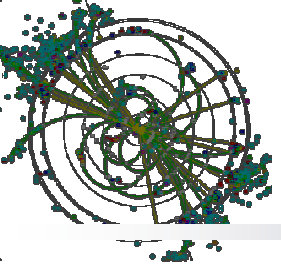
- Moving sampling point relative to reset pulse, I was able to measure voltage drift of about **0.1 mV/μs** both for pixels A and B. Applying measured value of sensor capacitance 4.48 fF, we will get the value of leakage current of  **$4.48 \cdot 10^{-13}$  A per pixel**, or  **$1.8 \cdot 10^{-8}$  A/cm<sup>2</sup>**. This is comfortable value.



# Conclusions



- Tests of the first chronopixel prototypes are completed.
- Tests show that general **concept is working**.
- **Mistake was made in the power distribution** net on the chip, which led to only **small portion of it is operational**.
- Calibration circuit **works as expected in test pixels**, but for unknown reason **does not work in pixels array**.
- Noise figure with “soft reset” is within specifications ( $0.86 \text{ mV}/35.7\mu\text{V}/e = 24 \text{ e}$ , specification is 25 e).
- Comparator offsets spread **25 mV** is about 10 times larger than specified, but expressed in input charge (**700 e**) is only **2.8 times larger** required (250 e). Reduction of sensor capacitance (increasing sensitivity) may help in bringing it within specs.
- Sensors leakage currents ( $1.8 \cdot 10^{-8} \text{ A}/\text{cm}^2$ ) is not a problem.
- Sensors timestamp maximum recording speed (**7.27 MHz**) is adequate.



## Next steps



- We plan to meet SARNOFF engineers in the **beginning of April** to discuss design of the **next prototype**. In addition to fixing found problems, we hope to move to deep **p-well process**, which will allow us to have high efficiency of hit registration.
- Simultaneously with production of next prototype, **test stand will be modified**.
- We hope to get next prototypes by the **end of the year 2010**, and will start testing immediately.