

Micromegas-TPC Z resolution with charge dispersion  
& r- $\varphi$  resolution with an improved algorithm

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Collaborators

# Outline

- ILD-TPC goal:  $\sigma_0(r-\varphi) \leq 100 \mu\text{m}$  (all tracks up to 2 m drift).
- Not possible with proportional wire/cathode pad TPC
  - Resolution limited by intrinsic ExB effects.
- Possible with conventional MPGD-TPC readout, but:
  - sub-mm readout pads ( $\sim 3,000,000$  channels)
  - Detector cost, complexity & heat removal problems
- Alternative - charge dispersion MPGD readout
  - $\sigma_0(r-\varphi) \sim 50 \mu\text{m}$  for 2-3 mm pads - published results
  - But previous analysis techniques not robust.
- A new more robust algorithm for  $r-\varphi$  resolution & results
- A first measurement of  $z(t)$  resolution for the charge dispersion readout.

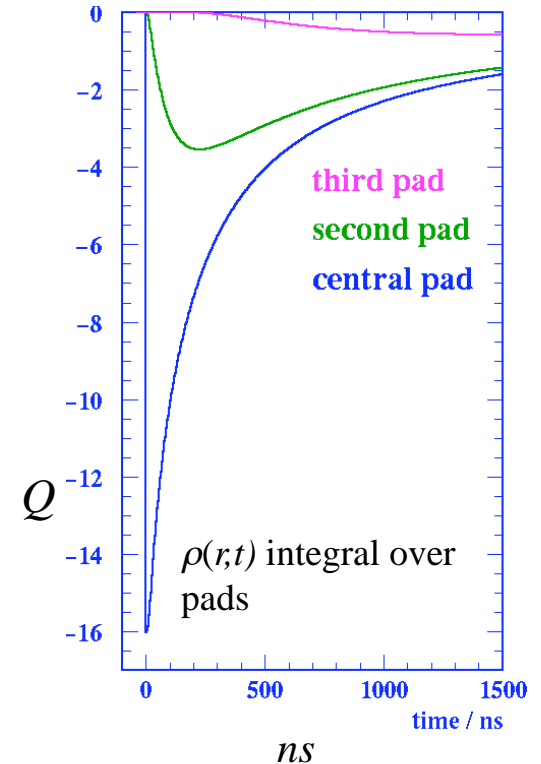
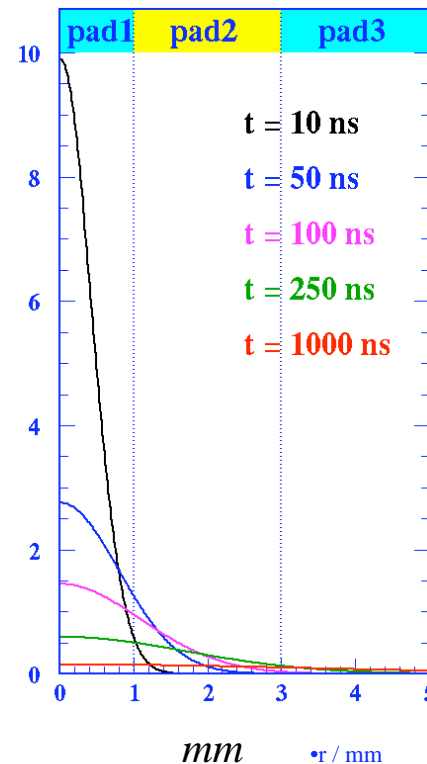
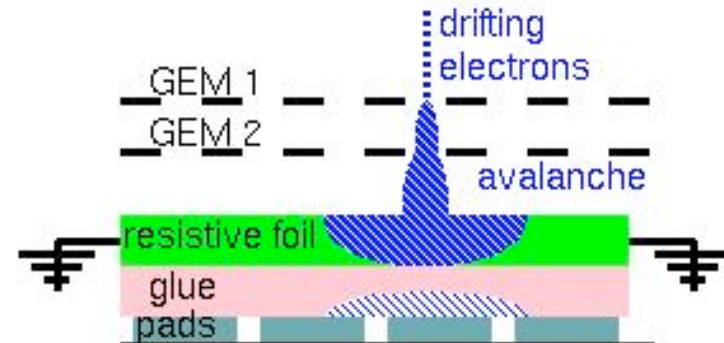
# Charge dispersion in a MPGD with a resistive anode

- Modified MPGD anode with a high resistivity film bonded to a readout plane with an insulating spacer.
- 2-dimensional continuous RC network
- Point charge at  $r = 0$  &  $t = 0$  disperses with time.
- Time dependent anode charge density sampled by readout pads.
- Equation for surface charge density function for the 2-D continuous RC network:

$$\frac{\partial \rho}{\partial t} = \frac{1}{RC} \left[ \frac{\partial^2 \rho}{\partial r^2} + \frac{1}{r} \frac{\partial \rho}{\partial r} \right]$$

$$\Rightarrow \rho(r,t) = \frac{RC}{2t} e^{-\frac{r^2 RC}{4t}}$$

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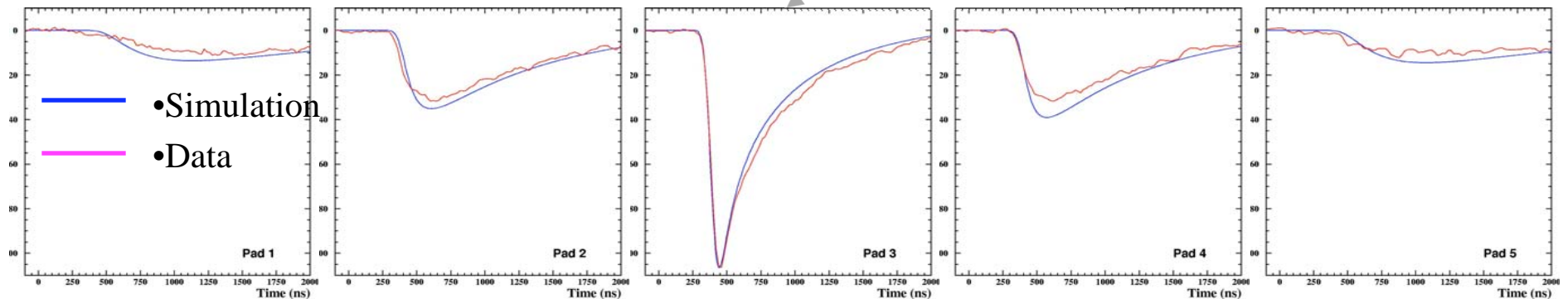
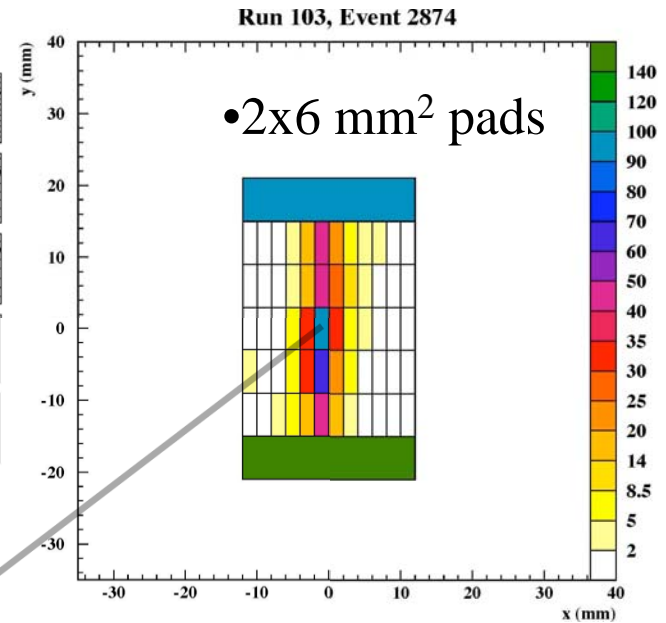
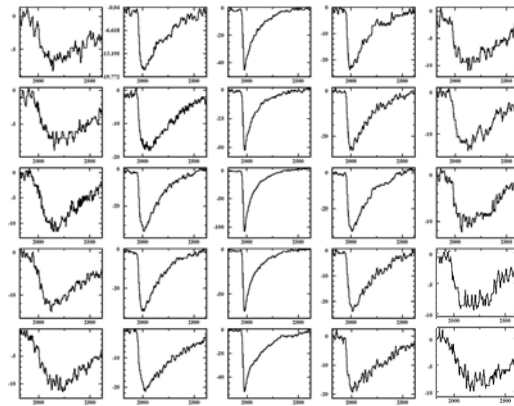
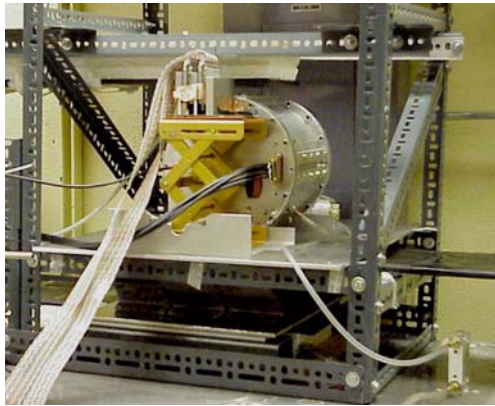
•LCWS10, Beijing

## Using the charge dispersion signal for tracking

- Unusual highly variable pulse shape.
- Pulse on the charge collecting pad: Large pulses with fast rise-time. The decay time depends on the system RC, the pad size & on the position of the track.
- Charge dispersion pulses on adjacent pads: Smaller pulse height & slower rise & decay times determined by the system RC & pad location relative to the track.
- Both the pulse shape and the pulse height contain position information
- How to define the pad signal "amplitude" for optimum determination of position from the measured pulse?

# GEM TPC charge dispersion simulation (B=0)

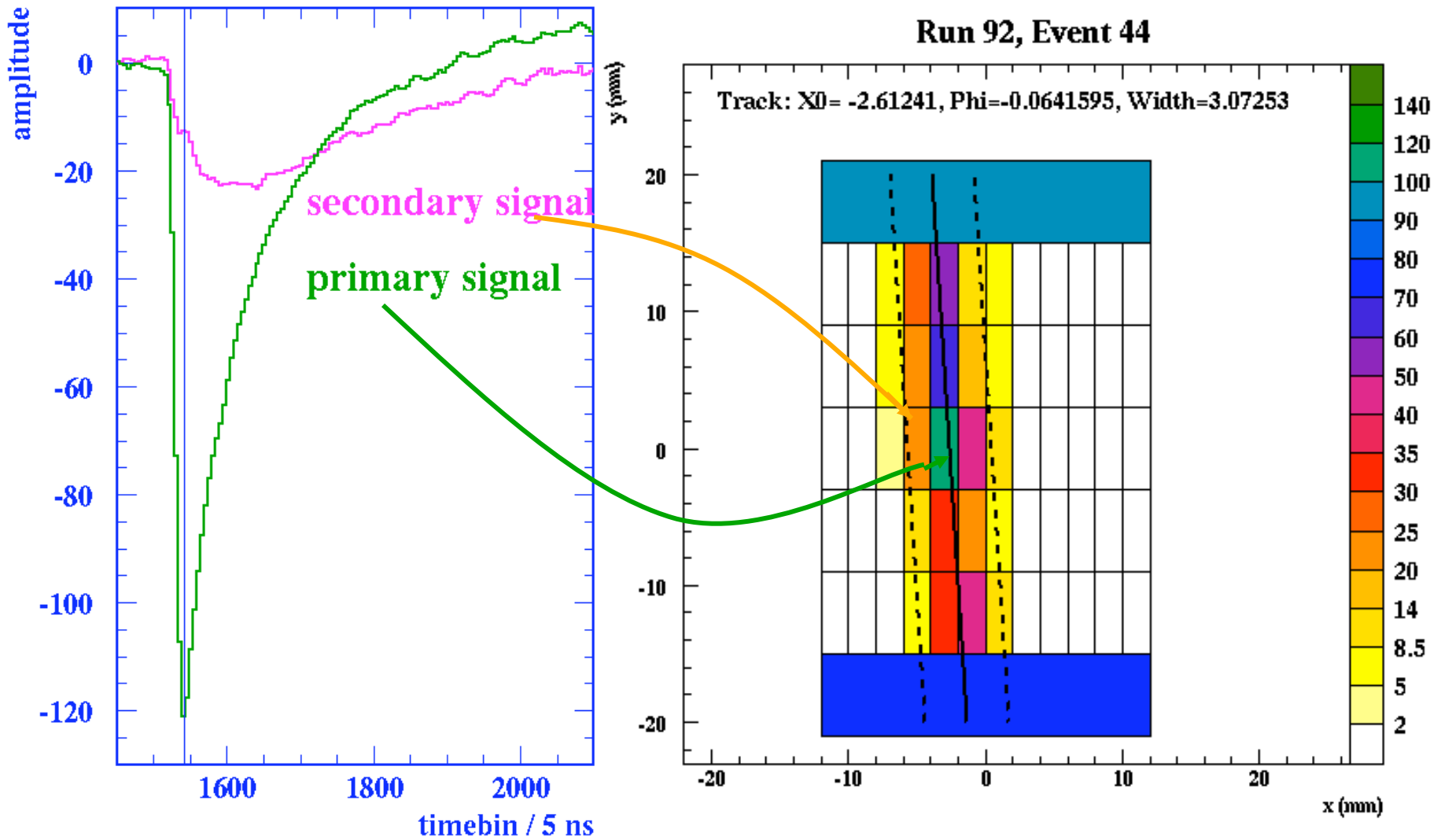
## Cosmic ray track, Z = 67 mm Ar+10%CO<sub>2</sub>



Centre pulse used for normalization - no other free parameters.

# Cosmic ray track signals with charge dispersion readout

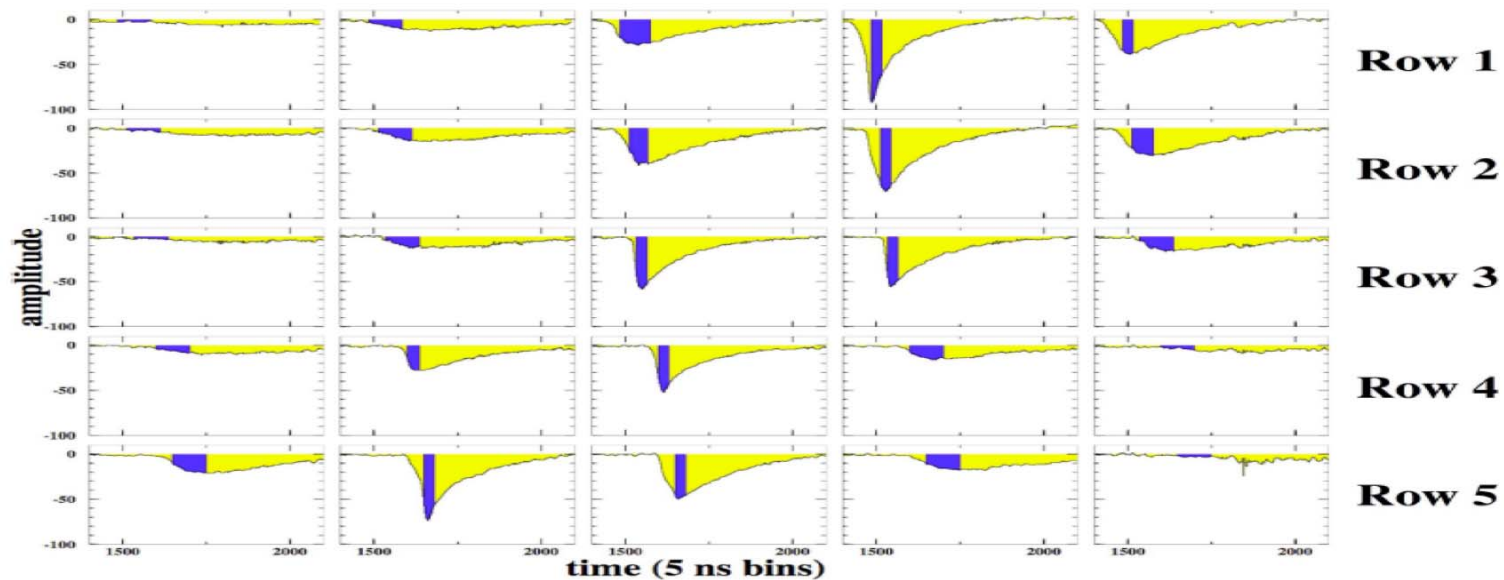
2 mm x 6 mm pads



# The pad response function (PRF)

- The PRF is a measure of pad signal "amplitude" dependence on the track position.
- With variable pulse shape & both rise time & pulse height carrying position information, there is no unique algorithm to define the PRF.
- The PRF is a tool which may be optimized for specific analysis. It is not a fundamental property of data. Much more information is contained in the digitized charge pulse shape.
- More than one PRF can be defined, optimized for single track resolution, two track resolution etc.

# The track pad response function (PRF)



- Our first PRF algorithm was developed for single hit ( $r-\varphi$ ) resolution
- It integrated pulses over a time window with width determined by the details of pulse shape
- A  $\sigma_0 \sim 50\mu\text{m}$  was achieved for 2 mm x 6 mm pads
- However, the PRF algorithm needed tuning & was sensitive to noise.



## The PRF shape is parameterized for track fit analysis

- The PRFs are not Gaussian.
- The PRF depends on track position relative to the pad:  $PRF = PRF(x, z)$
- PRF can be characterized by its FWHM  $\Gamma(z)$  & base width  $\Delta(z)$ .
- PRFs determined from the data have been fitted to a functional form consisting of a ratio of two symmetric 4th order polynomials.

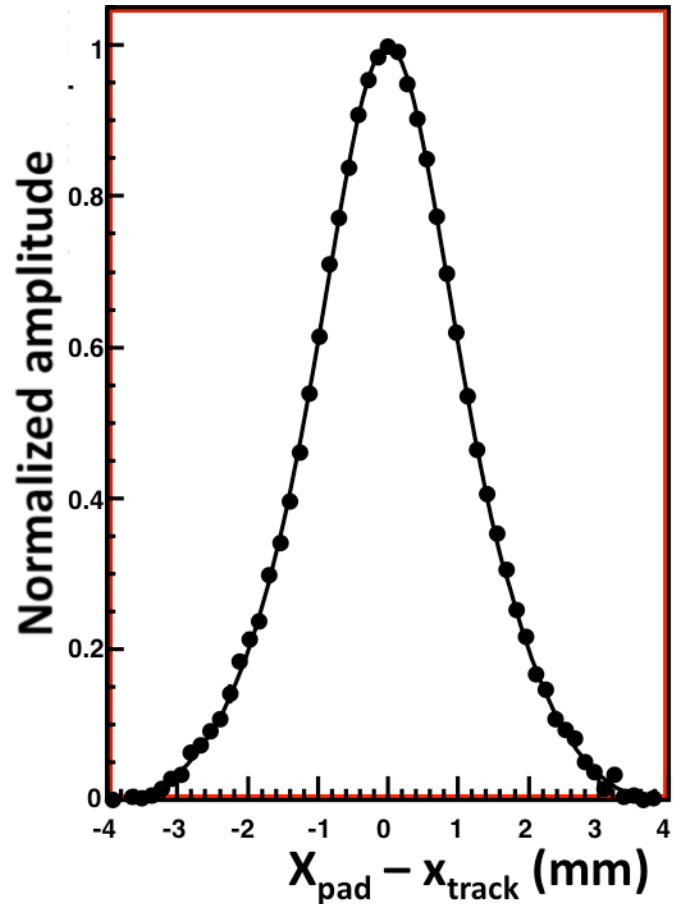
$$PRF[x, \Gamma(z), \Delta, a, b] = \frac{(1 + a_2 x^2 + a_4 x^4)}{(1 + b_2 x^2 + b_4 x^4)}$$

$a_2$   $a_4$   $b_2$  &  $b_4$  can be written down in terms of  $\Gamma$  and  $\Delta$  & two scale parameters  $a$  &  $b$ .

# The PRF for a Micromegas-TPC in a 5 T field

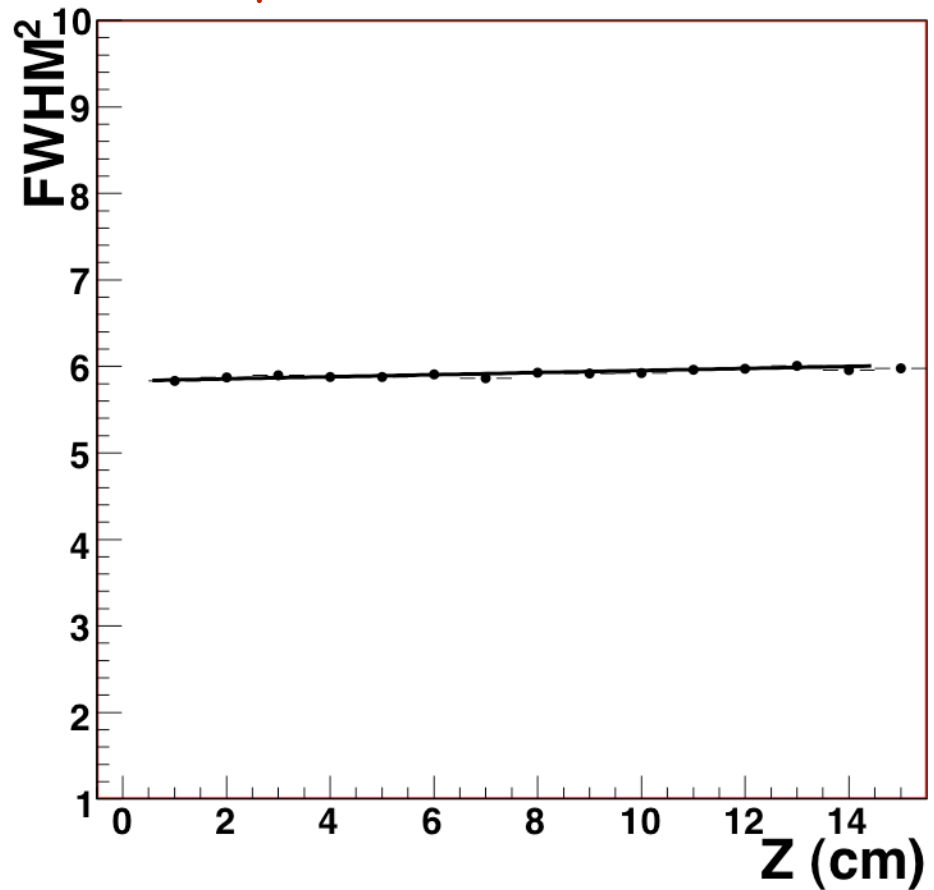
2 mm x 6 mm pads Ar+2%C4H10+3%CF4

PRF at 1 cm drift



(a)

The dependence of PRF width on z



(b)

## A better algorithm for charge dispersion analysis

- The previous PRF algorithm parameters needed to be tuned if TPC operating conditions were changed
- We have developed a more robust algorithm not requiring fine tuning
- Tested several new ideas with simulated data
- The new algorithms were tested by reanalyzing old data
- Criteria: PRF can be applied consistently and easily over a wide range of TPC operating conditions.
- A simple fixed window algorithm works the best!

# Two data sets were re-analyzed with the improved PRF algorithm & for $z(t)$ resolution

## **KEK: 4 GeV $\pi^+$ at 1 Tesla October-Nov 2005**

1. Number of Good Events: 12754
2. Gas Mixture: Argon(95%) + Isobutante(5%)
3. B Field: 1 T
4. E Field: 70 V/cm
5. Transverse Diffusion: 124  $\mu\text{m}/\text{cm}^{**0.5}$
6. Longitudinal Diffusion: 479  $\mu\text{m}/\text{cm}^{**0.5}$
7. Drift Velocity: 25.3  $\mu\text{m}/\text{ns}$
8. Theta Distribution: [-5,5]

## **DESY: Cosmics tests at 5 Tesla Nov-Dec 2006**

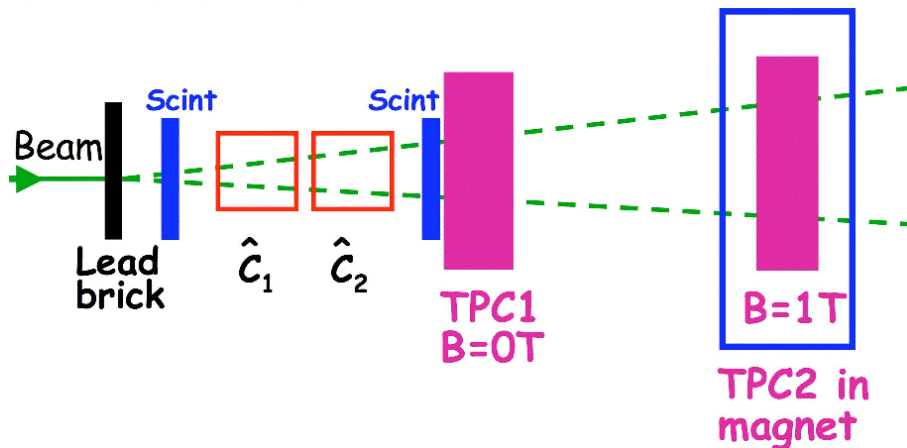
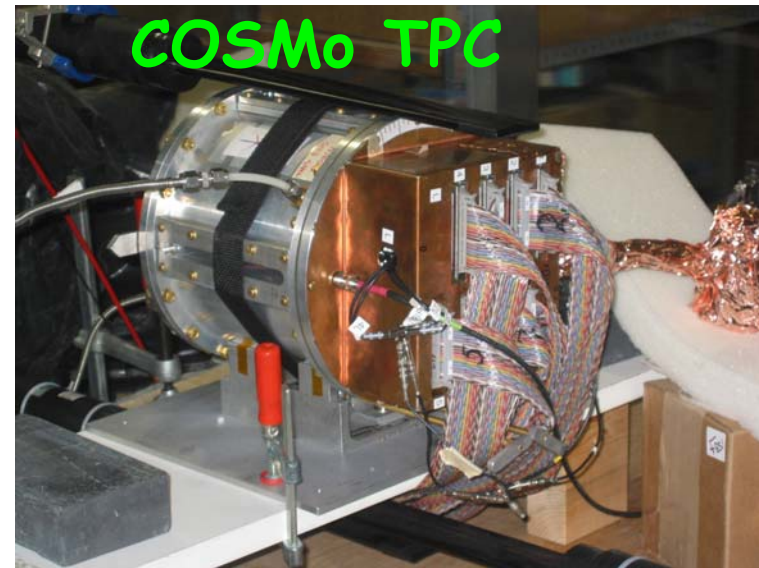
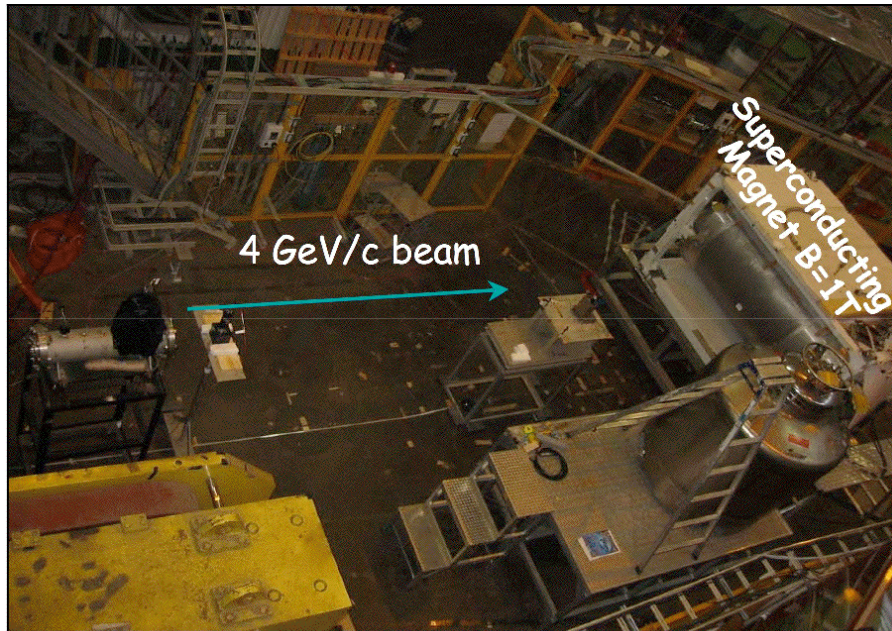
1. Number of Good Events: 5663
2. Gas Mixture: Argon(95%) + Isobutante(2%) + CF4(3%)
3. B Field: 5 T
4. E Field: 200 V/cm
5. Transverse Diffusion: 18.6  $\mu\text{m}/\text{cm}^{**0.5}$
6. Longitudinal Diffusion: 248  $\mu\text{m}/\text{cm}^{**0.5}$
7. Drift Velocity: 72.7  $\mu\text{m}/\text{ns}$
8. Theta Distribution: [-30,30]

COSMo (Carleton-Orsay-Saclay-Montreal) TPC  
DESY cosmic ray tests at 5 T  
Nov-Dec 2006





# 4 GeV beam tests in a 1 Tesla magnetic field (2005)



- Micromegas 10x10 cm<sup>2</sup>
- Drift distance: 16 cm
- 126 2 mm x 6 mm pads in 7 rows
- Preamps from ALEPH TPC at LEP

# KEK 2005 beam test collaborators

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Kinnki University  
Hiroshima Univ.

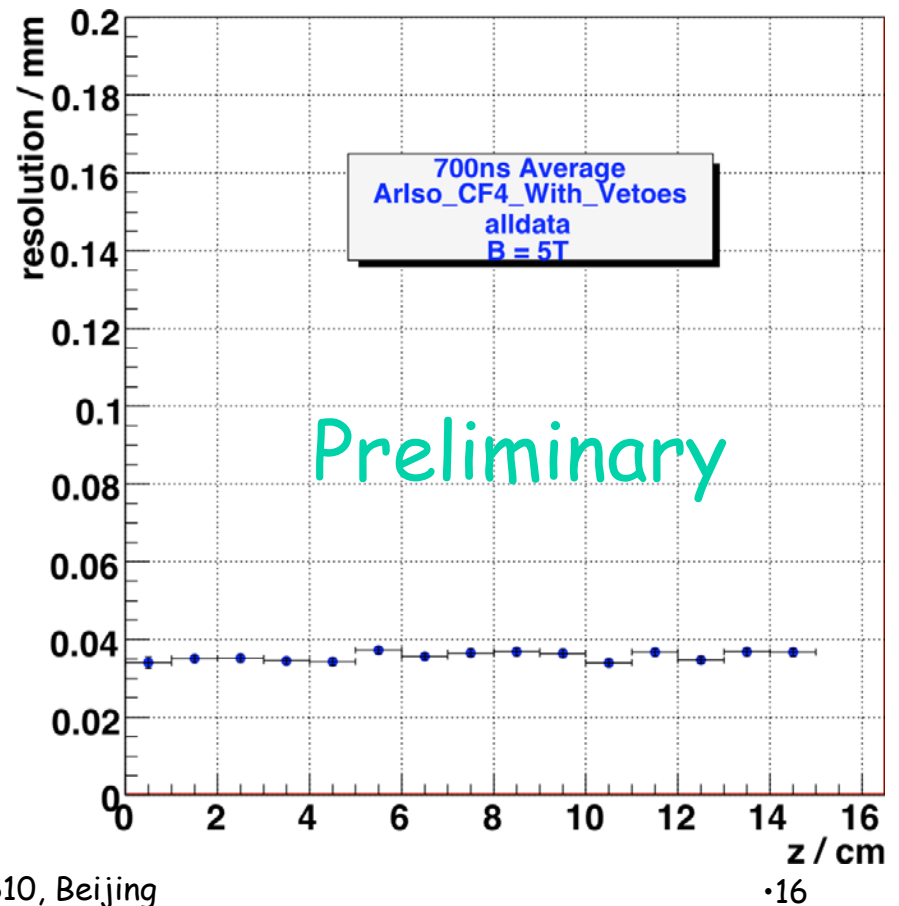
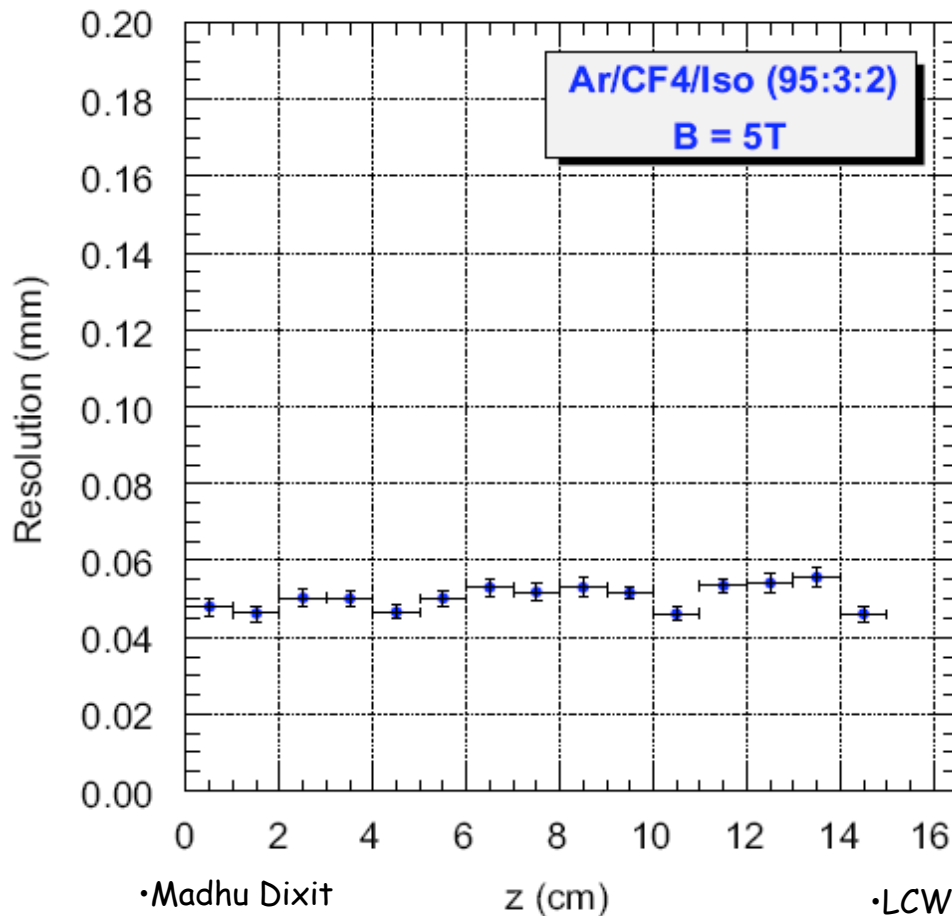
# Resolution comparison - DESY 5 T cosmic ray tests

## Old algorithm vs new fixed window PRF algorithm

- Old algorithm 3652/17669  
Constant  $\sim 50 \mu\text{m}$  resolution  
independent of  $z$  over 15 cm.

- New algorithm 5663/17669  
• Constant  $\sim 35 \mu\text{m}$  resolution  
independent of  $z$ .

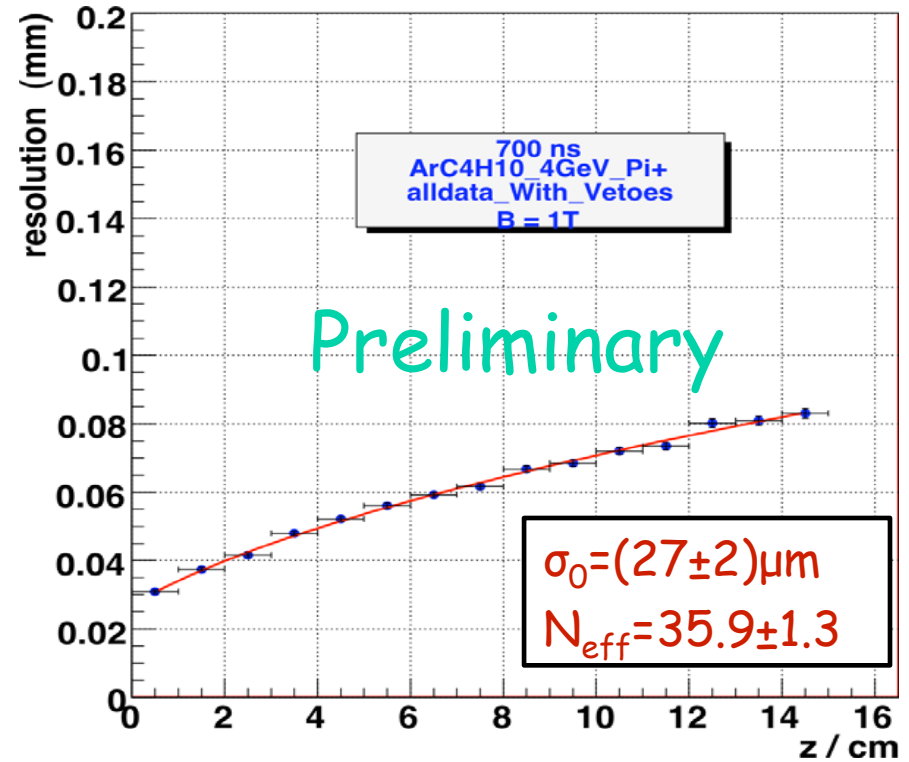
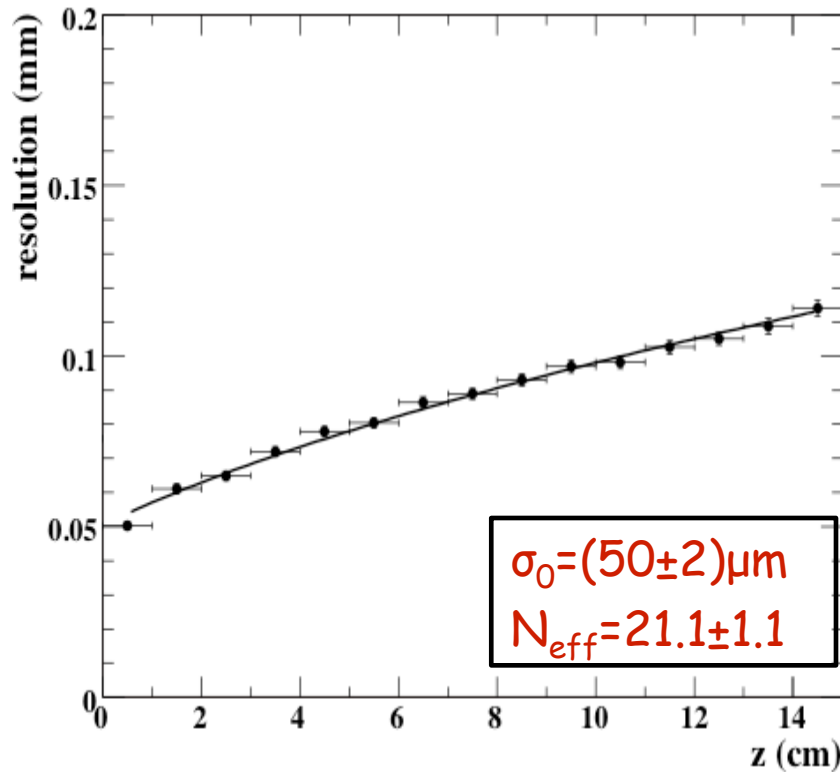
The new algorithm results in fewer track fit failures





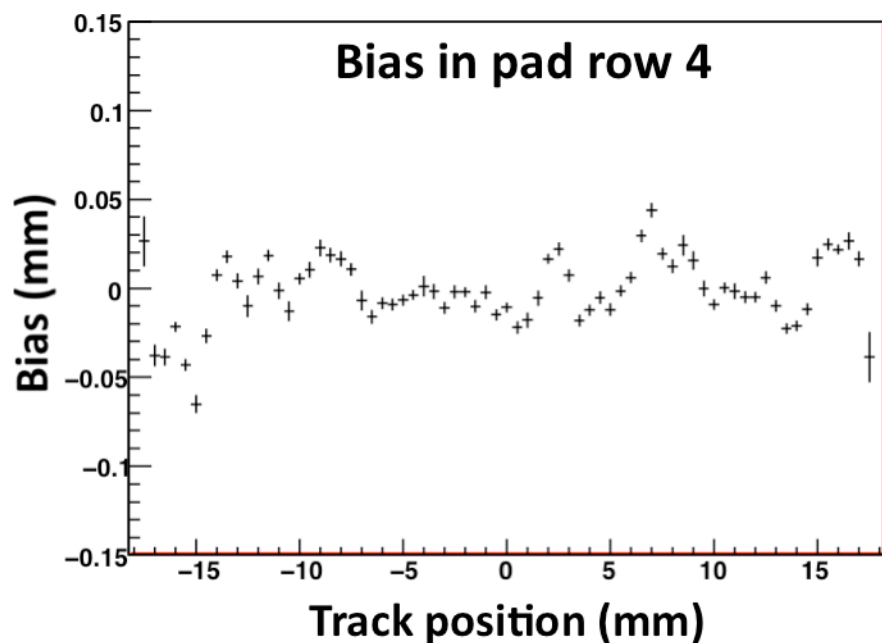
# KEK B=1T 4 GeV $\pi^+$ beam - resolution comparison Old algorithm vs new fixed window PRF algorithm

Transverse spatial resolution Ar+5% $\pi^+$ C4H10  
 $E=70V/cm$   $D_{Tr} = 124 \mu/\sqrt{cm}$  (Magboltz) @  $B=1T$

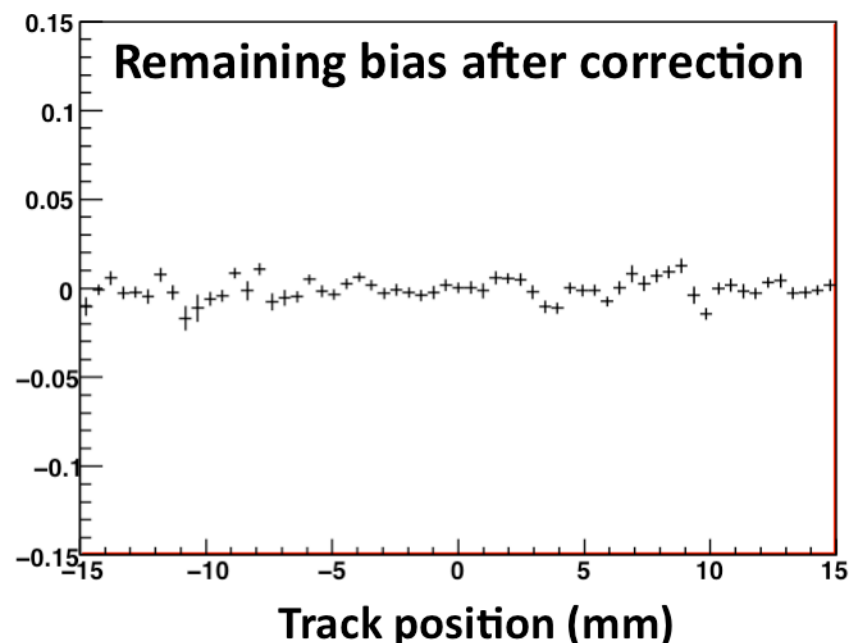


2 mm x 6 mm pads

## Residual bias is now comparable with resolution



(a)



(b)

Bias remaining after correction  $\sim 20\text{-}25\ \mu\text{m}$

Residual bias is now significant and comparable to resolution achievable with charge dispersion  $\sigma_0(r-\phi) \sim 30\ \mu\text{m}$

Improved fabrication and better resistive films needed to minimize RC non-uniformities and to reduce bias further

Time resolution with charge dispersion  
readout from DESY 5Tesla cosmic ray  
& KEK 4 GeV beam test data sets

## Determination of z or timing resolution

The time resolution is determined from r-z track fit following the r- $\phi$  track fit

r- $\phi$  track fit

$$\chi^2 = \sum_{rows} \sum_{i=pads} \left( \frac{A_i - PRF_i}{\delta A_i} \right)^2$$

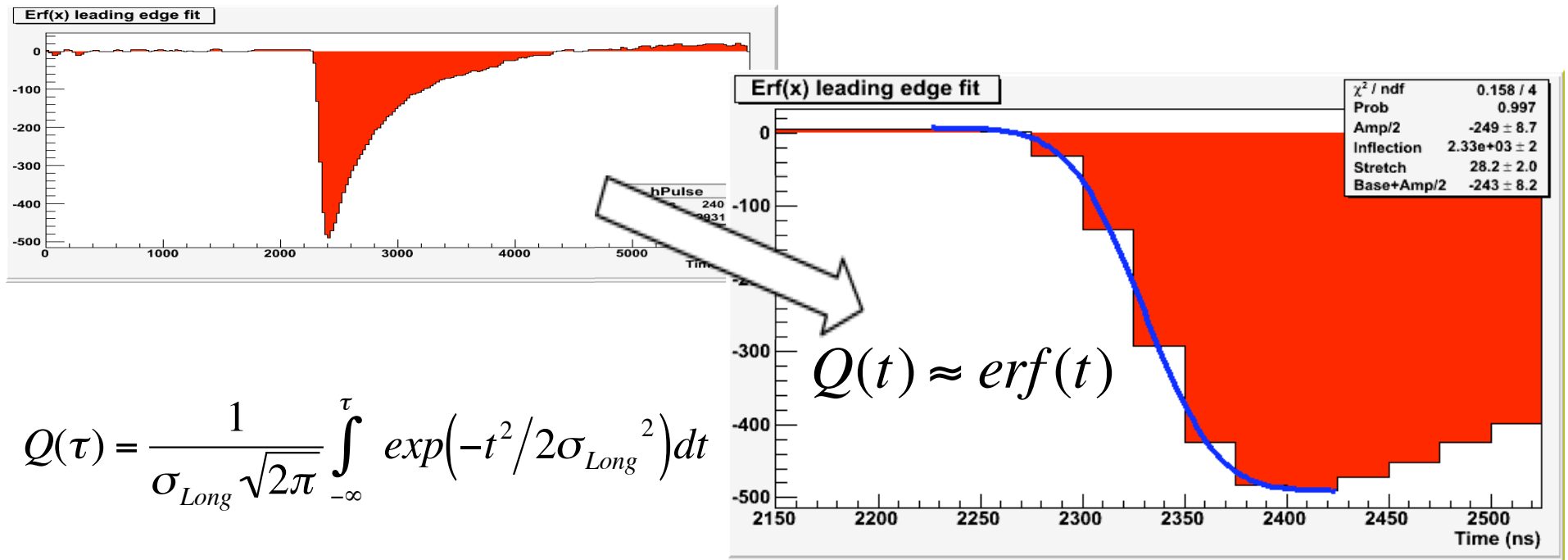
- Track parameters  $x_0$  &  $\phi$  for  $x_{track} = x_0 + y \tan(\phi)$  from  $\chi^2$  minimization
- Identify main charge collecting pad in each row for z(t) resolution fit

r-z(t) track fit performed for main charge collecting pads only

$$\chi^2 = \sum_{i=rows} \left( \frac{t_i - t_{track}}{\delta t_i} \right)^2$$

- Determine track parameters  $t_0$  and  $\theta$  for  $t_{track} = t_0 + y \tan(\theta)$
- Determine  $t_{row}$  by fitting error function to main charge pulse
- Residuals:  $R = t_{row} - t_{track}$
- Resolution determined from standard deviation of residuals

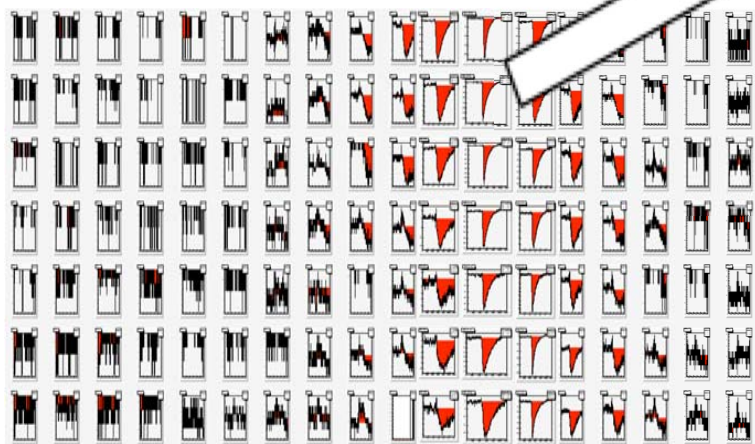
# The main charge collecting pad signal shape is determined mainly by longitudinal diffusion



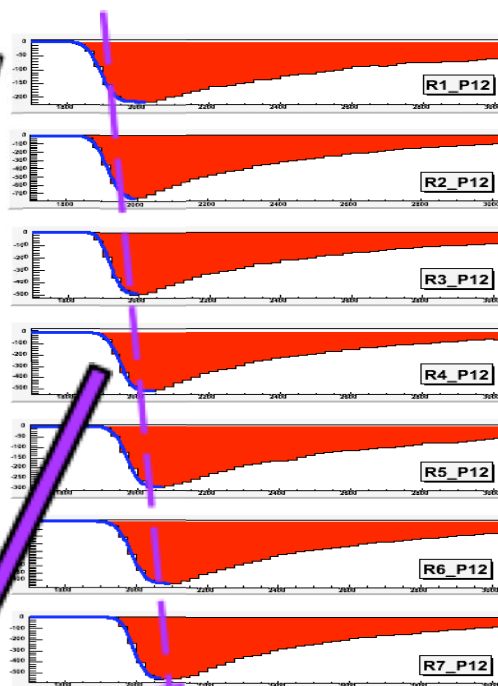
$$Q(\tau) = \frac{1}{\sigma_{Long} \sqrt{2\pi}} \int_{-\infty}^{\tau} \exp\left(-t^2 / 2\sigma_{Long}^2\right) dt$$

Timing determined by error function fit to the leading edge

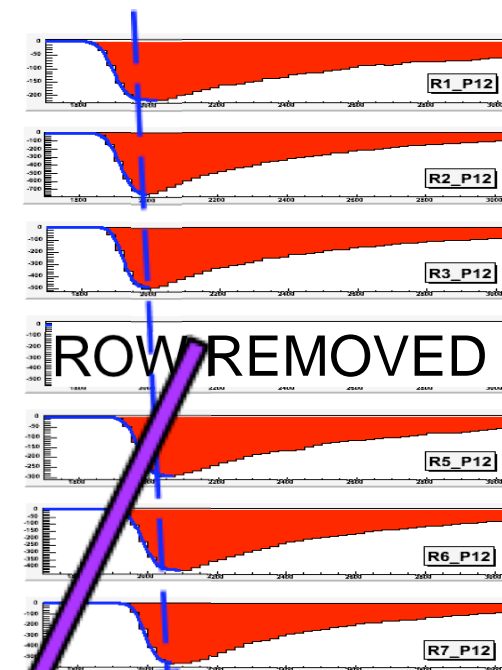
# r-z(t) track fit



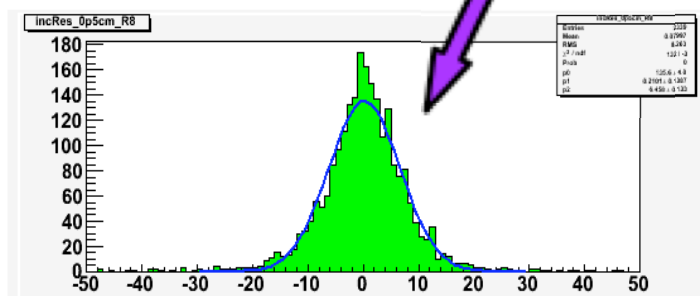
• Primary pads from r- $\phi$  track fit



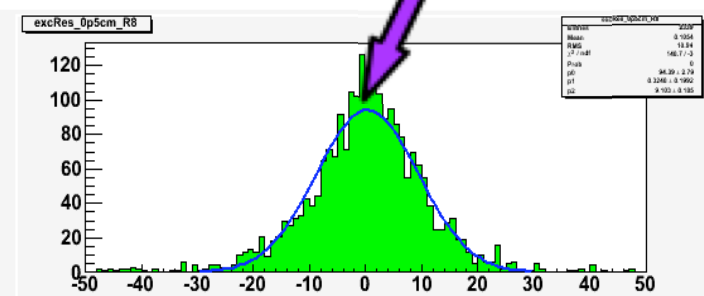
• Inclusive fit



• Exclusive fit



$\sigma_{inc}$



$\sigma_{exc}$

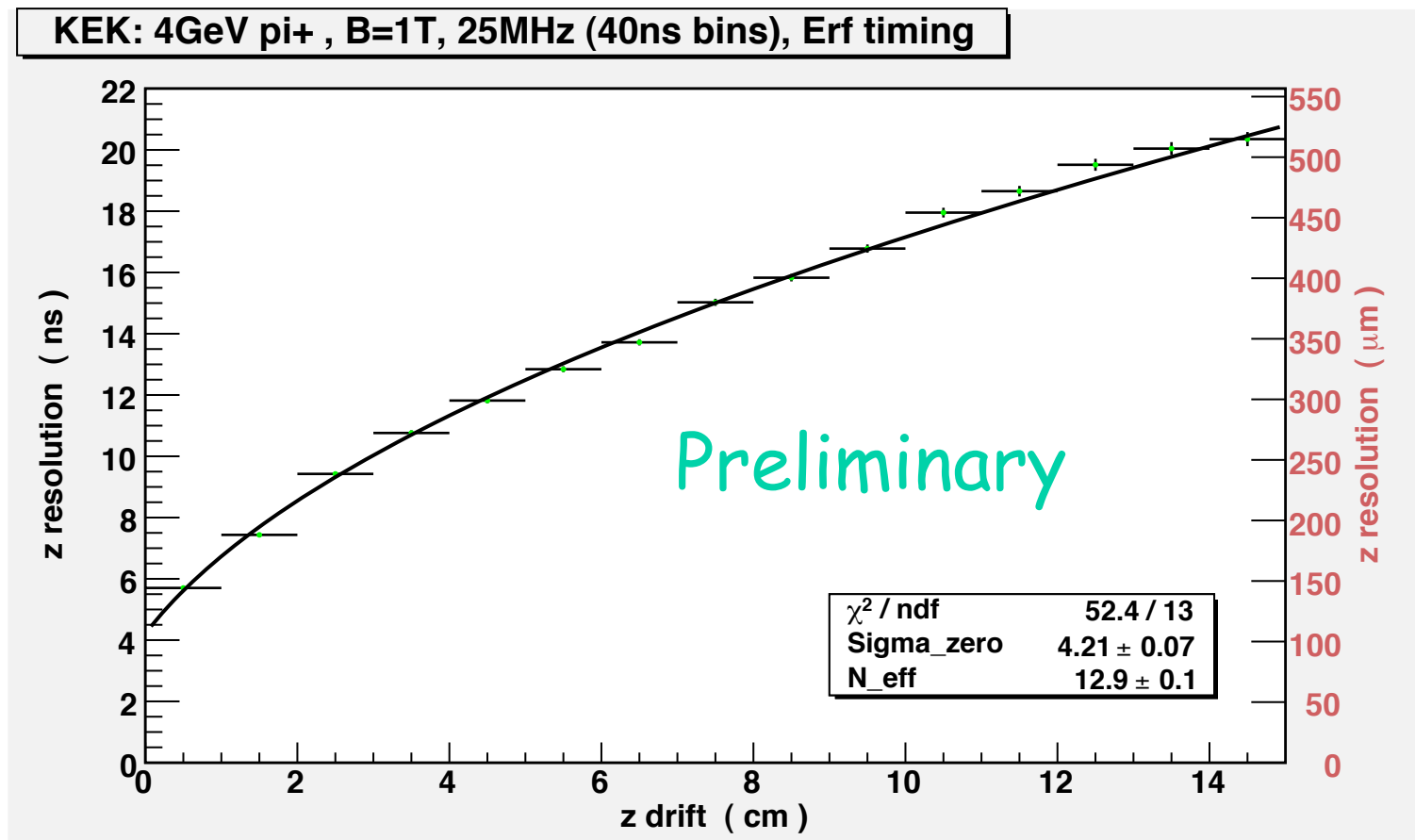
• Madhu Dixit

$$\sigma = \sqrt{\sigma_{inc} * \sigma_{exc}}$$

# KEK B=1T 4 GeV $\pi^+$ beam time resolution

Ar+5% $i$ C4H10

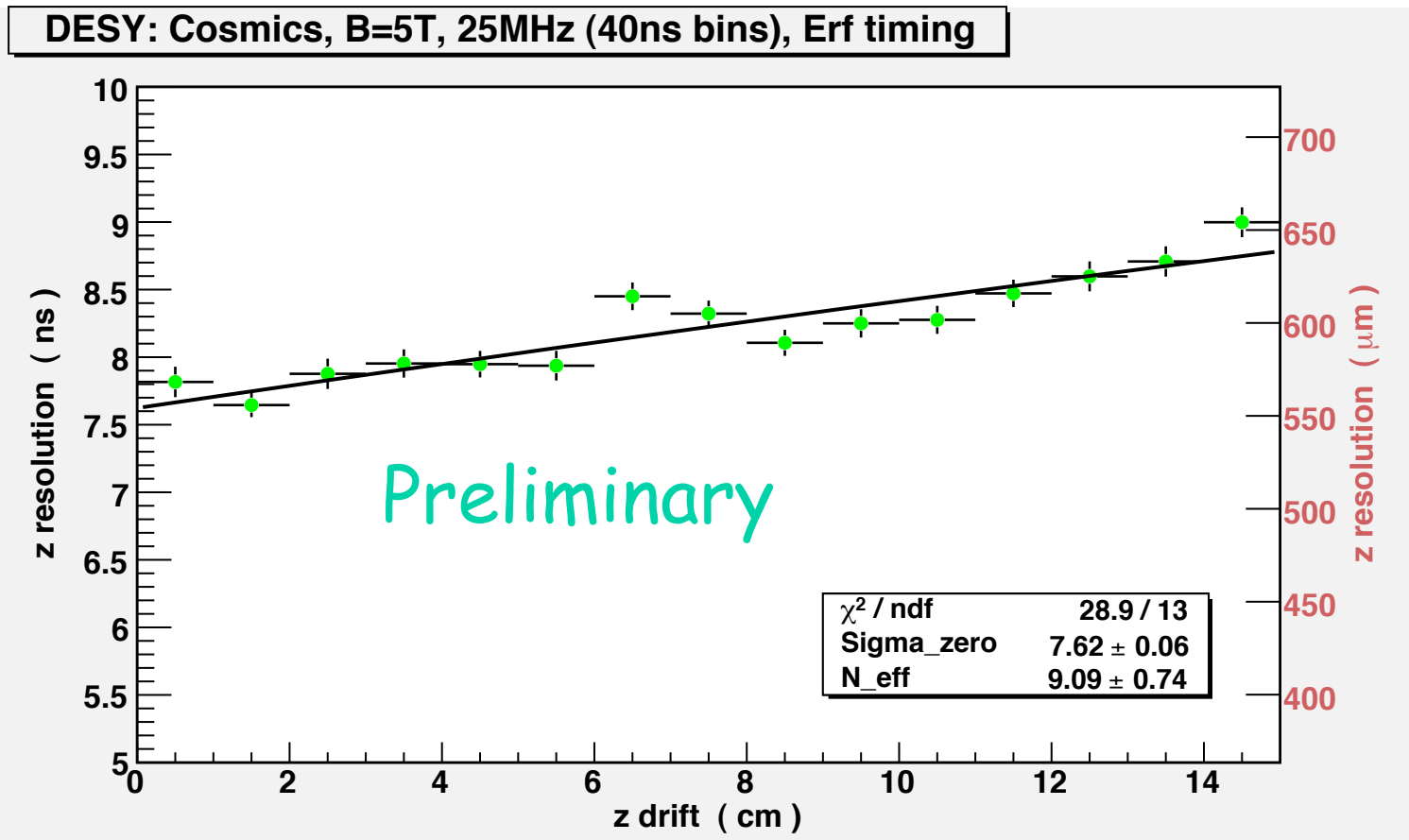
$E=70\text{V/cm}$   $V_{\text{drift}}=25\ \mu\text{m/ns}$ ,  $D_{\text{Long}}=479\ \mu/\sqrt{\text{cm}}$



# DESY 5 T cosmic tests

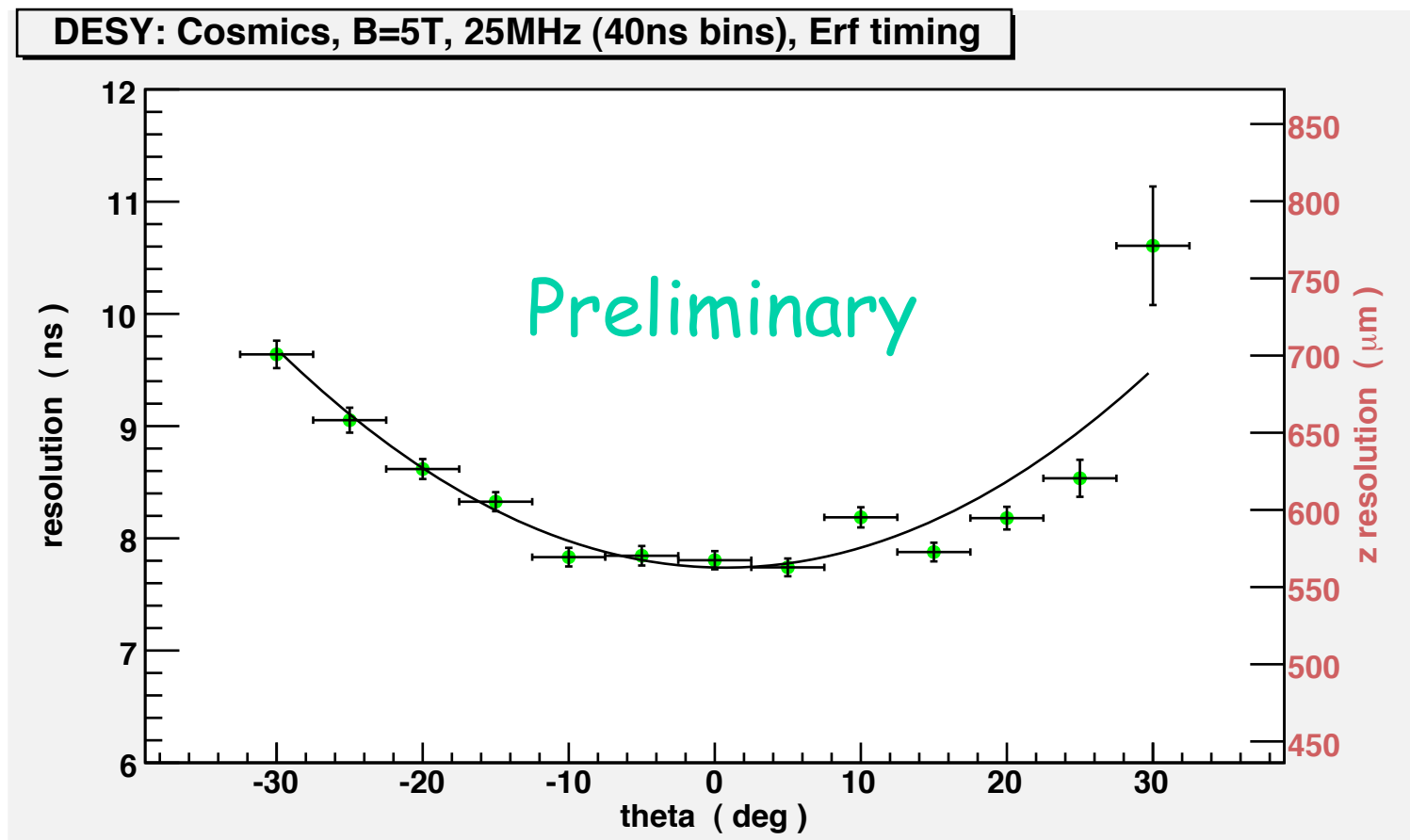
Ar+2%*i*C4H10+3%CF4

$E=200\text{V/cm}$   $V_{\text{drift}}=73\text{ }\mu\text{m/ns}$ ,  $D_{\text{Long}}=249\text{ }\mu\text{/}\sqrt{\text{cm}}$





# Track angle dependence of time resolution



# Summary

- Charge dispersion makes MPGD position sensing independent of pad width. High resolution can be achieved with relatively wide pads
- The original PRF algorithm was “undemocratic” resulting in the analysis being sensitive to noise.
- $\sigma_0(r-\phi) \sim 30 \mu\text{m}$  achieved for 2 mm x 6 mm pads is now comparable to the “residual bias” from anode structure RC non-uniformities.
- Improved materials and fabrication techniques should further reduce bias.
- A first measurement z resolution for Micromegas with charge dispersion readout:
  - $\sigma_0(z) \sim 550 \mu\text{m}$  (fast gas,  $v_{\text{Drift}} = 73 \mu\text{m/ns}$ )
  - $\sigma_0(z) \sim 100 \mu\text{m}$  (slow gas,  $v_{\text{Drift}} = 25 \mu\text{m/ns}$ )
- $N_{\text{eff}}$  significantly smaller for longitudinal measurements than for transverse.