ILD: Forward Detectors

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## Forward Region



LumiCal: luminosity measurement



LumiCal detector = 2 identical calorimeters positioned at  $\pm$  2500 from IP

# And expected background – Monte Carlo studies

From physics: the main contribution from 2-photon processes –four fermions in final state





## LumiCal - calorimeter

Single sampling calorimeter :  $30 X_0 \text{ Si} / W$ thickness tungsten plane:  $3.5 \text{ mm} (\sim 1 X_0)$ , calorimeter will be split into half cylinders (left and right) and will be clamped around the beam pipe. Opening/closing with accuracy better than ~4 µm. Odd/even planes rotated by 7.5 degree, to each tungsten plate, on one side, silicon detectors will be glued.

X/Y/Z position: 15.9/0/±2500 mm with respect to the outgoing beam The outer radius of the calorimeter: 260 mm to cover the space for FE electronics, readout cables, cooling system and precision positioning sensors (alignment).

The mechanical inner radius: 76 mm After Lol:

the diameter of tungsten plates have been lowered from 231.5 mm to 200 mm to reduce of heavy (dead) material which was not covered by silicon sensors. The final shape of tungsten planes is under work, there are calculations of the stiffness for mechanical structure recently proposed.

Water (liquid) cooling system is required to reduce heat of ~ 30 W created by FE electronics .

Sensors:

Sensor thickness:  $320 \ \mu m$ The sensitie region:  $(80 - 195.2) \ mm$  in radius 64 rings which cover  $\theta$  range:  $35.3 - 83.9 \ mrad$ 48 azimuthal divisions The next step – after Lol - towards the final structure





In mechanical construction two types of rings are required, With the special bolts, calorimeter can be asembled and placed on the support.



Yellow sector: produced by Hamamatsu company (40 such silicon sensor sectors are available in FCAL)

Proposed structure for TB measurements



# LumiCal: integration aspect(1) – place and free space





LumiCal: available free space ~ 3 cm in front of and ~ 5 cm behind – for positioning system and electronics. Cables together with VTX and FDET will be above and under LumiCal.

A gap between LumiCal and EndCap square hol (Ecal ring) will be used for front end electronics, cabling and cooling. This space is also used for inner cables outgoing from VTX nad FDET rings. The reserved space for cables ~  $360 \text{ cm}^2$ .

Cables outgoing from the inner detectors via a square support tube must have connectors to disconnect them from the inner part of ILD maintenance. A possible space for connectors behind LumiCal is foreseen.

LumiCal cooling –temperature-stable water together with temperature stabilization – thermal insulation An opening scenario assume a temporary support for LumiCal for assemly and disassembly in the ILD detector

# LumiCal : integration aspect(2) - alignment



Alignment: laser beams + CCD (CMOS sensors) – LumiCal position measurement relative to beam pipe or QD0 magnet (~ 100  $\mu$ m). The final LAS system – interferometric (FSI) method.



The required accuracy in distance measuremet between two calorimeters : less than 100  $\mu m$ 

Possible vacuum pipes (4-6) inside support tube for laser beam lines (FSI). Capacity sensors and/or IR laser with semi transparent sensors will be used for internal layers displacement measurements – a required accuracy few micrometers







Carbon tube made with pipes for laser beams (higher stiffness) Possible (?) windows in beam pipe for laser beams

## Beam pipe shape

Two possible solutions for beam pipe shape in front of LumiCal



Particles which enter LumiCal traverse the beam pipe and secondary particles are created. Such preshowers depend on thickness and material of the beam pipe

Particles traveling from IP to LumiCal do not pass practically any material – very little matter in front of LumiCal

Beryllium beampipe, with inner radius of 5.5cm, and outer radius of 6cm (the minimal radii for a 14 mrad crossing angle).

Problems with required vacauum at the edges of the beam pipe near LumiCal (no place for a pump in the forward direction? Possible disturbances for the magnetic field – boundary conditions ?

## An example of MC studies



From Monte Carlo studies (B.Pawlik, I. Sadeh): different shapes, and materials (Be, Fe) - influence on relative error in luminosity measurements  $\Delta L/L \sim \Delta \theta$  (offset on rec. angles) /  $\theta_{min}$  (lowest angle accepted):

a few % an increase in polar angle offset and polar angle resolution for tube option for Bhabha events. This induces a relative bias in the efficiency of the Bhabha selection process.

For beamstrahlung: optimalisation on minimalisation in hits number and maximalisation for event rate was done. Results beam pipe should be centered on outgoing beam-line, better case for conical type.

In any way, the conical shape allows to get required accuracy in luminosity measurements

# LumiCal : Background studies (Mokka)

For conical shape of beam pipe





### BeamCal: challenges

#### PRC Report, DESY, November 2009

Detailed simulation studies on background effect on BeamCal sensors and FE electronics coming from:

- beamstrahlunhg e<sup>+</sup>e<sup>-</sup> pairs
- neutrons



#### neutrons

An example of obtained results: the total number of low energy (< 1 MeV) neutrons as function of the layer depth : for 5 BX, a maximum appeared at ~7-9 layers with about 10 000 neutrons, an even higher value was observed for neutrons with energy > 1 MeV. The presence of QD0 behind BeamCal increases the flux of neutrons in the second half of BeamCal. Neutron fluence for electronics: in the selected layers (19,24) fluence (n/mm<sup>2</sup>) was on the lewel below 0.1, an increase was observed at the last layer of FE electronics when QD0 was included in geometry for Monte Carlo simualtion

# BeamCal

Bottom half

Low-Z mask graphite as additional absorbersuppresion of detector backgrounds

Cutout for assembly

and maintenance

BeamCal -

installed in the

ILD support tube

30 X<sub>0</sub> (sensors: not yet choosen / W sampling calorimeter Tungsten thickness: ~ X<sub>0</sub> (3.5 mm) Sensor thickness: ~0.5 mm X/Y/Z: 24.2/0/ $\pm$ 3450 mm 10 cm graphite in front Rin / Rout (sensor) 20 /150 mm Rout (mechanics) 200 mm  $\theta$  range: 5.8 – 43.5 mrad ~ 40 k readout channels

### **BeamCal mechanics**



(a) BeamCal half-layer assembly.

Graphite shield – reduction of backscattering decrease performance



#### BeamCal -

two parts an upper and a lower half: it allows for installation and disassembly without interrupting the vacuum. This required the possibility to open the upper part of support tube to access.

ΙĒ

3350 mm

#### Special frames for assembly BeamCal

A special support structure: static and sets of rolls – allows for BeamCal rotation around its axis. Grey parts temporary used before beam pipe installation – removed during calorimeter installation

# Summary

- The systematic, large progress towards the final design for all forward detectors are observed.
- The recent developments take into account the requirements of the tasks for which they will be build and their expected contributions to physics study at ILD.
- The serious problem comes from unwanted background, limited available space inside the ILD structure and from machine requirements (beam pipe, magnents) – MDI
- The R&D work for forward detectors will be continuing to get final engineering technical projects at 2012. But what if the financial support will be not enough in the next two years? A realistic estimation a cost and man power for future work should.