

Cavity BPM: Multi-bunch analysis

N Joshi, S Boogert, A Lyapin, F. Cullinan, et al.

Nirav.Joshi.2009@live.rhul.ac.uk

Royal Holloway University of London, ATF team.





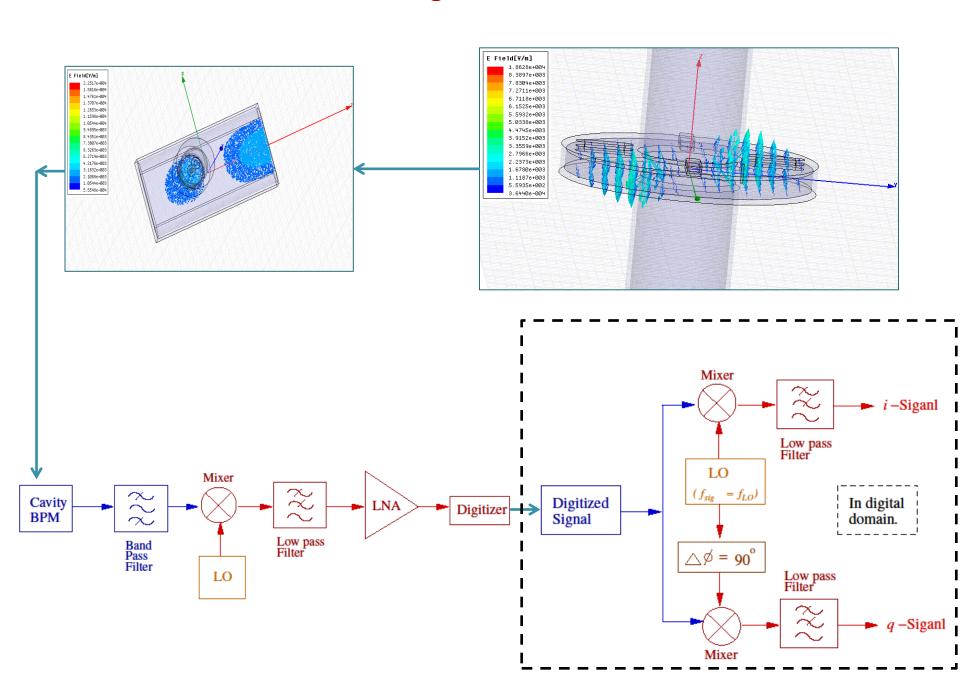
System information

- □ Data was acquired during the machine operation in multibunch(train) mode for FONT shift in December 2010.
 - O Bunch separation, Δt_b : 154 ns
 - Number of bunches, n:3
- Cavity parameters

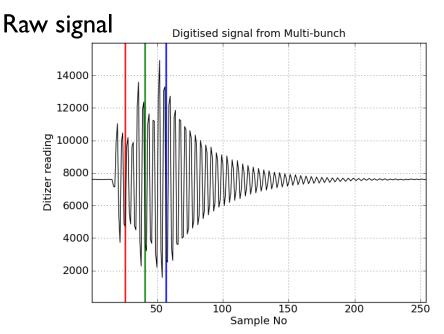
Parameter		Dipole cavity	Reference cavity
Cavity used for calculation		QM13FF	REFI
Direction		Υ	
IF frequency	(GHz)	6.423586	6.4223
Decay time constant $ au$ (ns)		305.49	300.66

Only one mover scan was recorded to minimize any disturbance in on going operation.

Block diagram: Process flow



Signal Processing



Colour convention:

Bunch1

Bunch2

Bunch3

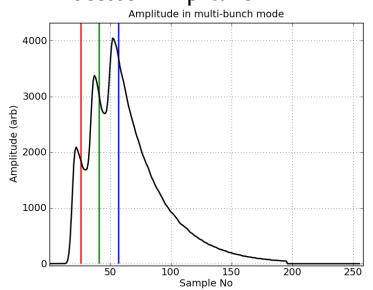
Normalization:

$$I(n) = \frac{A_{BPM}}{A_{REF}} \cos (\phi_{BPM} - \phi_{REF})$$

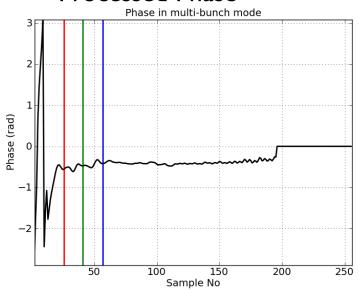
$$Q(n) = \frac{A_{BPM}}{A_{REF}} \sin (\phi_{BPM} - \phi_{REF})$$

$$Q(n) = \frac{A_{BPM}}{A_{REE}} \sin \left(\phi_{BPM} - \phi_{REF} \right)$$

Processed Amplitude



Processed Phase

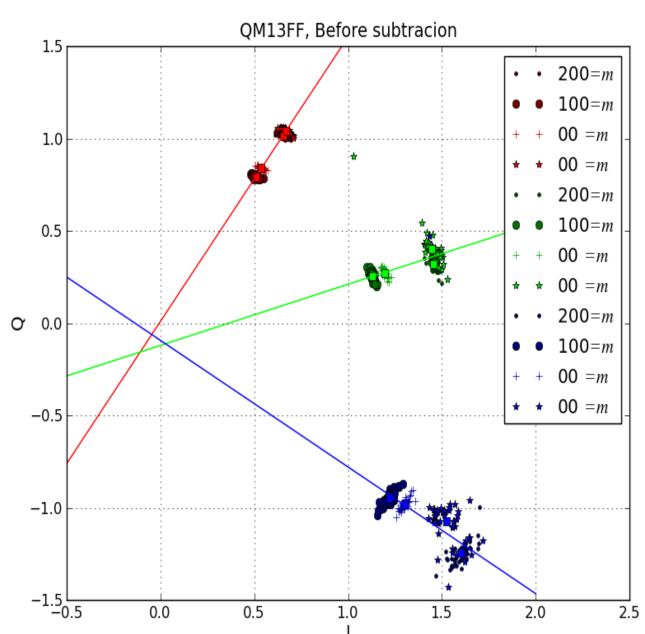


IQ: Without bunch subtraction

- BPM is moved along Y axis at 200, 100, 0, 0μm positions respectively.
- I & Q are calculated in a similar way as single bunch calibration, without any bunch subtraction.
- With change in mover position, I&Q from Ist bunch moves along a straight line in IQ plane passing through (0,0)
- Steps along straight lines in IQ plane from 2nd and 3rd bunches shows the behaviour expected from a cavity BPM.
- IQ signal from a bunch is polluted by the decayed signal from previous bunches.

Rotation Angle:

Bunch No	ϕ (rad)	$ \Delta\phi $ (rad)
1	0.98778	
2	0.32898	0.65883
3	-0.59777	0.92671



IQ: After bunch subtraction

Bunch Subtraction:

- o i & q signals from BPM and reference cavities are subtracted separately before normalization.
- Decayed i & q from previous bunch is subtracted from current bunch.

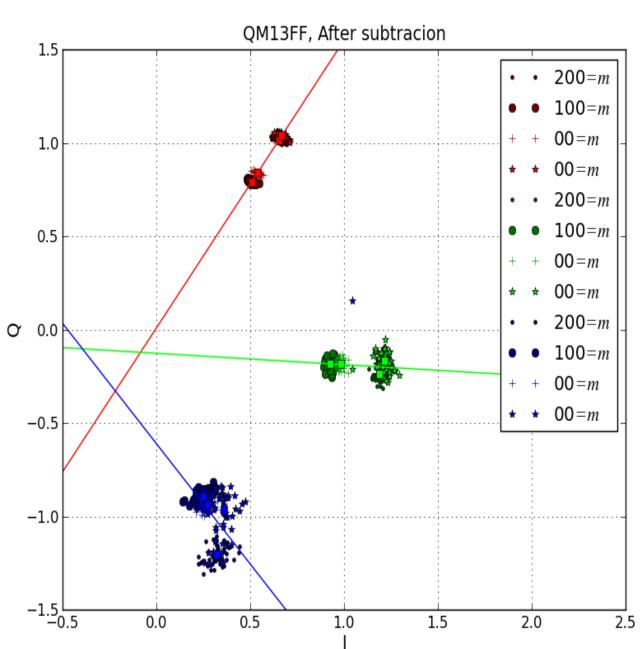
$$i_s(n) = i(n) - i(n-1)e^{\frac{-\Delta t_b}{\tau}}$$

$$q_s(n) = q(n) - q(n-1)e^{\frac{-\Delta t}{\tau}}$$

- Subtracted signal is then normalized.
- Phase difference between bunches becomes even.

Rotation Angle:

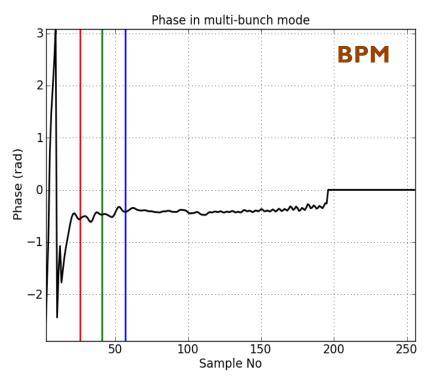
Bunch No	ϕ (rad)	$ \Delta \phi $ (rad)
1	0.98778	
2	-0.04182	1.029609
3	-0.96794	0.926120

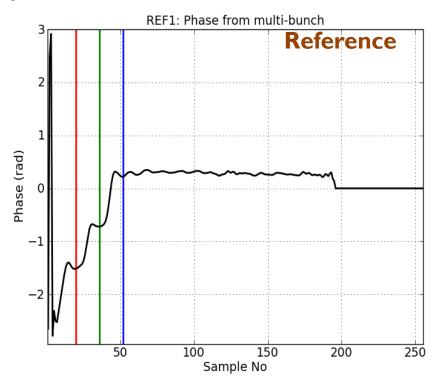


Phase difference between bunches

One of the reason can be the difference in frequency between BPM and reference cavity. It will generate certain phase difference over a period of time.

$$\Delta \phi = \Delta \omega \times \Delta t_{b}$$





- The difference in frequency is 1.2MHz., the bunch separation of 154ns will generate phase difference of 1.1611 rad, which agrees with observation.
- o If BPM and reference cavities have different frequency and decay constant, then their effects can be removed by normalizing with following general equation.

$$I(|Q|) = \frac{A_{BPM}}{A_{REF}} e^{-\left(\frac{1}{\tau_{BPM}} - \frac{1}{\tau_{REF}}\right)\Delta t_b} \times e^{i\left[\left(\phi_{BPM} - \phi_{REF}\right) - \left(\omega_{BPM} - \omega_{REF}\right)\Delta t_b\right]}$$

Conclusions

Position scan was recorded for BPM during multi-bunch operation mode. IQ plots, for each bunch, point towards a single point in plane. That indicates that the system is working as a beam position monitor in multibunch mode as well. Observed difference in phase, between bunches, is in agreement with its theoretical explanation derived till date. Future work More data will be recorded for different BPMs over different position range. Jump in IQ phase between bunches is being studied. Results will be scanned over range of parameters, such as the digital filter bandwidth and data extraction sample points.

Ultimate goal is to make BPM system online in multi-bunch mode as well.

