

OTR Monitors and Emittance Measurements



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IFIC (CSIC-UV)

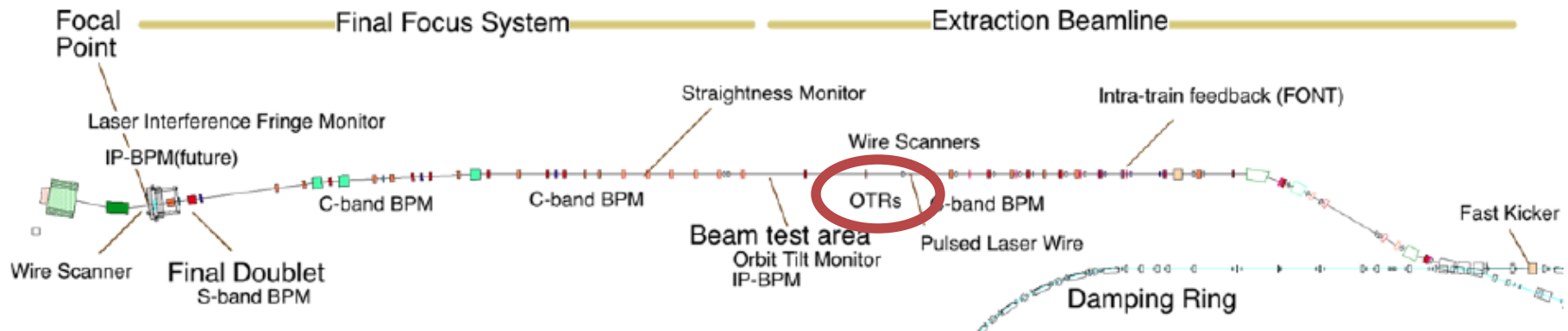
D. McCormick, G. White,
J. Cruz, M. Woodley

SLAC

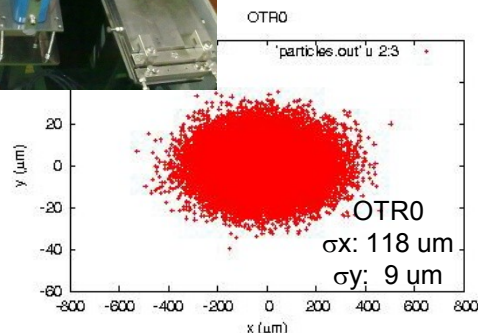
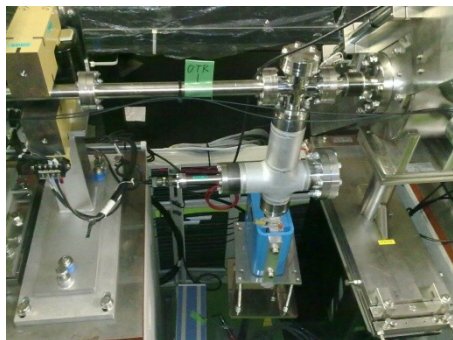
and

KEK team

Multi-OTR System Overview



- The multi-OTR system of **4 OTR monitor** installed in the zero-dispersion part of EXT line
- **Fast emittance measurements** with high statistics
- Design based on existing OTR1X with improved features and we will get **2um resolution**
- **Installed near WS** for comparison and confirmation of OTR as a beam emittance diagnostic device



13-14 January

11th ATF2 Project meeting

Multi-OTR System February 2010: H/W Tests



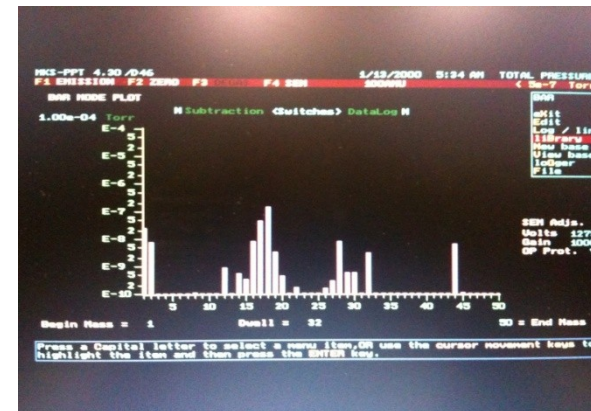
Assembling and first tests at SLAC and IFIC labs after fabrication



Vacuum test made at SLAC



without OTR

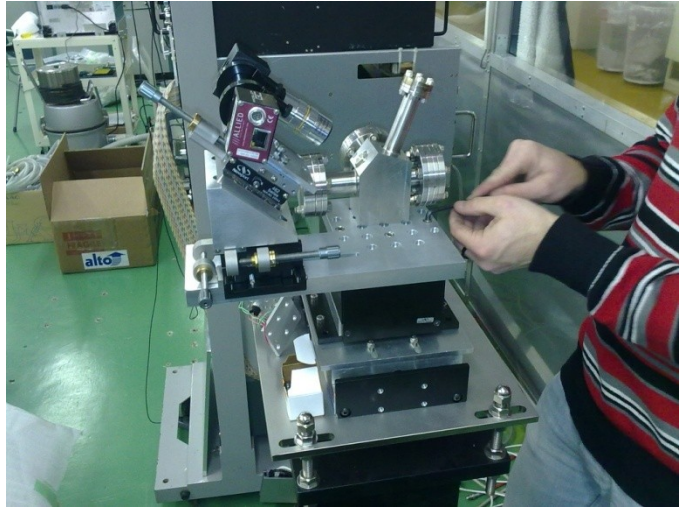


with OTR₃

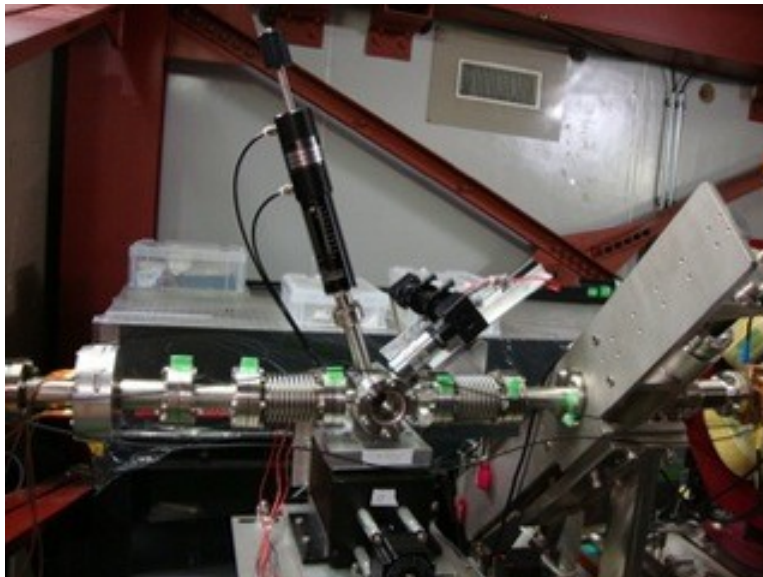
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Multi-OTR System April / May 2010: H/W Installation



April: All **4 OTRs**
were assembled
at ATF clean
room



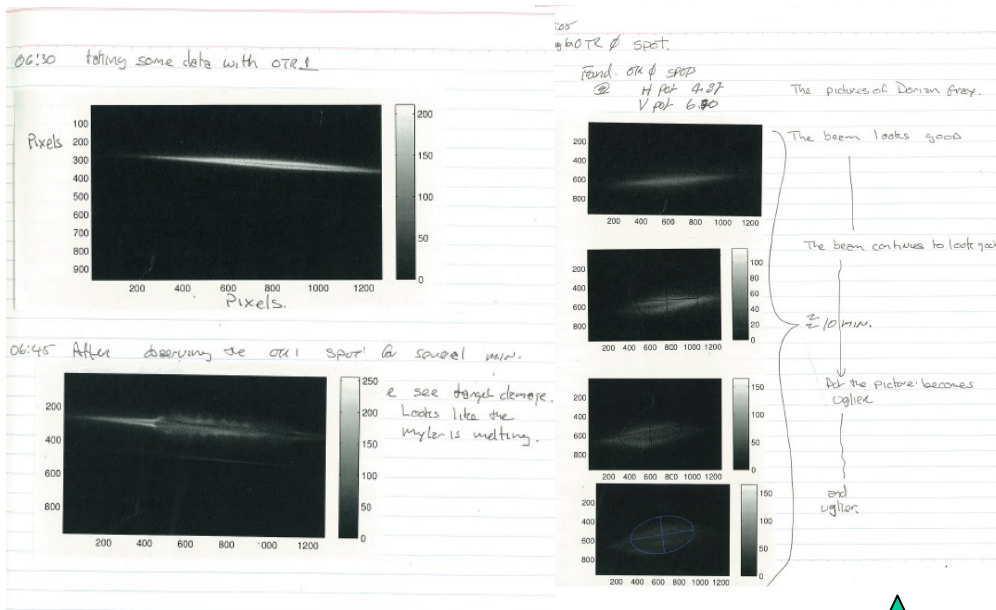
May: All **4 OTRs**
installed in the EXT line

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4

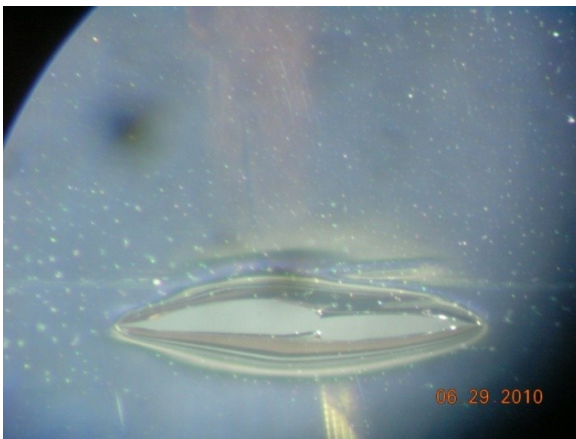
Multi-OTR System June 2010: First Measurements



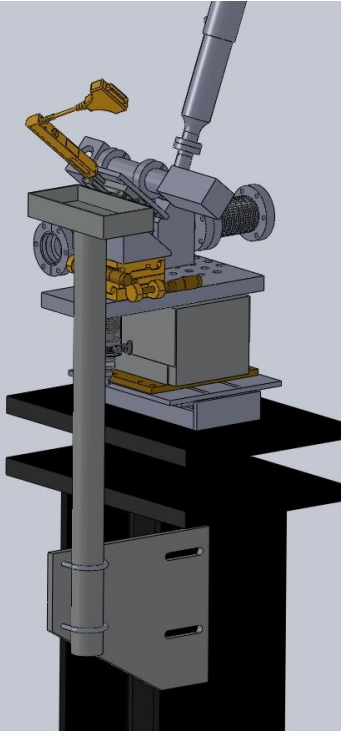
- Exercise and calibration of vertical and horizontal **movers** and read-back **potentiometers**

- Tests of 4 OTRs during beam time: beam seen but 3 **targets** (nitrocellulose coated aluminum) **were damaged** (4×10^9 e⁻ per pulse)

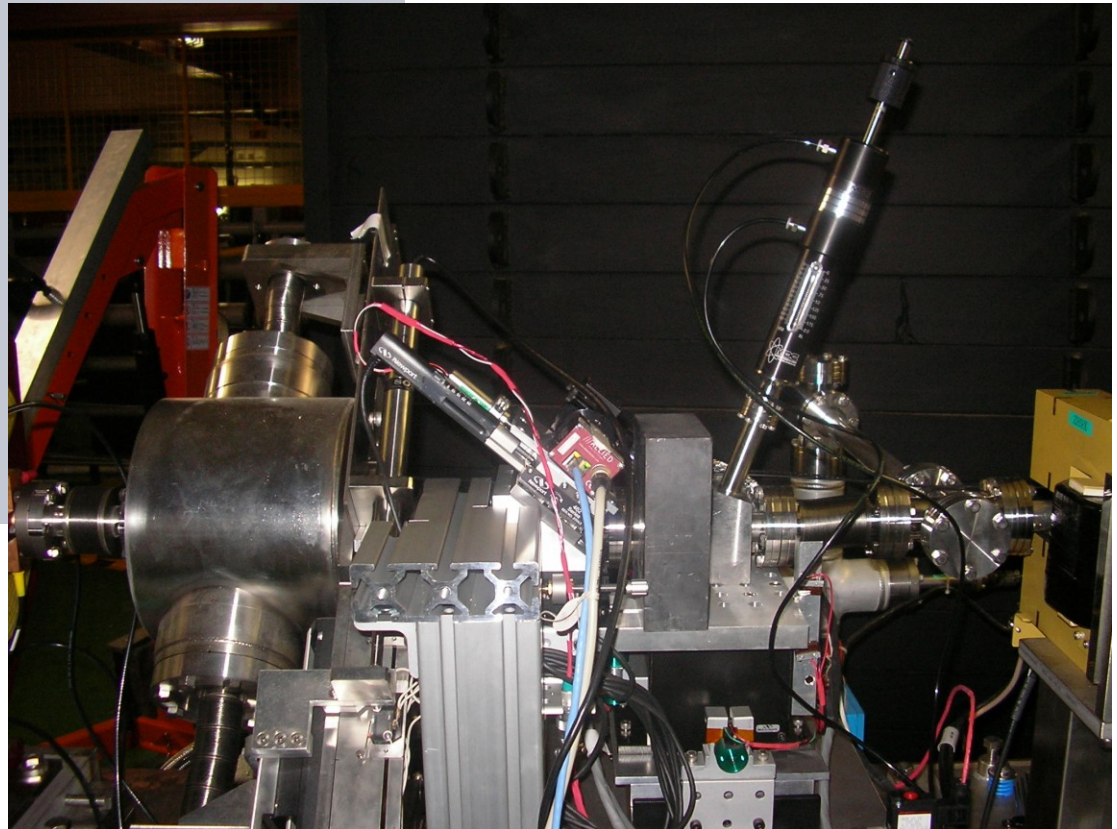
- CCD **Cameras** suffer from **radiation**, some pixel are dead.

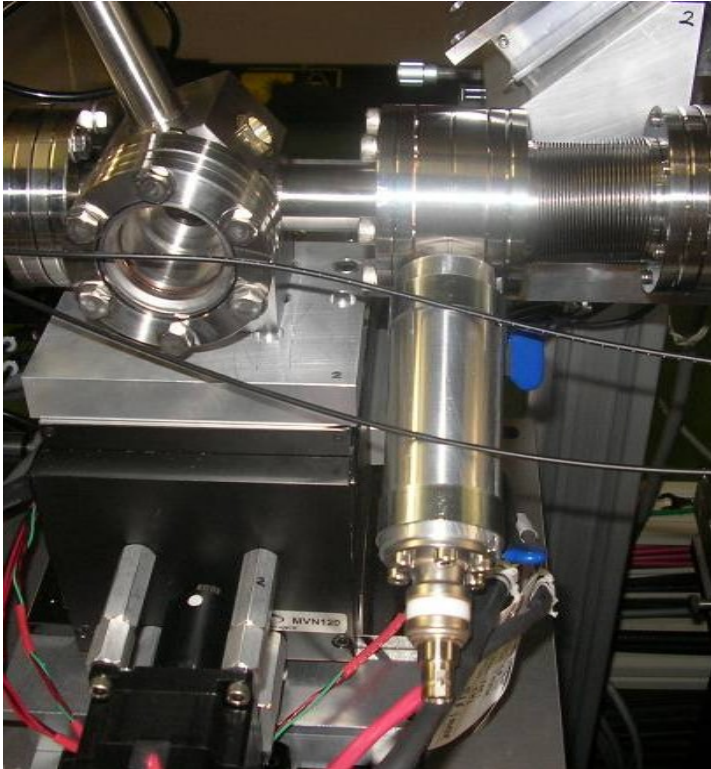


Damaged target



Lead blocks has been added to protect cameras from the radiation

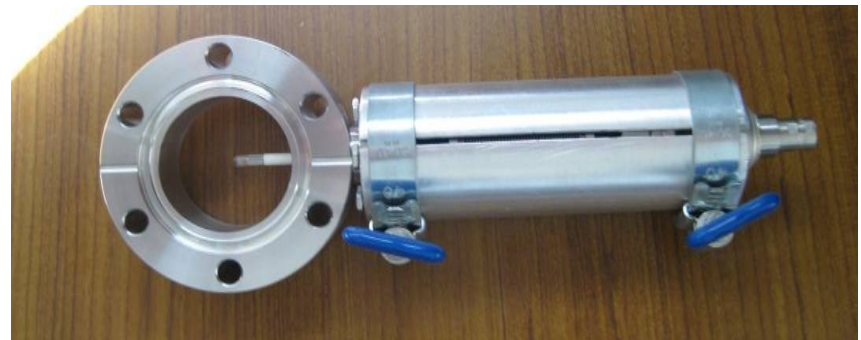




Illuminators were installed to facilitate calibrating tasks by **lighting** the **target** from the **beam direction**



BNC feedthrough, copper connector, ceramic tube with bulb, SS tube (ceramic tube holder), bellow and flange with port.



Aluminium tube and clamp to hold the bellow



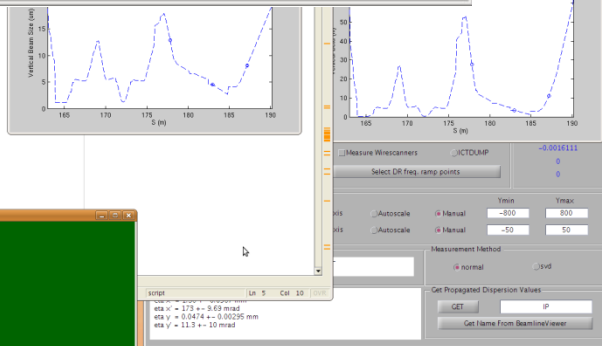
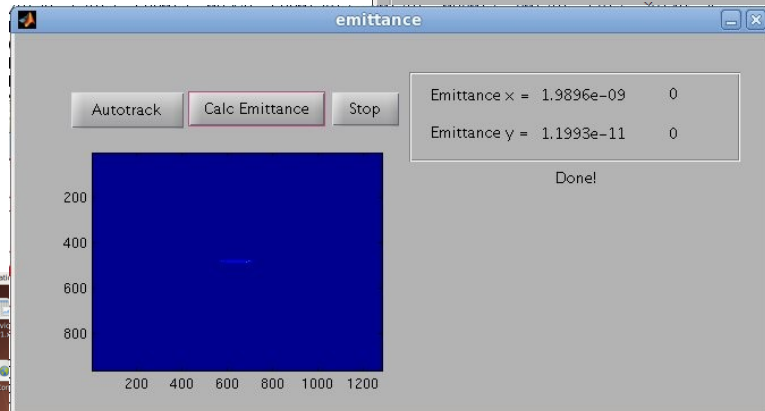
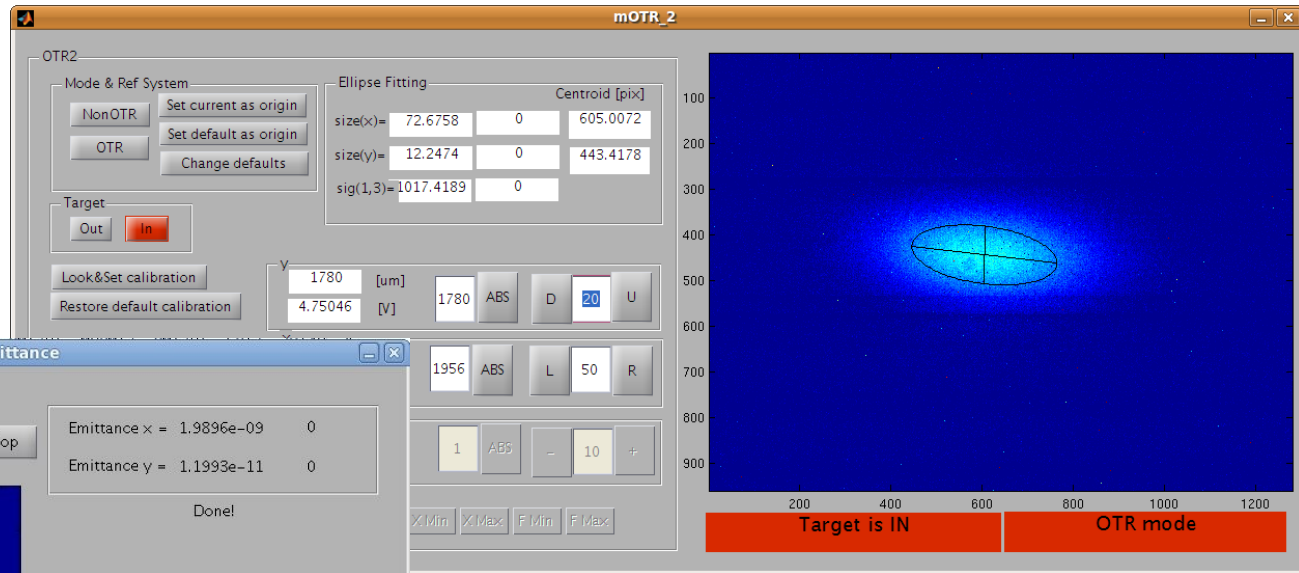
New targets could **stand the beam currents** for several minutes without being damaged



Two **new targets** were installed, two made with **aluminium** and two with **aluminized kapton**. Besides, together with all them were installed the **wire targets, made with 4 wire**, one horizontal, one vertical and two tilted.

Multi-OTR System

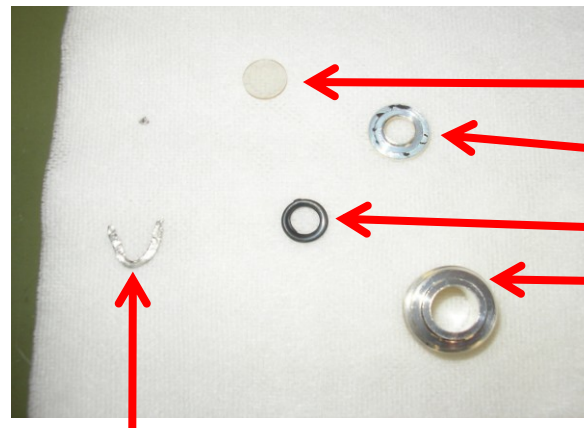
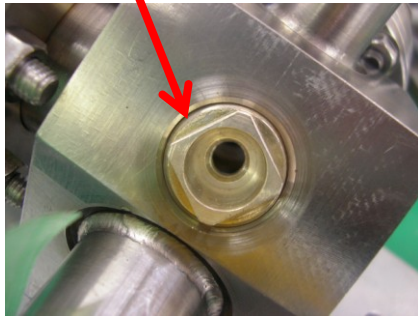
November 2010: First calibration of vertical scale and first software test



First **GUI tests** and some **initial calibrations** using **IPBSM** were made.

Multi-OTR System December 2010: Vacuum leak repaired

Leak in the camera window



Old indium washer

window

Thrust washer

O-ring

Nut

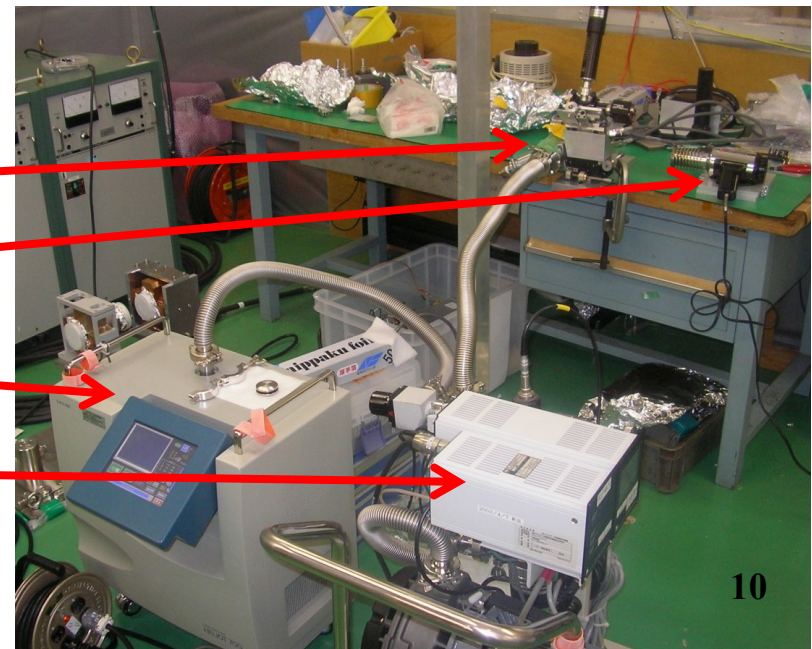
Important **vacuum leak** in the camera window of OTR2 was **repaired** by changing the indium washer

OTR

Heat gun

Helium leak check

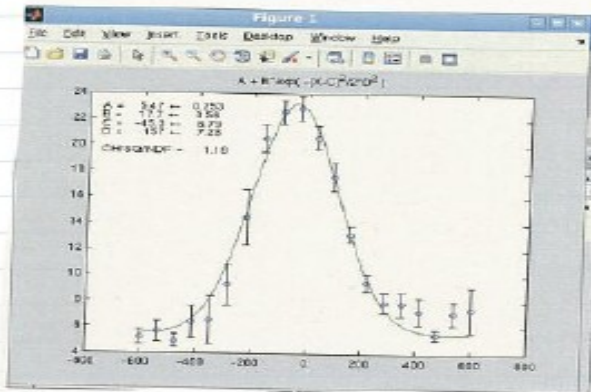
Vacuum pump



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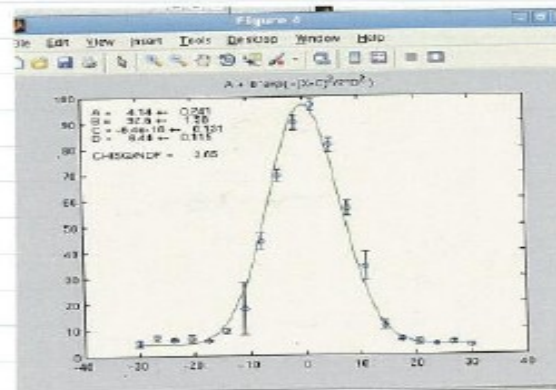
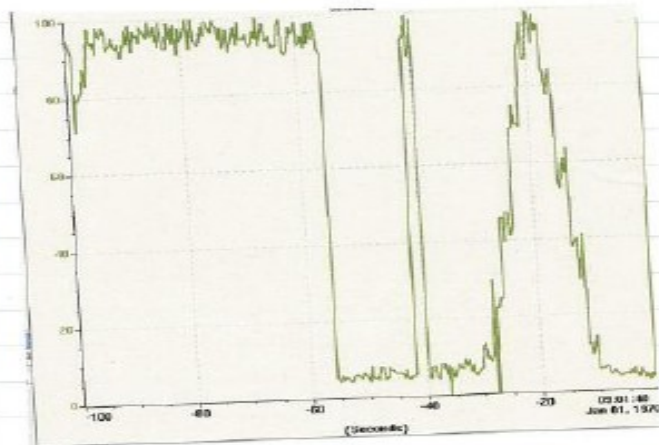
X wire scan from OTR3
 $\sigma = 157 \pm 7 \mu\text{m}$

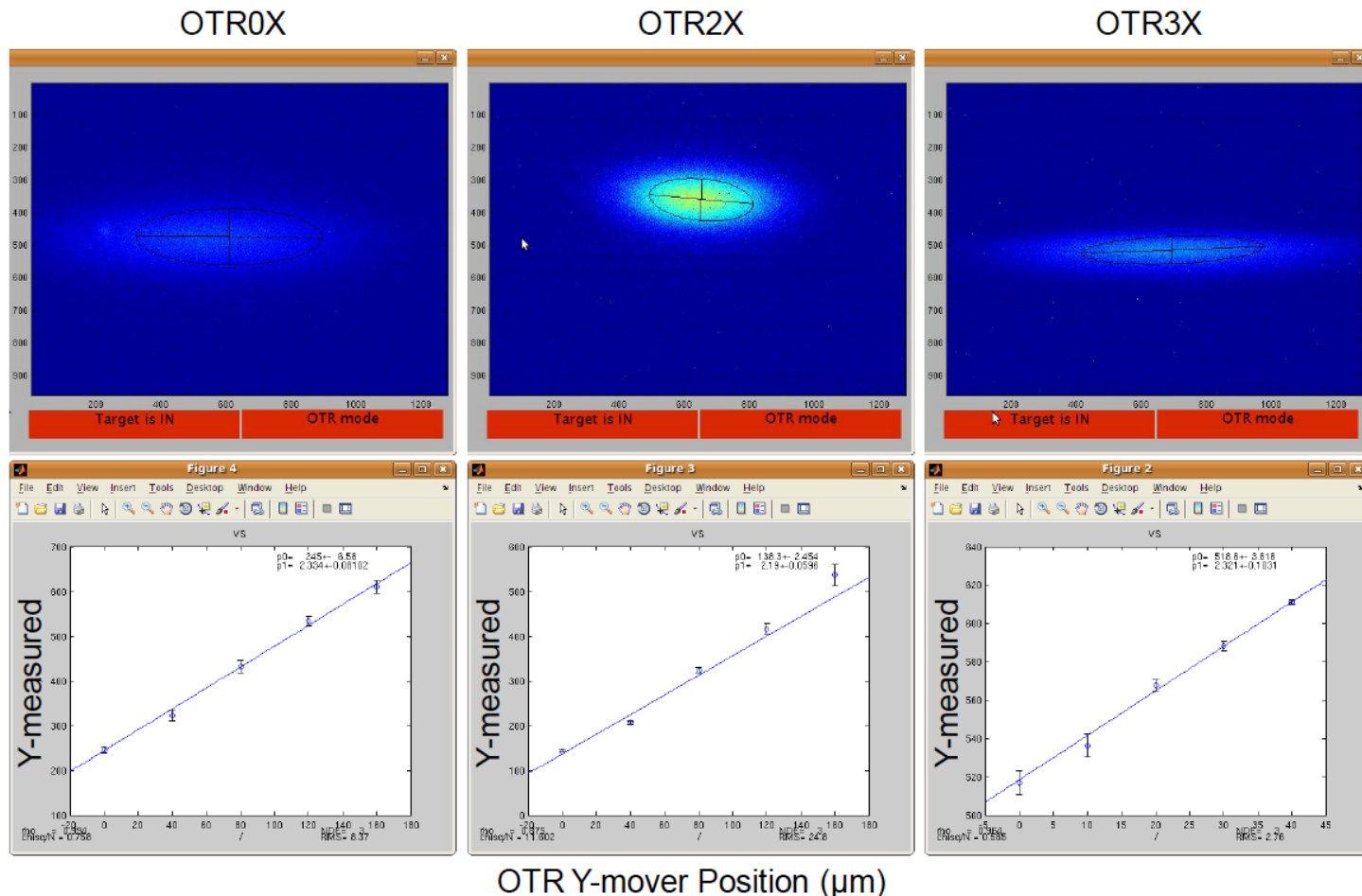


Scan wires vs. signal from IPBSM background detector.

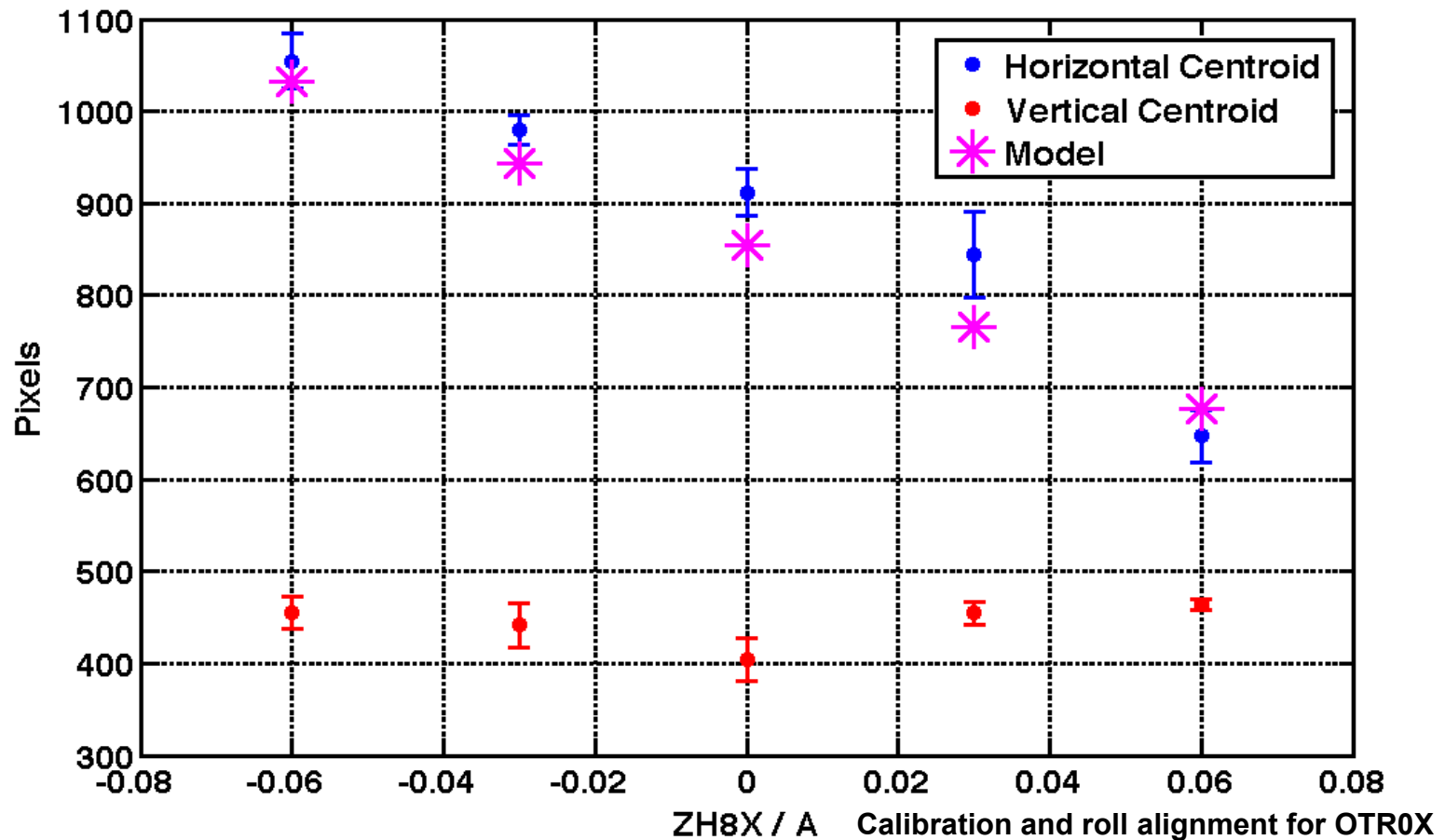
Made to cross check wire scans with observed beam sizes. Numbers agree within fit errors.

Y wire scan from OTR3
 Bism signal





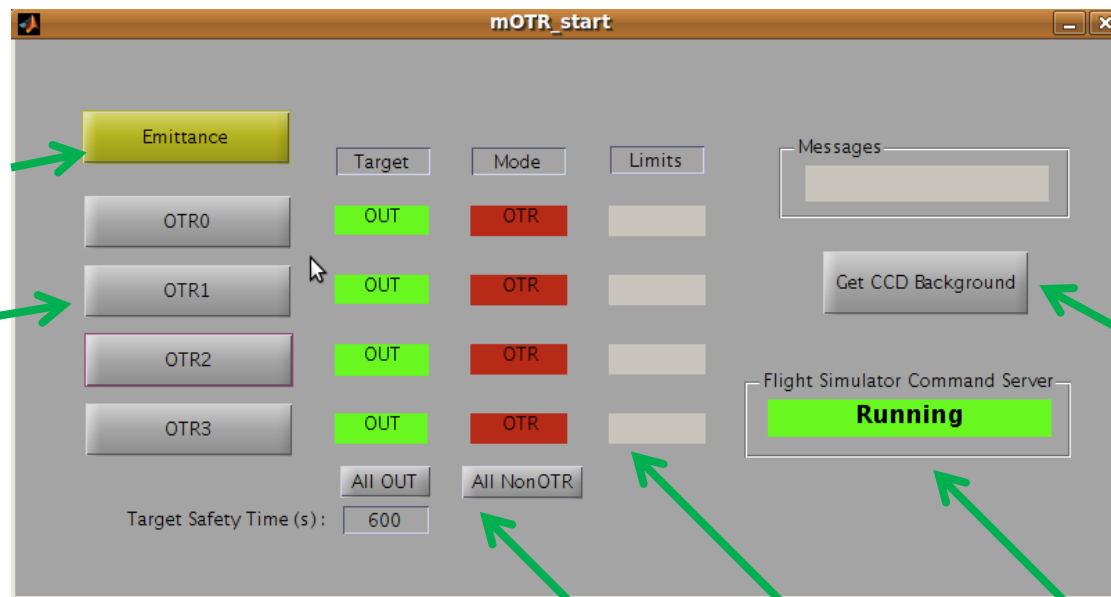
Vertical scale calibration done by scanning the vertical mover stage and recording the motion of the observed beam centroid. Thus the vertical calibration factor $\mu\text{m}/\text{pixel}$ is obtained.



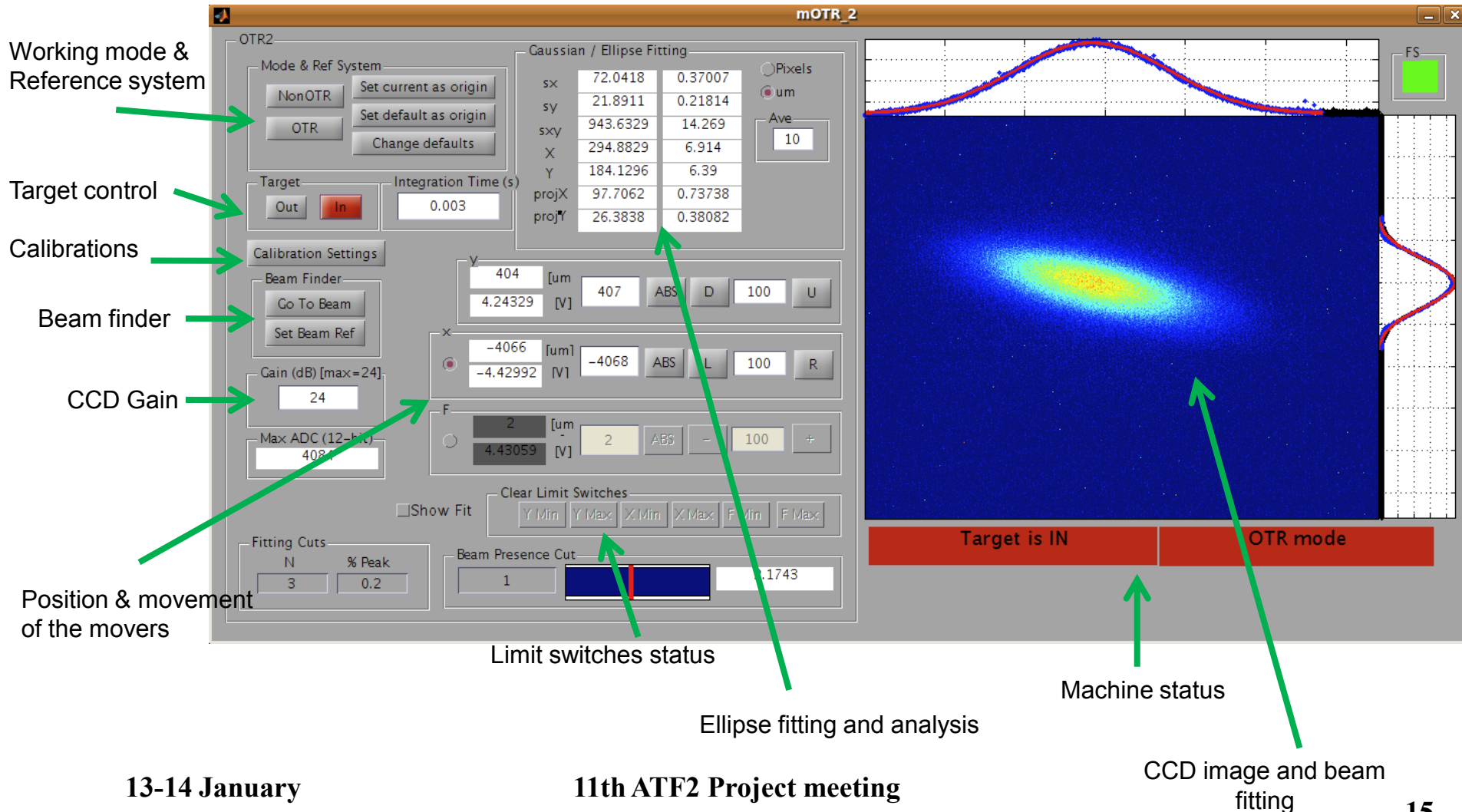
To test the **calibration** an **upstream corrector** is **scanned** and the response is observed on the OTR. To test **roll alignment** (of the OTR CCDs) we have to look for **no motion in the opposite plane**.

- **OTR software** is an standalone compiled executable from **Matlab**.
- Some functions like **emittance calculation** or beam finder need the Flight Simulator running.
- OTR status reported and displayed on global **ATF alarm panel** showing **OTR actuator status**.
- All useful **data is stored in EPICS PVs** and archived in the EPICS archival system.

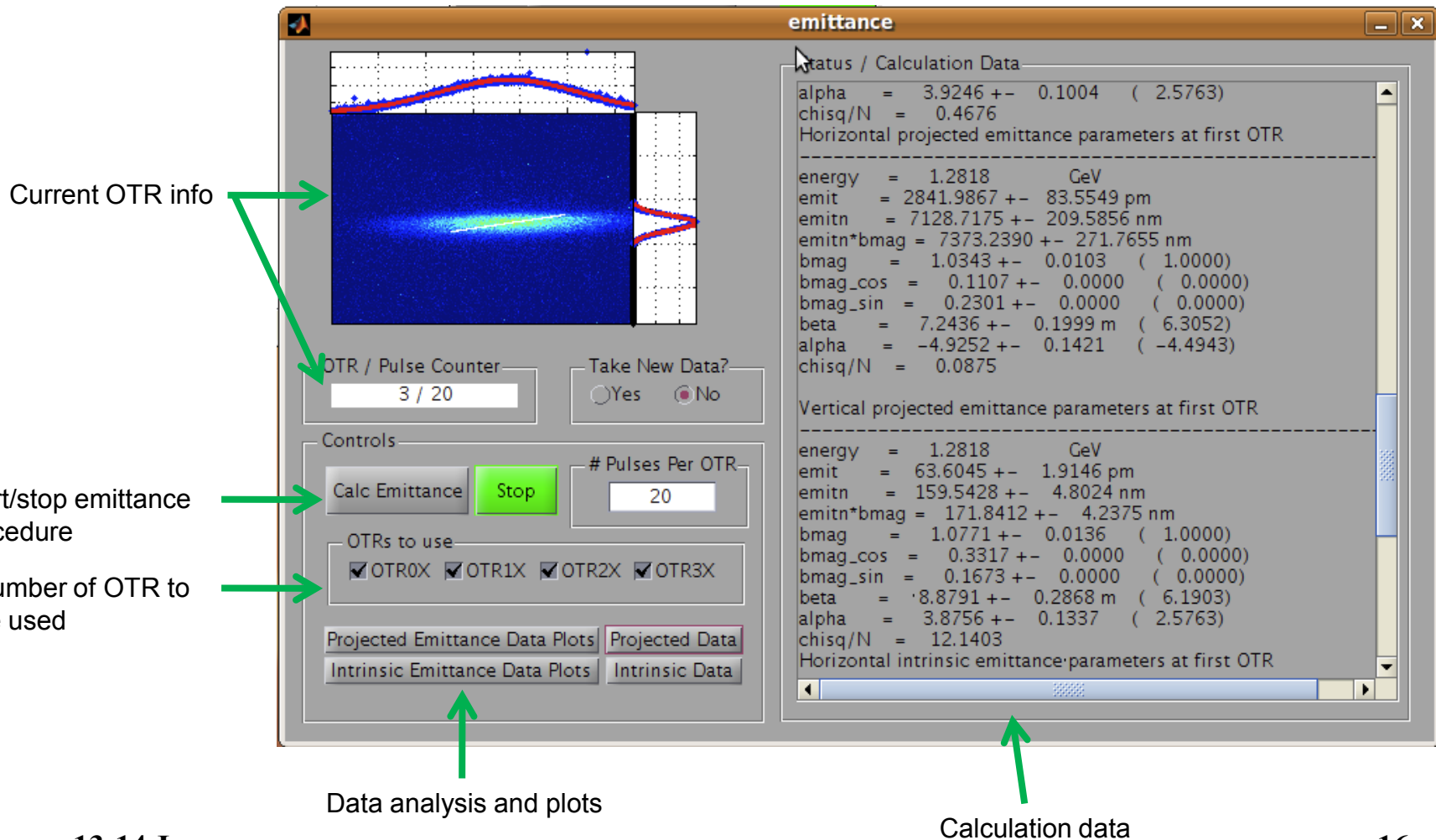
Main start panel

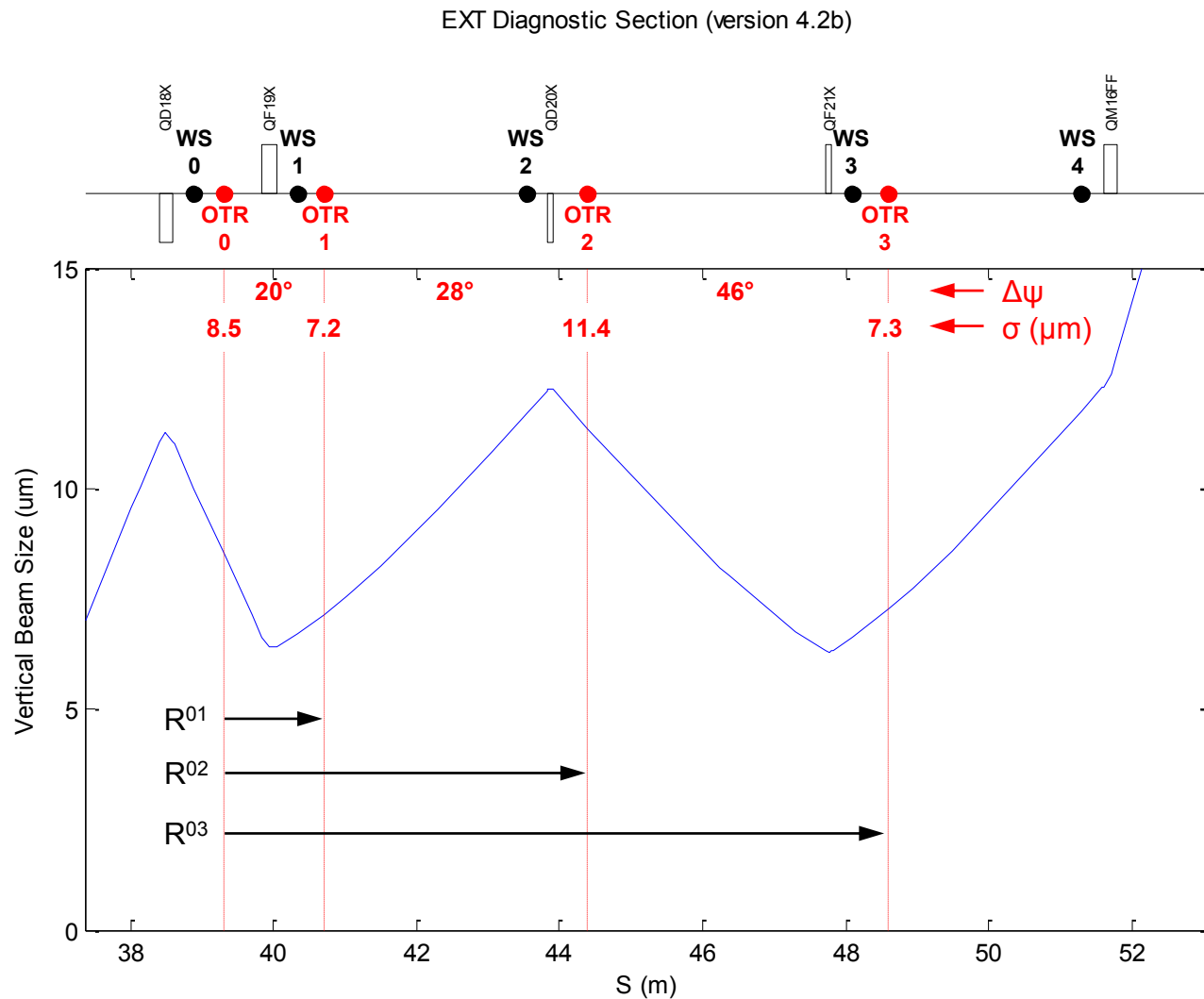


Single OTR panel



Emittance panel





$$\sigma = \begin{bmatrix} \sigma_{33} & \sigma_{34} \\ \sigma_{43} & \sigma_{44} \end{bmatrix}, \sigma_{34} = \sigma_{43}$$

$$\sigma^n = (R^{0n}) \sigma^0 (R^{0n})^T$$

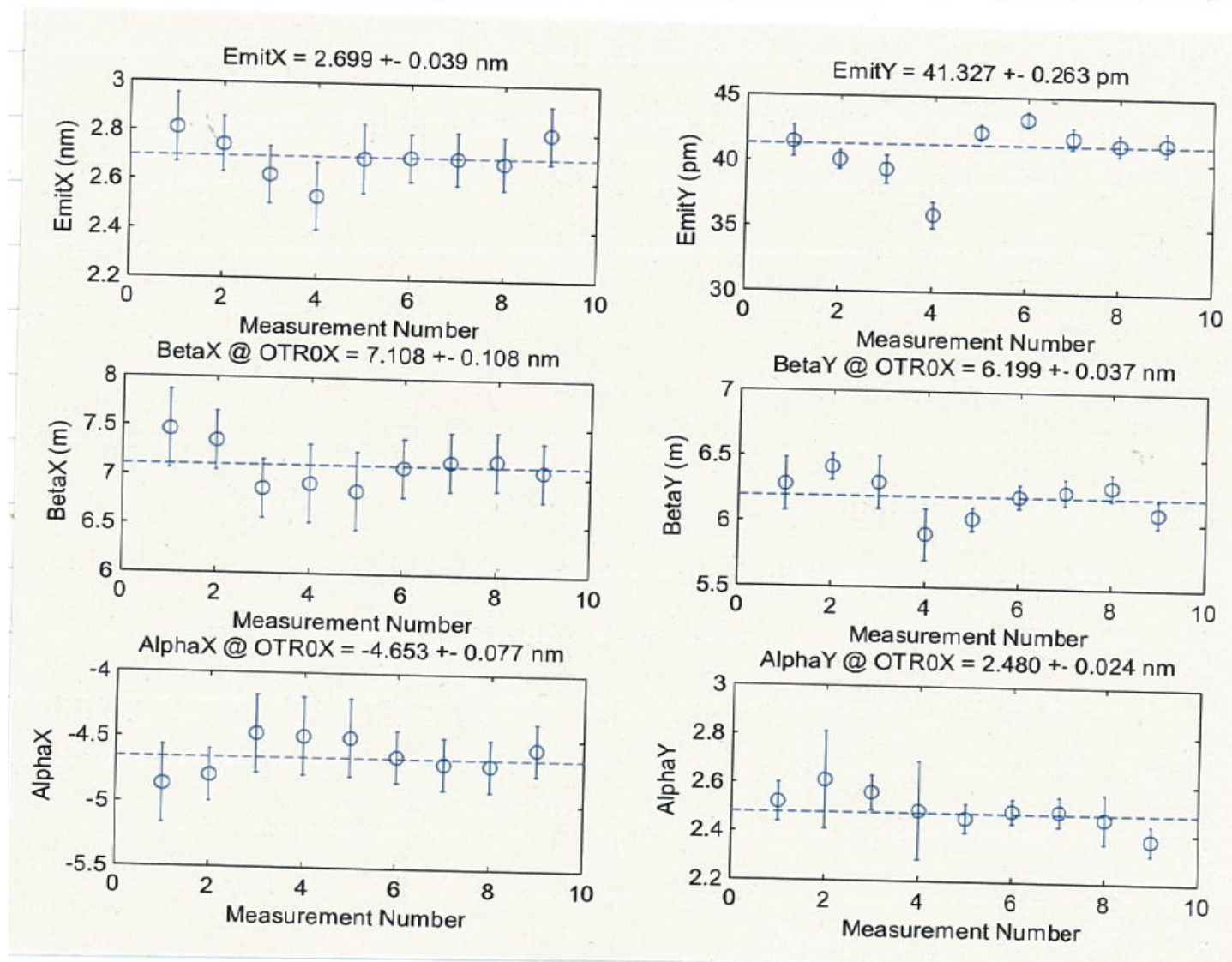
$$A\vec{x} = b$$

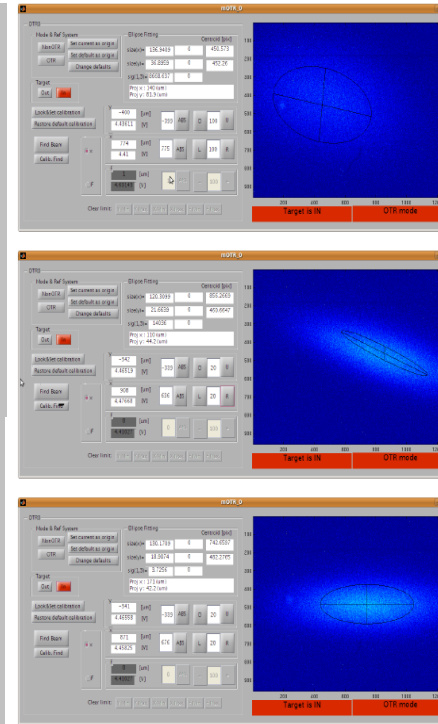
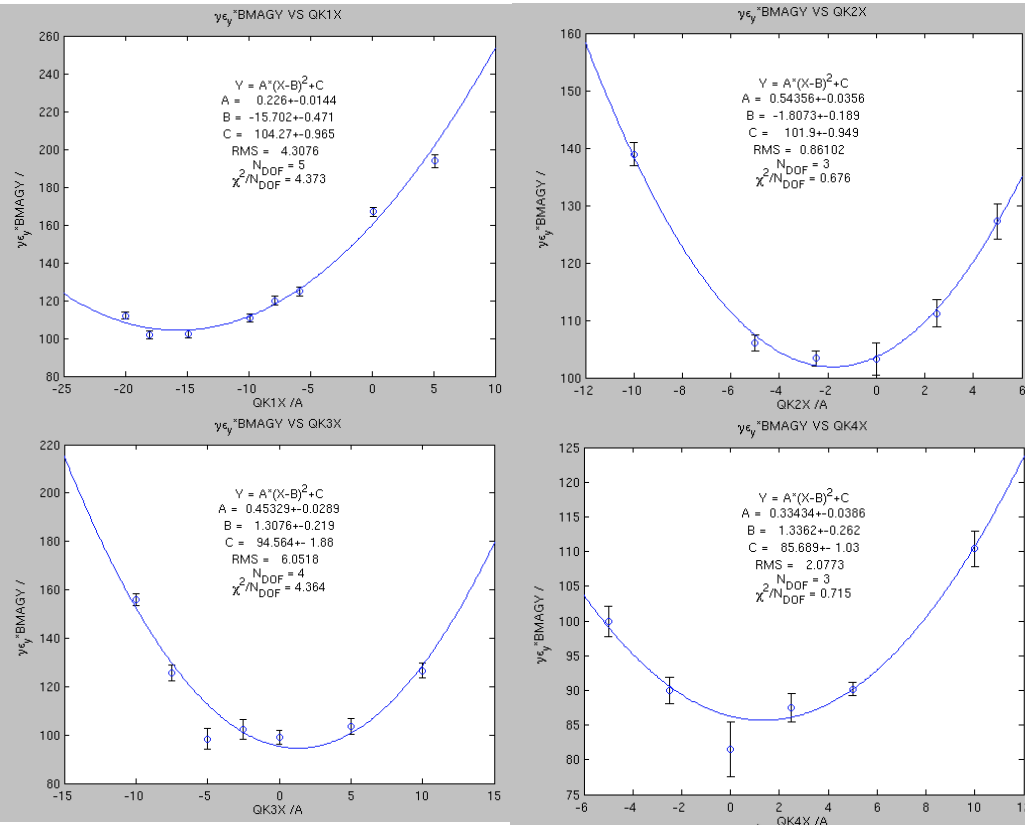
$$\vec{x} = \begin{bmatrix} \sigma_{33}^0 & \sigma_{43}^0 & \sigma_{44}^0 \end{bmatrix}^T$$

$$\vec{b} = \begin{bmatrix} \sigma_{33}^0 & \sigma_{33}^1 & \sigma_{33}^2 & \sigma_{33}^3 \end{bmatrix}^T$$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ (R_{33}^{01})^2 & 2R_{33}^{01}R_{34}^{01} & (R_{34}^{01})^2 \\ (R_{33}^{02})^2 & 2R_{33}^{02}R_{34}^{02} & (R_{34}^{02})^2 \\ (R_{33}^{03})^2 & 2R_{33}^{03}R_{34}^{03} & (R_{34}^{03})^2 \end{bmatrix}$$

- **Measure projected OTR beam sizes σ_n and their rms errors $\delta\sigma_n$ ($n=0,1,2,3$)**
 - Gaussian fits to projections
 - statistical rms of measured beam size over N pulses at each OTR
 - correct measured beam sizes for known dispersion (quadrature subtraction)
- **Solve 3-parameter linear least-squares problem $Ax = b$ using all data**
 - parameters: σ_{33} , σ_{43} , and σ_{44} at OTR0 (first one)
 - use rms errors and A matrix to compute covariance matrix (T)
- **Compute Emittance, Twiss, BMAG, etc. from fitted parameters**
 - use ∇f and covariance matrix to estimate errors
- **Implemented in Flight Simulator**
 - R-matrices from extant EXT model
 - propagated dispersion values at OTRs from extDispersion package
 - σ_n and $\delta\sigma_n$ at OTRs from OTR emittance measurement package via EPICS (x and y simultaneously)
 - emittance, Twiss, BMAG, etc. computed and displayed (coupling not included)
 - graphics for measured/fitted/projected beam sizes and Twiss parameters





OTRX before corrections

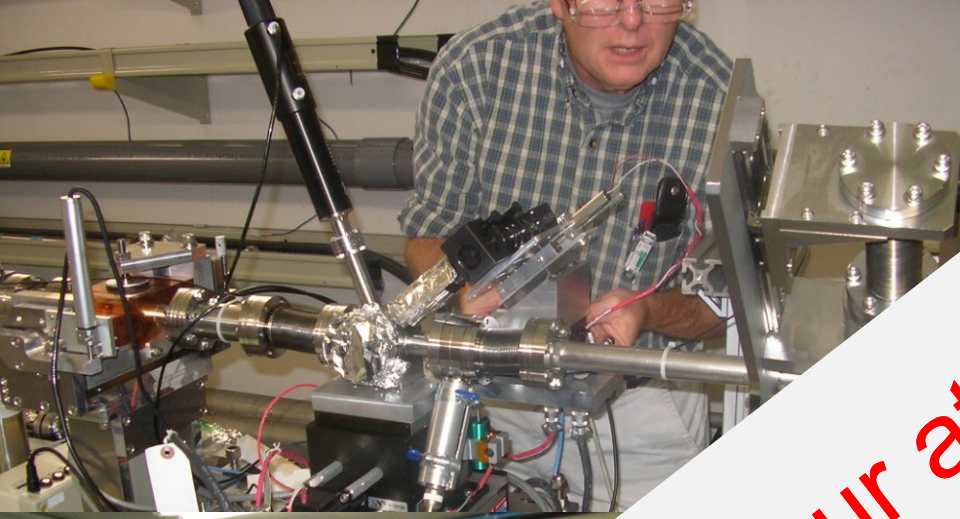
OTRX after dispersion correction

OTRX after coupling correction

Coupling correction in the EXT achieved by scanning each of the 4 EXT skew quads. For each scan the quantity (vertical normalised emittance)*BMAGY is plotted and taken the optimal from a parabolic fit.

- Get the **Beam finder** working.
 - Work required on Flight Simulator online orbit fitting
 - Work required on OTR software implementation
- Finish **test calibration and roll** for OTR1-3X (no roll means all OTRs in the same coordinate frame and can use ellipse fit tilt with other measurements for the 4D emittance measurement)
- **4D intrinsic emittance** calculation.
 - Algorithm development, flight simulator calculation and OTR software implementation.
- Install a **LAN controllable power strip in-tunnel** and build in power cycle controls into the OTR software (CCD cameras can be put into a mode of operation unresponsive to the OTR software and needs to be reset by power cycling the cameras being the power supplies in-tunnel)

- Provide the capability of doing **automated scans from the emittance GUI** (e.g. Automate the scan QK^*X and plot versus $emit^*BMAG$ to search the minimum).
- Install **switchable de-magnifier lens** (?)
- **Documentation** (user's guide started)
- Systematic **Measurement campaign during 2011**



Thanks for your attention

