



Powering requirements and constraints of the Mstrip-FTD detector

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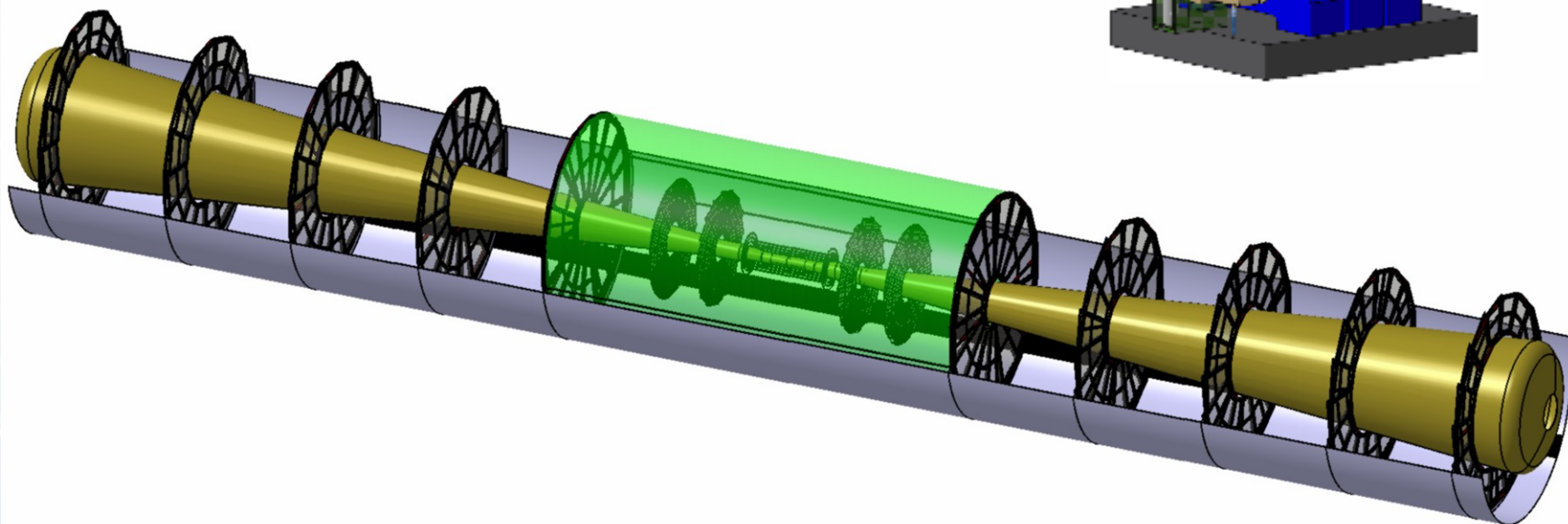
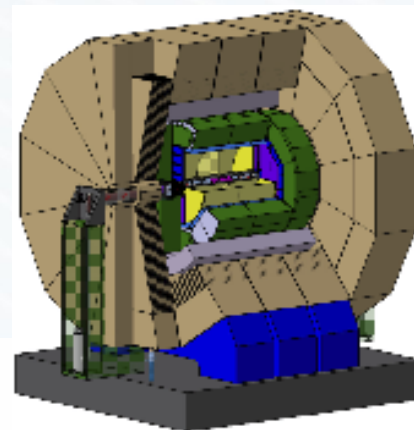
OUTLINE

- 1. Mstrip-FTD detector
- 2. Power requirements
- 3 Main power design parameters
 - Transients
 - EMI
- 4. Powering schemes
 - Power scheme based on DC-DC converters
- 5. Conclusions



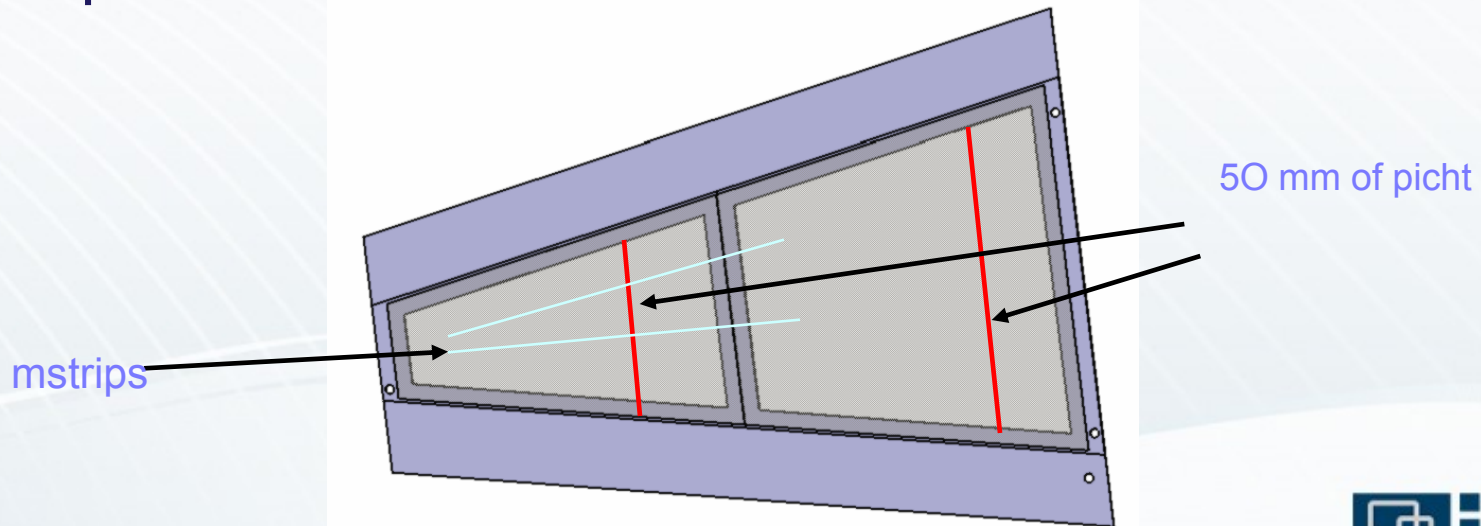
1. FTD detector

- The mstrip-FTD system is a silicon strip tracker located in the innermost part of the tracker region of the ILD.
- It constitutes of 10 disks.



1. FTD detector

- Each disk is constituted of 16 petals.
- Each petal has 2 modules
 - One on the top & One on the back
 - Total : 4 sensors per petal
- The sensors in a 6 inch Wafer
- Fine pitch sensors
 - 50 μm in the center line of each sensor



1. FTD detector

- The total number of strips is higher than a million
 - Non –uniform distribution

	MIDDLE PITCH									
<i>FTD</i>	<i>FTD3</i>		<i>FTD4</i>		<i>FTD5</i>		<i>FTD6</i>		<i>FTD7</i>	
	<i>TOP</i>	<i>BOT</i>	<i>TOP</i>	<i>BOT</i>	<i>TOP</i>	<i>BOT</i>	<i>TOP</i>	<i>BOT</i>	<i>TOP</i>	<i>BOT</i>
<i>Nº STRIPS PER SENSOR</i>	2048	1280	2048	1280	2304	1536	2304	1792	2304	1792
<i>TOTAL Nº STRIPS</i>	212992		212992		245760		262144		262144	
<i>TOTAL Nº STRIPS Strip-FTD</i>			1196032							

2. Power requirements

- First estimation is based on some considerations:
 - FEE is based on new generation of Tracker systems.
 - 128 channel chip
 - Optical links.
 - Two operation voltages
 - 2.5V
 - 1.25V
- Power estimation based also on granularity issues.
 - First approach
 - 1 Power group per 4 petals
 - 4 Power groups per disk
 - FTD : 40 power groups



2. Power requirements

- Currents consumption of Strip - FTD

FTD	MIDDLE PITCH									
	FTD3		FTD4		FTD5		FTD6		FTD7	
	TOP	BOT	TOP	BOT	TOP	BOT	TOP	BOT	TOP	BOT
<i>Nº STRIPS PER Module (2sensors)</i>	4096	2560	4096	2560	4608	3072	4608	3584	4608	3584
<i>Chips per petal</i>	52		52		60		64		64	
<i>Optical links per petal</i>	1		1		1		1		1	
<i>I2.5 (A) per Petal</i>	2.56		2.56		2.8		2.92		2.92	
<i>I1.25 (A) per Petal</i>	1.18		1.18		1.34		1.42		1.42	
<i>I per petal</i>	3.74		3.74		4.14		4.34		4.34	
<i>I per disk</i>	59.84		59.84		66.24		69.44		69.44	
TOTAL Mstrip- FTD Current			649 A							



2. Power requirements

- Currents consumption of FTD per power group

		MIDDLE PITCH									
<i>FTD</i>	<i>FTD3</i>		<i>FTD4</i>		<i>FTD5</i>		<i>FTD6</i>		<i>FTD7</i>		
	<i>TOP</i>	<i>BOT</i>	<i>TOP</i>	<i>BOT</i>	<i>TOP</i>	<i>BOT</i>	<i>TOP</i>	<i>BOT</i>	<i>TOP</i>	<i>BOT</i>	
<i>12.5 (A) per PG</i>	10.24		10.24		11.20		11.68		11.68		
<i>11.25 (A) per PG</i>	4.72		4.72		5.36		5.68		5.68		
<i>Power Groups</i>	4		4		4		4		4		
<i>TOTAL FTD Power groups</i>			40								

3. Main power design parameters

- The amount of current required by Strip-FTD is around **650 A**
- The ILC accelerator has a duty cycle of 0.5%
 - 1 ms bunch train every 200ms
- If the power demanded by the FEE is synchronized to the bunch train, it helps to save energy
 - Energy dissipated will be lower
- The total Strip-FTD current demanded per bunch crossing (a peak current) is 650 A
 - Mean current 6.5 A. per cycle (no power–no bunch)
 - Max Current per power group lower than :
 - 12 A (1.25V) & 6A (2.5V)



3. Main power design parameters

- However several important issues have to be considered during the design of the power system:
 - Transient phenomena
 - EMI phenomena
- All these phenomena have an impact in the design of the power supply distribution system
 - Topology
 - Cooling and material budget
- A very simple study has been carried out to define the implications of these issues in the design of the power system.
 - We have assumed FEE power off when no bunch



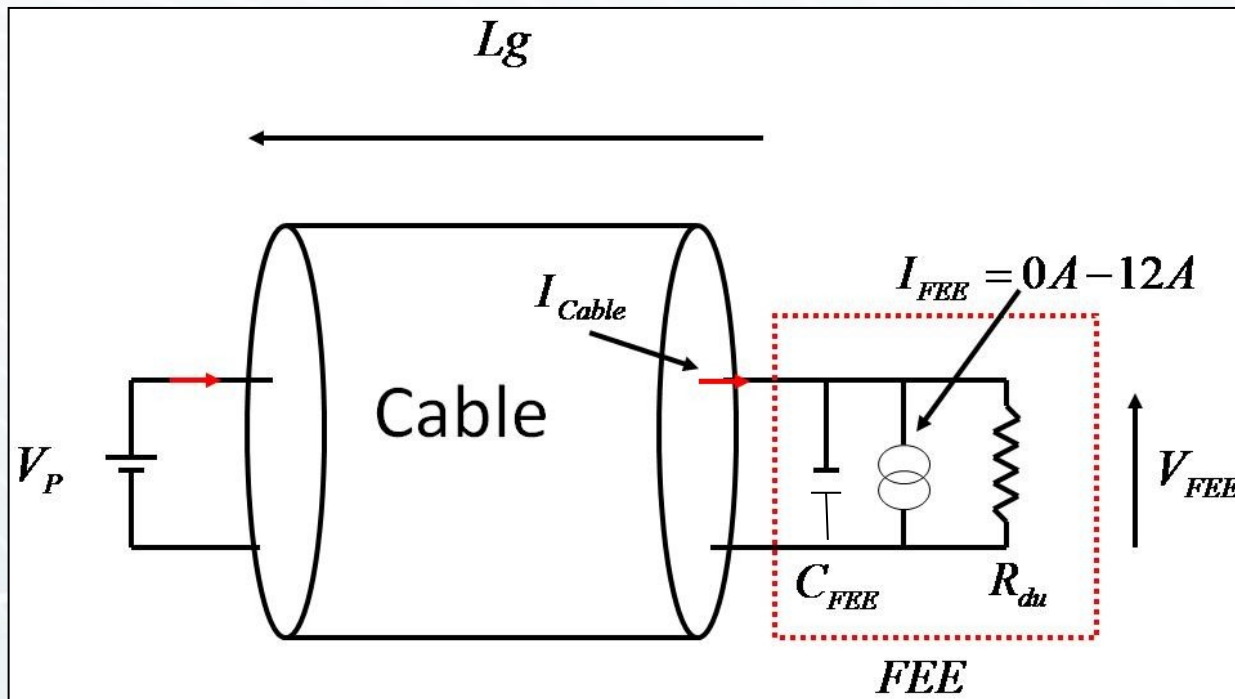
3.1 Main power design parameters: Transients

- The current variation per bunch crossing generates transients
 - Cable inductance
 - Cable resistance
- Transient characteristics depends on:
 - Cable length
 - Capacitors located at FEE level
 - Current variation amplitude
- A very simple power group has been analyzed
 - $V=1.25V$ & $I = 12 A$

3.1 Main power design parameters: Transients

– Two analysis

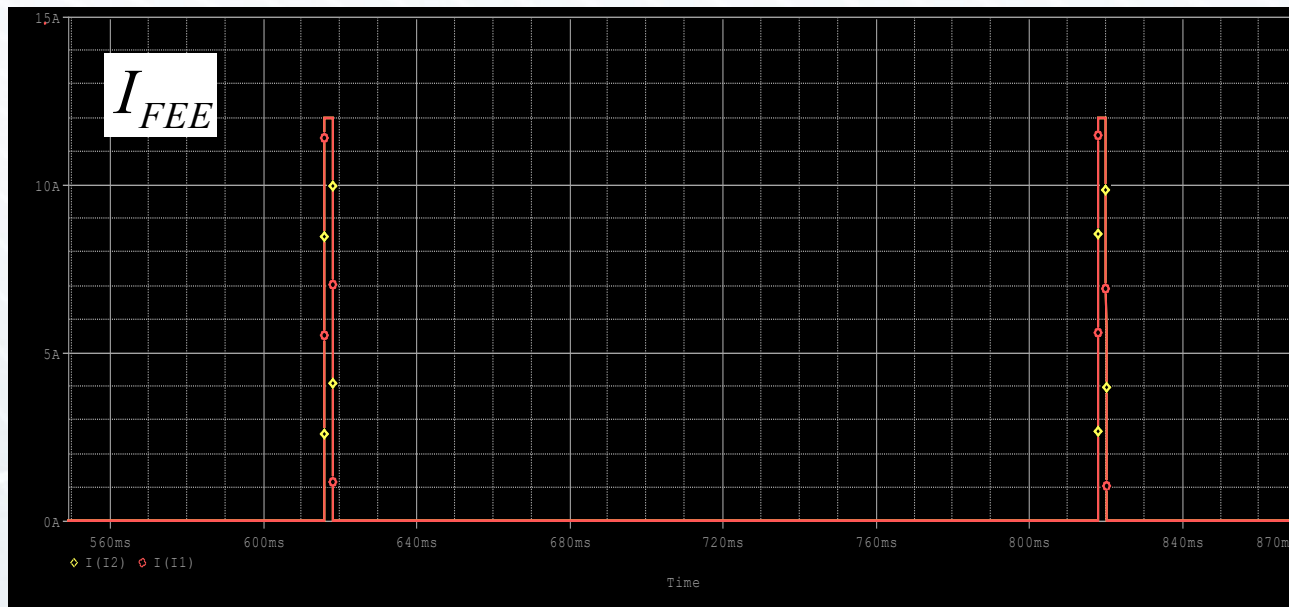
- Cable length (L_g) (local or remote powering)
 - 1 m & 50 meters
- Local capacitors (C_{FEE})
 - 100 μF , 200 μF and 400 μF



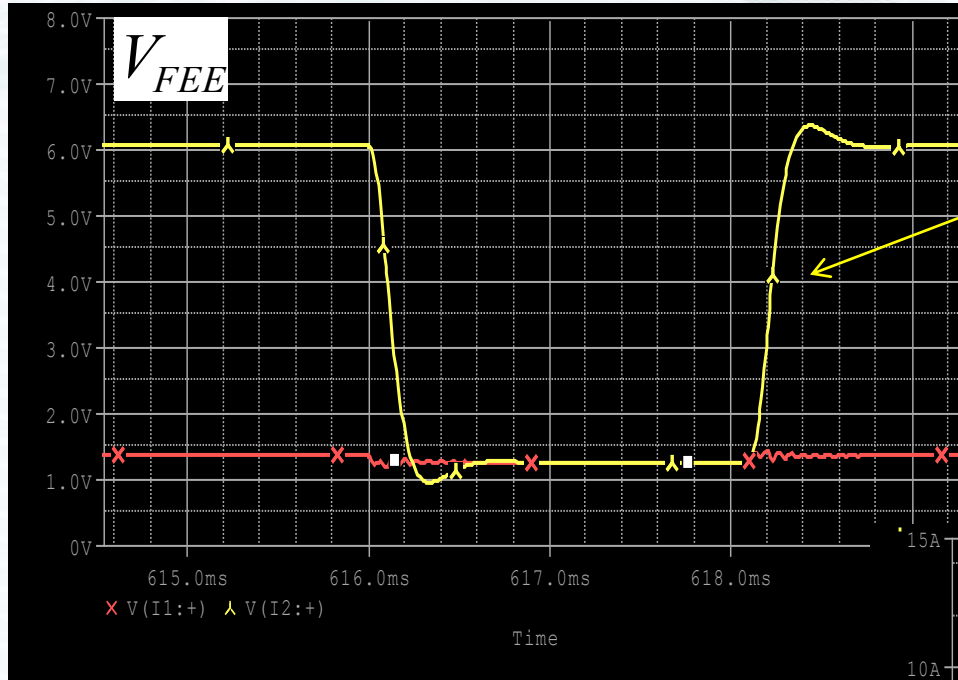
3.1 Main power design parameters: Transients

• Cable length

- This analysis presents some implications of local or remote powering of the FEE
 - 1 m (red)
 - 50m (yellow)
- We have considered no remote sensing
 - No regulation



3.1 Main power design parameters: Transients

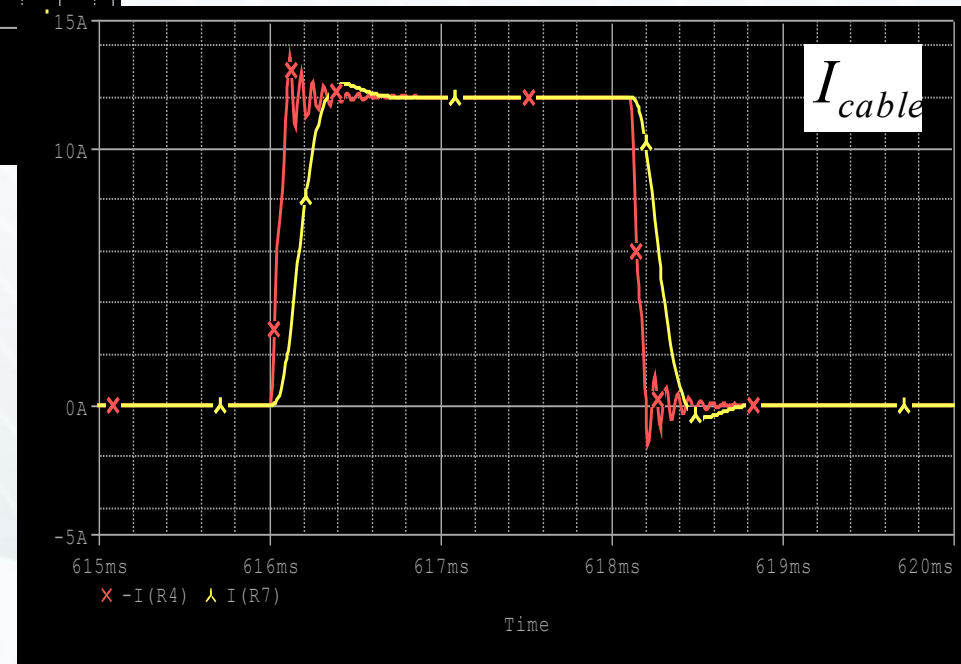


• Voltage

- Long cable requires voltage compensation due to cable resistance
 - Complex power unit
- Short cable do not need it

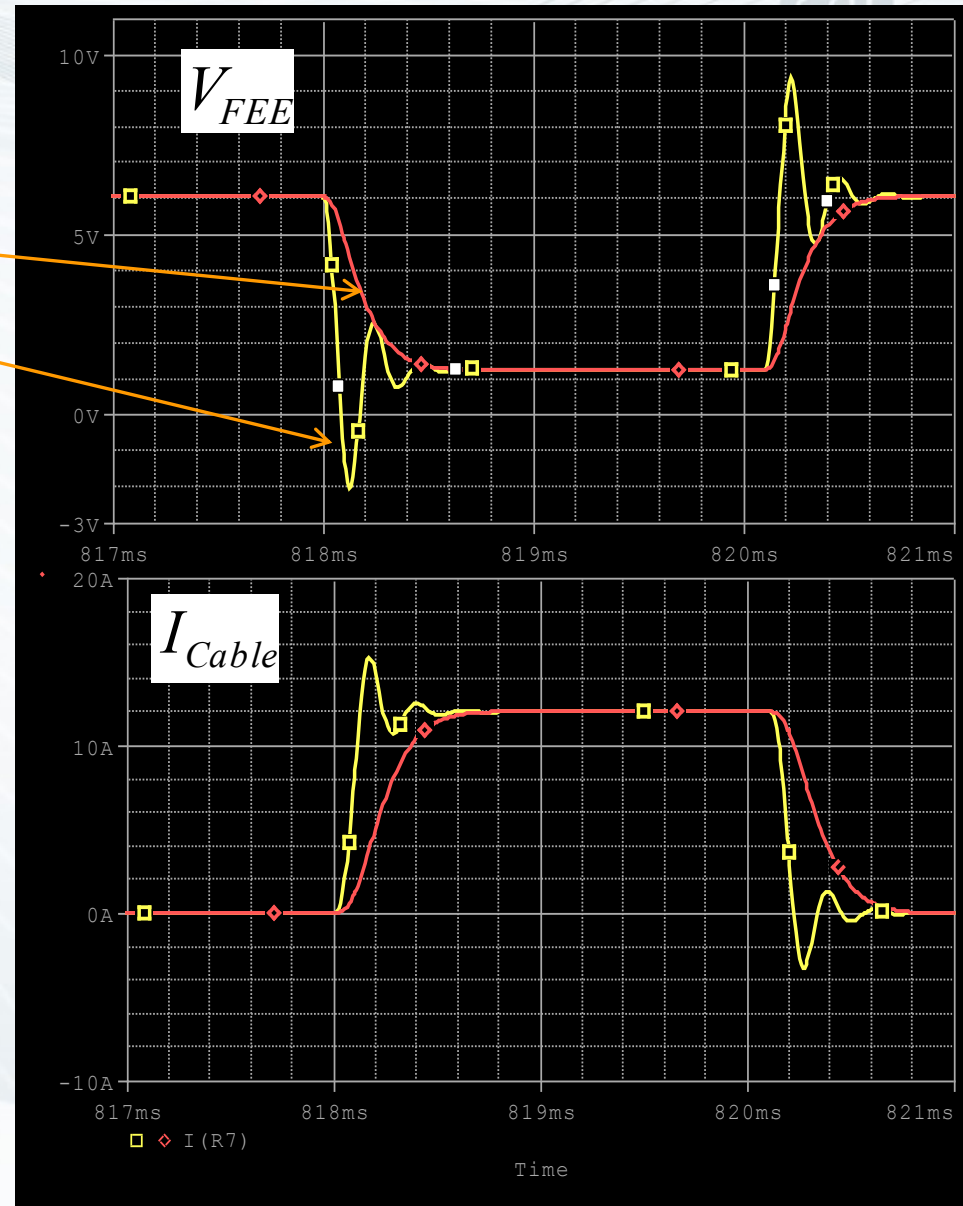
• Cable currents

- Short cables has ringing effect due to small cable resistance.



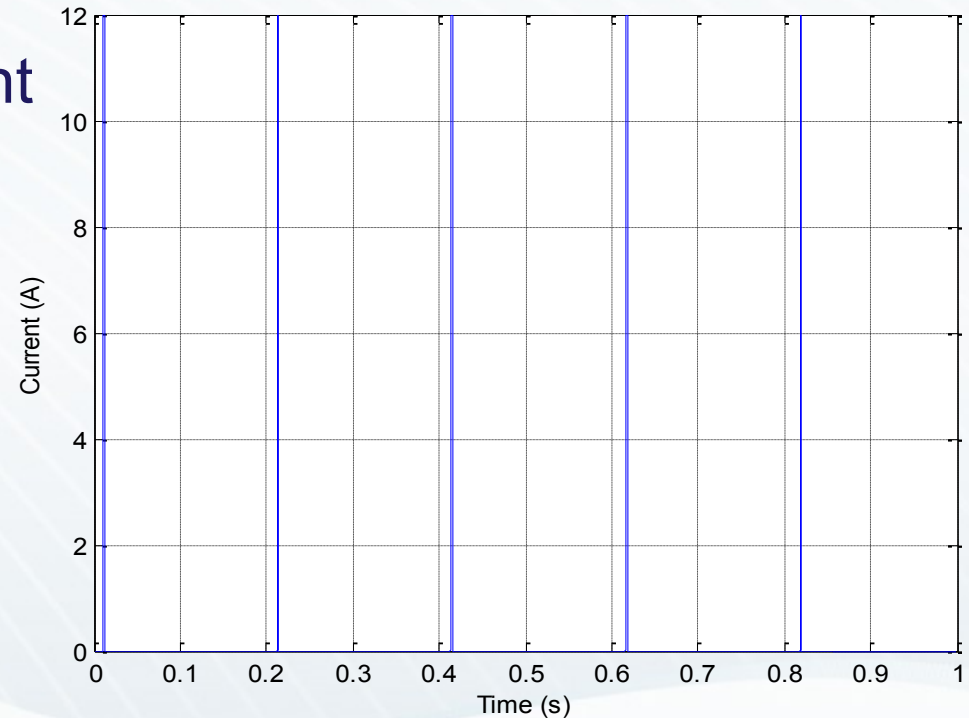
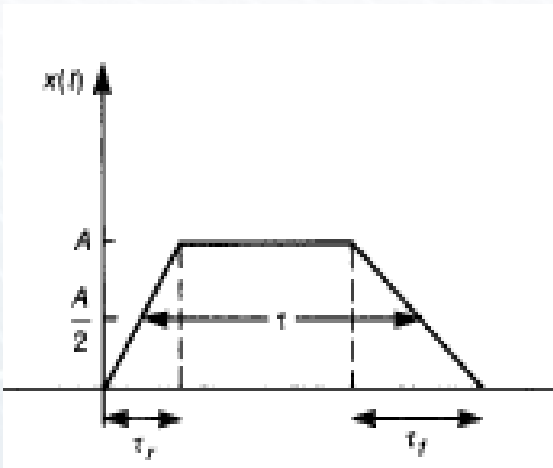
3.1 Main power design parameters: Transients

- FEE capacitor
 - Two cases
 - 100 μF & 400 μF
 - Cable length : 50m
- Low C values generates
 - Voltage dips
 - Important in the digital electronics
 - Overvoltage
 - Important in analogue electronics
- Both cases stabilization time similar
- High C Values
 - Reliability issues



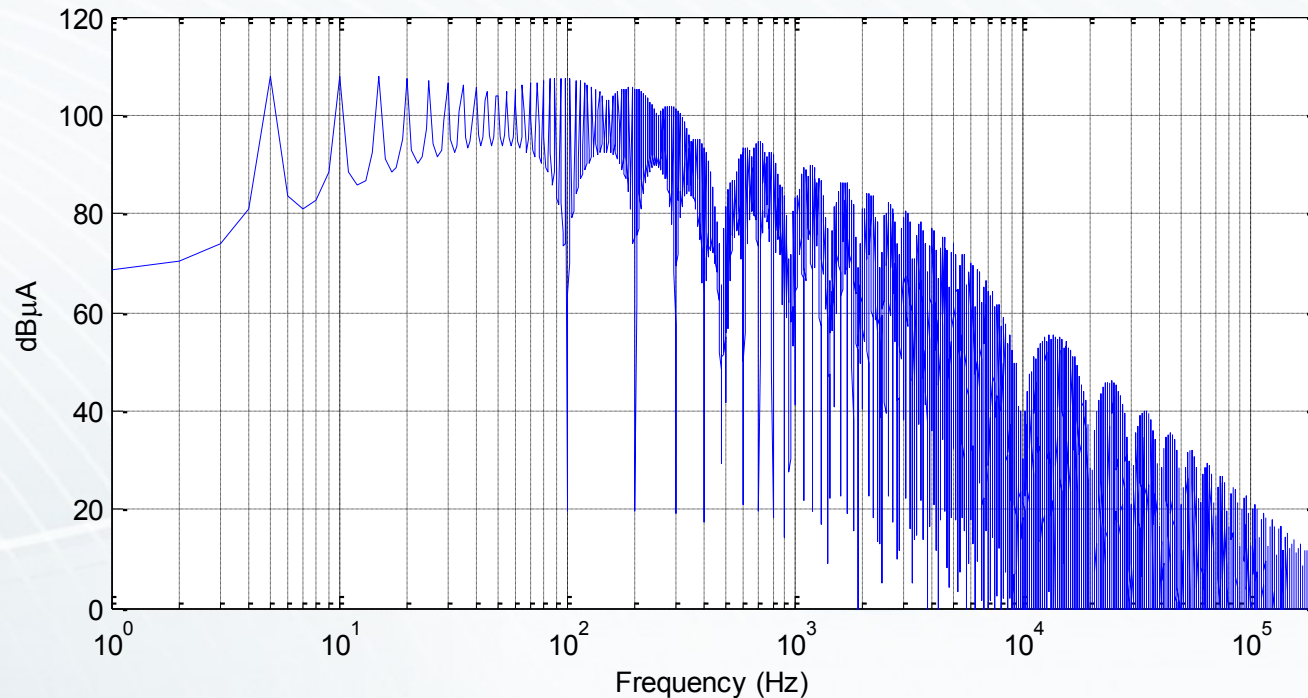
3.2 Main power design parameters: EMI

- The synchronization of the FEE power operation with the bunch crossing introduces a current periodic signal with a spectra content in the power supply system.
 - FEE became a noise source
- It will depend on:
 - Amplitude of the current
 - Duty cycle
 - Rise and fall time

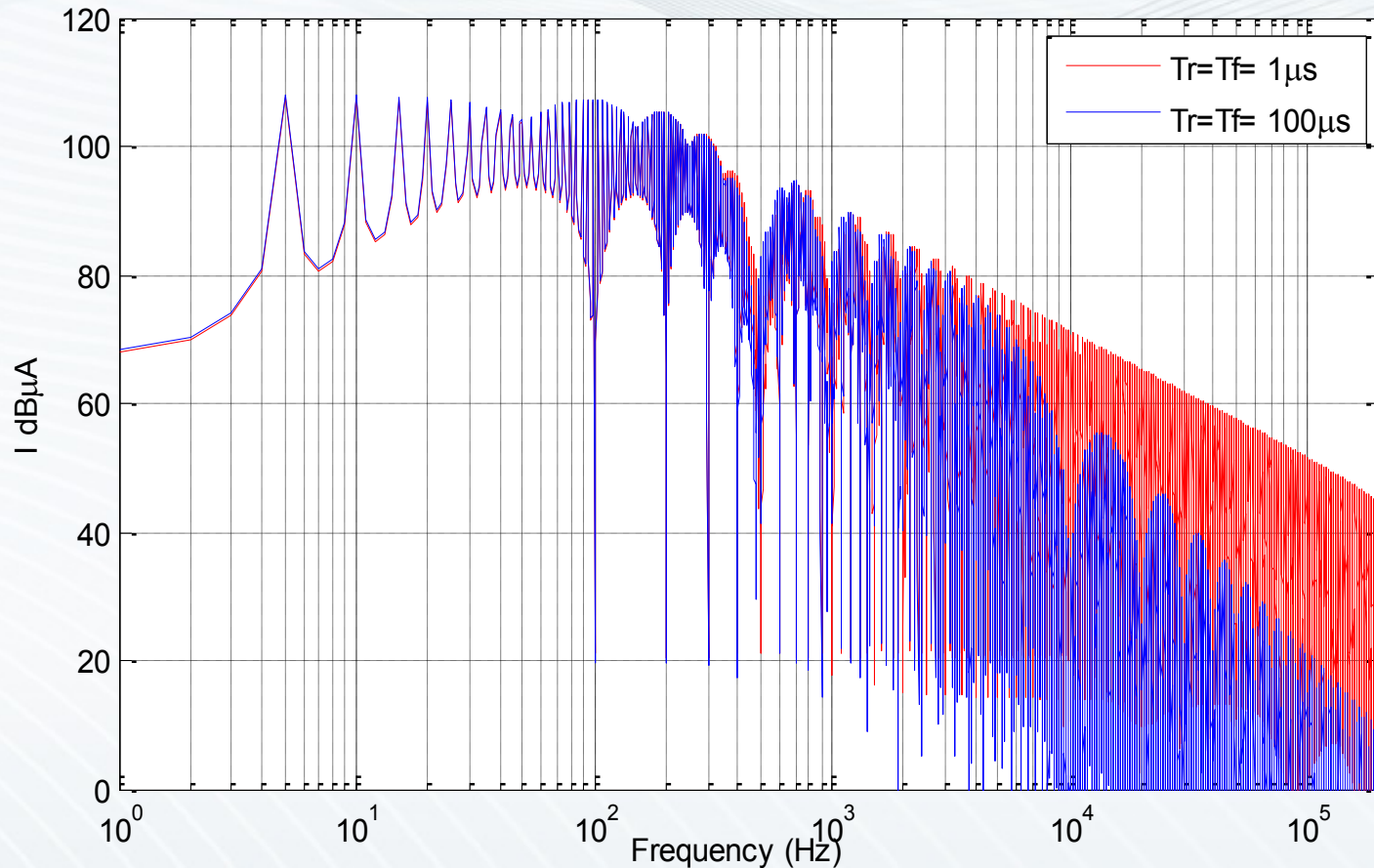


3.2 Power supply distribution systems: EMI

- The spectra content varies between few Hz up to several hundreds of kHz
 - LF- Problematic due near field : Magnetic field
 - Every 5 Hz a pulsing magnetic field higher than 0.2 A each
 - $I_{\text{total}} = 40 \times 0.2 \text{ A} = 8 \text{ A}$
 - **It may cause mechanical problems**
 - Vibrations – wire bounding degradation



3.2 Power supply distribution systems: EMI



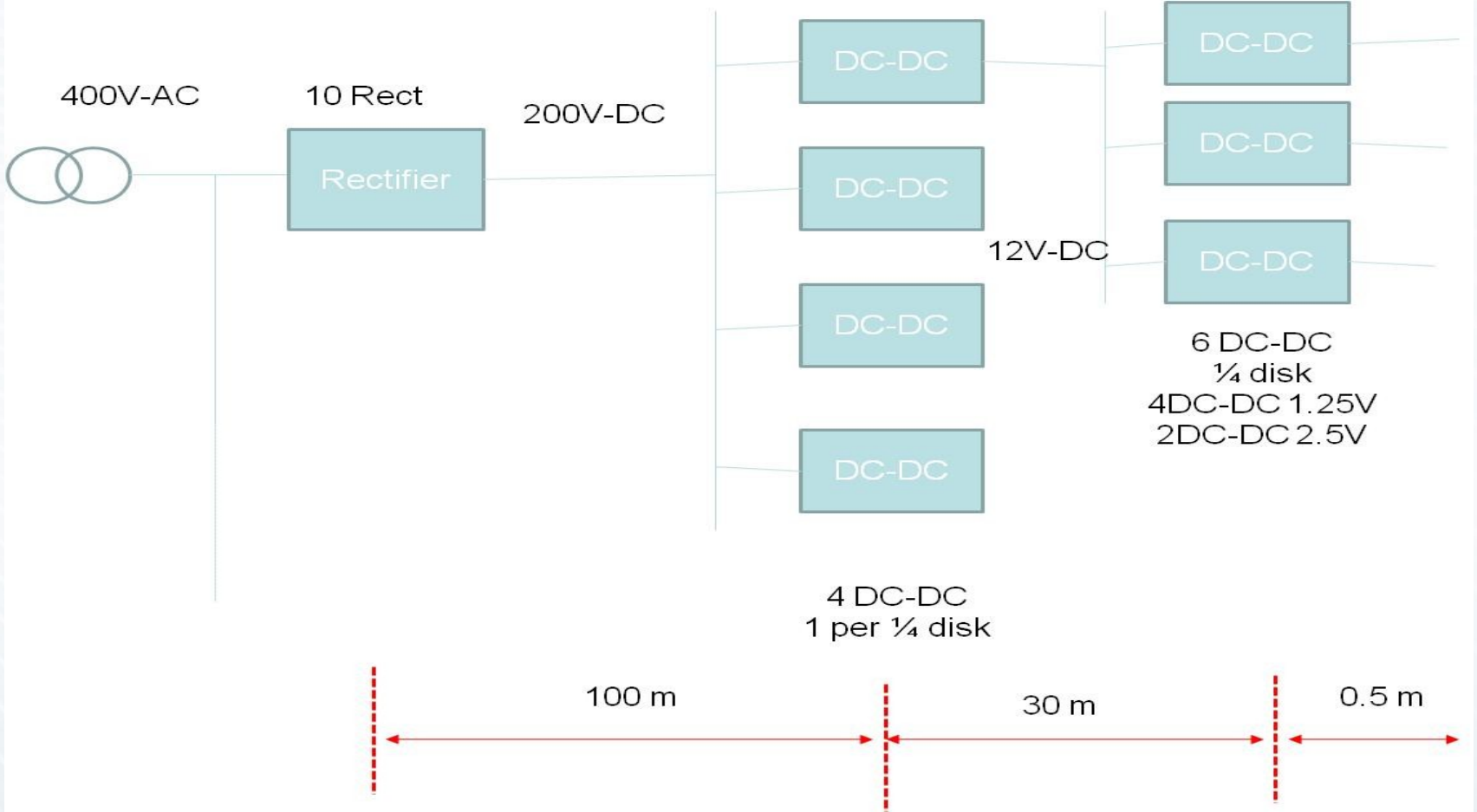
- Transition time T_r / T_f :
 - HF noise contribution increase if transition times decreases

4. Powering schemes

- There are several topologies that may be implemented in the FTD.
 - DC-DC based power distribution
 - Local LV RAD-hard regulators
 - Remote power supply
- Each of them has advantages and disadvantages
- we consider DC-DC as the first option of analysis:
 - To absorb transients associate to power pulsing system.
 - Keep transients locally at FEE level.
 - Low currents before DC-DC due to converter ratio
 - Low transients
 - Synergy with SLHC and new DC-DC hard-rad design.
 - HF noise & Rad issues



4.1 Powering schemes: DC-DC based Power System



4.1 Powering schemes: DC-DC based Power System

- Power values per group:
 - Routing Inside each petal:
 - 6 DC-DC converters
 - 4 DC-DC (12V -2.5V)
 - 2 DC- DC (12V- 1.25V)
 - Max out current per DC-DC less than 3 A (low transients)
 - Short cabling – Less 1 meter (low voltage drop)
 - Outside petal
 - 1 DC-DC per power group
 - 200V – 12V
 - Max out current per DC-DC less than 3 A
 - Transients attenuated by the DC-DC
 - Outside experiment
 - 1 AC-DC per disk
 - 400V 50 Hz – 200V DC
 - Max current per cable less than 1 A



4.1 Powering schemes: DC-DC based Power System

HIGH VOLTAGE
POLARIZATION
CABLE

AWG 32 CABLE
FROM DC-DC
TO THE CHIPS

CHIPS+KAPT
ON

128 Channel
CHIPS

OPTOHYBRID
KAPTON

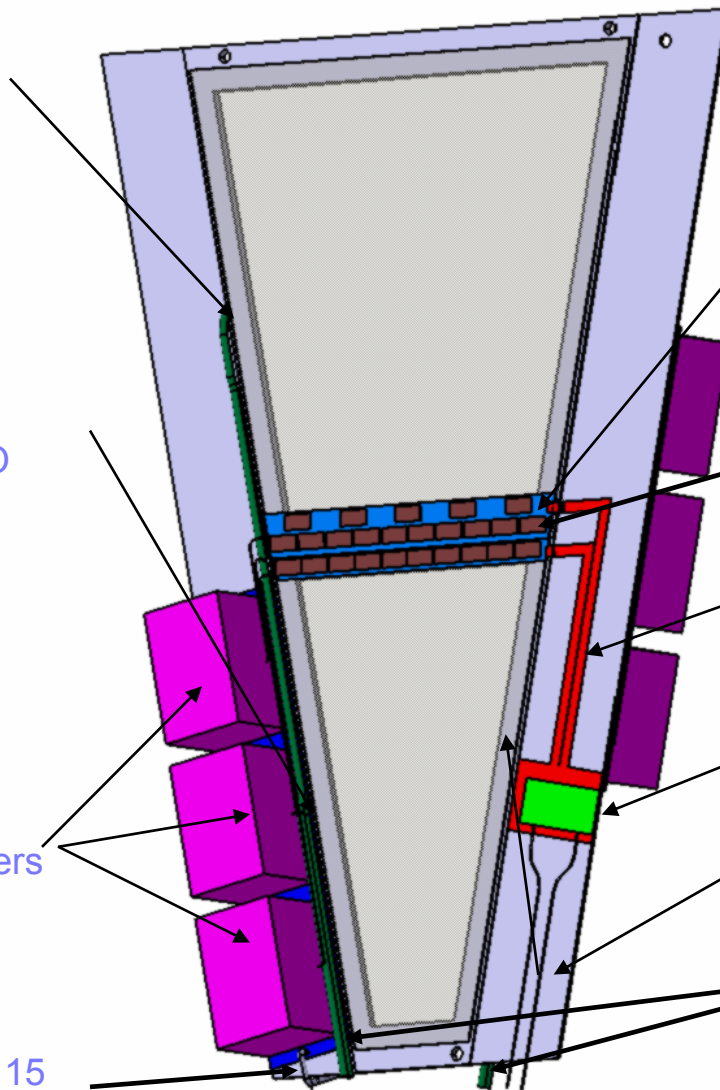
OPTOHYBRID

DC-DC
converters

Fiber optics

12 V AWG 15

HIGH
VOLTAGE
CABLE



- Detailed study is on progress.

- Location
- Material
- Transients

5. Conclusions

- The very first analysis of the power supply distribution system of Mstrip-FTD detector has been presented
 - Total current detector is around 650 A
- The power cycling of the FEE helps to decrease the power dissipation of FEE and cables
- However, it introduces two aspects that have to be considered during the design of the power supply distribution system.
 - Transients
 - Overvoltage or Voltage dips
 - EMI
 - LF noise (magnetic field)
- First analysis is focused on DC-DC based power distribution system
 - Analysis is still on going
 - It seems good option to keep transients locally