



Remote Handling of ILC Target

Jia Xuejun

Institute of High Energy Physics, CAS

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Target Wheel

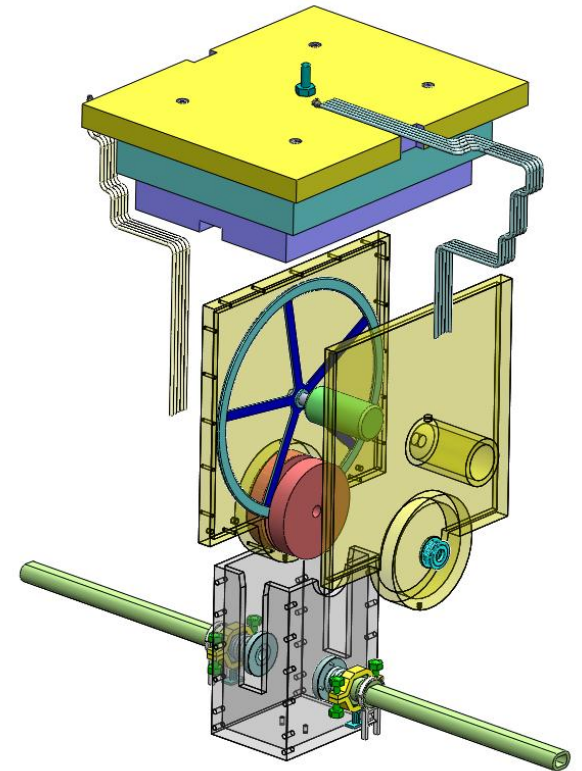
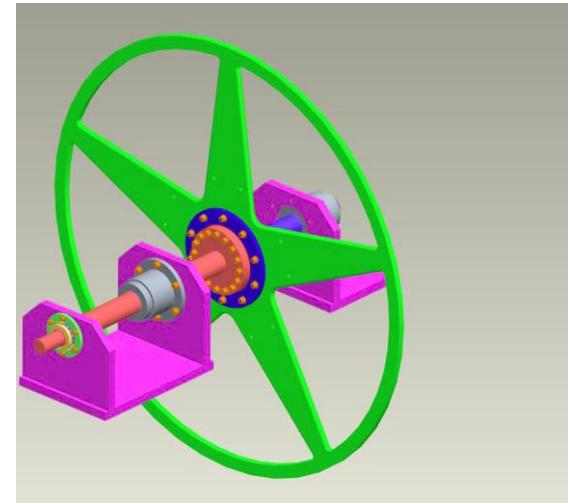
Titanium Alloy

Rotates at 100m/s at rim

Cryo-cooler, cryostat and vacuum pump

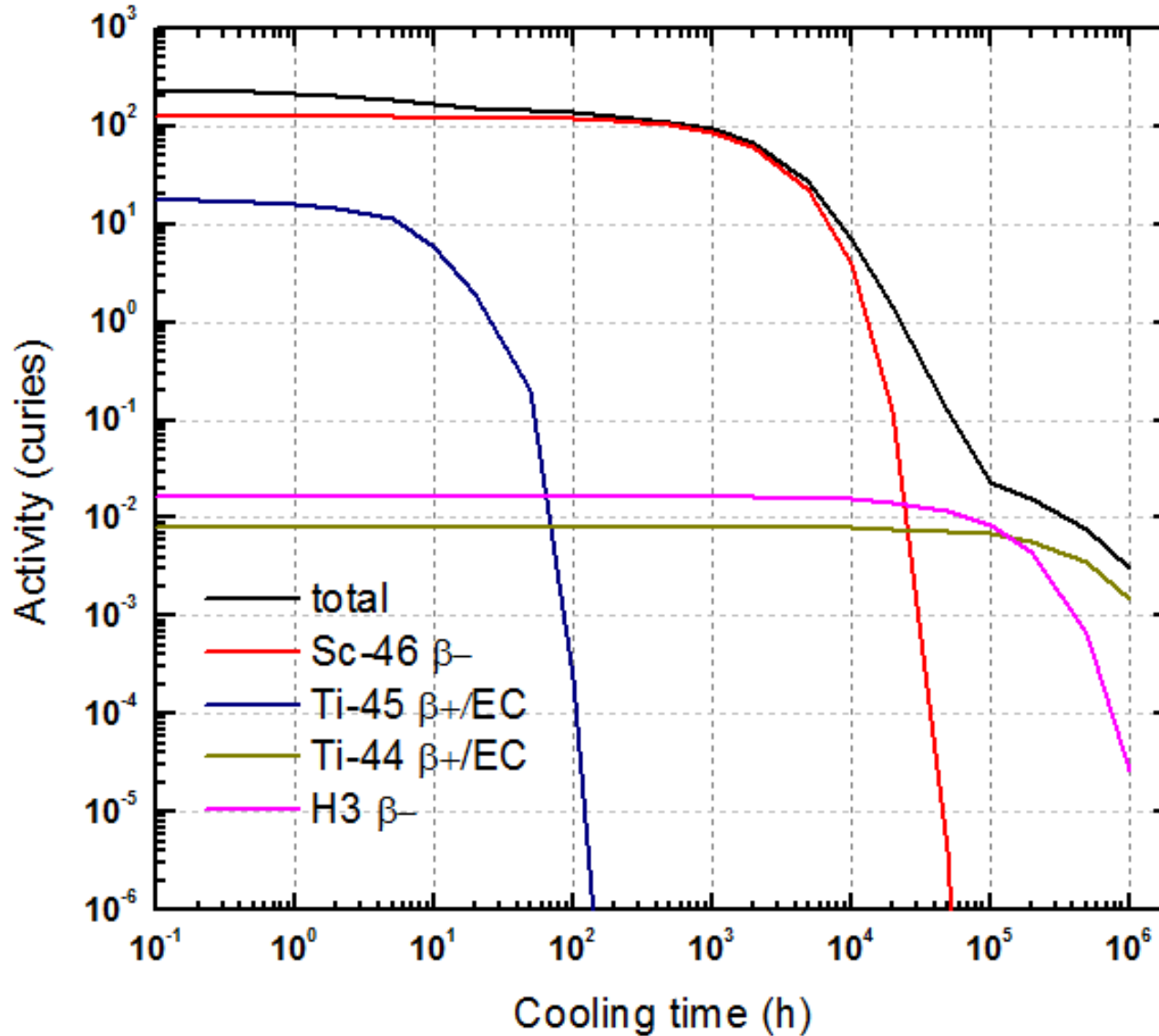
If can be immersed in strong magnetic field then capture more positrons

Strong Eddy current effects



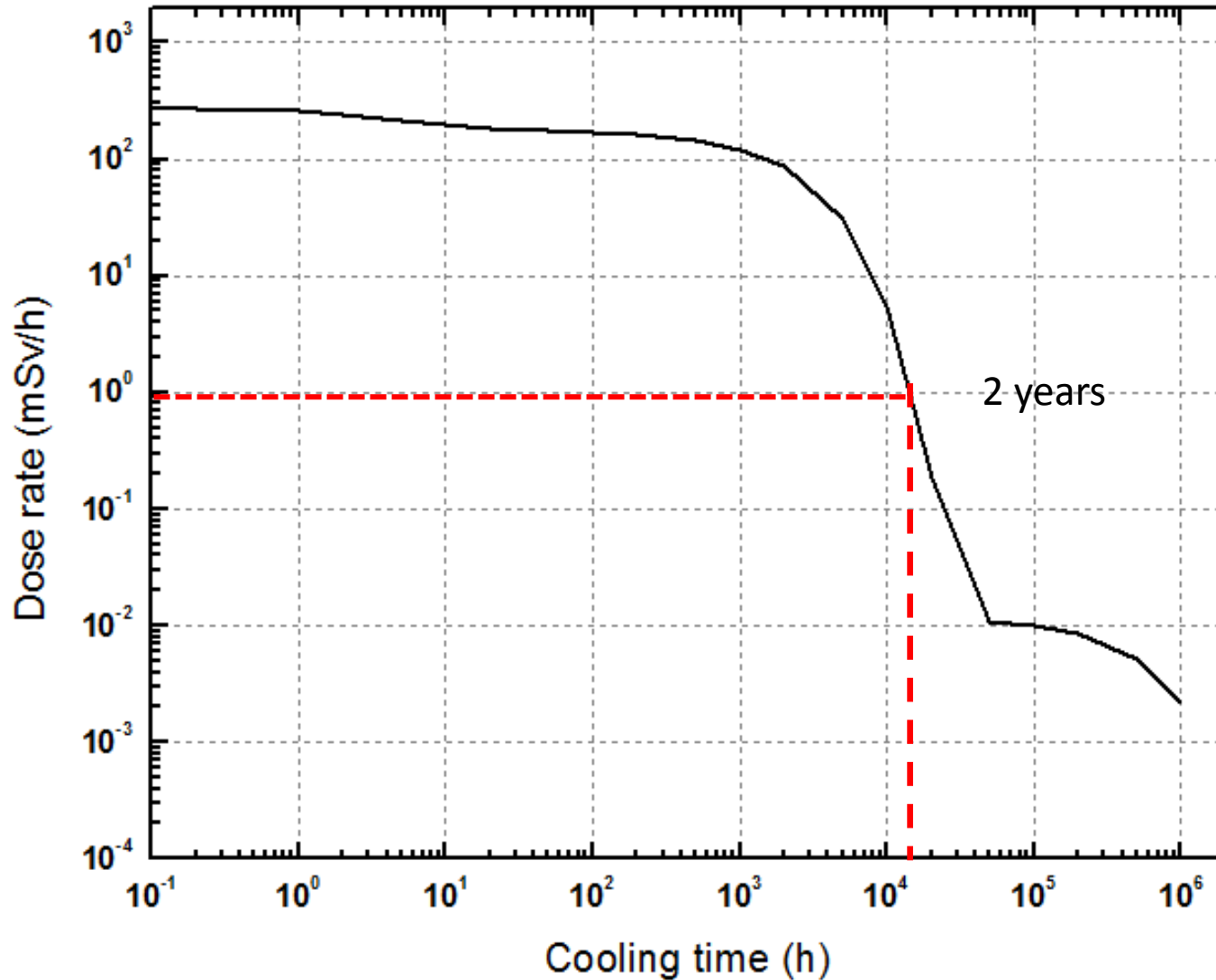


Target Activity (150kW, 5000h)





Dose rate of used Target (mSv/h@1m)





Shielding calculation

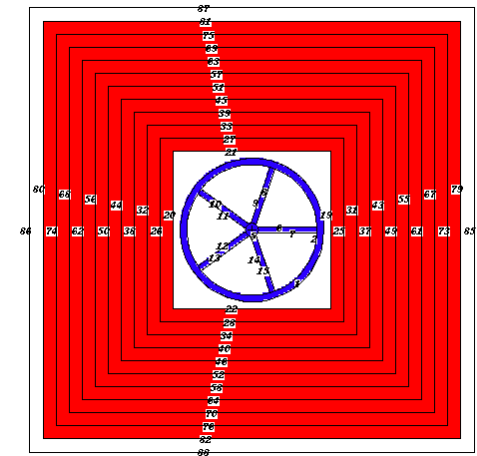
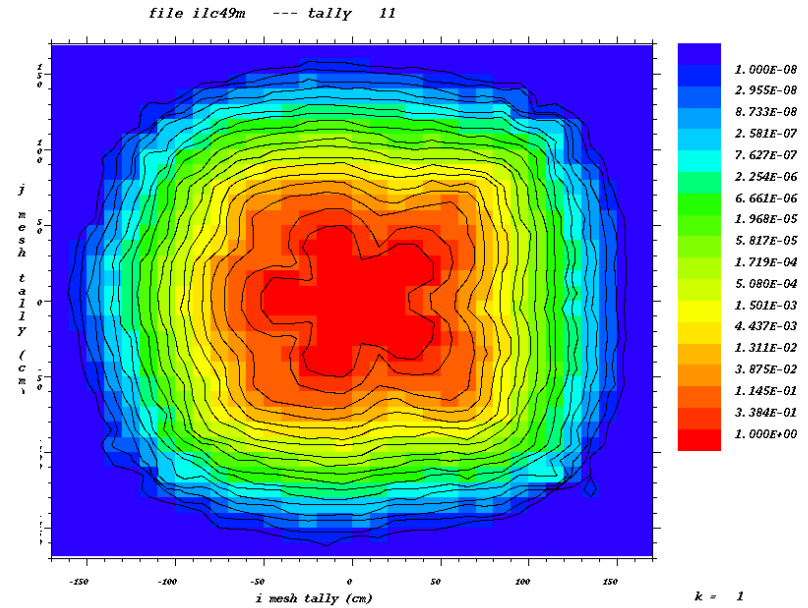
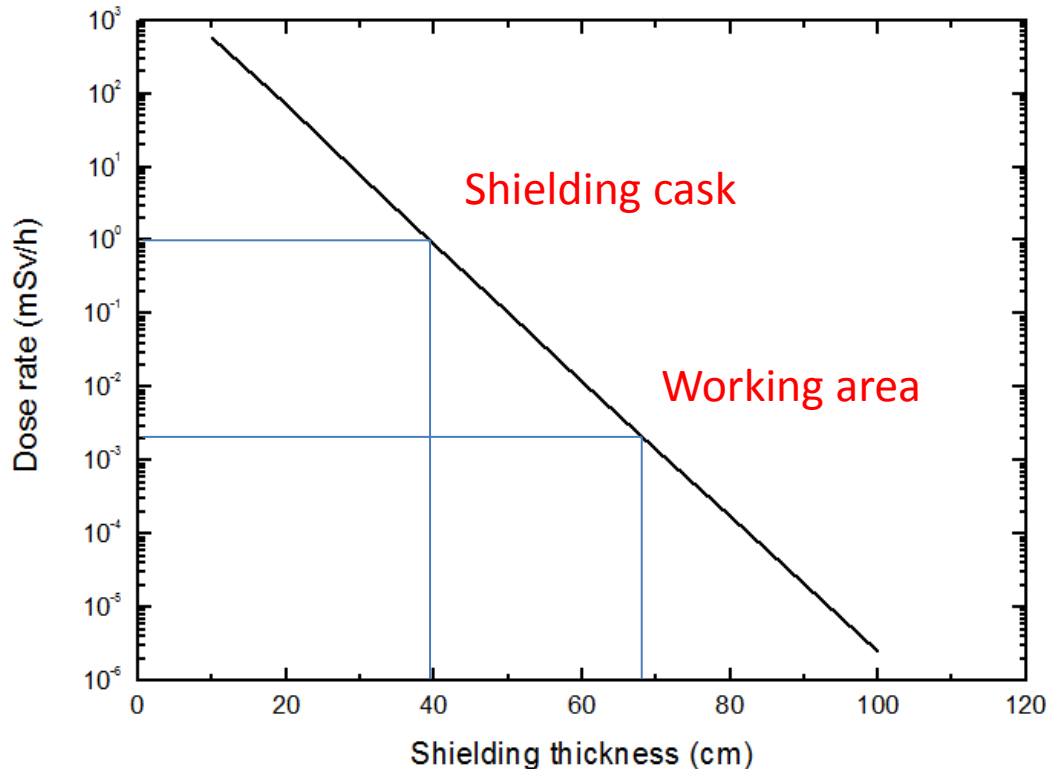
Codes and libraries

MCNPX2.5.0, CINDER90,

libraries:mcplib04, e103, endf60

Target: Ti-6%wtAl-4%wtV, density 4.5g/cc

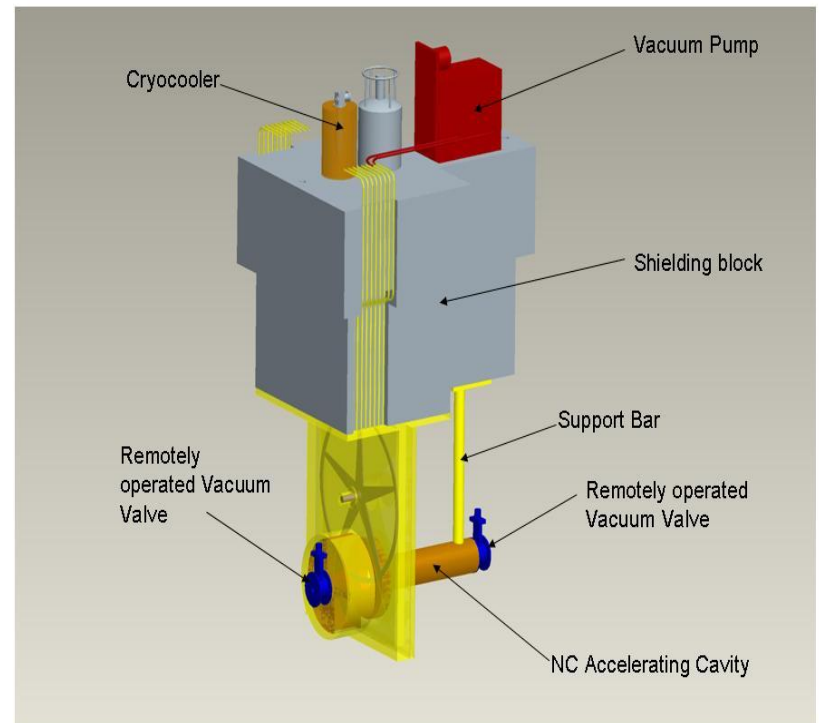
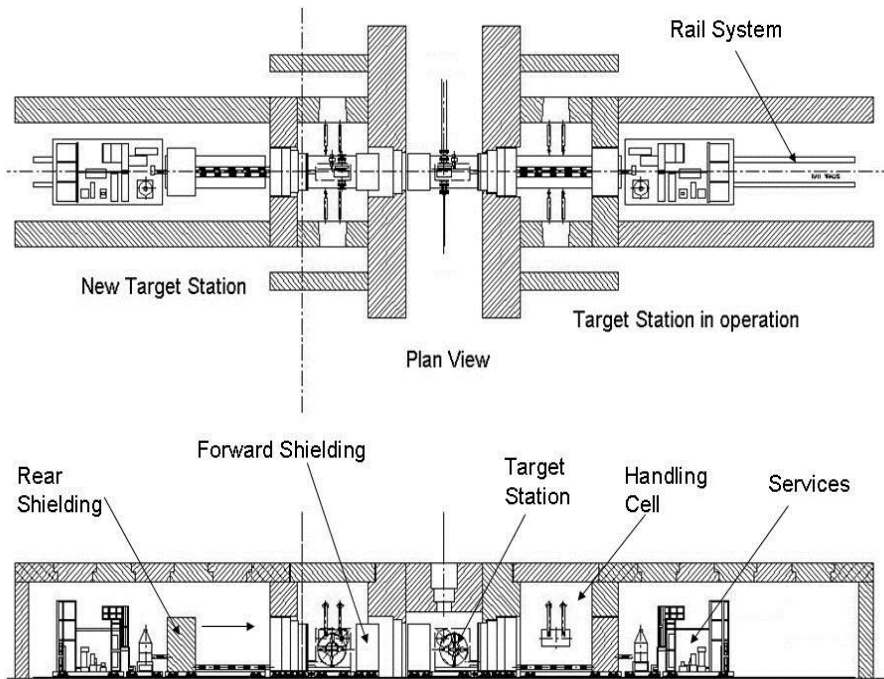
Magnetite concrete: density 3.53 g/cc





Remote handling concept

Horizontal or vertical?





Horizontal

ISIS target concept

Hot-cell Very Expensive

Complicated hydraulics,
interlock systems

Long period requirement

Difficult to engineer

vertical

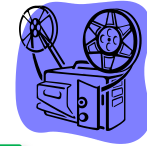
Whole plug replacement

Not hot-cell, but plug
storage pit (or area)

Short period requirement

Less shielding, less
tunnelling

All connections hands-on

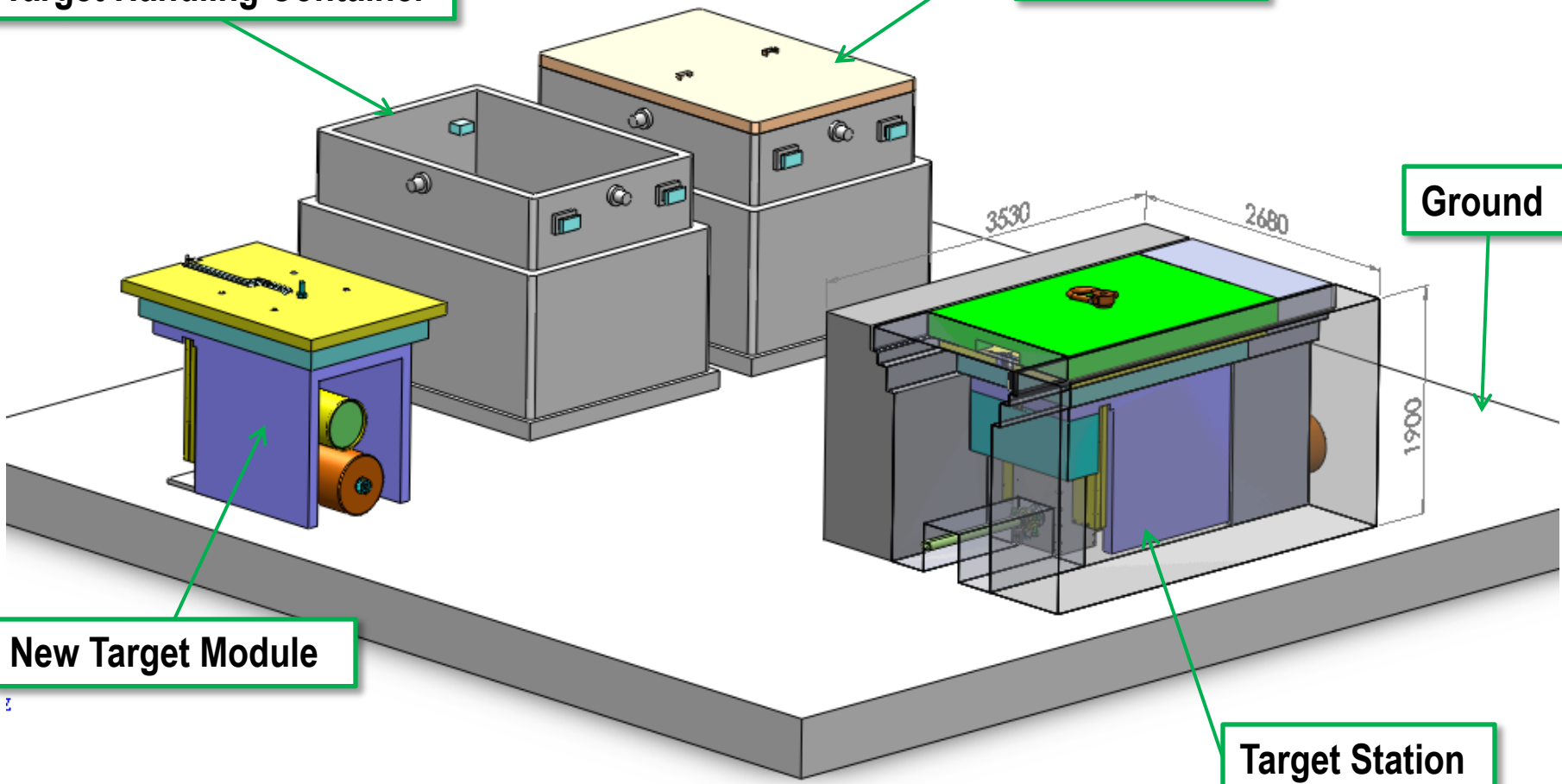


1. General Layout

Target Handling Container

Used Target & Container

Ground

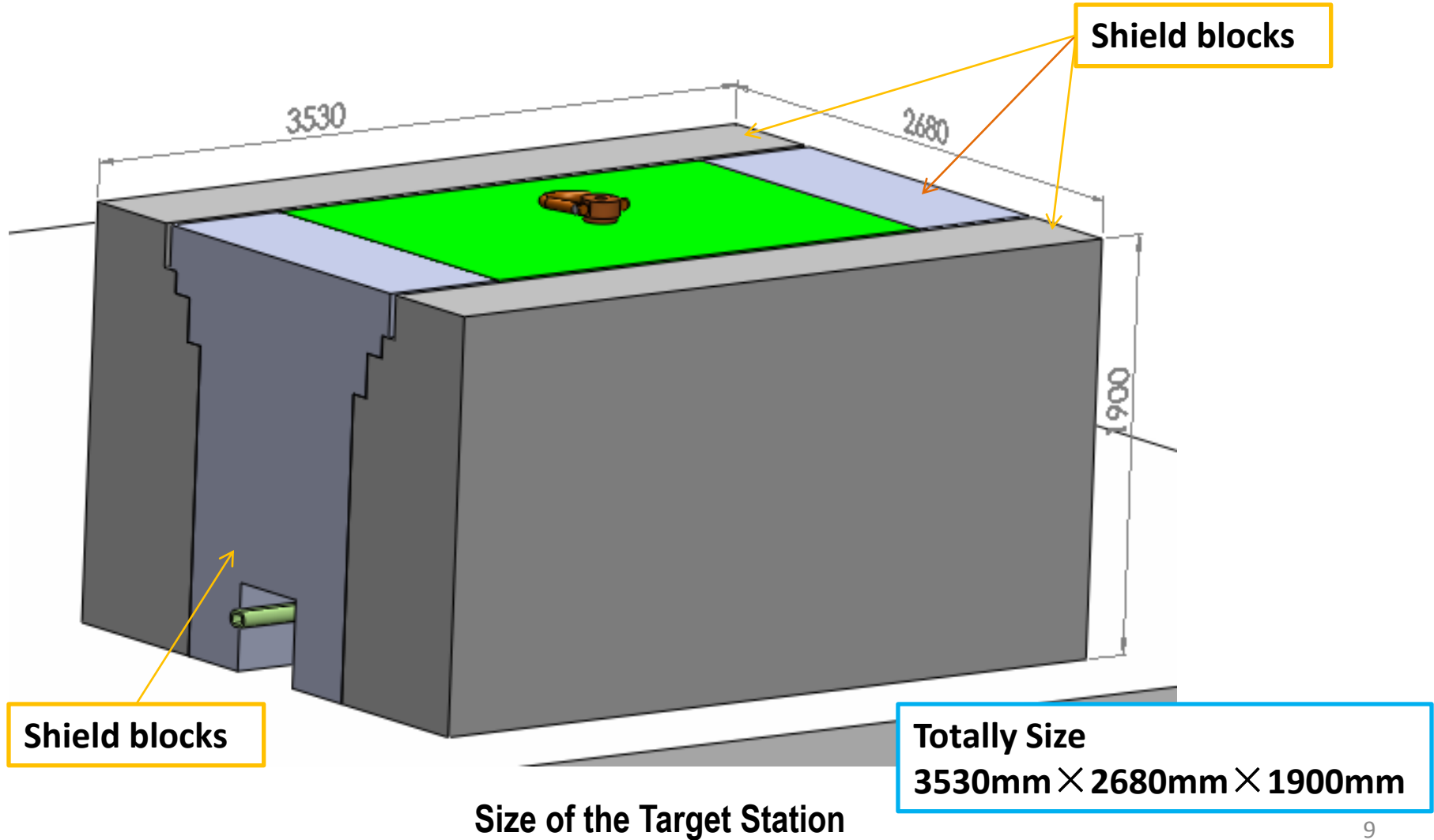


New Target Module

Target Station

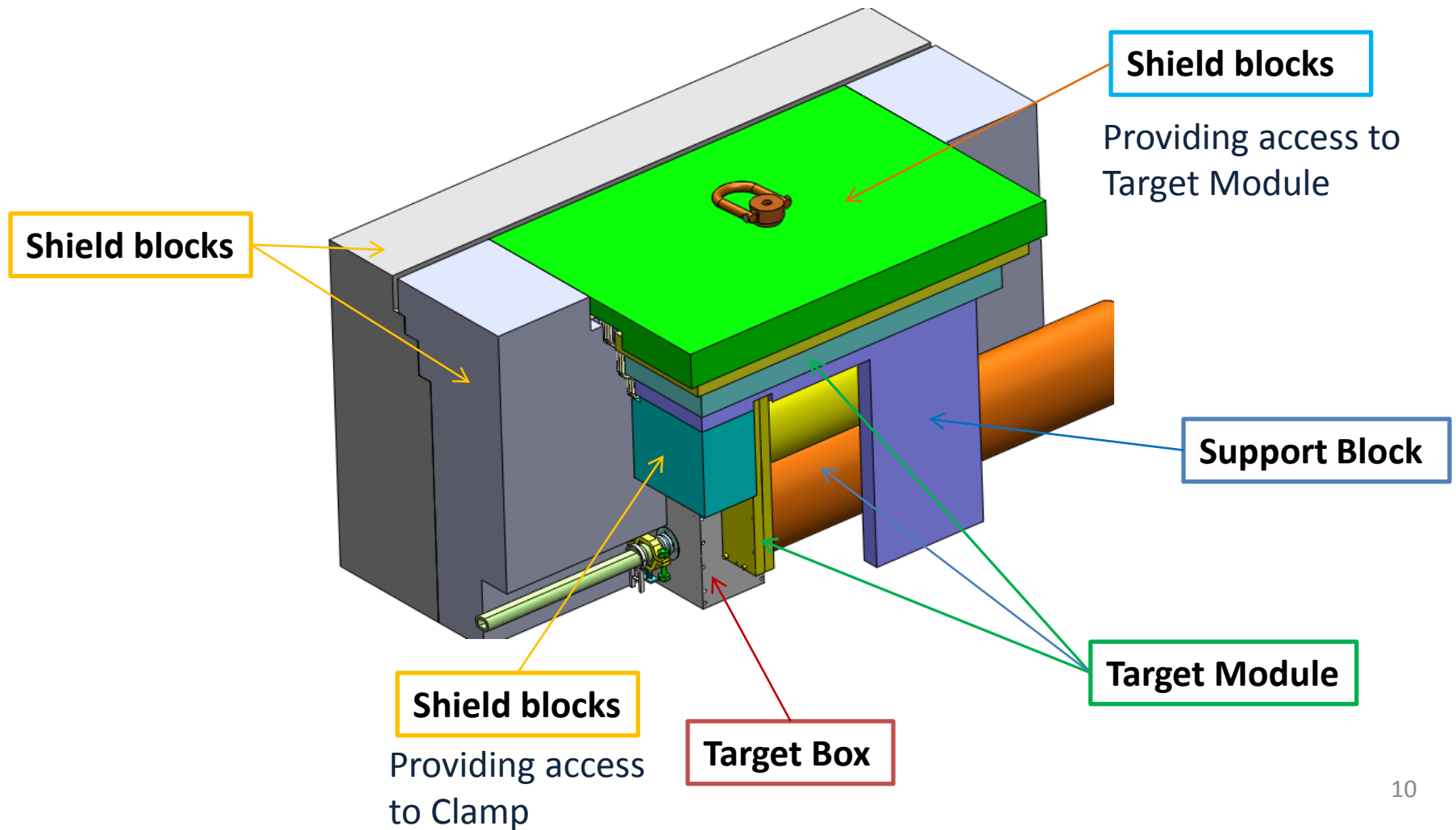


2. Components of the Target Station Assembly

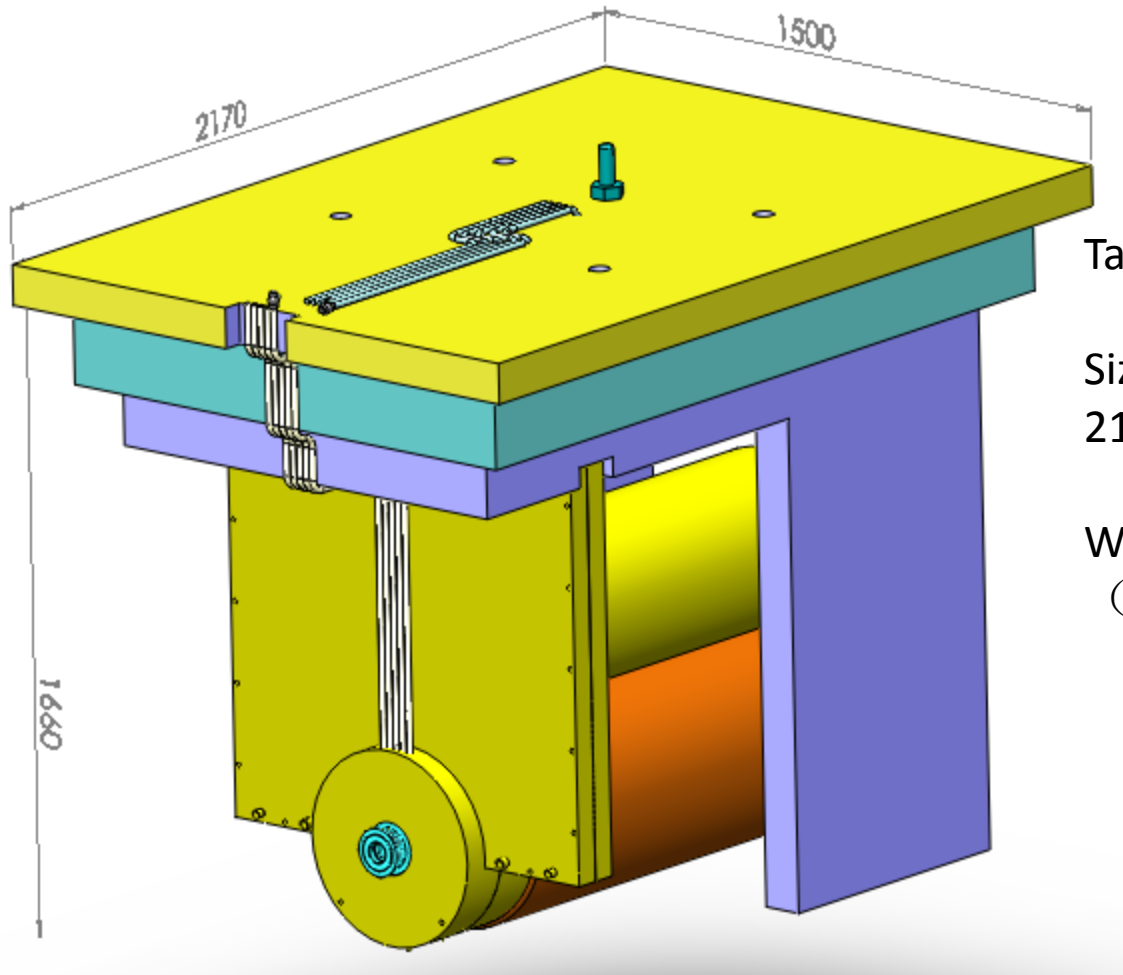




2. Components of the Target Station Assembly



2. Components of the Target Station Assembly



Target Module

Size:

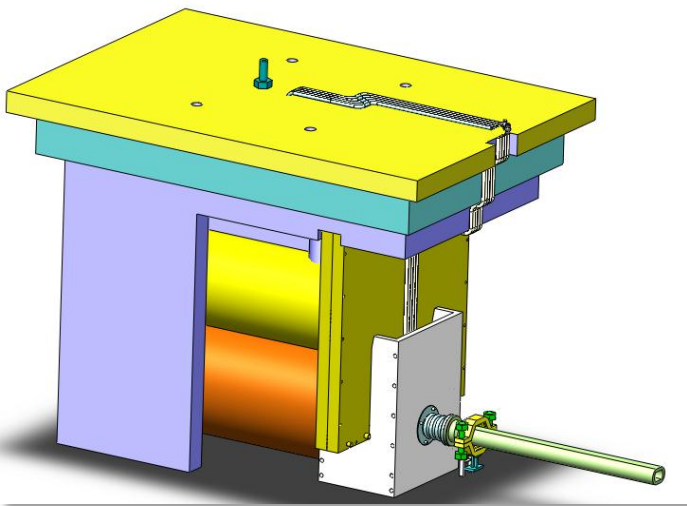
2170mm × 1500mm × 1660mm

Weight: 12943 Kg

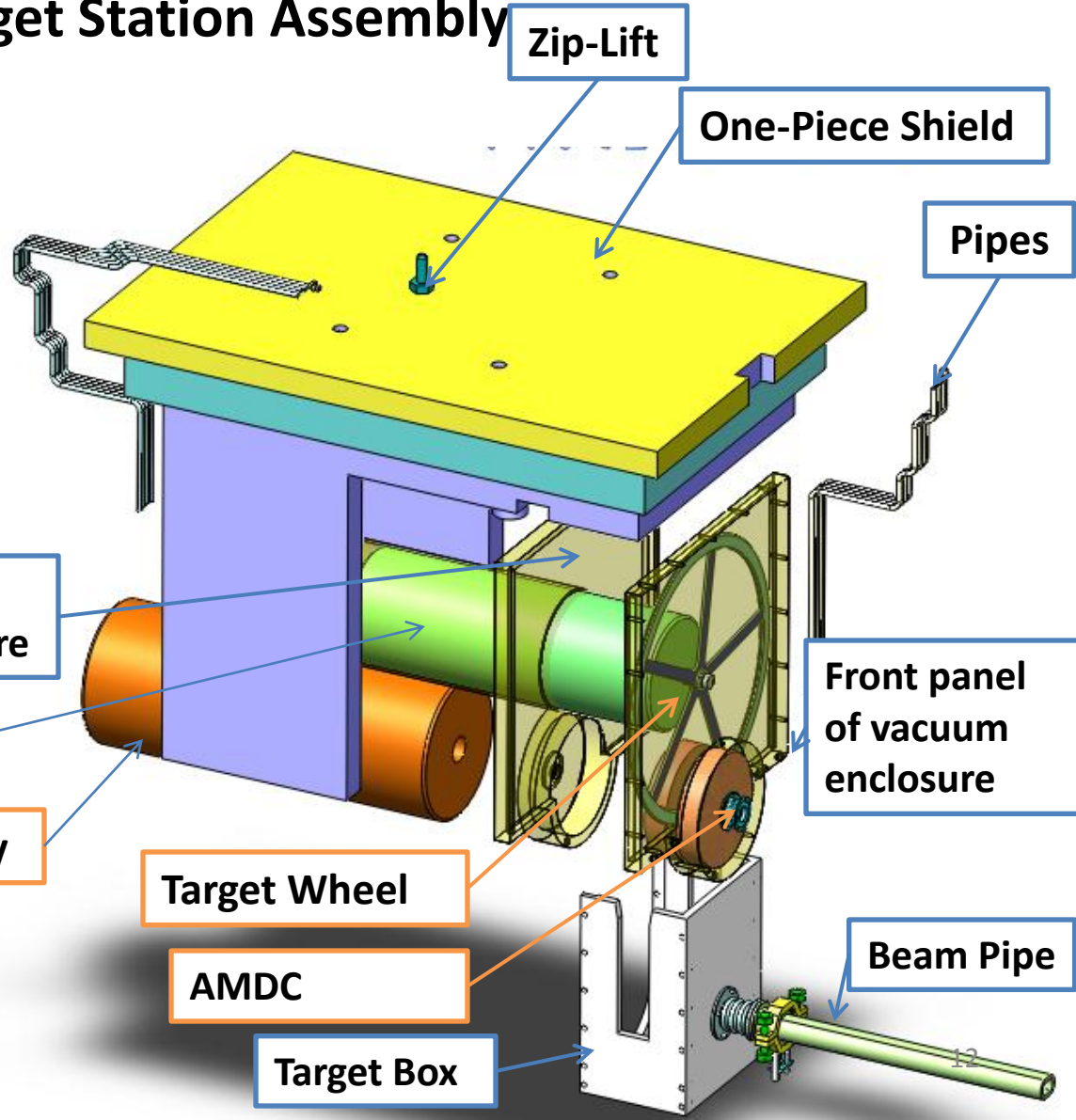
(Density choose $7.9 \times 10^3 \text{Kg/m}^3$)



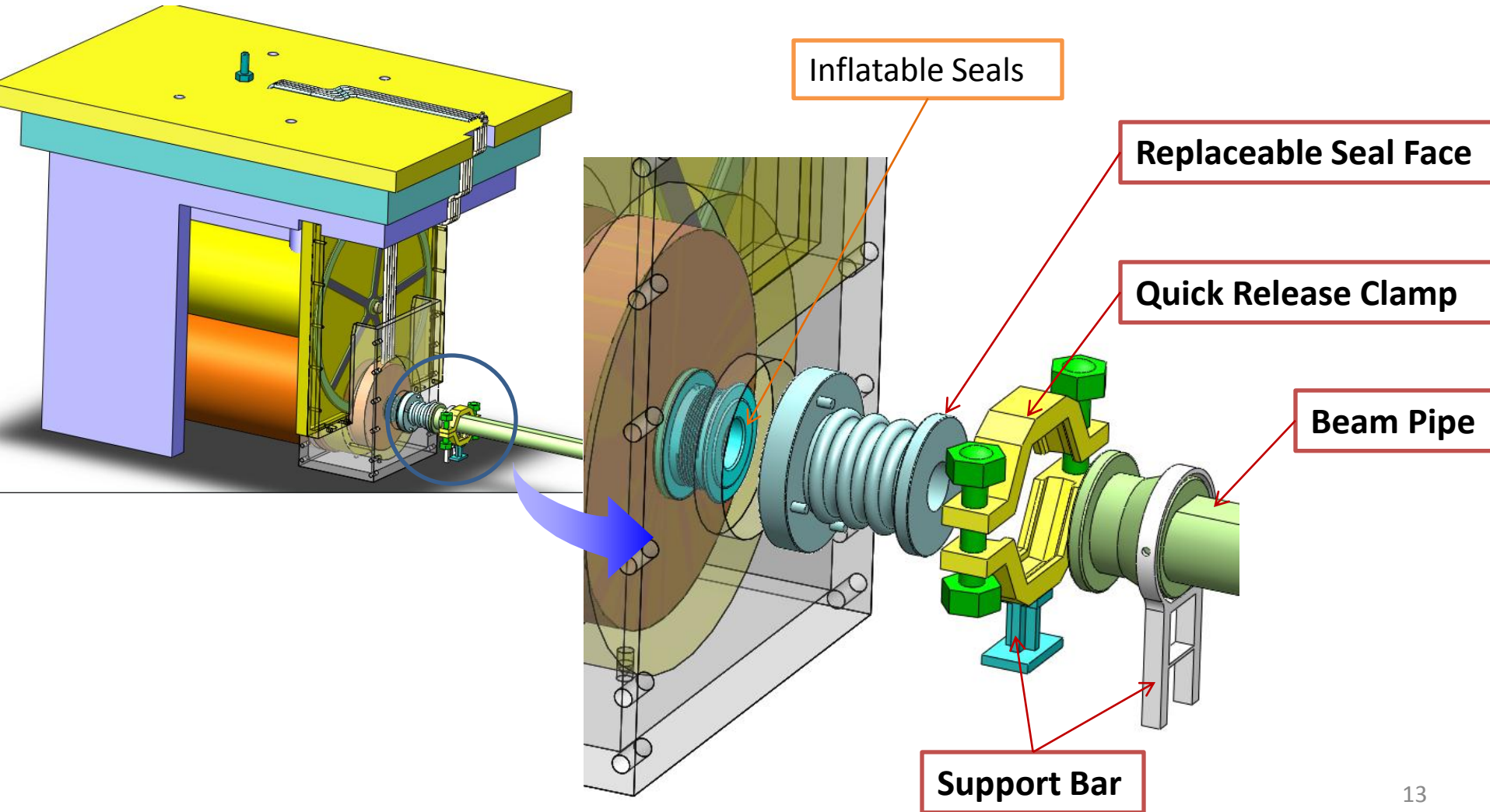
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Target Module



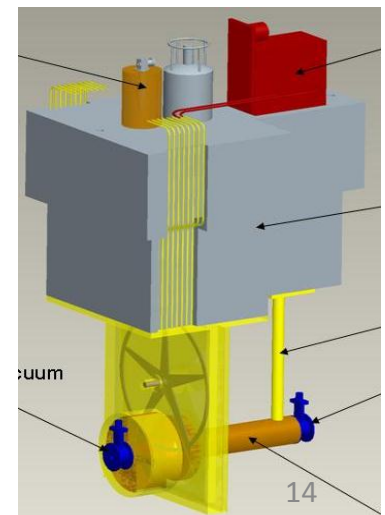
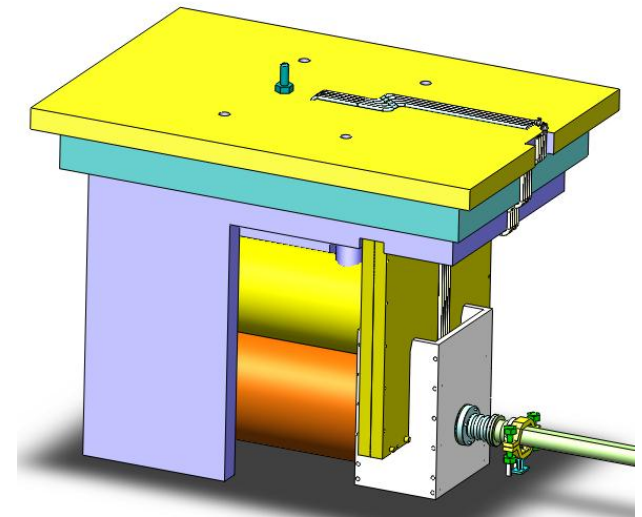
2. Components of the Target Station Assembly





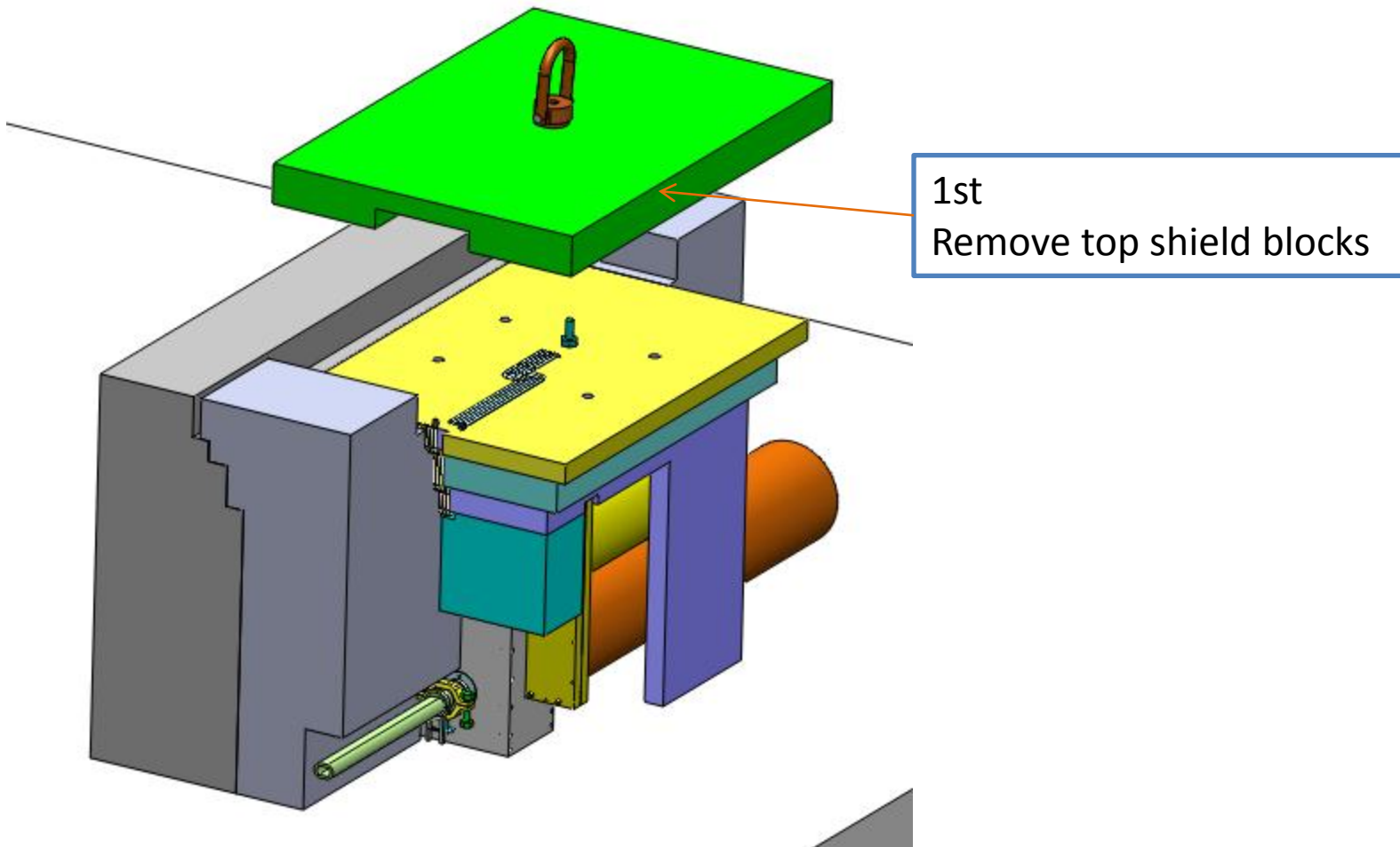
Differences between the new Target Station Assembly and the former

- ❑ Rearrange the service pipes and equipments.
- ❑ Add a target box to help the location and fixed of the target.
- ❑ Apply the replaceable seal face and quick release clamp to instead of the remotely operated vacuum valve, which reduce the pipes and simplify the target module structure.

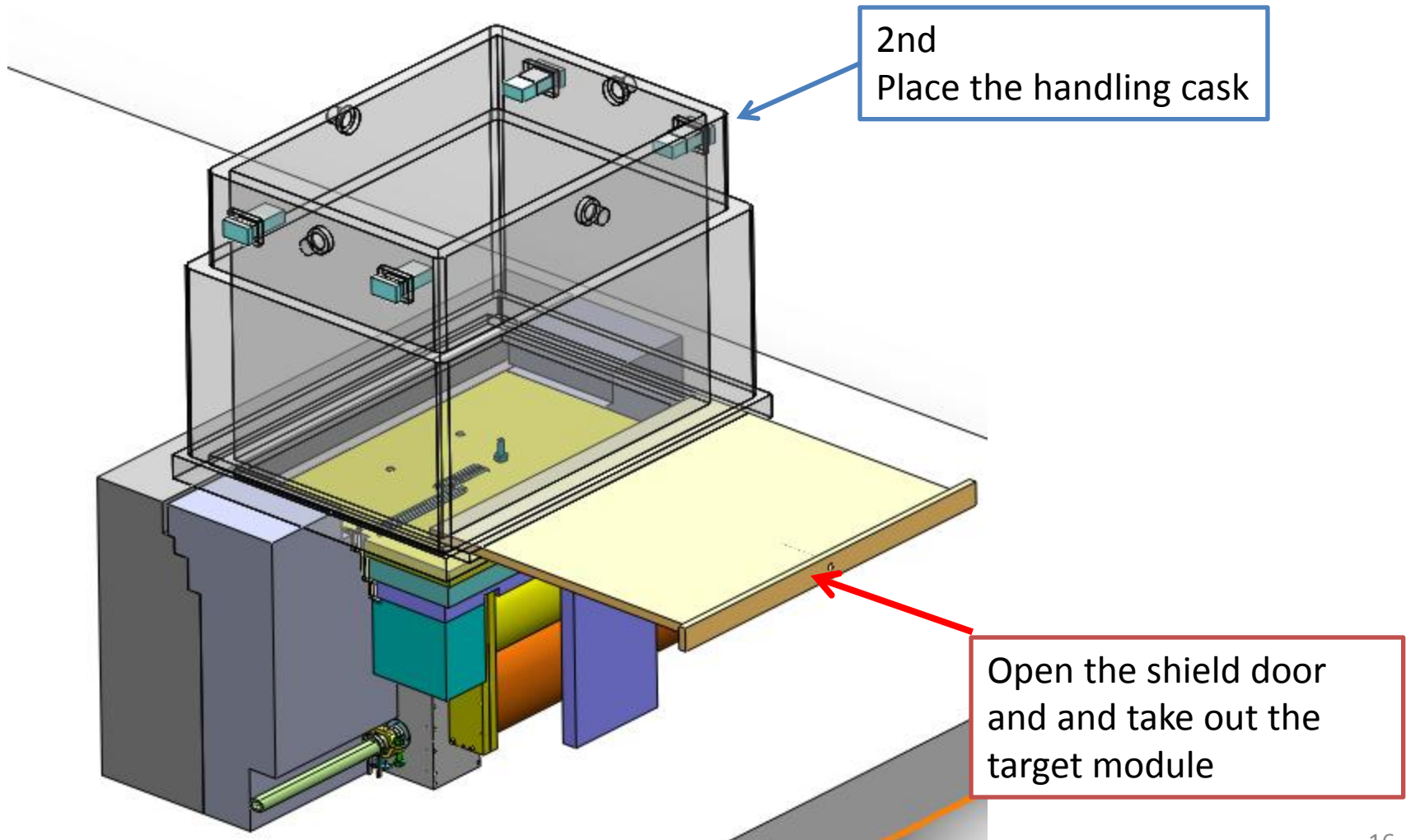




3. Replacement of Target Module

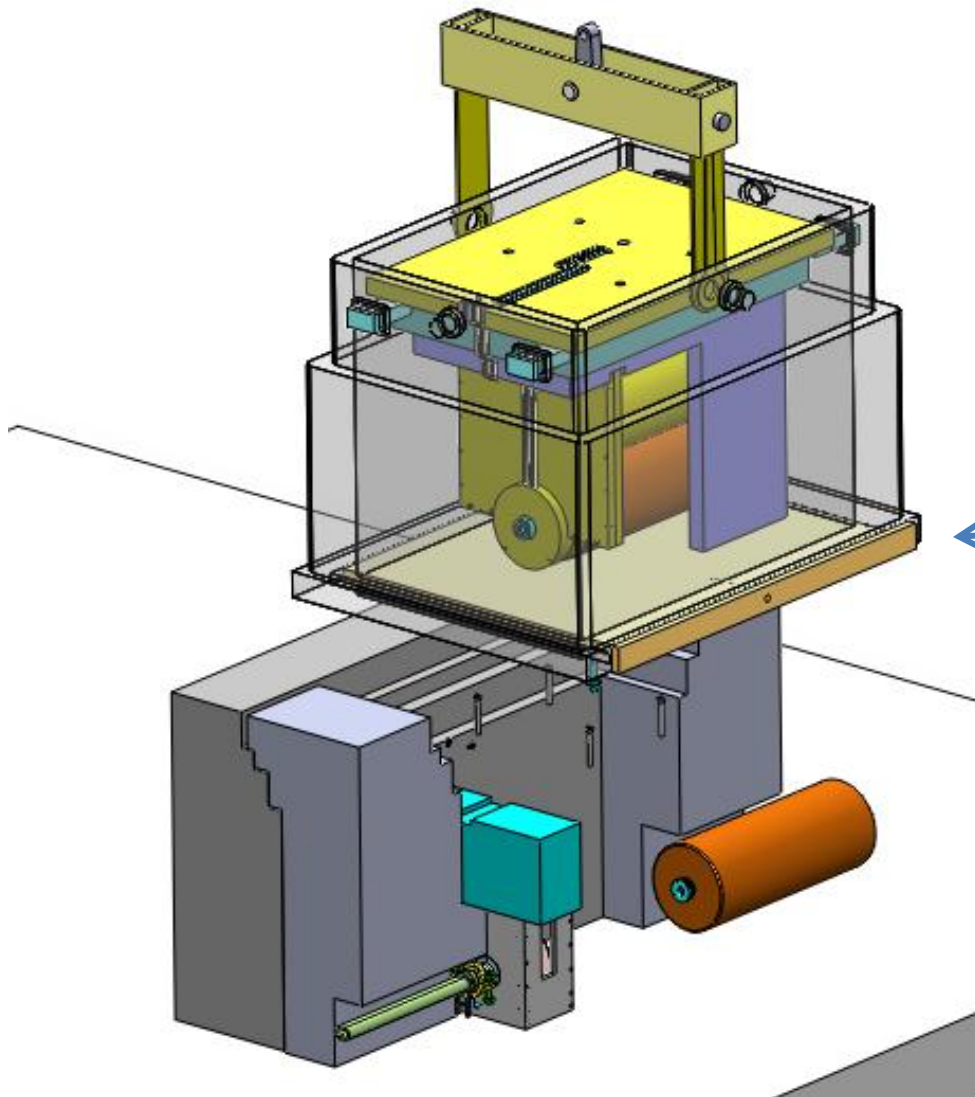


3. Replacement of Target Module





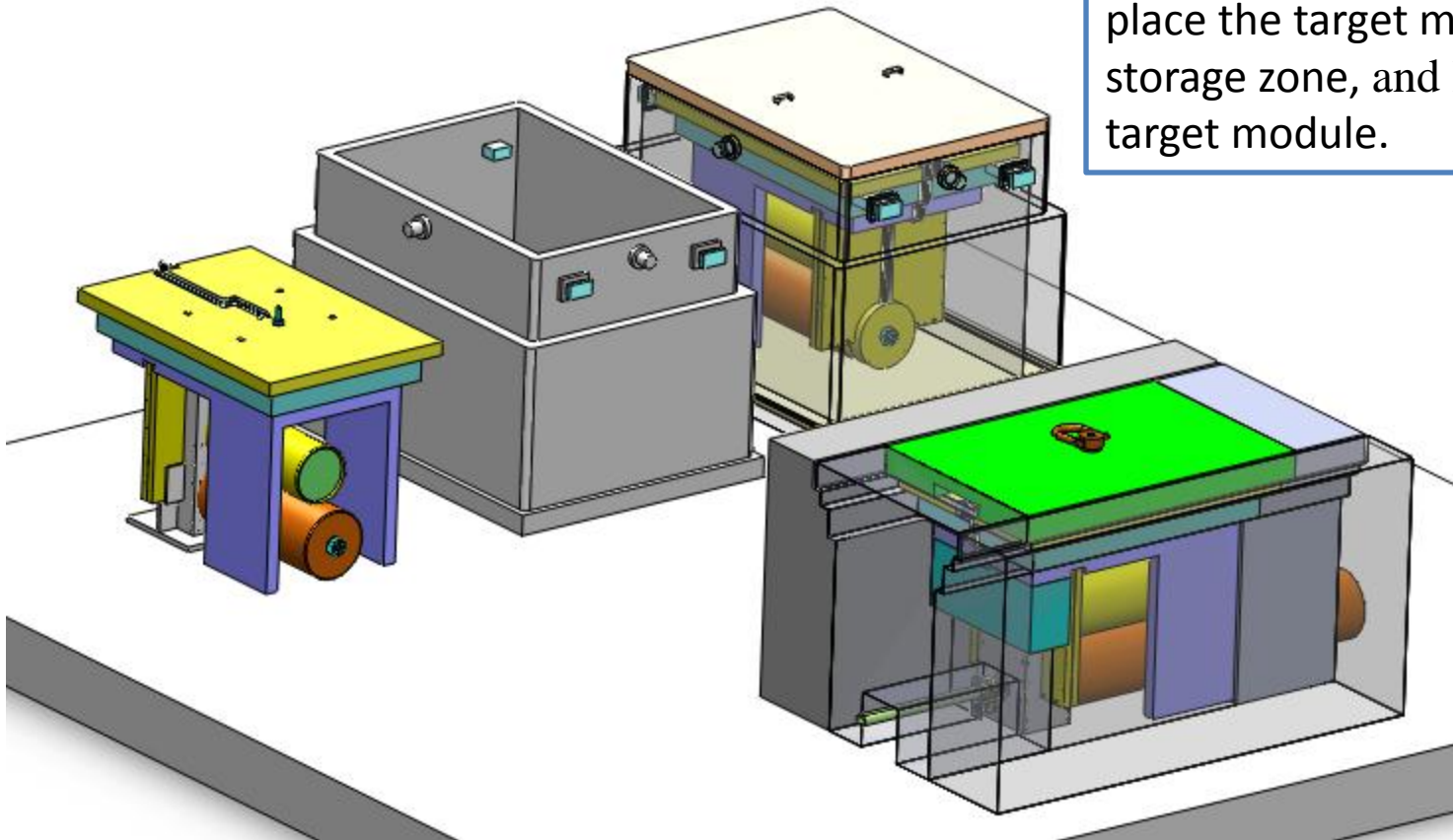
3. Replacement of Target Module



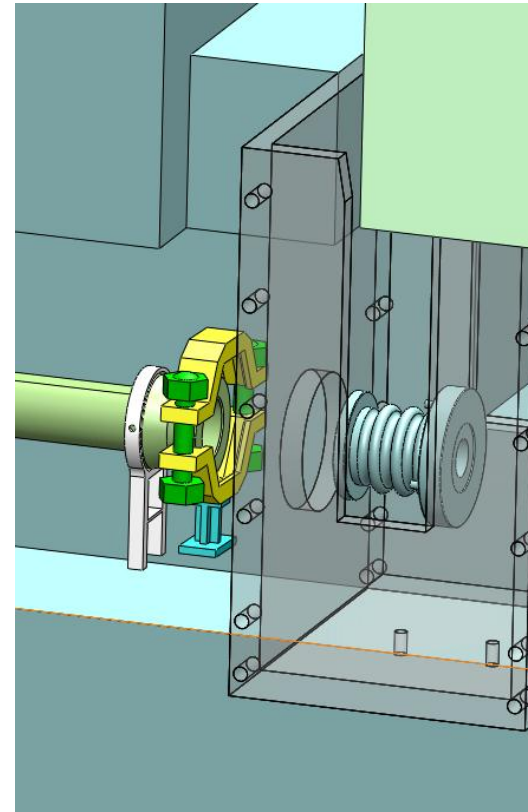
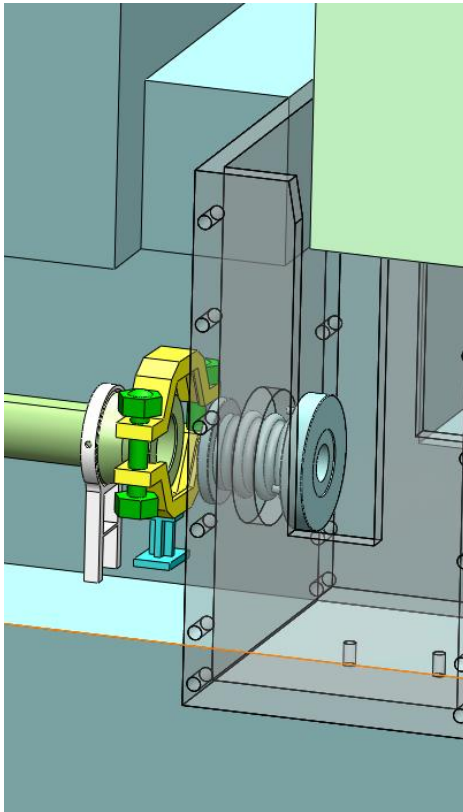
3rd
Close the shield door and
place the target module to
storage zone.

3. Replacement of Target Module

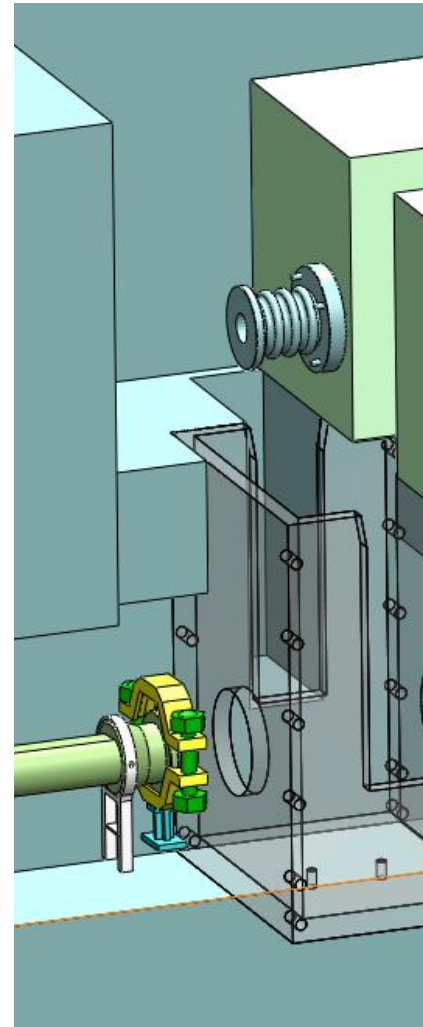
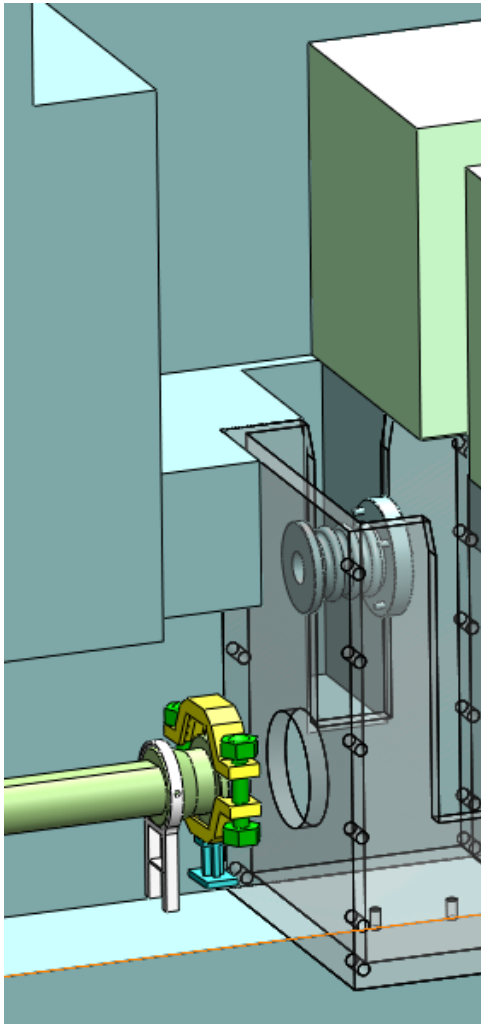
3rd
place the target module to
storage zone, and load a new
target module.



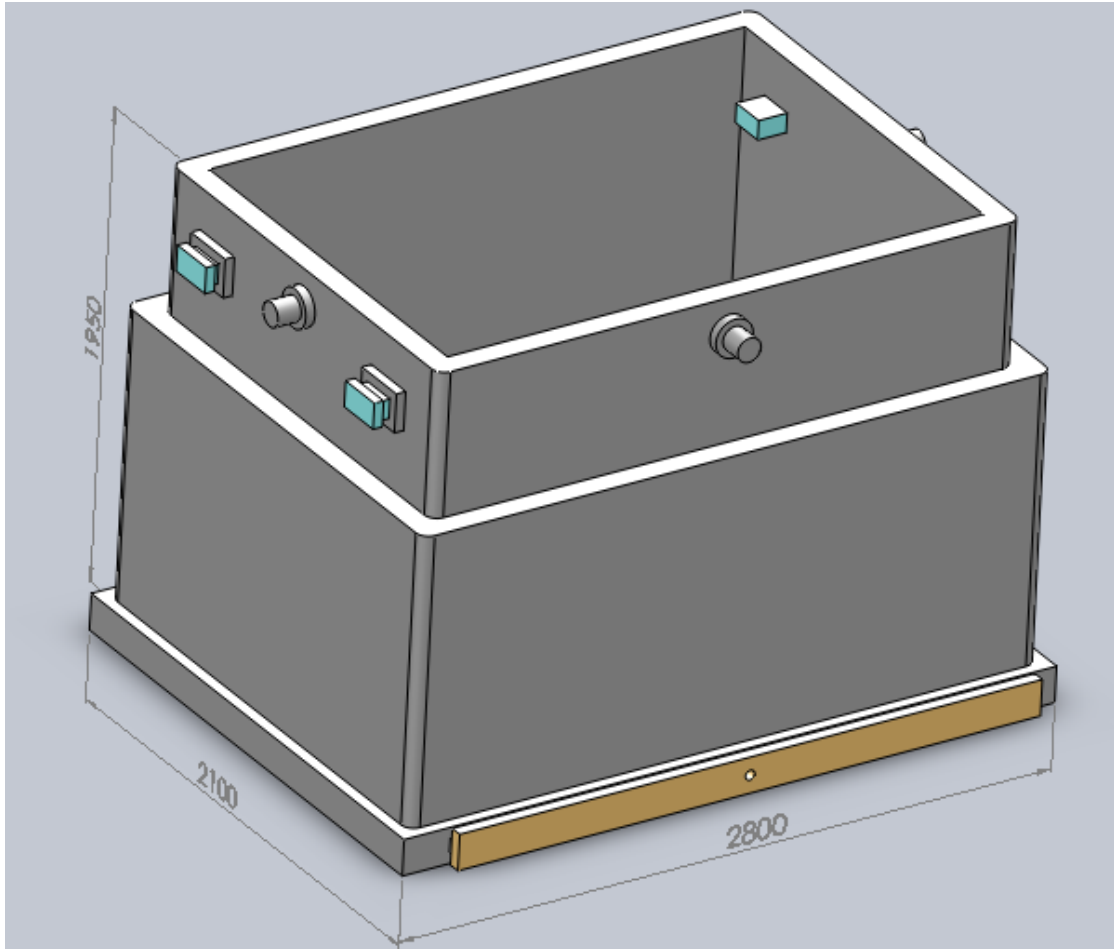
4. Removal of Replaceable Seal Face (If got weared)



4. Removal of Replaceable Seal Face



5. Important parameters of remote handling



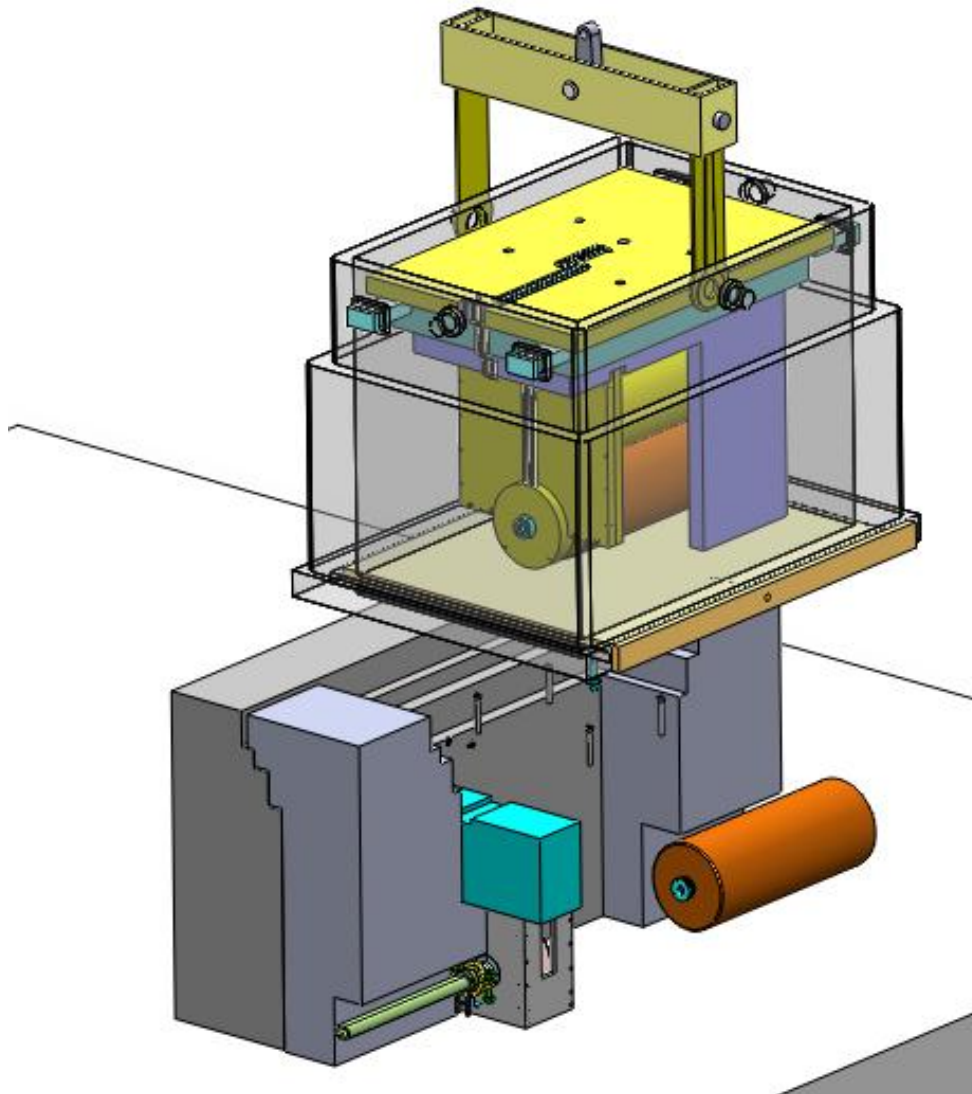
Size:

2800mm × 2100mm × 1950mm

Weight: **34305 Kg**

(Density choose $11.3 \times 10^3 \text{Kg/m}^3$)

5. Important parameters of remote handling



1. The minimum lift weight
(Target Mould + Handling Cask)
47248KG

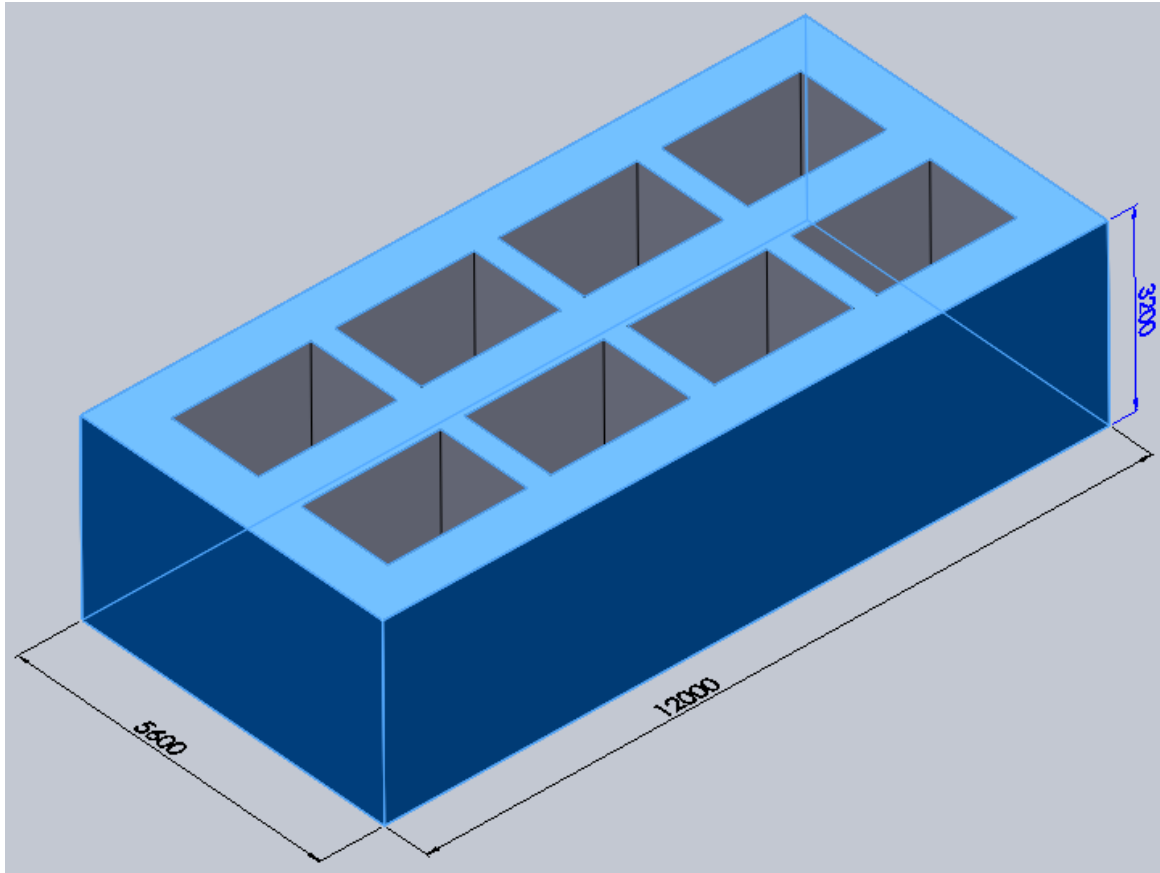
2. The remote handling height
above 6000mm

3. The waste Target Moulds need
to place into shielding casks or
special waste room with shielding
(above 800mm thickness concrete)

Suggestion:

**If the Motor and Accelerating
Cavity can separate with the
target module, the tool will
become much smaller.**

5. Important parameters of remote handling



Waste room(For example)

Size:
12000mm × 5600mm × 2500mm

Store 8 waste target.



5.Target Remote Handling Scenario

| Step | Operation | Time - hrs |
|---------------|---|------------|
| Remove | | |
| 1. | Switch off and isolate electric power to magnets (overhead cable system) | 3 |
| 2. | Switch off and isolate power to Target Wheel motor | |
| 3. | Stop Target Wheel coolant pump | 1 |
| 4. | Remove/disconnect water supply | |
| 5. | Close actuated vac valves on beam line each side of target station. | |
| 6. | Close actuated vac valve on AMD side of target station | 2 |
| 7. | Close actuated vac valve on NC Accelerating Cavity side of target station. | |
| 8. | De-pressurise both inflatable seal units and close vac valve on top of target mould | 1 |
| 9. | Attach lifting rods | |
| 10. | Attach lifting beam | 2 |
| 11. | Blow out top shield block | 0.5 |
| 12. | Lift target station complete with shield container and vac valve closed. | |
| 13. | Place into parking enclosure | 2 |
| 14. | Disconnect from crane | 1 |



5.Target Remote Handling Scenario

| Replacement | | |
|-------------|--|-----------|
| 15. | Connect lifting rods and beam to new unit with vac valve closed (already under vacuum) | 4 |
| 16. | Lower into position – locate | |
| 17. | Replace/reconnect water and gas pipes | 2 |
| 18. | Pressurise and activate both inflatable seal units | |
| 19. | Open actuated vac valve on NC Accelerating cavity side of target station | |
| 20. | Open actuated vac valve on AMD side of target station | |
| 21. | Test target station vacuum for leaks | 3 |
| 22. | Open actuated vac valves on beam line each side of target station | |
| 23. | Reconnect power to target wheel motor | |
| 24. | Test wheel motor. Test water flow through target wheel | 2 |
| 25. | Connect electric power supply to magnets | 4 |
| 26. | Replacement the top shield block | 0.5 |
| | TOTAL | 28 |



Estimated cost

- Pillow seal: 2X150k
- Supporting structure, alignment : 300k
- Replaceable seal : 2X 80k
- Zip-lift, Remote handling tools: 300k
- Transfer cask and supporting : 300k
- Utilities: 150k (?)
- Crane : 100k (20tons)
- Required storage area : $\approx 60 \text{ m}^2$



Many Thanks!