

MarlinReco

A Marlin based Reconstruction Toolkit for the ILC

Frank Gaede
DESY
ECFA ILC Workshop, Vienna
August 14-17, 2005

Outline

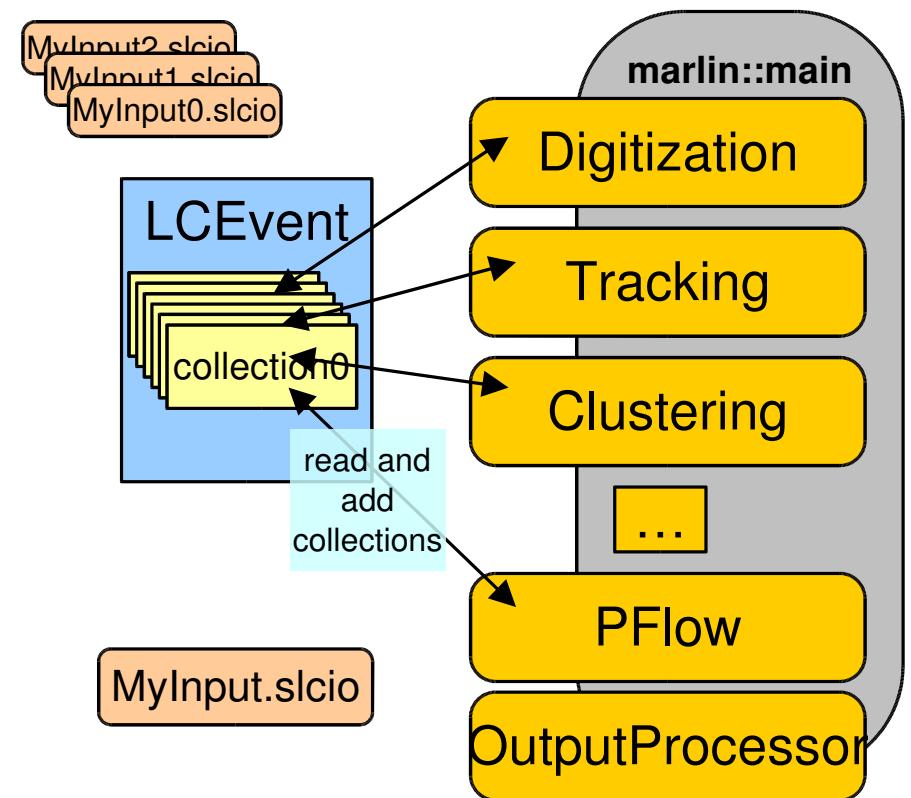
- Introduction
 - Marlin, Gear
- Overview MarlinReco
 - Reconstruction algorithms
 - PFlow
 - Utilities
- Status
- Summary/Outlook

MarlinReco developers:
S. Aplin, F. Gaede, T. Kraemer, P. Krstonosic,
A.Raspereza, J. Samson, O. Wendt

Marlin

Modular Analysis & Reconstruction for the L I Near Collider

- modular C++ **application framework** for the analysis and reconstruction of LCIO data
- uses LCIO as transient data model
- software modules called Processors
- provides main program !
- provides simple user steering:
 - program flow (active processors)
 - user defined variables
 - per processor and global
 - input/output files



Gear

```

<gear>
  <!--
    Example XML file for GEAR describing the LDC detector
  -->
  <detectors>
    - <detector id="0" name="TPCTest" geartype="TPCParameters" type="TPC">
      <maxDriftLength value="2500."/>
      <driftVelocity value=""/>
      <readoutFrequency value="10"/>
      <PadRowLayout2D type="FixedPadSizeDiskLayout" rMin="386.0"
        maxRow="200" padGap="0.0"/>
      <parameter name="tpcRPhiResMax" type="double"> 0.16 </parameter>
      <parameter name="tpcZRes" type="double"> 1.0 </parameter>
      <parameter name="tpcPixRP" type="double"> 1.0 </parameter>
      <parameter name="tpcPixZ" type="double"> 1.4 </parameter>
      <parameter name="tpcIonPotential" type="double"> 0.00000003
    </detector>
    - <detector name="EcalBarrel" geartype="CalorimeterParameters">
      <layout type="Barrel" symmetry="8" phi0="0.0"/>
      <dimensions inner_r="1698.85" outer_z="2750.0"/>
      <layer repeat="30" thickness="3.9" absorberThickness="2.5"/>
      <layer repeat="10" thickness="6.7" absorberThickness="5.3"/>
    </detector>
    - <detector name="EcalEndcap" geartype="CalorimeterParameters">
      <layout type="Endcap" symmetry="2" phi0="0.0"/>
      <dimensions inner_r="320.0" outer_r="1882.85" inner_z="2820."
      <layer repeat="30" thickness="3.9" absorberThickness="2.5"/>
      <layer repeat="10" thickness="6.7" absorberThickness="5.3"/>
    </detector>
  </detectors>
</gear>

```

GEometry API for Reconstruction

- well defined geometry definition for reconstruction that
 - is flexible w.r.t different detector concepts
 - has high level information needed for reconstruction
 - provides access to material properties - planned
- abstract interface (a la LCIO)
- concrete implementation based on XML files
- and Mokka-CGA – planned

compatible with US – compact format

MarlinReco

- Marlin serves as a **framework** for the distributed development of reconstruction algorithms
 - provides a well defined modularity
- MarlinReco is a **toolkit** which aims at providing reconstruction algorithms for detector concept studies
 - (almost) complete set of standard reconstruction (pflow)
 - cheaters for cross checks (and replacements)
 - all processors can seamlessly be combined together with other reconstruction code or plugged into your analysis
 - e.g. together with MAGIC-clustering (see talk by C. Ainsley)

MarlinReco packages

- **TrackDigi**

- FTDDigi
- VTXDigi
- TPCDigi

- **CaloDigi**

- LDCCaloDigi

- **Tracking**

- BrahmsTracking
- TrackCheater

- **Clustering**

- TrackwiseClustering
- ClusterCheater

- **Pflow**

- Wolf

- **Analysis**

- EventShapes
- SatoruJetFinder

most MarlinReco processors (algorithms) are geometry independent
→ they can be applied to other detector concepts (via Gear file)

MarlinReco Digitization

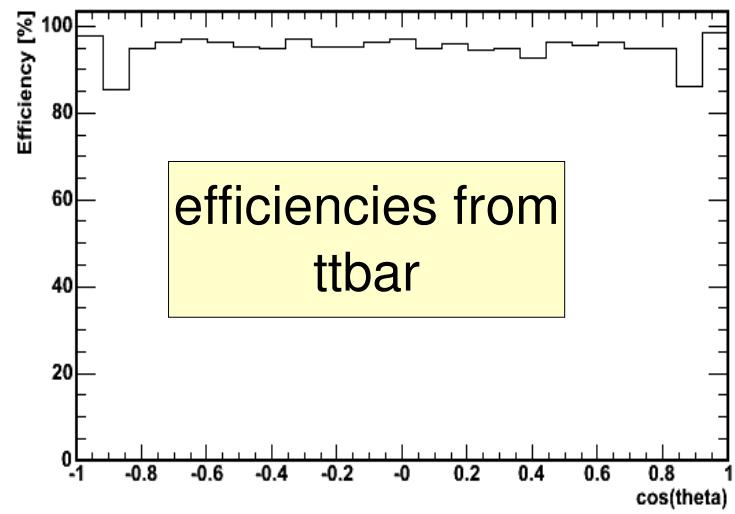
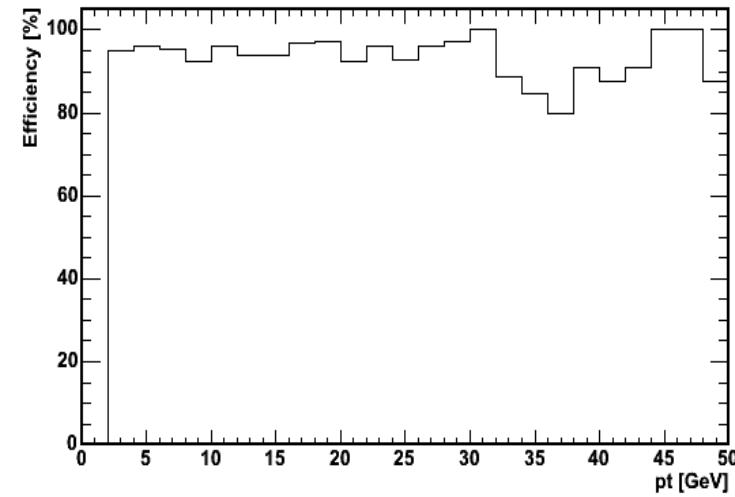
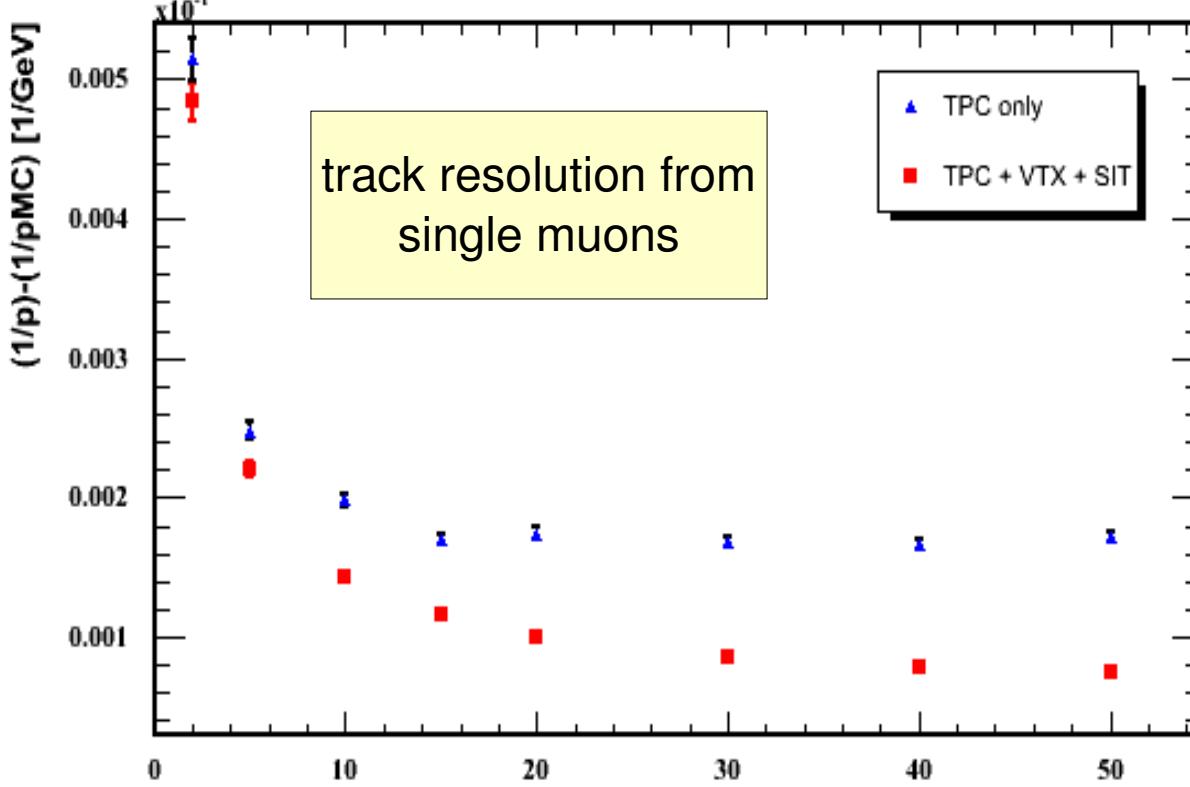
- **Tracker** (S.Aplin)
 - TPC: Gaussian smearing of position in z and r-phi
 - Silicon: exact position from simulation –
 - more meaningful clustering under development (A.Raspereza)
- **Calorimeter** (A.Raspereza)
 - calibration only - no smearing
 - optional energy cut
 - ganging (investigate different granularity)

MarlinReco Tracking

- **Central Tracks:** (S.Aplin)
 - algorithms taken from LEP (ALEPH and DELPHI)
 - f77 code from Brahms
 - track finding based on out-in search using circle fit
 - fit with Kalman Filter takes material into account
 - start with TPC tracks and then include VTX hits (next slide)
- **Track Cheater** (A.Raspereza)
 - uses Monte Carlo for track finding
 - fitted with a helix hypothesis

Tracking including VTX hits

- vtx hits now included in track fit
- use TPC tracks as 'seed'
- standalone VTX tracking under development



S.Aplin, O.Wendt

MarlinReco Clustering

- **Trackwise Clustering** (A.Raspereza)
 - algorithm needs spatial information only
 - -> applicable to both digital and analogue calorimeters
 - minimal dependence on detector geometry
 - -> can be used for other detector concepts

- **Cluster Cheater** (A.Raspereza)
 - uses Monte Carlo to combine hits into clusters
 - proximity criterion for 'realistic' clusters

PFlow

- Track-Cluster matching (A.Raspereza)
 - extrapolate tracks into the calorimeter
 - use only outer track hits and apply helix fit
 - proximity criterion to assign cluster to track
 - charged objects (E, p) from track
 - neutral particles (E, p) from cluster
- Particle ID (A.Raspereza)
 - cluster shape analysis
 - fraction of energy in ECAL
 - longitudinal and transverse profile
 - test of MIP hypothesis

Analysis

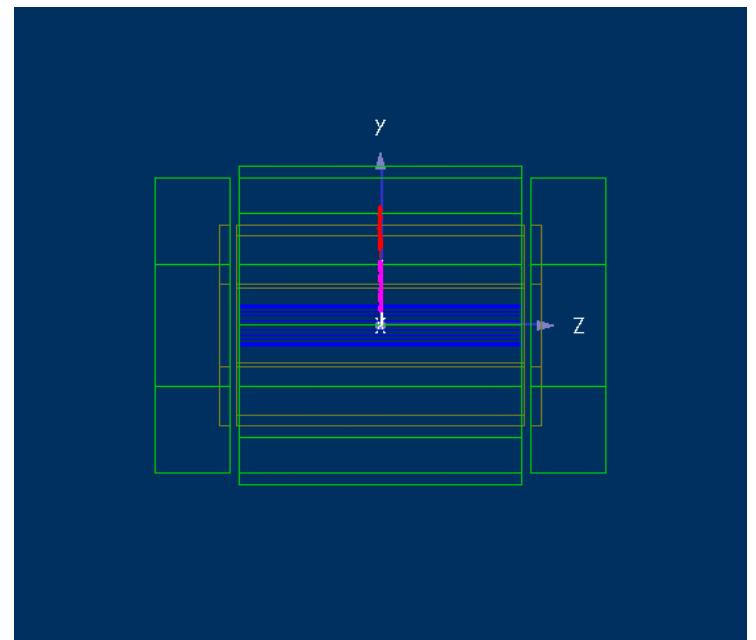
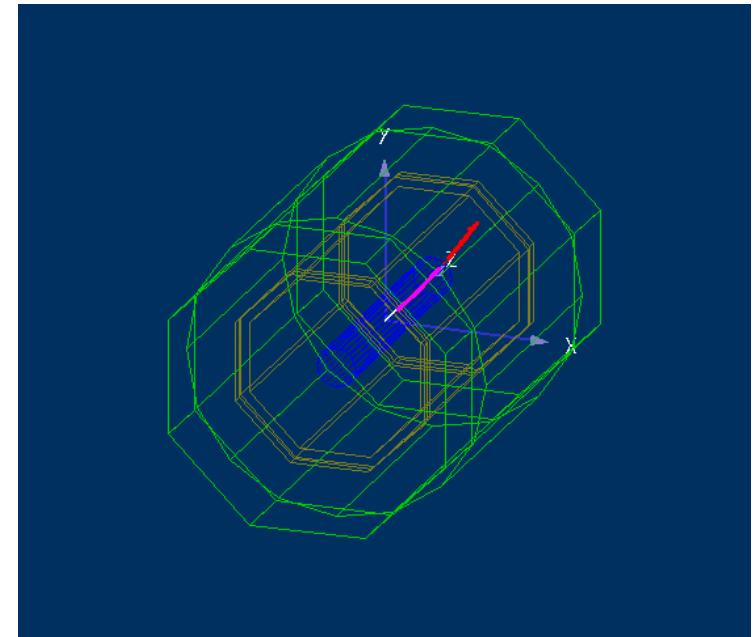
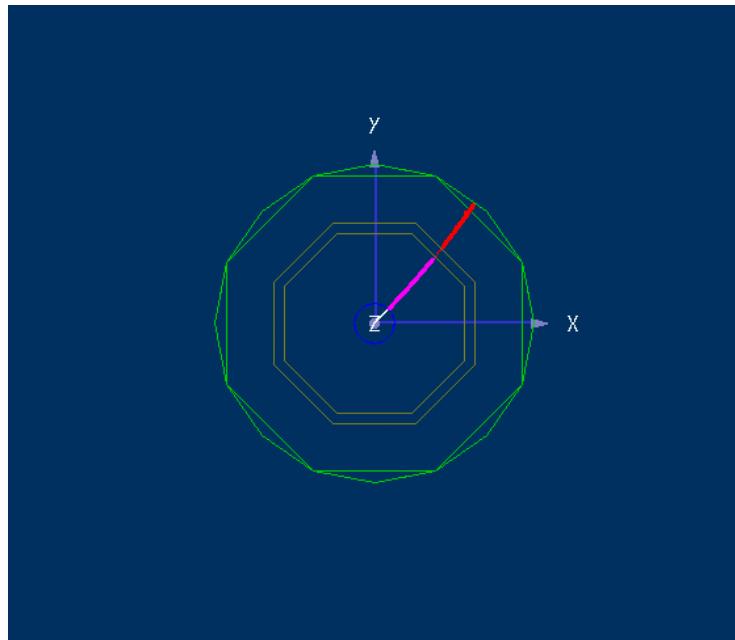
- **Event Shapes** (T. Kraemer, P. Krstonic)
 - ThrustReconstruction: Tasso & Jetnet algorithms
 - Sphere: sphericity, aplanarity, ...
- **SatoruJetFinder** (J. Samson)
 - originally developed by Satoru Yamashita for OPAL
- **BenchmarkPlots**
 - not yet -> input needed

MarlinReco support packages

- **MarlinUtil** (O. Wendt)
 - Utility and Helper classes
 - helix fitter
 - cluster shapes
 - common code for CED
- **CED** (A. Zhelezov)
 - event display based on GLUT/ OpenGL
 - client server architecture
- **CEDViewer**
 - event display client processors

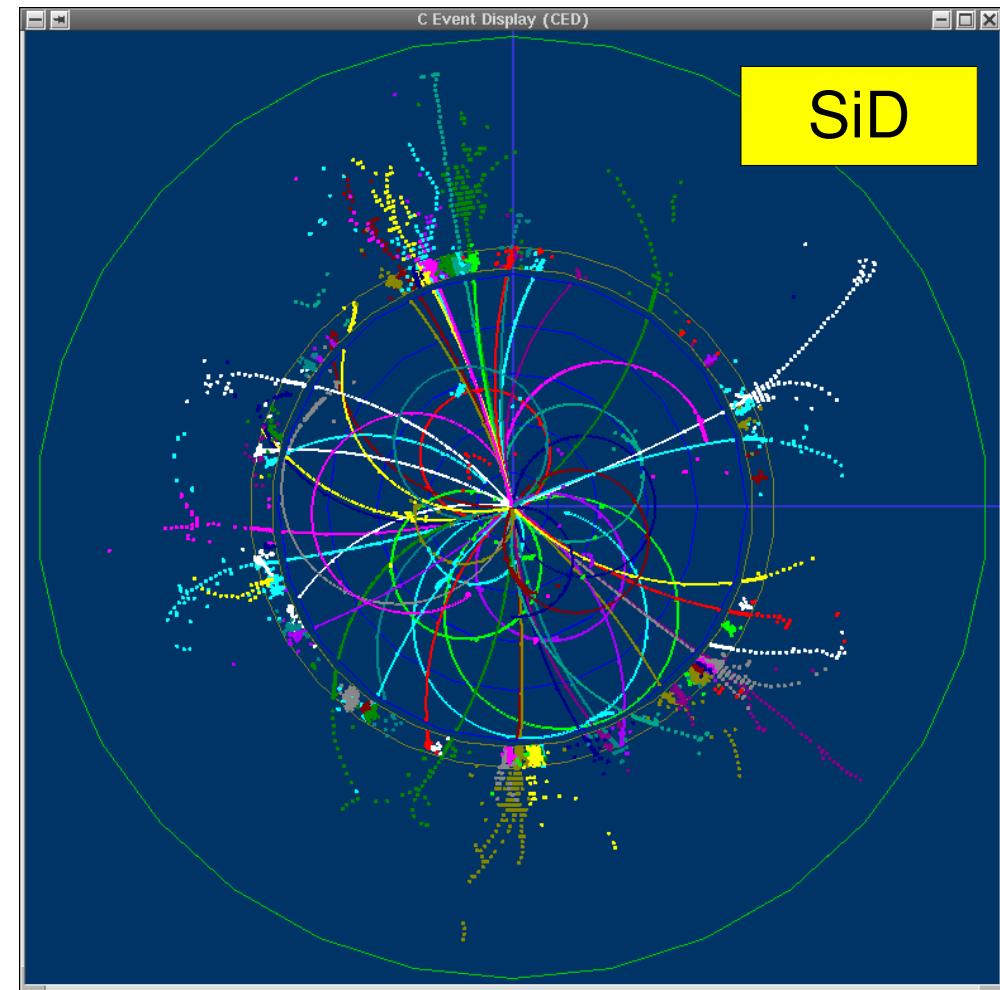
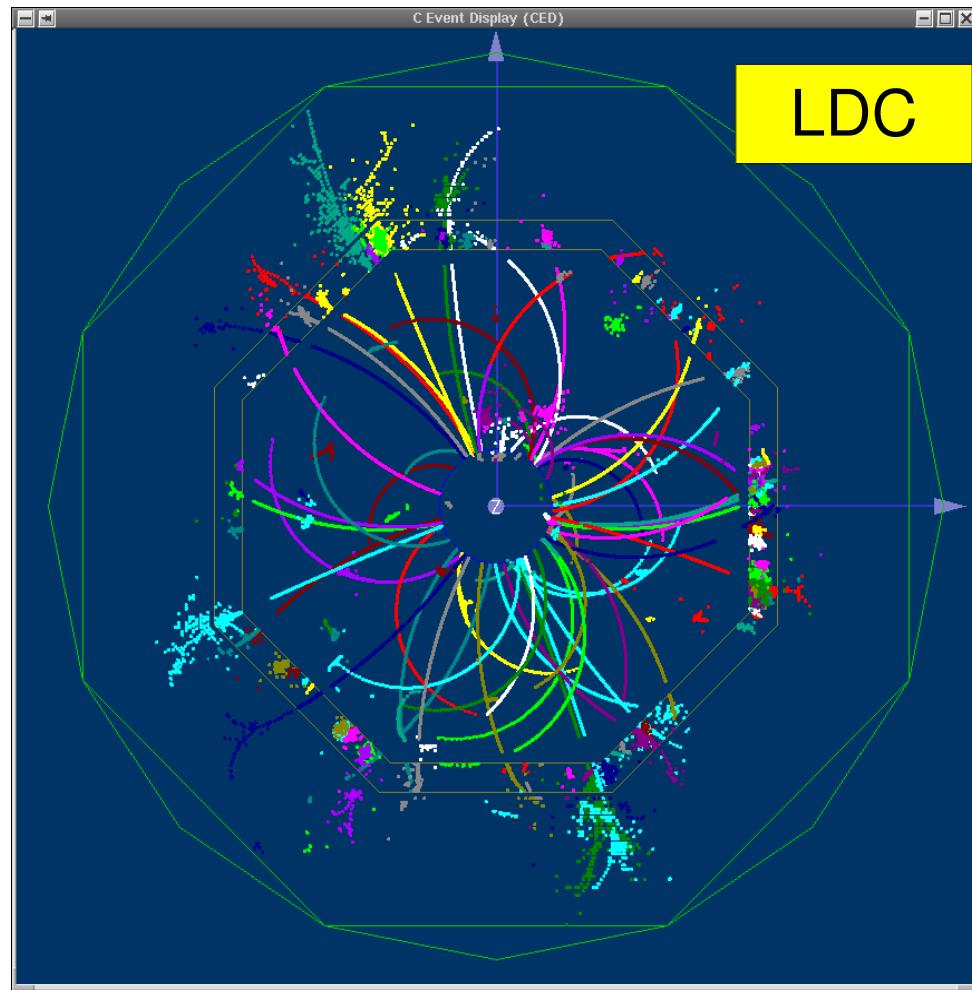
CEDViewer

simple example taken from
\$MarlinReco/examples/LDC
steer_ldc.xml
gear_ldc.xml



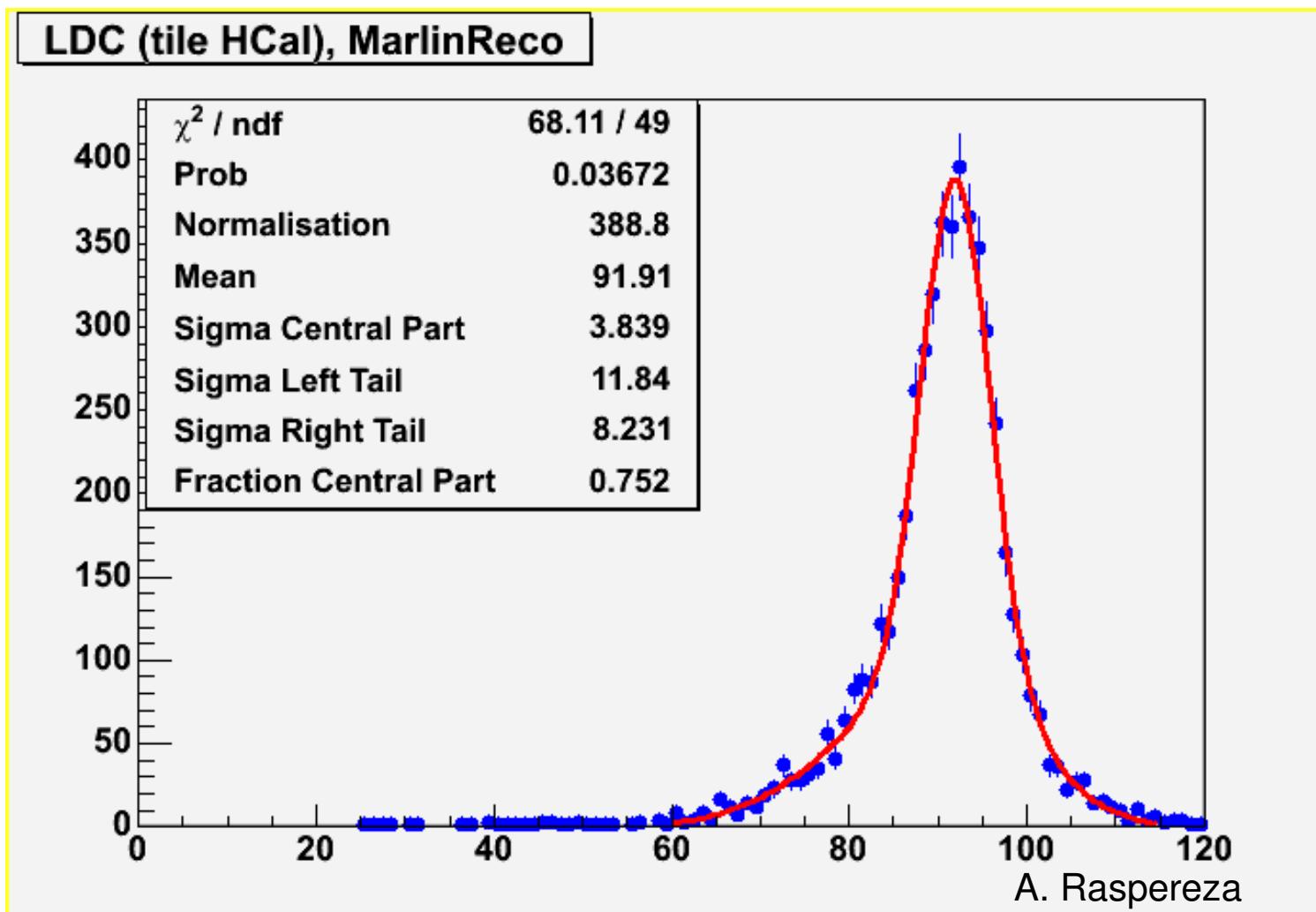
ttbar events with MarlinReco

No cheaters, only full reconstruction



Initial results

- e+e- → Z → qqbar using full reconstruction



Status I

- first official release of MarlinReco: v00-01
 - changes wrt. snowmass DVD:
 - comprehensive manual (T.Kraemer)
 - including VTX hits for central tracking
 - detailed API documentation for every processor
 - utility packages released:
 - CEDViewer v00-01
 - MarlinUtil v00-01
 - CED v00-01
 - works with
 - Gear v00-02
 - Marlin v00-09-02

Status II – To Do

- neutral vertex and kink finding algorithms
- more realistic digitization
- vertex tracking
- forward tracking
- vertexing
- particleID
- ...

your input (code) is welcome !

MarlinReco on the web

The screenshot shows the ILC Software Portal interface for the MarlinReco project. The left side features a navigation menu with links to various software packages like Brahms, CEDViewer, Gear, LCIO, Marlin, MarlinUtil, Mokka, and CED. A login form is also present. The main content area displays the MarlinReco project details, including its latest release (v00-01), download links for CVS and tarball, and a project description. The description explains that MarlinReco is a software package for reconstruction events using simulated raw data of an ILC detector, utilizing separate modules for track finding and cluster reconstruction.

This screenshot shows the CVSweb interface for the MarlinReco repository. It lists the directory structure under the root. The 'File' column contains icons for each directory, and the 'Rev.' column shows the revision number (e.g., 1.1.1.1 for GNUmakefile). The 'Last log entry' column shows the commit message: 'Initial version'. At the bottom, there are buttons to 'Show all releases', 'Download this directory in tarball or zip archive', and a 'Done' button.

The screenshot shows the documentation page for the MarlinReco project. It includes a navigation menu, a login form, and a 'Forgot your password?' link. The main content area is titled 'MarlinReco' and describes it as a 'Marlin based Reconstruction Package for the ILC'. It credits T. Krämer et.al., DESY. The page also includes a 'Contents' section with links to 'Introduction', 'Dependency on other Packages' (which lists LCIO, Marlin, Gear, and MarlinUtil), and a 'Documentation' section which is a comprehensive manual for the project.

Software Portal:
<http://ilcsoft.desy.de>
[aka: <http://www-flc.desy.de/ilcsoft>]

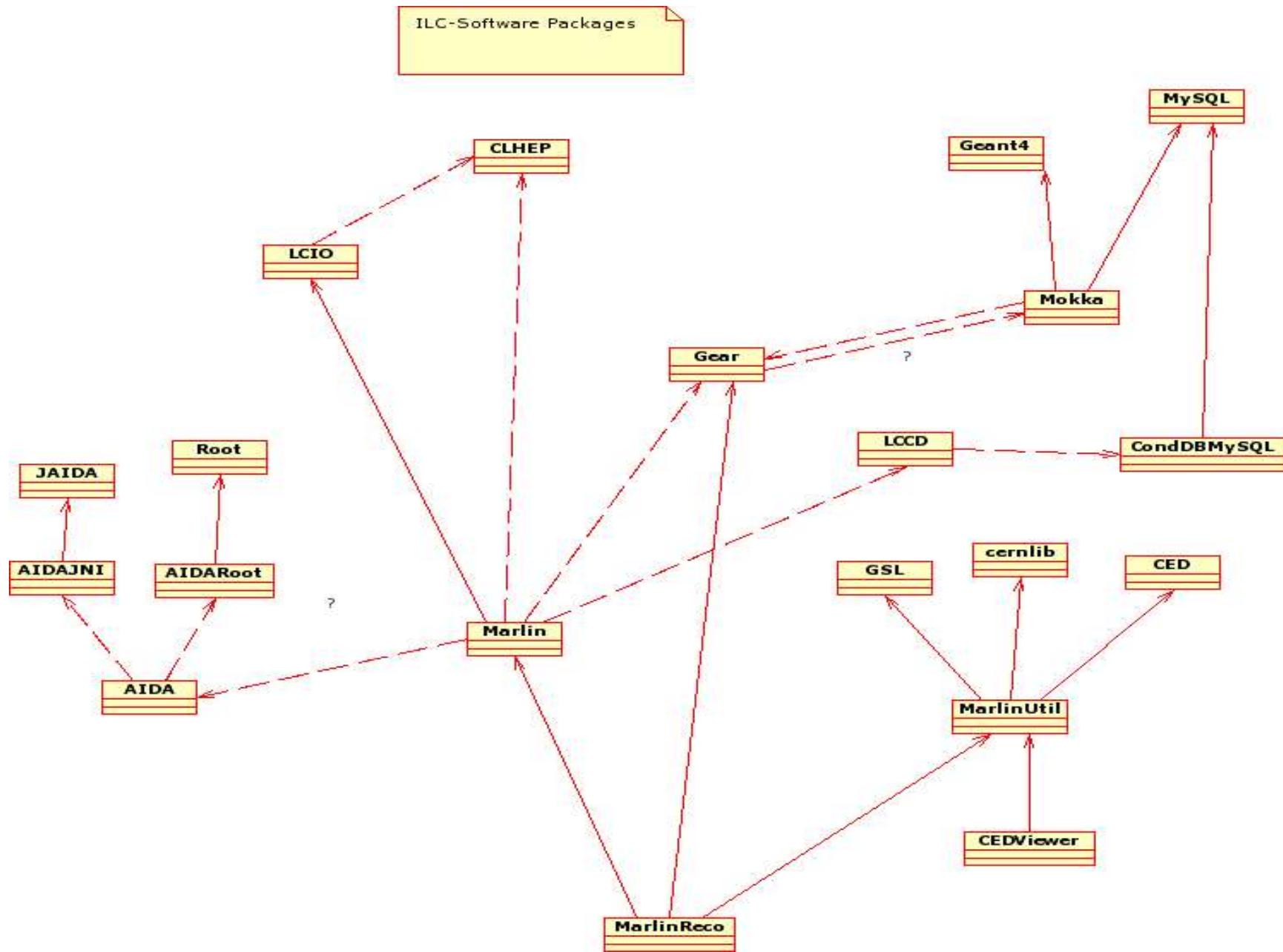
Summary/Outlook

- MarlinReco is a reconstruction toolkit for the ILC
 - (almost) complete set of standard reconstruction
 - cheaters for cross checks (and surrogates)
 - **flexible**: can be used for other detector concepts
 - **extensible**: use/combine with other processors
- v00-01 released
- plans to extend functionality exist
- your input is welcome !

MarlinReco is a tool for answering the
questions raised by the detector concept studies
-> use it now !

Backup slides...

MarlinReco dependencies



Marlin Processor

- provides main **user callbacks**
- has **own set of input parameters**
 - int, float, string (single and arrays)
 - parameter description
- naturally modularizes the application
- **order of processors is defined via steering file:**
 - easy to exchange one or several modules w/o recompiling
 - can run the same processor with different parameter set in one job
- **processor task can be as simple as creating one histogram or as complex as track finding and fitting in the central tracker**

```
marlin::Processor  
init()  
processRunHeader(LCRunHeader* run)  
processEvent( LCEvent* evt)  
check( LCEvent* evt)  
end()
```

```
UserProcessor  
processEvent( LCEvent* evt){  
    // your code goes here...  
}
```



XML files configure a Marlin Application

```

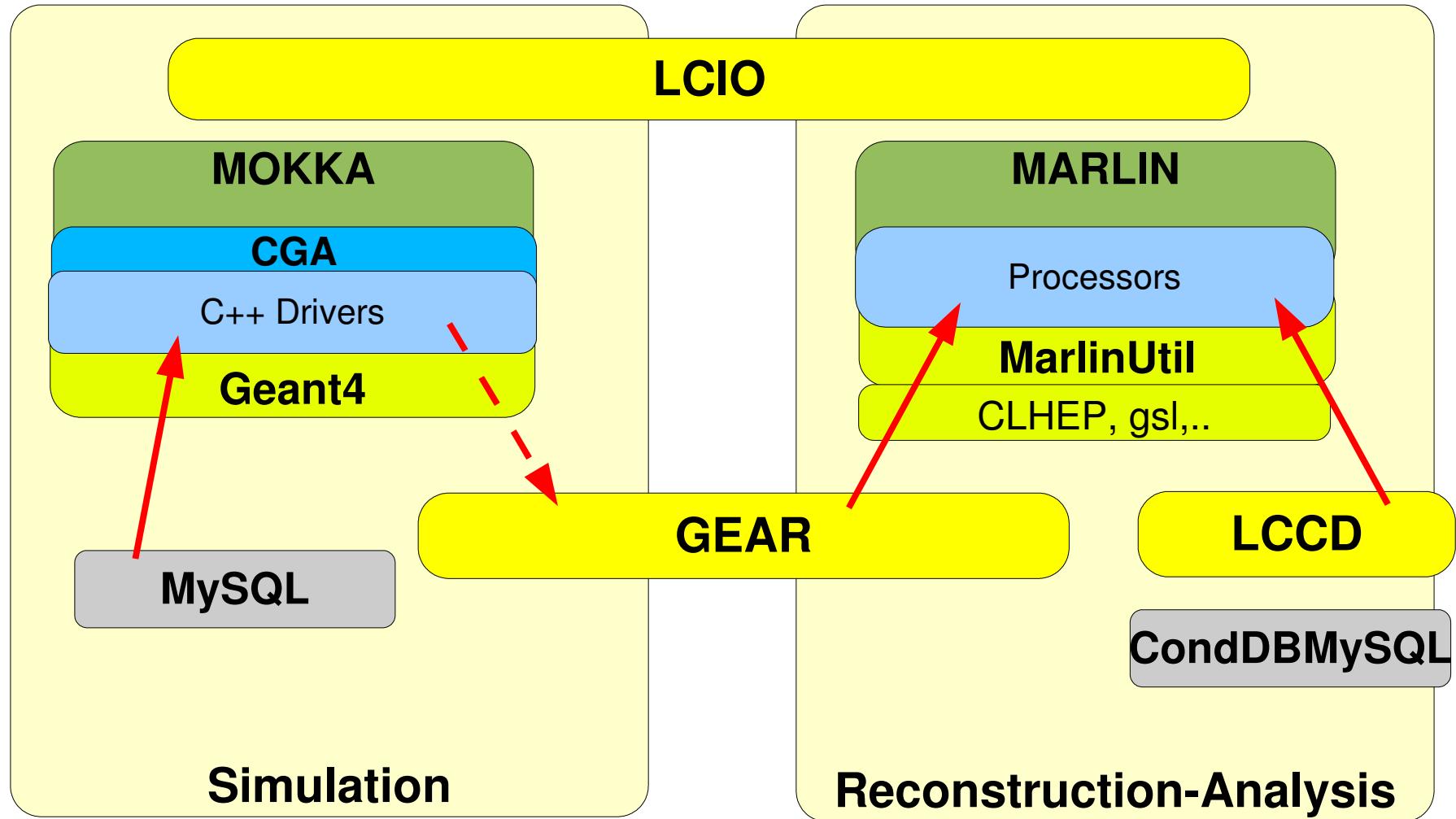
- <marlin>
  - <execute>
    <processor name="MyAIDAProcessor"/>
    <processor name="MyEventSelection"/>
    - <if condition="MyEventSelection">
      <group name="Tracking"/>
      <processor name="MyClustering"/>
      <processor name="MyPFlow"/>
      <processor name="MyLCIOOutputProcessor"/>
    </if>
  </execute>
  - <global>
    <parameter name="LCIOInputFiles"> simjob.slcio </parameter>
    <parameter name="MaxRecordNumber" value="5001"/>
    <parameter name="SupressCheck" value="false"/>
  </global>
  - <processor name="MyLCIOOutputProcessor" type="LCIOOutputProcessor">
    <parameter name="LCIOOutputFile" type="string">outputfile.slcio </parameter>
    <parameter name="LCIOWriteMode" type="string">WRITE_NEW</parameter>
  </processor>
  - <group name="Tracking">
    <parameter name="NTPCLayers" value="200"/>
    <processor name="MyTrackfinder" type="Trackfinder"/>
    - <processor name="MyTrackfitter" type="Trackfitter">
      <parameter name="Algorithm" value="DAF"/>
    </processor>
  </group>
  <!-- ... -->
</marlin>
```

- Active processors defined in `<execute>...</execute>` section
- Logical conditions from booleans set by preceding processors

- Parameters: global and per processor
- Parameters defined as content of `<parameter/>` tag or as its value attribute

- Processors can be enclosed by `<group/>` tag
- Parameters in `<group/>` joined by all processors

LDC simulation framework



Marlin on the web

Modular **A**nalysis & **R**econstruction for the **L I N**ear Collider

Releases

v00-08 has been released and is available for [download](#). Marlin can now optionally be linked against [LCCD](#) to provide easy access to conditions data. [documentation](#) has been improved.

Download

All tagged versions and the current HEAD of the repository can be downloaded from the [SVN repository](#).

Documentation

[Current API documentation.](#)

Talks

LCIO & Marlin ([pdf](#)) - talk given at the DESY Simulation WS 2004.

Last modified: Fri Mar 11 16:01:59 2005 by Frank.Gaede@desy.de

Done

latest release: **v00-09-02**

<http://ilcsoft.desy.de/marlin>

Marlin (v00-08)

Marlin [Modular Analysis and Reconstruction for the LINear collider] is a simple modular application framework for analysis and reconstruction code based on LCIO.

Overview

Marlin is a modular development of reconstruction and analysis code based on LCIO. As a lot of different groups are involved in the development of Marlin, it is designed to have distributed development of modules and combine existing modules as needed in a larger system. The `marlin::Processor` class defines a set of callbacks that the user can implement in their subclasses. A steering file defines the sequence of processors. These are then called for every event using the `LCEvent` as container for input and output data in the form of `LCIO` objects.

The diagram illustrates the data flow: Input files (`MyInput.slcio`) are read and added to an `LCEvent`. The `LCEvent` then feeds into a collection of `Processor`s (Processor0, Processor1, Processor2, ..., ProcessorN). Finally, the results are processed by an `OutputProcessor`.

Installation

The installation of Marlin is described in the [README](#).

Running Marlin

After having installed Marlin you have to write your own `marlin::Processor`(s) subclass that performs the computation. This is fairly straight forward and Marlin provides an example in [/examples/mymarlin](#) that can serve as a template for your own projects.

Note: there is no need to write a main program as this is provided by Marlin. Existing Processors are automatically registered with Marlin provided one instance exists in the library as described in the [README](#).

Steering files

Done