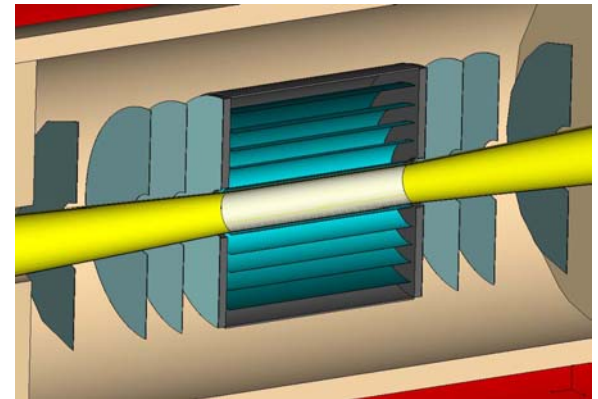
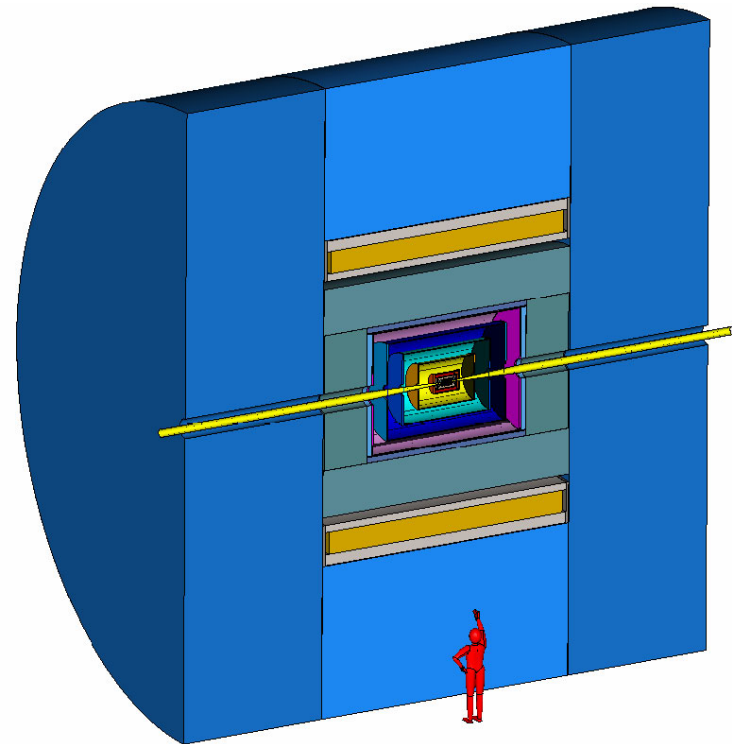


# Design and Performance of Silicon Tracking in SiD

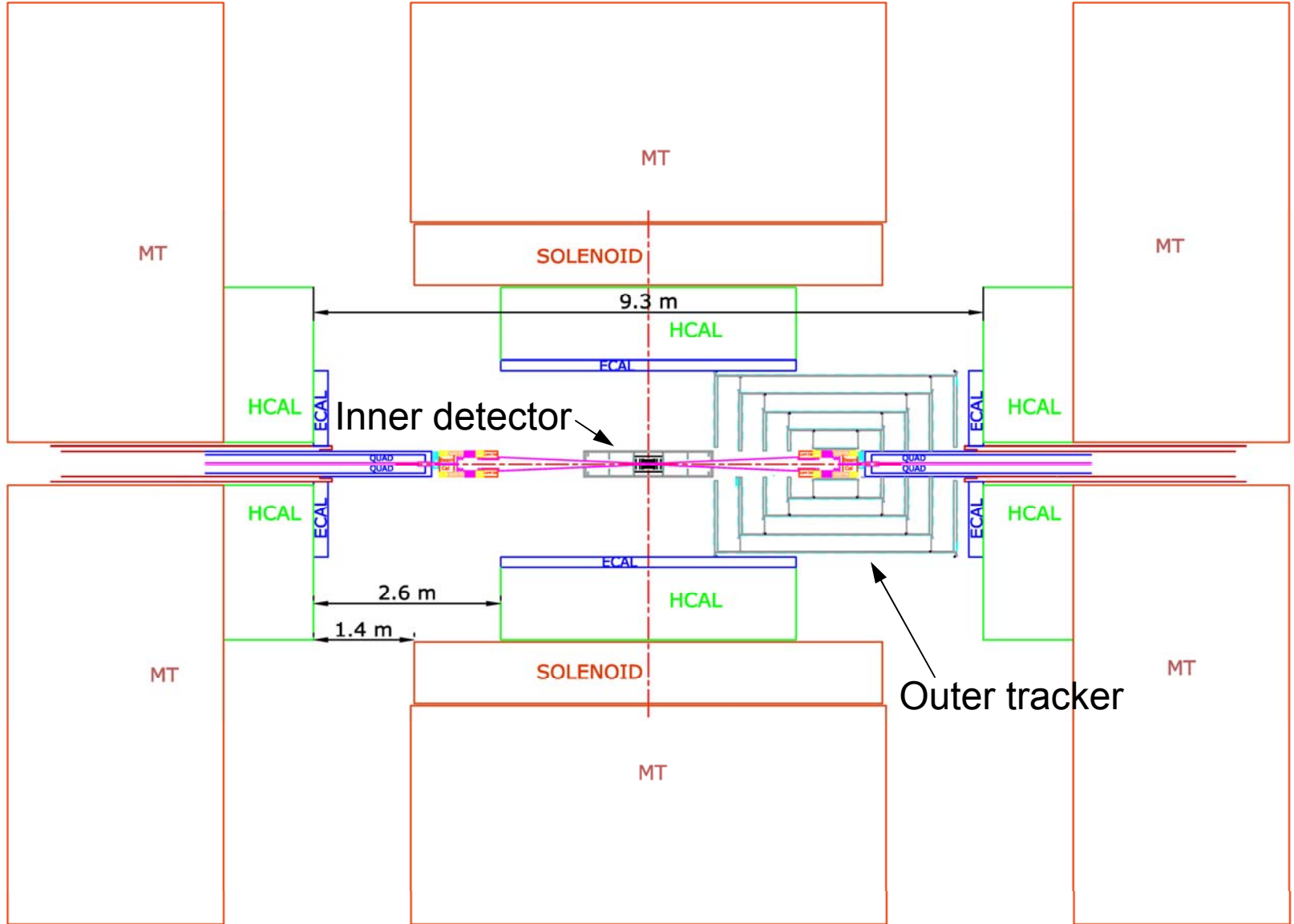
Bill Cooper  
Fermilab



# Overall Detector and Silicon Tracking

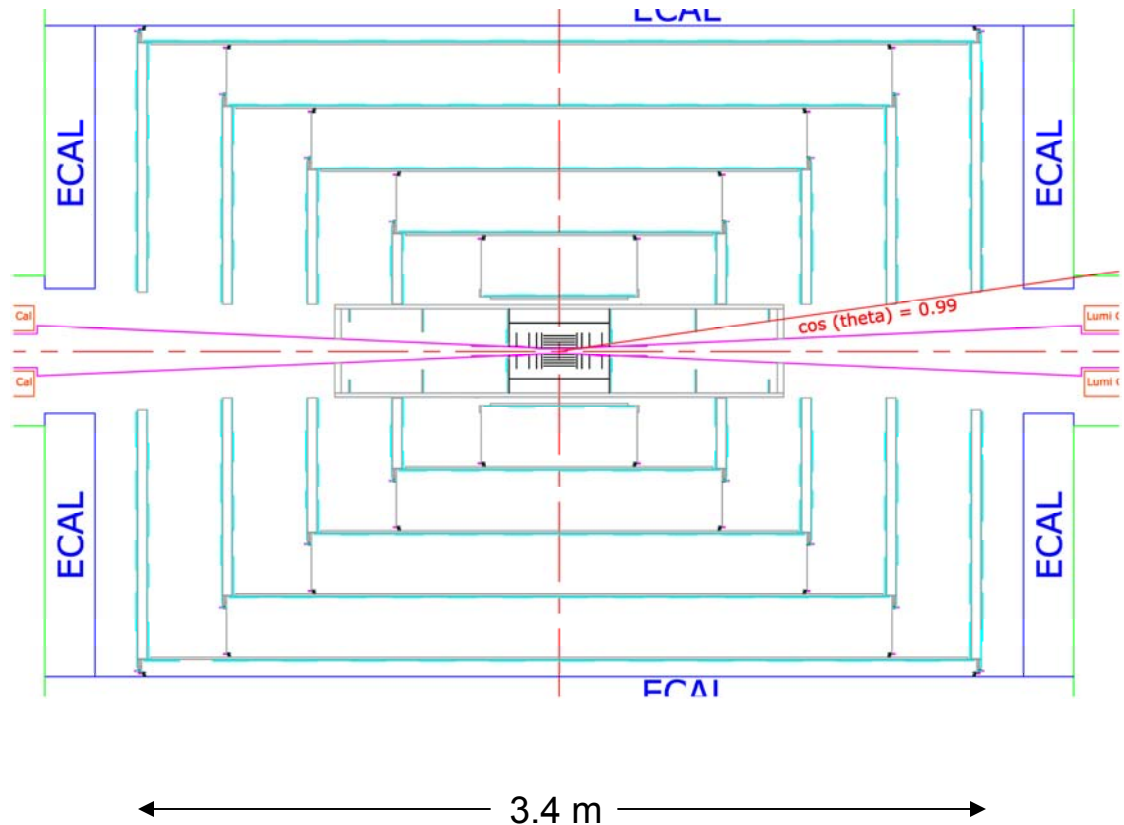
- An integrated detector design for ILC depends critically on the Particle Flow Algorithm (PFA), which is used to measure jet energies and uses all parts of the detector.
  - The detector should be hermetic.
- Tracking inboard of calorimetry is separated into an inner vertex detector and an outer silicon tracker.
  - The vertex detector finds tracks and vertices and makes initial measurements of momenta.
  - The outer tracker increases the precision with which momenta are measured and links tracks to calorimetry and the muon system.
  - A solenoid immediately outside the central calorimeter provides a 4 T to 5 T magnetic field for momentum measurements.
- During servicing of silicon tracking, the endcaps are opened, the inner vertex detector and beam pipe remain fixed, and the outer silicon tracker rolls longitudinally.

# Detector Open with Full Access to Inner Detector



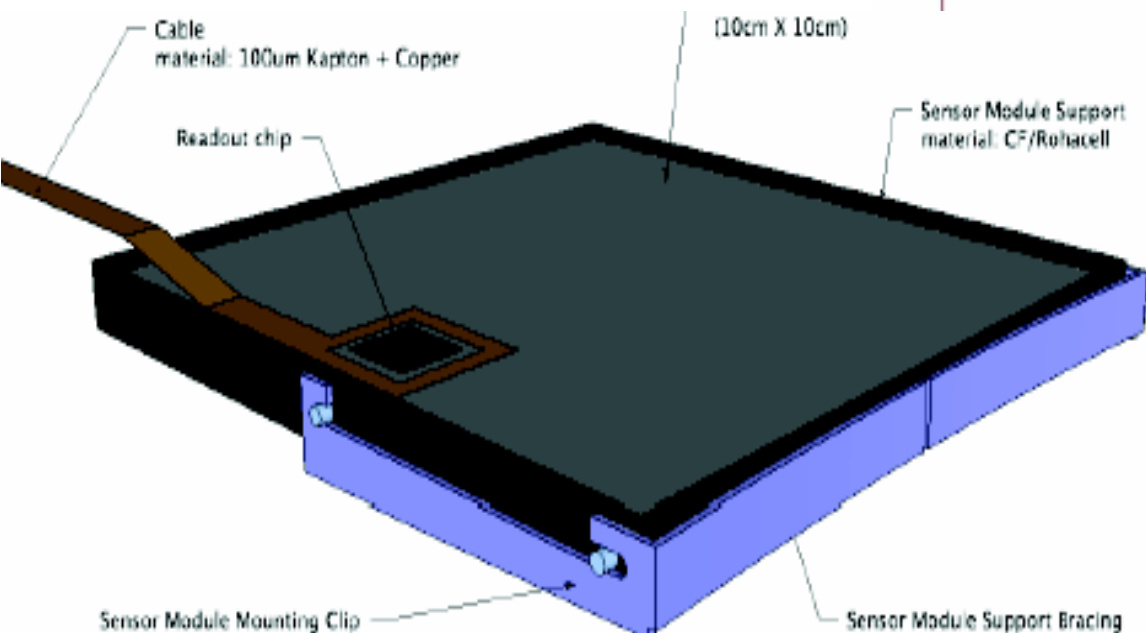
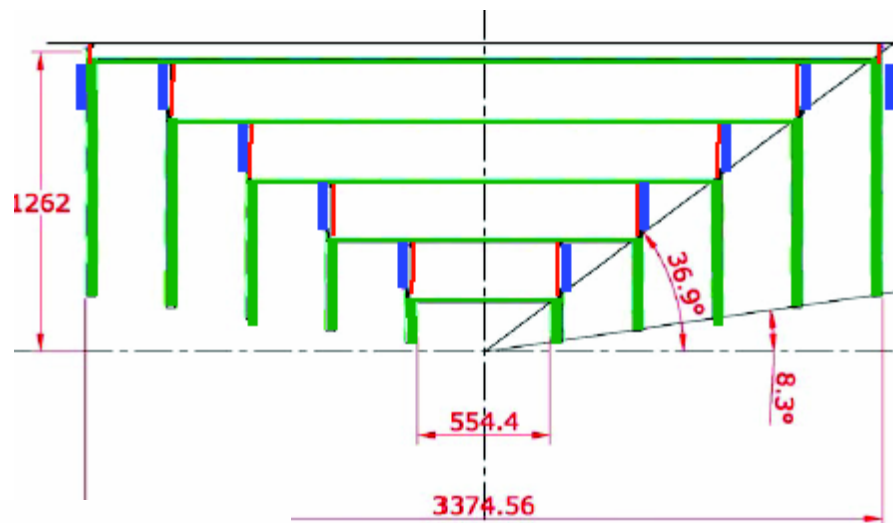
# Silicon Tracking Layout

- Outer tracker
  - 5 barrel layers
  - 5 disks per end
  - OR = 1.25 m
  - IR = 0.2 m
    - May need to adjust inner radius to accommodate beam-line elements
  - Supported from ECAL
- Inner detector
  - VXD
    - 5 barrel layers (may increase to 6)
    - 4 disks per end
  - Additional “forward” disks
  - Supported from conical portions of beam pipe



# Outer Tracker as Modeled in SiD<sub>00</sub>

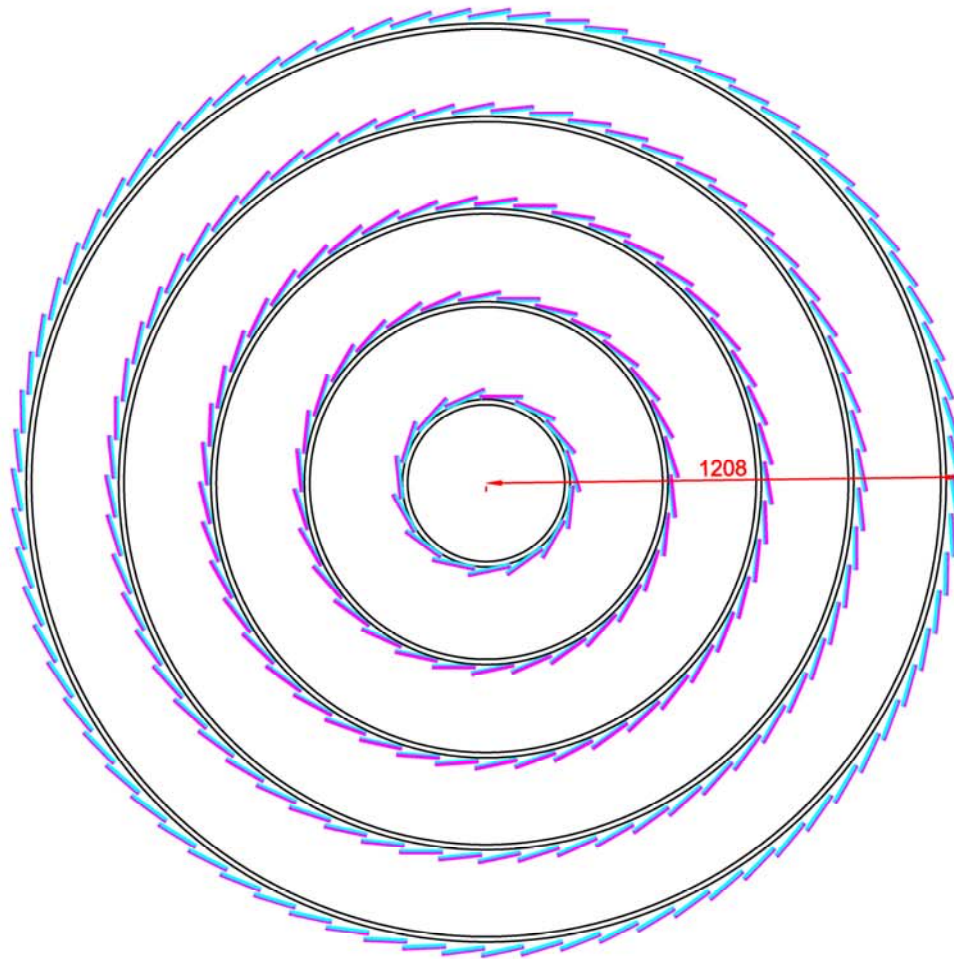
- Closed CF/Rohacell cylinders
- Nested support via annular rings
- Power/readout motherboard mounted on support rings



- Cylinders tiled with 10x10cm sensors with readout chip
- Single sided ( $\phi$ ) in barrel
- R,  $\phi$  in disks
- Modules mainly silicon with minimal support (0.8%  $X_0$ )
- Overlap in  $\phi$  and  $z$

T. K. Nelson, SLAC

# Outer Tracker with a Single Type of Module



## Sensors:

Cut dim's: 104.44 W x 84 L

Active dim's: 102.4 W x 81.96 L

## Boxes:

Outer dim's: 107.44 W x 87 L x 4 H

## Support cylinders:

OR: 213.5, 462.5, 700, 935, 1170

Number of phi: 15, 30, 45, 60, 75

Central tilt angle: 10 degrees

Sensor phi overlap (mm):

Barrel 1: 5.3

Barrel 2: 0.57

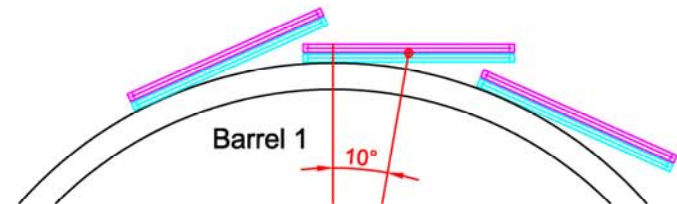
Barrel 3: 0.40

Barrel 4: 0.55

Barrel 5: 0.63

Cyan and magenta sensors and boxes are assumed to be at different Z's and to overlap in Z.

Within a given barrel, cyan sensors overlap in phi as do magenta sensors.





# Beam Pipe

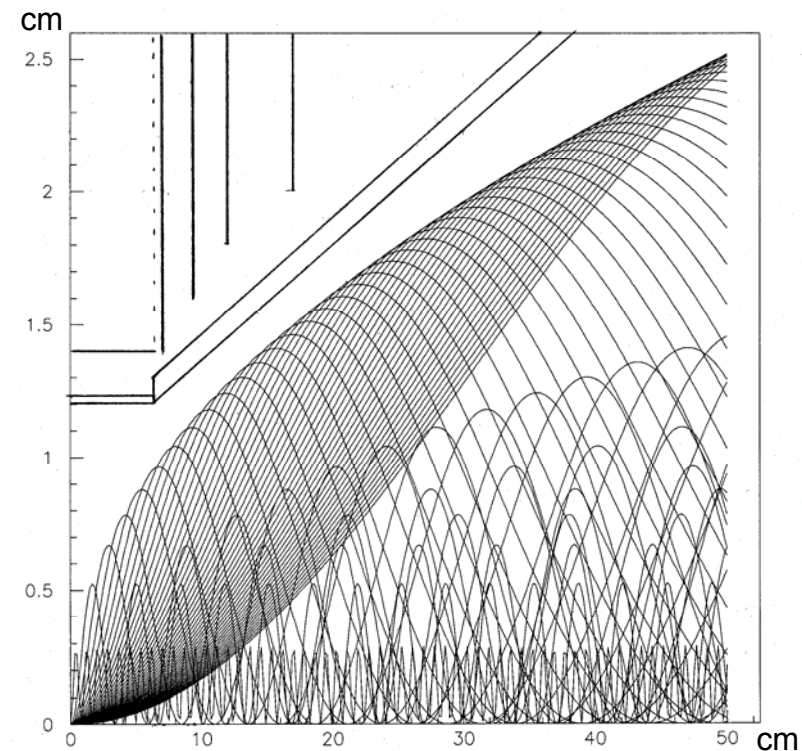
- An all-beryllium beam pipe was assumed for design purposes.
  - Portions of cones could be SS.
- Avoidance of pair backgrounds leads to a conical beam pipe shape beyond the central region.
- sidaug05 assumes a beam pipe inner radius of 1.2 cm within the region  $Z = \pm 6.251$  cm. Beryllium wall thickness = 0.04 cm.
  - Sonja Hillert and Chris Damerell have stressed the importance silicon at a small radius.

<http://nicadd.niu.edu/cdsagenda//askArchive.php?base=agenda&categ=a0562&id=a0562s4t2/moreinfo#262>

- Beam pipe liners are under study.
  - sidaug05 assumes a 0.0025 cm titanium shield in the central region and 0.0075 cm titanium shields in the conical regions to absorb low energy ( $<50$  keV) photons and fluorescent x-rays. Tungsten masks were assumed in the conical regions, but consequences of tungsten weight will need to be examined.

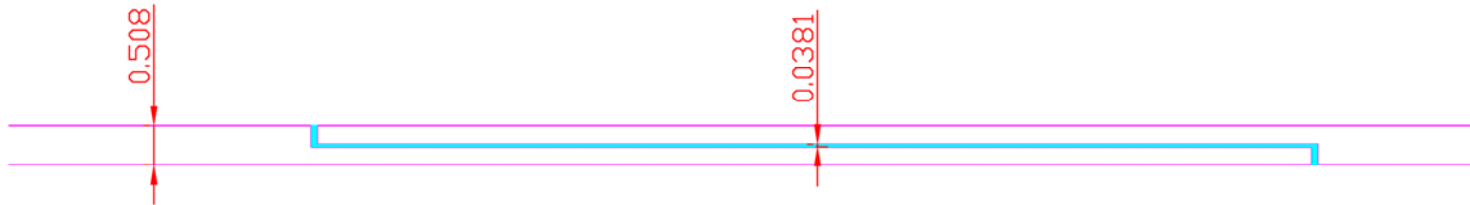
Takashi Maruyama

500 GeV Nominal 5  
Tesla + 20 mrad xing

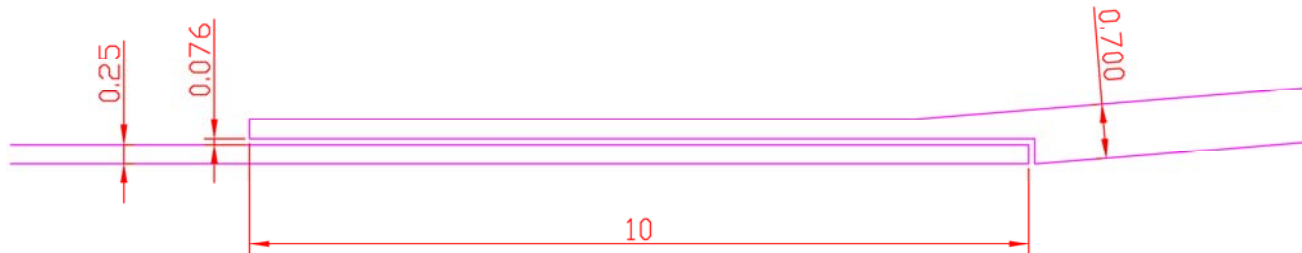


# Beam Tube Joints

- Brush-Wellman Electrofusion developed a proprietary electron beam brazing technique for beryllium to beryllium joints. The braze material is thought to be aluminum.
- Joint concept for 1.16" OD (14.7 mm OR) DZero beam pipe:



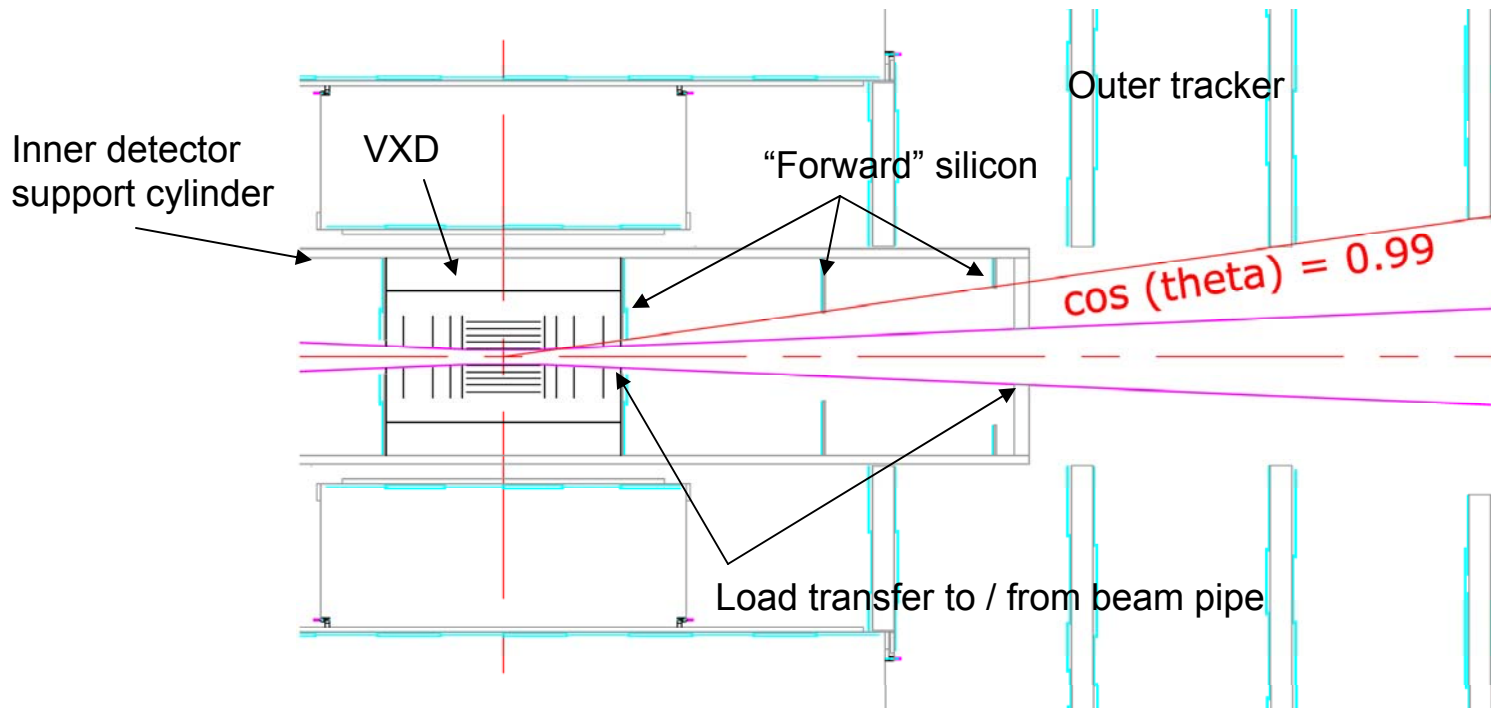
- Similar concept for ILC (note that sidaug05 assumed 0.4 mm, rather than 0.25 mm in the straight portion):





# Concept of Inner Detector (VXD) Support

- To allow installation on the beam pipe, the inner detector and its support structures are based upon half-cylinders.
- Outer support half-cylinders could be thermally insulating
  - Detector elements are supported from those half-cylinders.
- Support half-disks couple to the beam pipe at approximately  $Z = \pm 0.2$  m and  $Z = \pm 0.9$  m and aid in maintaining beam pipe straightness.
- To reduce material, many of the support structures could be strut-like.

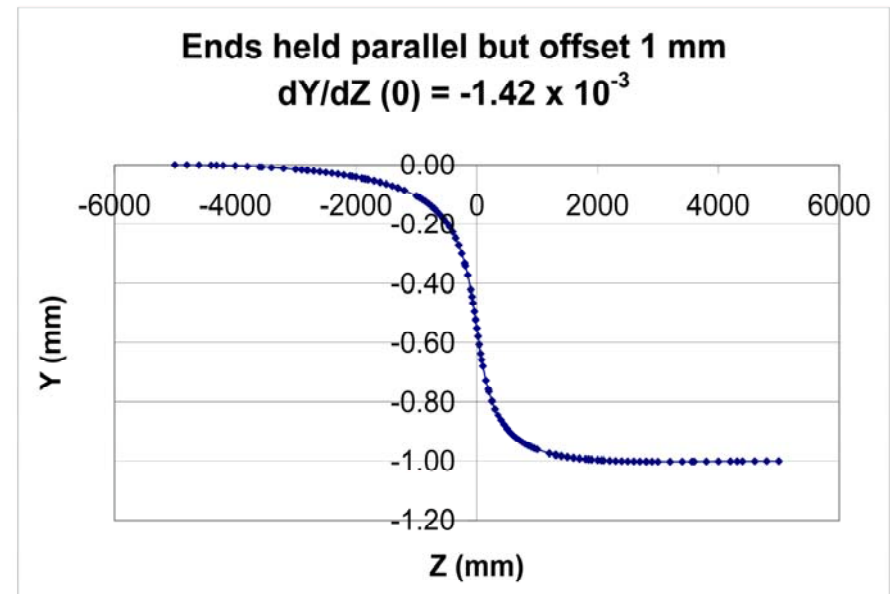
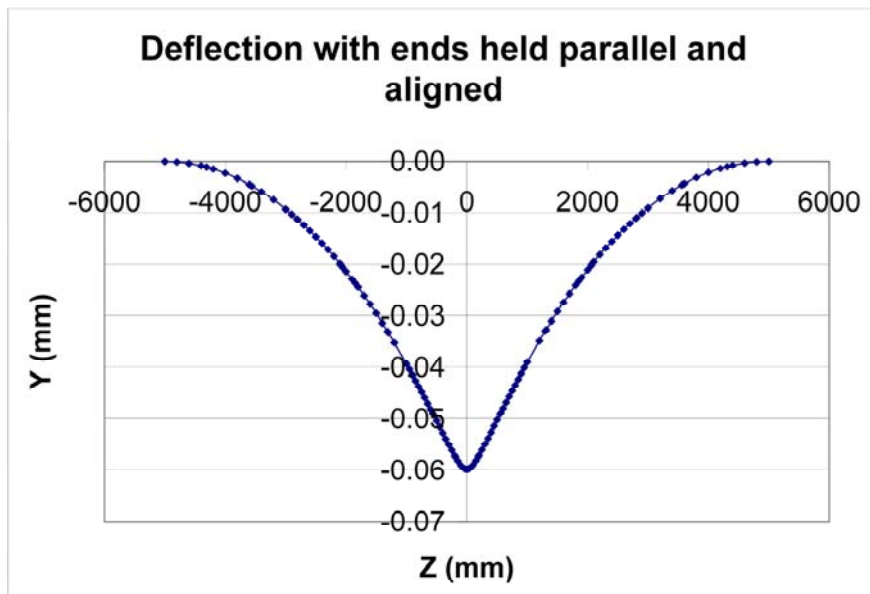


# Beam Pipe Deflections

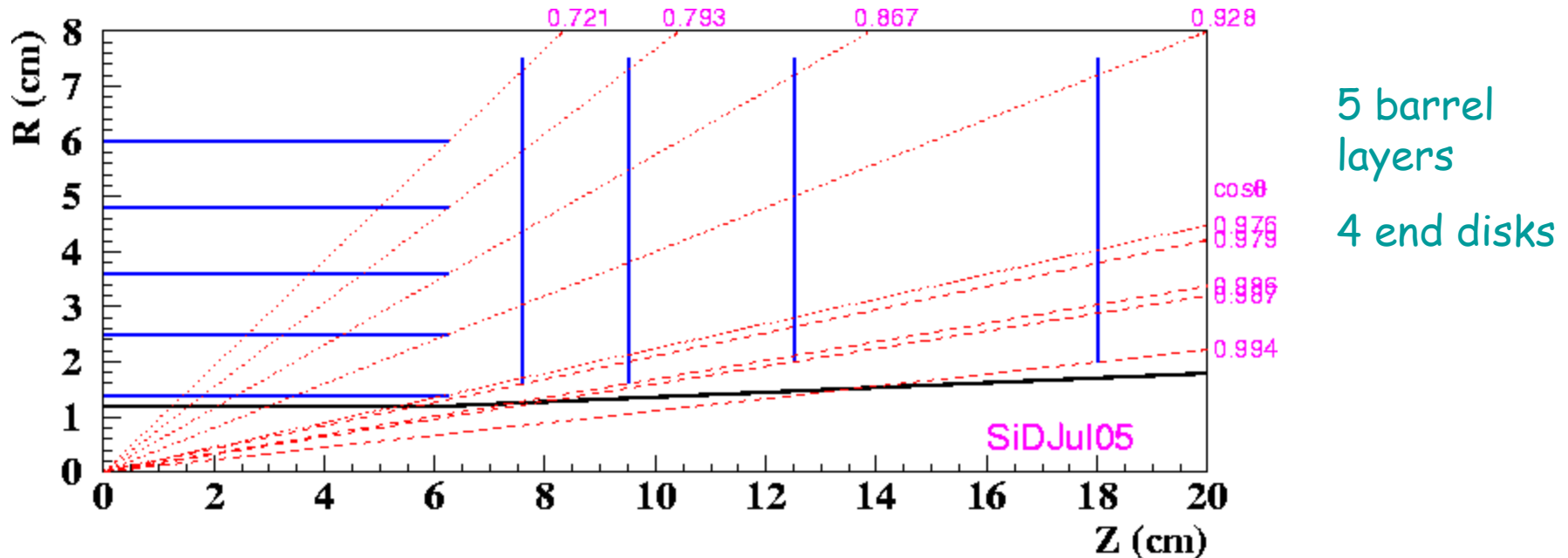
- A wall thickness of 0.25 mm was assumed in the central, straight portion.
- The radius of conical portions was assumed to increase with  $dR/dZ = 17/351$ .
  - Wall thickness in the conical portions was chosen to correspond to collapse at slightly over 2 Bar external pressure.
- An inner detector mass of 500 g was assumed to be simply supported from the beam pipe at  $Z = \pm 900$  mm.

Inner detector weight contributes  $\sim 0.008$  mm.

Maximum stress  $\sim 20$  MPa



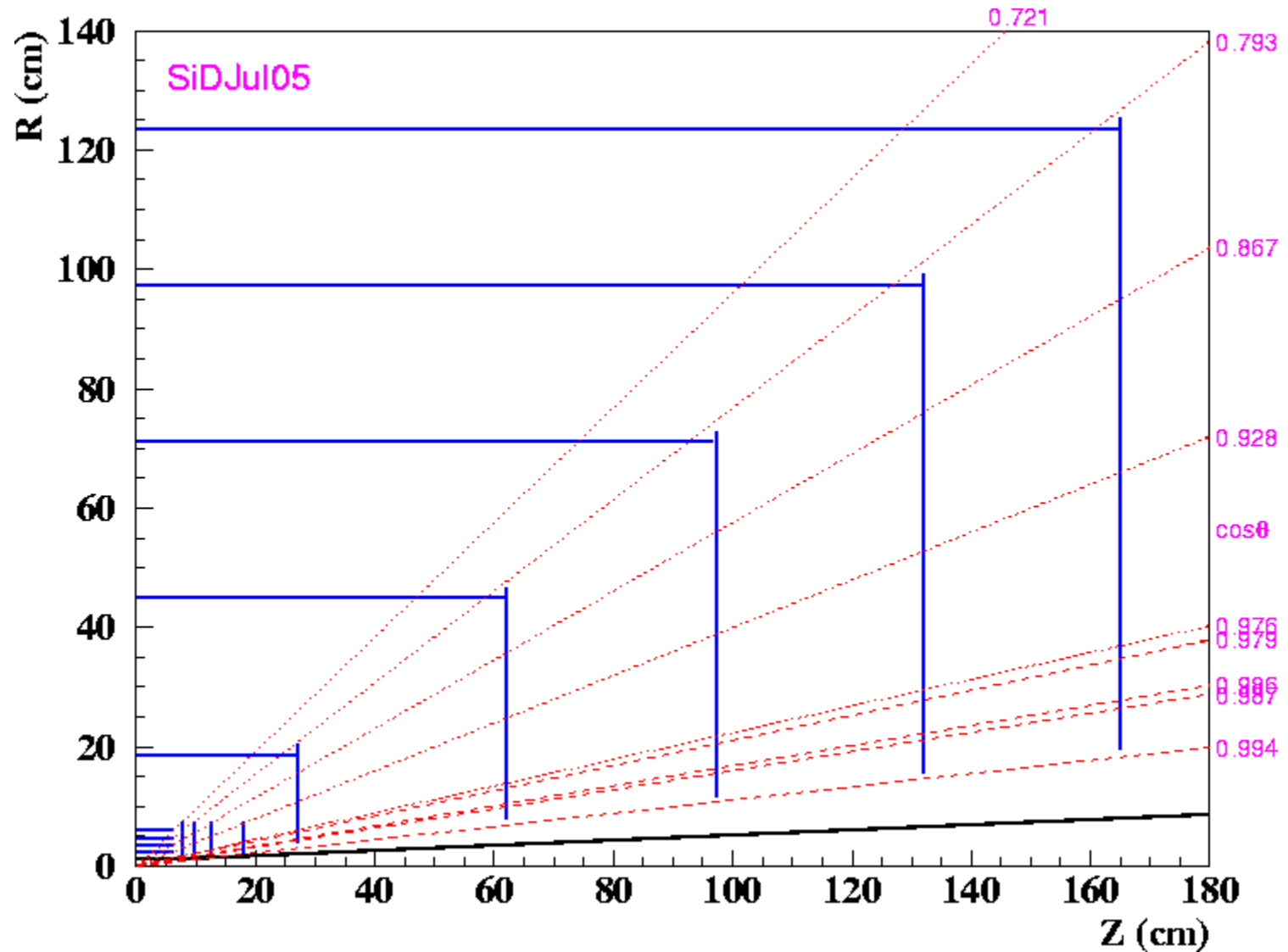
# SiD Vertex Detector Geometry (SiDAug05)



Aimed to get good 5 hit coverage at all angles for self tracking  
Many issues for  $\cos\theta > 0.98$   
Sensors are generic pixels of  $20 \times 20 \times 20 \mu\text{m}^3$

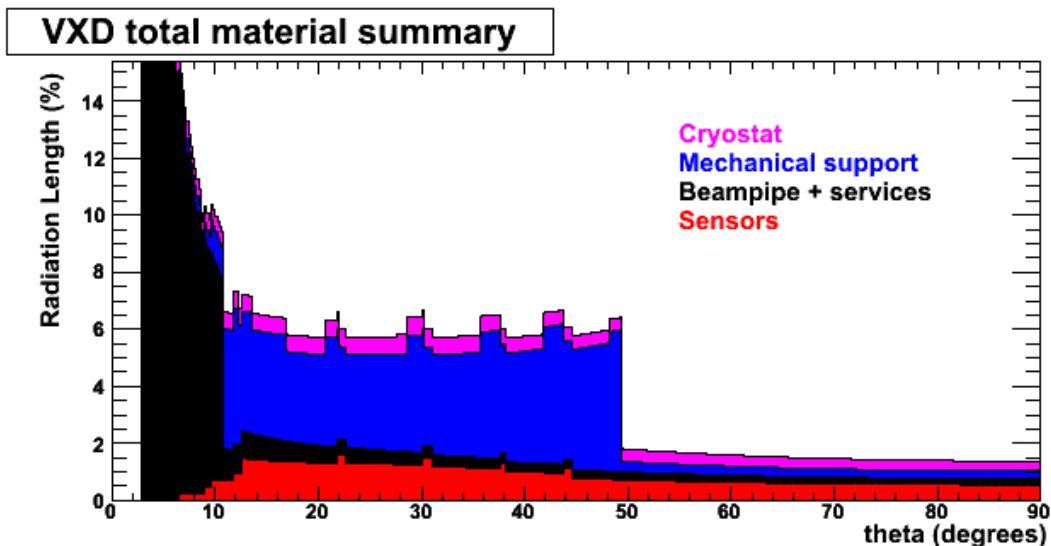
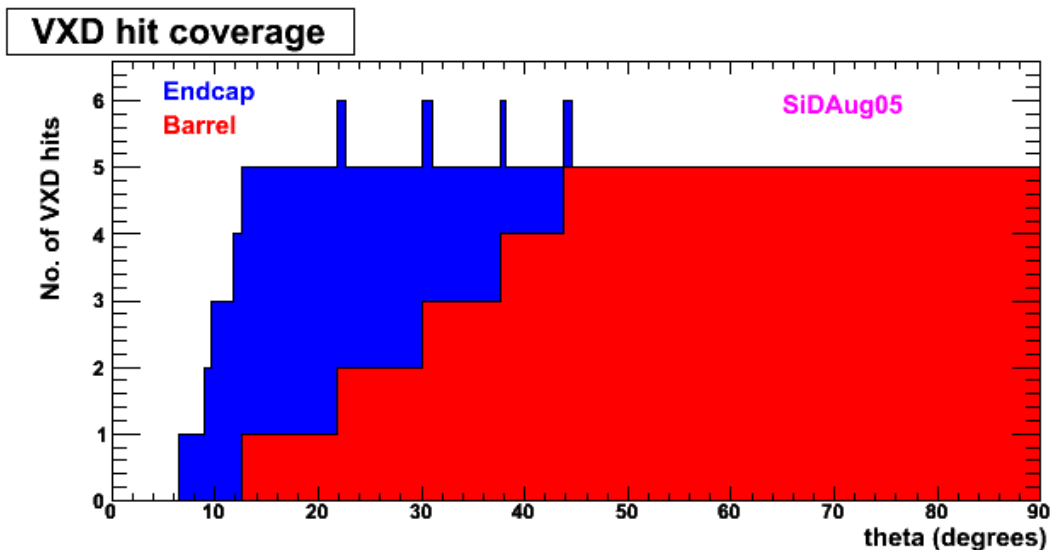
Su Dong, SLAC, Snowmass 2005

# Tracker+VXD matching



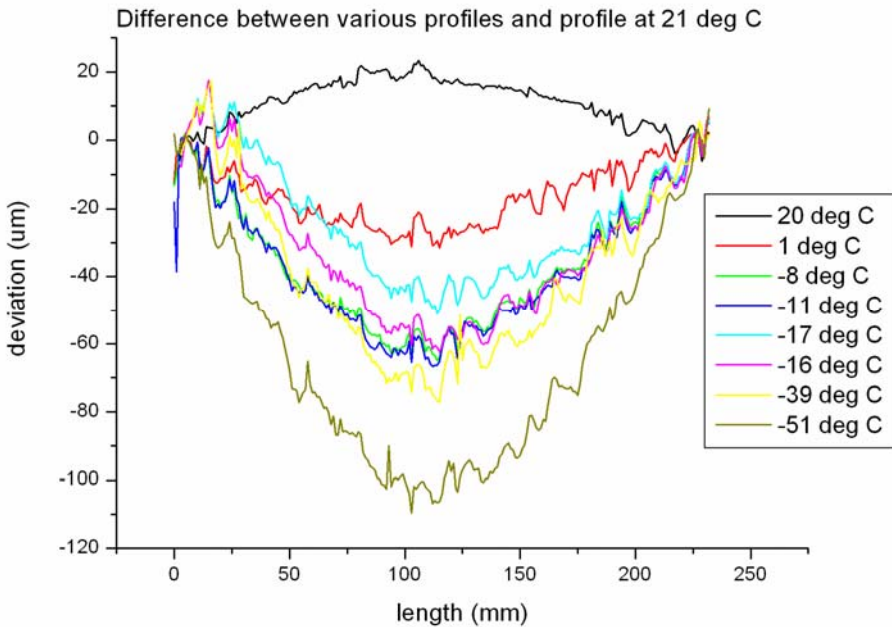
# VXD Hits and Material

- Overlaps between VXD barrels and disks have been chosen to provide good hermeticity.
- We are only beginning work on mechanical support structures and expect to investigate:
  - material selection
  - removal of unnecessary material, particularly in support disks
  - thermal and vibrational stability.
- We hope that the 6% in the forward region can be reduced to 3% - 4%.

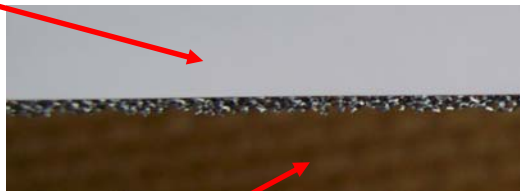


# VXD “Ladder” Tests with SiC Foam

## Thin glue layer



**20  $\mu\text{m}$  silicon**



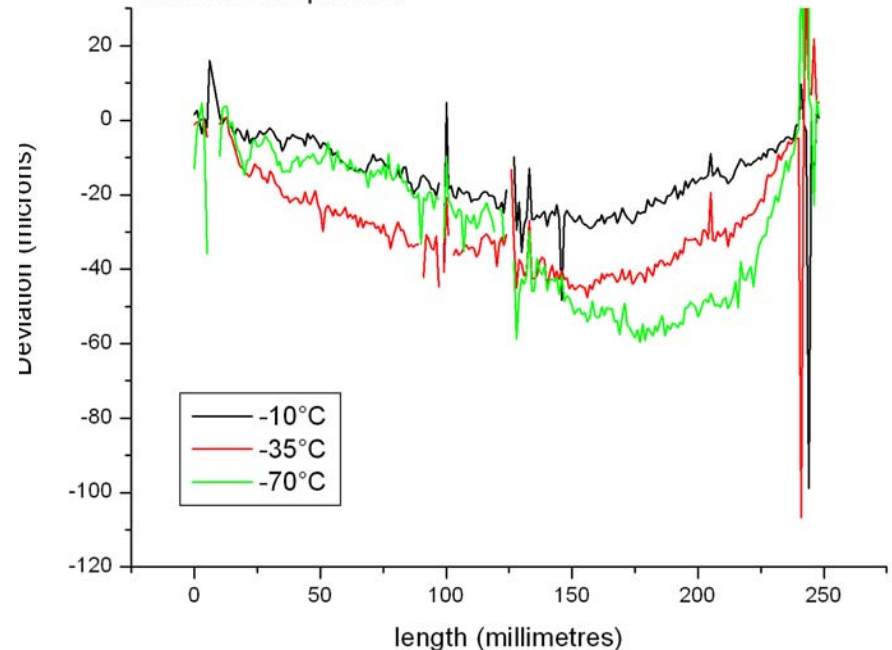
**1.5 mm silicon carbide**

- **8% Silicon Carbide**
  - Single-sided
  - 0.14% X0
  - 3-4% believed possible

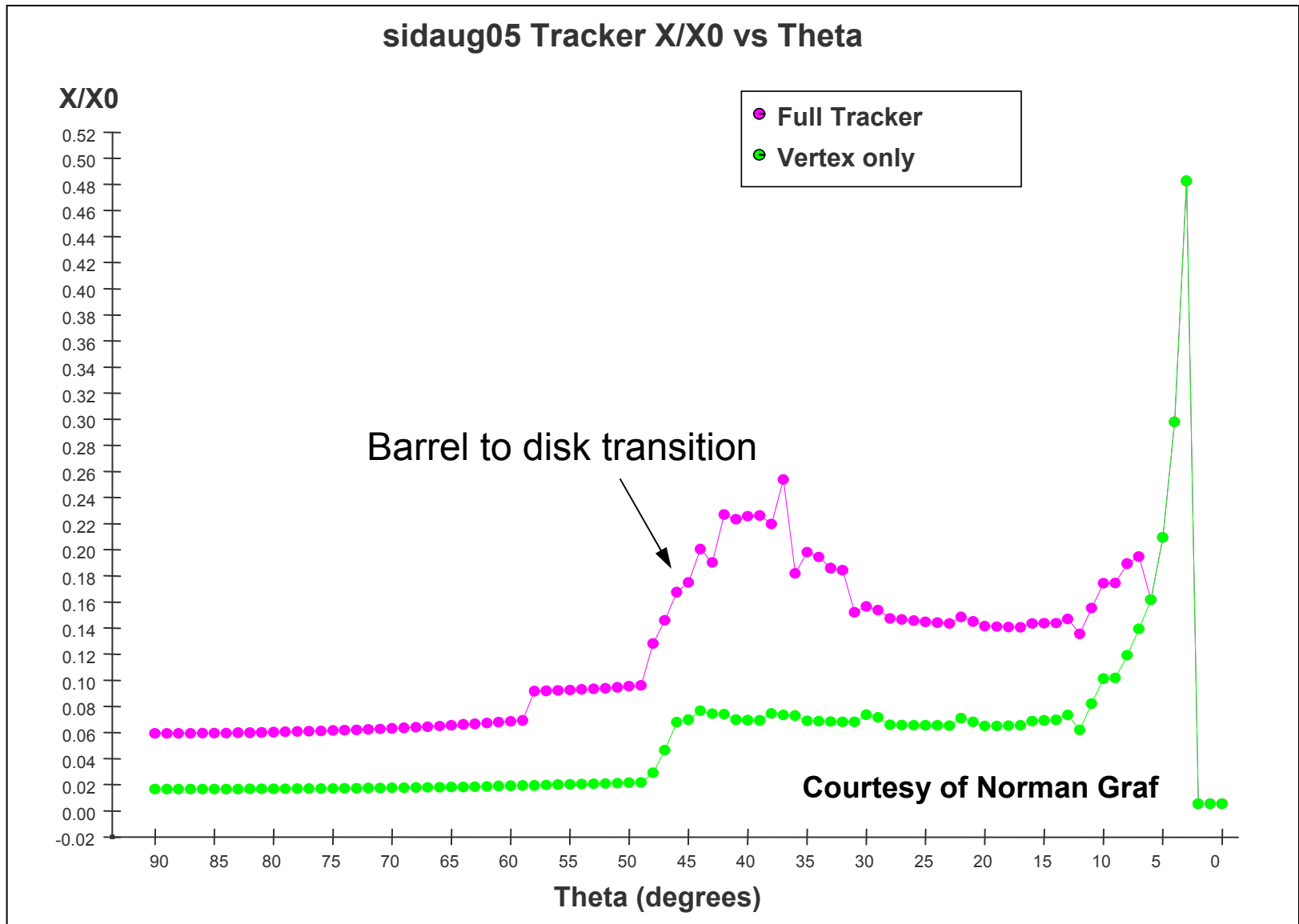
LCFI:  
J. Goldstein  
S. Worm

## Glue “pillars”

The Difference between profiles at various temperatures and room temperature



# August 2005 SiD Simulation

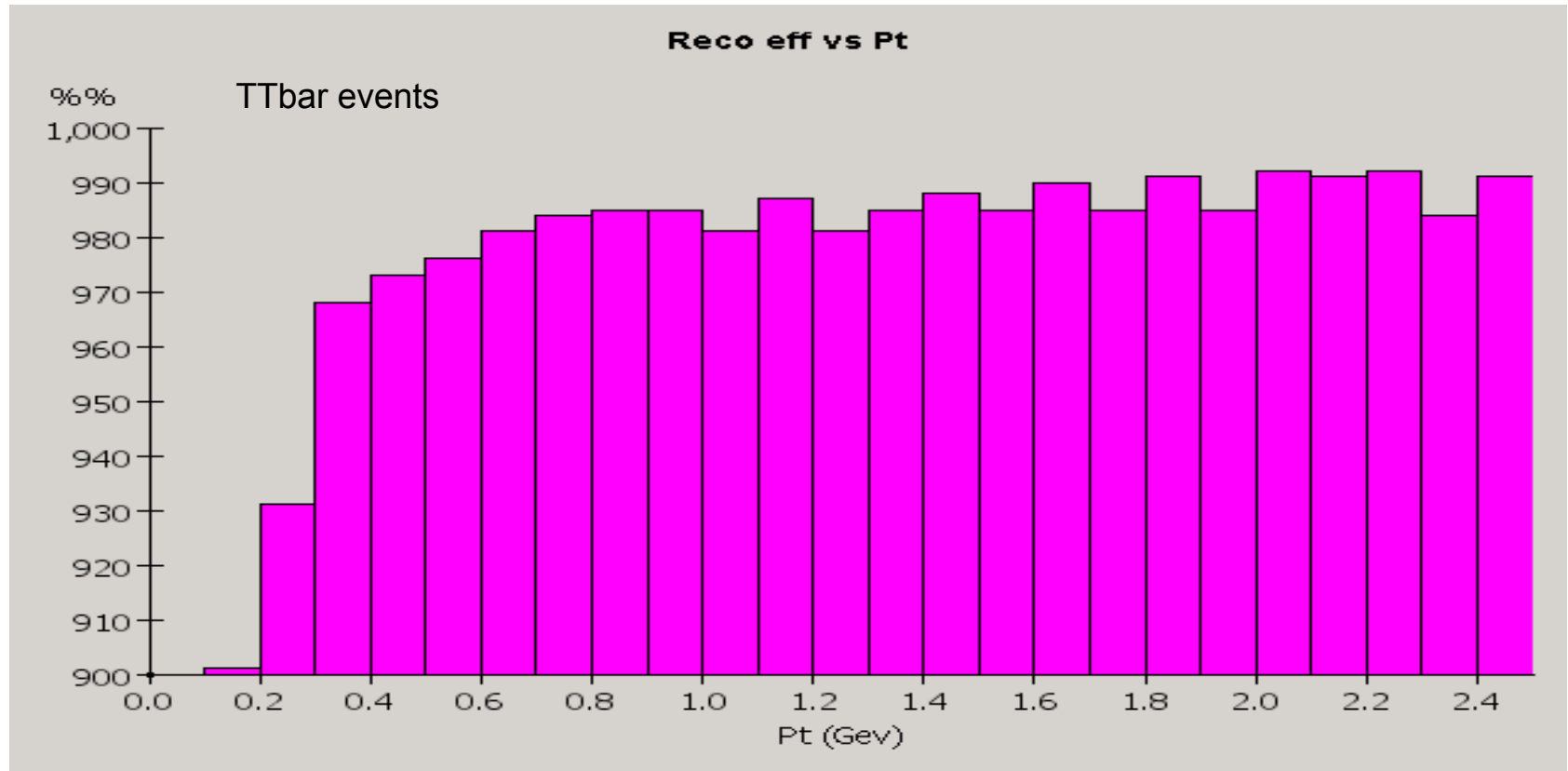




# Track Reconstruction Efficiency

- VXD-based tracking algorithms developed by N. Sinev
  - Outgrowth of earlier work by H. Videau and M. Ronan
- Start with hits in 3 VXD layers plus a very loose IP constraint, then require at least 4 VXD hits.
- Extrapolate to silicon micro-strips and add hits

<http://nicadd.niu.edu/cdsagenda/askArchive.php?base=agenda&categ=a0562&id=a0562s1t1/moreinfo#256,1,SiD>  
tracking using VXD as a primary tracking device



# Pt Resolution in the Central Region

August 2005

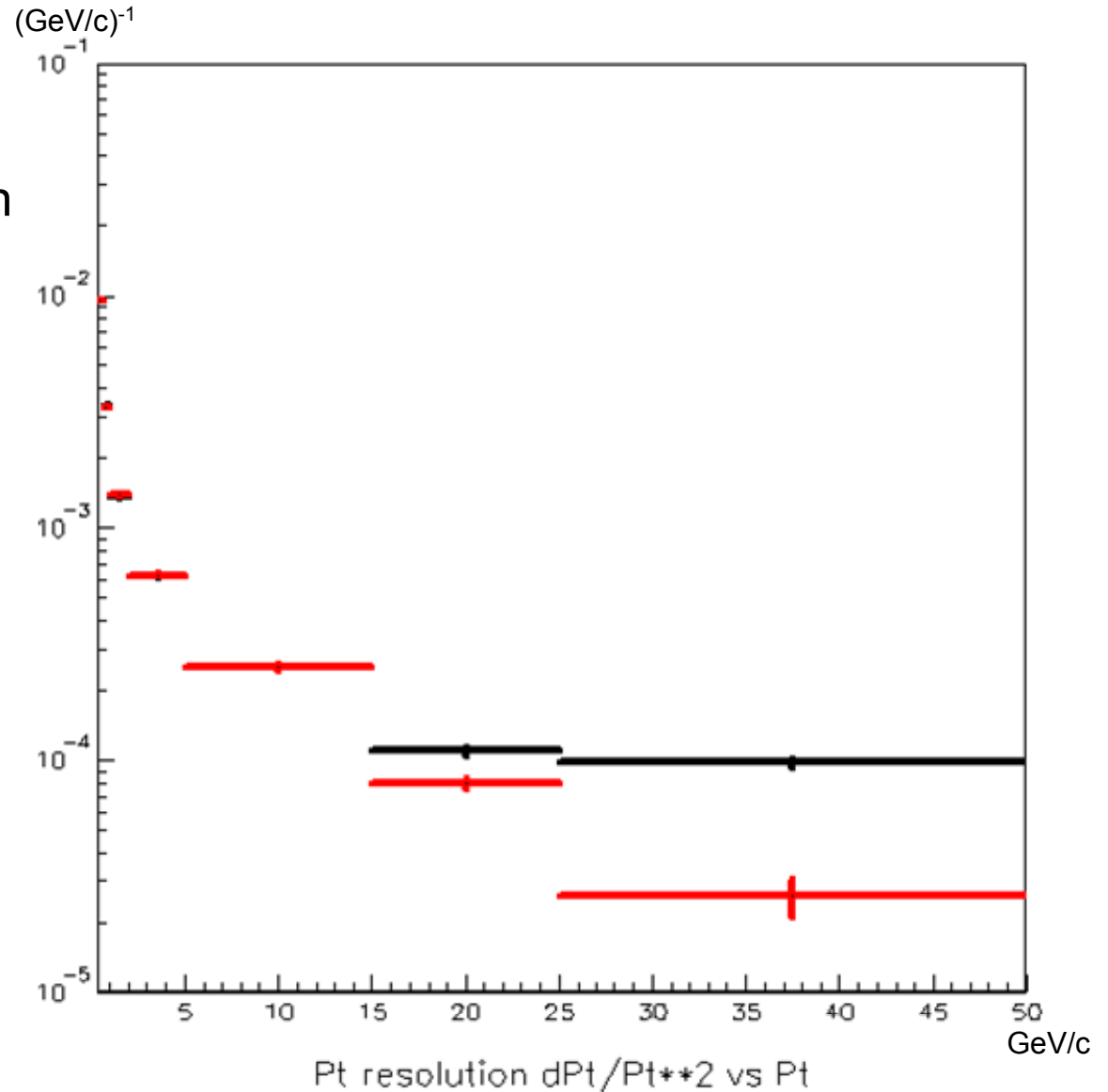
VXD-based reconstruction algorithm

Fitting remains to be implemented in the disks, so only barrel tracks are included.

Black: reconstructed tracks

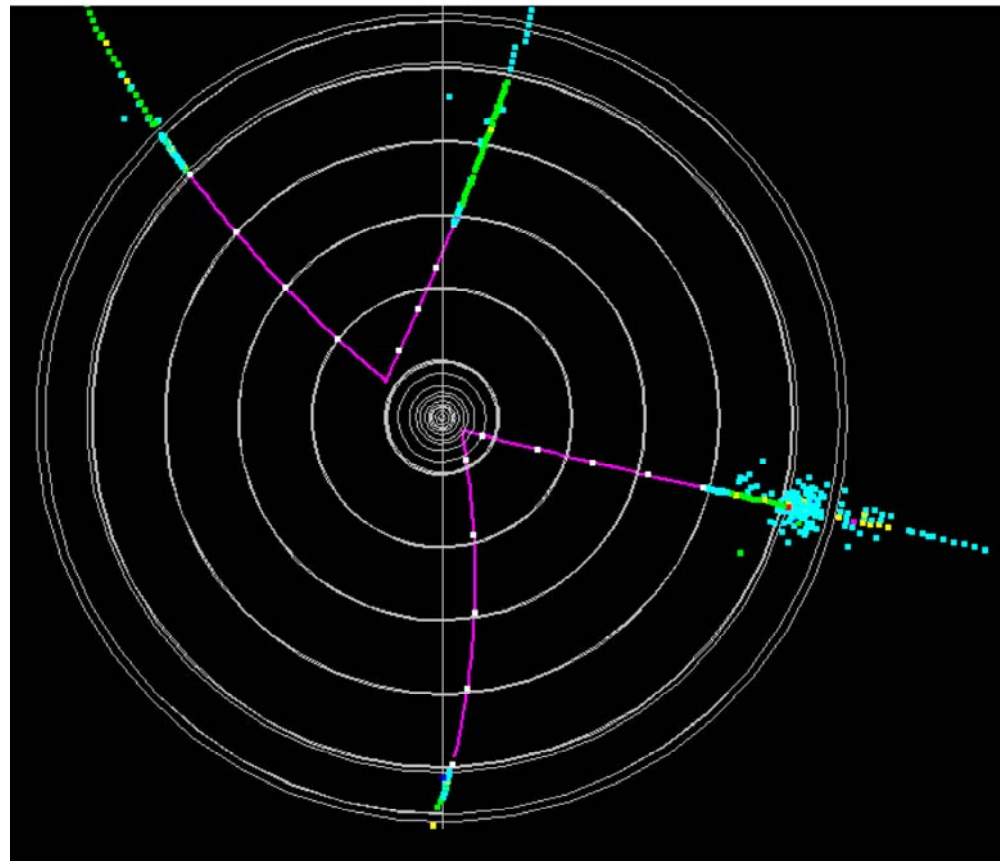
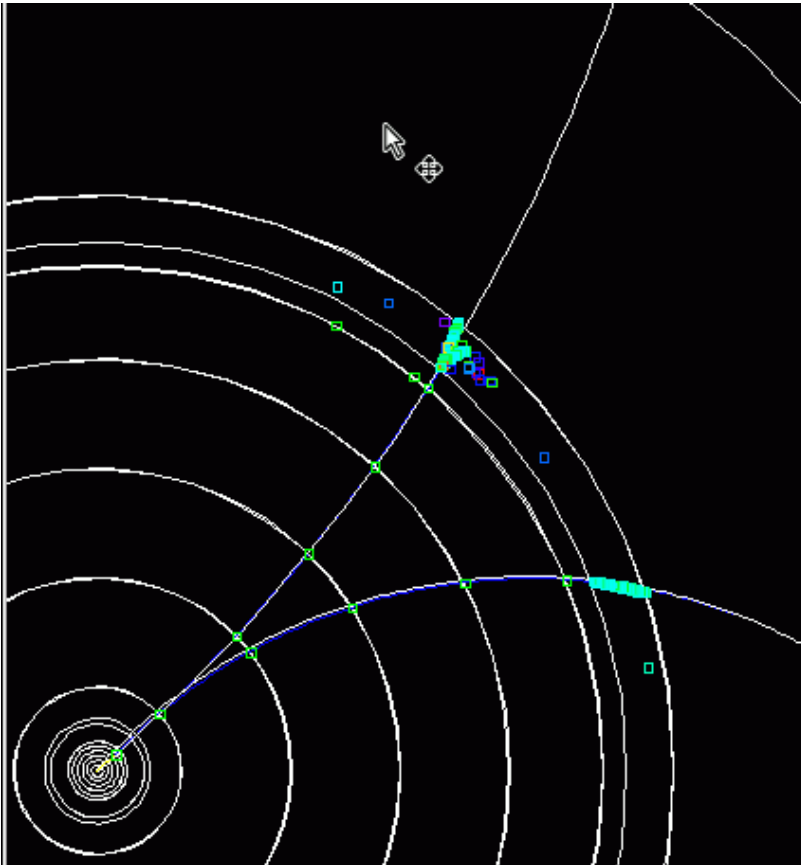
Red: after fitting which includes outer tracker hits

Nick Sinev, U. Oregon



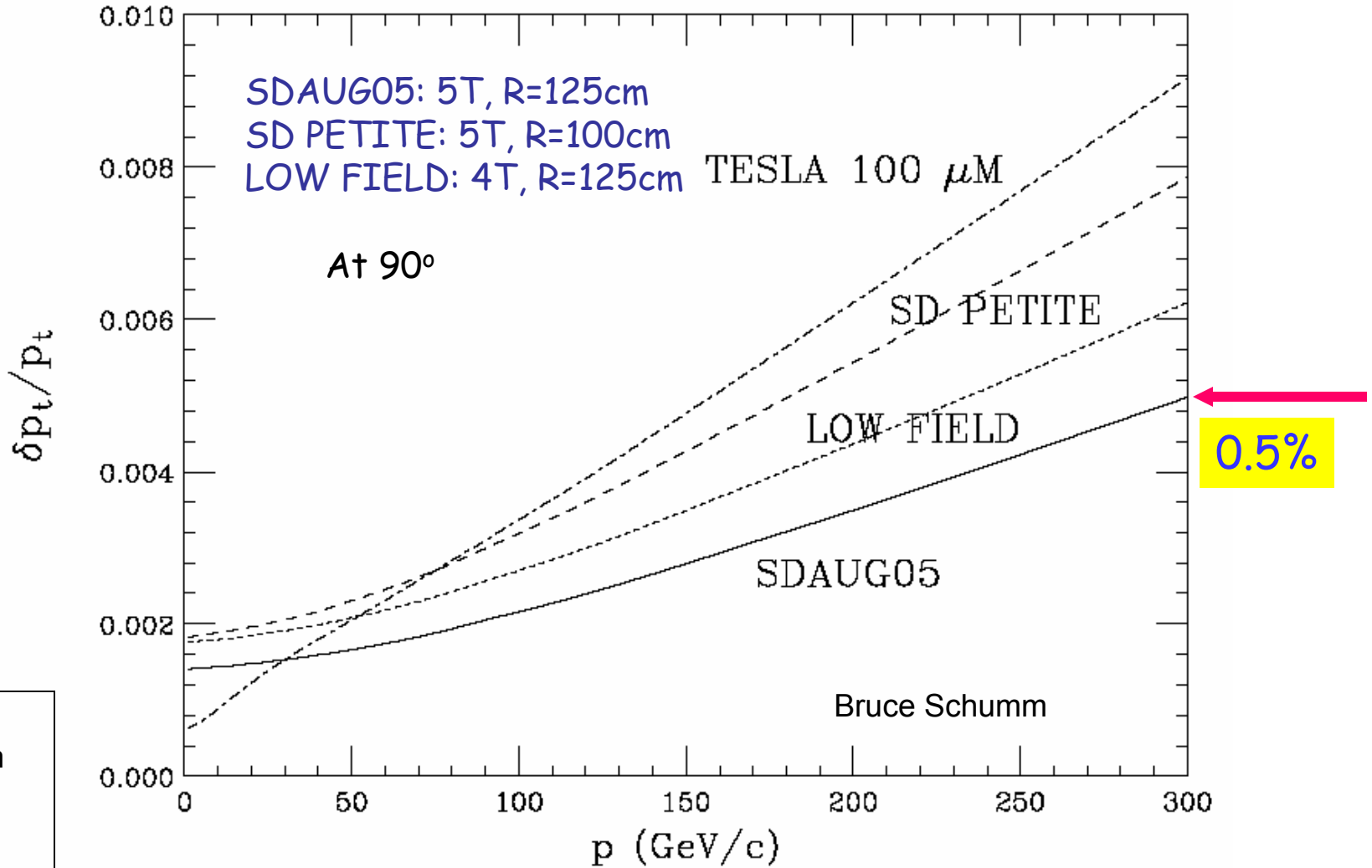
# Tracking from Outside Inward

- Dmitry Onoprienko has been developing algorithms for finding tracks starting from ECAL.
- Particularly helpful for decays outside VXD



# Tracker Momentum Resolution

WITH  $2\mu\text{M}$  BEAM CONSTRAINT



Analytic calculation by Bruce Schumm (UCSC).

# In Summary

- Realistic layouts have been developed for silicon tracking.
- The designs are hermetic.
- Designs take into account mechanical support and servicing issues.
- While we hope to make improvements, material budgets are understood.
- Tracking designs have been incorporated in simulations.
- Initial studies indicate excellent track reconstruction efficiencies and excellent precision of track momentum measurements.