

# Preparations for a Simulation Study of the Magnetic Field Requirements of the LC TPC

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# **Objectives**

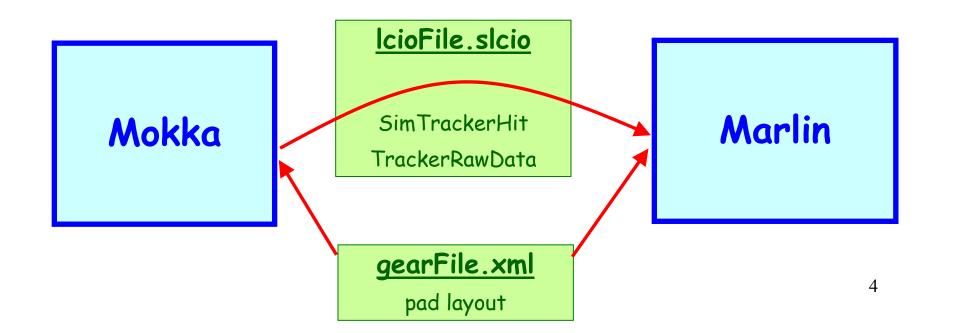
- ILC's crossing angle will cause magnetic field distortions
- Corrections for the inhomogeneous magnetic field will be needed for TPC's required momentum resolution  $(d(1/p) \sim 10^{-4} GeV^{-1})$
- Two ways to correct for magnetic field distortions;
  - a B-field map giving a first approximation
  - external data points (e.g. from the vertex detector)
- Back of the envelope estimations on the possible accuracy of these corrections have been done (see Snowmass 2005 talks by Ron Settles and Don Peterson)
- A simulation study is needed to determine the
  - influence of an inhomogeneous magnetic field on TPC's momentum resolution and the
  - possibility for magnetic field corrections to the reconstruction

# **Strategy**

- To study drift electrons distortion due to inhomogeneous magnetic field we edit Mokka's TPC to include
  - Drift electrons
  - GEM foils
  - Gas gaps
  - Endplate pads
- To study the effect on reconstruction add Marlin processes to
  - Read in and convert raw data
  - Make simple seed track fit (for now assume pattern recognition done)
  - Do the track fit (for now only single tracks)

## Mokka and Marlin

- We use a gear.xml file as input to both Mokka and Marlin since the pad layout is needed for both simulation and reconstruction
- The .slcio file from Mokka has both hits from the G4 energy deposition in the TPC (SimTrackerHit) and raw data from the pads (TrackerRawData)



# **TPCUVic Mokka Simulation**

#### **TPCUVic**

(G4 Detector Simulation)

#### **TPCSDUVic**

(G4 Sensitive Detector)

## ElectronCloudTransport

(UVic Code within Mokka)

#### ReadoutPadSD01

(G4 Sensitive Detector)

## StarFEEAmp

(Electronic Example Within Mokka)

#### FlashADC

(ADC Example Within Mokka)

#### SimTrackerHit

(LCIO Collections)

#### ElectronCloud

(UVic Code within Mokka)

## **G4Steps**

(G4 Representation of e<sup>-</sup>)

## ChargeSignal

(UVic Code within Mokka)

#### TrackerData

(LCIO Collections)

#### TrackerRawData

(LCIO Collections)

## **TPC Detector**

#### **TPCUVic**

- Geometry and Materials
- Edited the Tpc04 driver (not much, just some lines)
- User Limits
  - Maximum step size for ionizing particles (no layers needed)
    - Sometimes new step due to step size and sometimes new step due to EM process. Checked that there is no double counting
  - Maximum amount of time a particle can travel before being stopped
  - Maximum amount of energy it can deposit
- Sensitive Detector (TPCSDUVic)
- Copied and edited the MySQL database table "tpc06" to "tpcuvic" to our local MySQL database

# **TPC "Sensitive Detector"**

**TPCSDUVic** 

SimTrackerHit

ElectronCloud

- ProcessHits() gets the G4Steps
  - It stores the "hits" in a G4HitCollection, later saved as SimTrackerHits in a .slcio file
  - For each G4Step an ElectronCloud is produced
    - Number of electrons = The deposited energy / 26 eV
  - Transport the clouds with ElectronCloudTransport
    - For now; only primary particles are taken into account
    - Change later to deal with multiple tracks
      - Then reconstruction and track storage have to be changed as well "Trivial changes"

# A Cloud of Electrons (to save cpu)

#### ElectronCloud

- Member variables are
  - number of electrons
  - x, y, and z coordinates
  - standard deviation in xy
  - standard deviation in z
  - time coordinate

Transporting the drift electrons

ElectronCloudTransport

ElectronCloud

G4Steps

- transportToEnd() gets a cloud
  - transportThroughGap(driftGap, aCloud)
  - transportThroughGEM(gem1, aCloud)
  - transportThroughGap(transferGap, someClouds)
  - transportThroughGEM(gem2, someClouds)
  - transportThroughGap(inductionGap, someClouds)
  - hitReadoutPads(someClouds)
    - Extracts electrons and gives G4Steps (represent e-) to ReadoutPadSD01

# Transporting the drift electrons (cont)

## **Drift Volume**

- *implemented* First approach; homogenous fields in drift volume
  - The clouds are transported with one step to the first GEM
  - Parameterized diffusion of the e<sup>-</sup>
- future work Later approach; inhomogeneous magnetic field
  - The clouds will be transported with several steps to the GEM
  - In each step a field map (FieldX00Map) will be used to get the Lorentz angle

## **End Plate**

- Parameters for the GEMs (Gain, Collection and Extraction efficiency) is hard coded (in Gear file in future (?))
- Will this narrow area be effected by inhomogeneous magnetic field?
- "TPCEndPlate" is a hard coded name; don't change!

Assign electrons to pads

G4Steps

ReadoutPadSD01

ChargeSignal

- The function ProcessHit()
  - uses Gear functions to get the PadLayout and checks if electrons hit a pad
  - saves it to charge\_signals which is a std::map of PadIndex (Gear) to ChargeSignals
    - i.e. only pads that are hit are saved in the map

## **Electron Saved on a Pad**

# ChargeSignal

- Member variables are
  - number of electrons
  - mean time the electrons hit the pad  $(t_m)$
  - standard deviation from the mean time
  - induction time (t<sub>i</sub>)
    - the time the pad induce signal before the electron hit, normally the time the electron spent in the induction gap

# Front End Electronics Amplifier

## StarFEEAmp

ChargeSignal

## TrackerData

- As an example of front-end electronics we have implemented Star's amplifier (from Karlen's JTPC)
- Shaping according to equation, A(t), that gives #e- per time bin
  - Width of time bins from "readoutFrequency" in the Gear file
- Then convert it to mV per time bin
  - VoltagePerTimeBin = gain \* 10mV/fC \* A(t) \* CoulumbPerElectron
- Reads in parameters from Gear file
  - Gain
    - 3.3
  - Voltage threshold (indirect)
    - 10 mV ⇒ zero suppression, saves storage space
  - Rise and fall time
    - 30 ns and 2000 ns
  - mV per fC
    - 10

# Star's FEE Amplifier

For the time shaping equation these time constants  $\tau_1 = 729.878$  ns,  $\tau_2 = 89.0123$  ns,  $\tau_3 = 88.9504$  ns as well as the current rise time ( $\tau_4$ ) and fall time ( $\tau_5$ ) are used. The "star constants" are

$$s_{0} = 58 \cdot 4$$

$$s_{1} = k_{1} \frac{\tau_{1}^{3} \tau_{3}}{(\tau_{1} - \tau_{2})(\tau_{1} - \tau_{3})}$$

$$s_{2} = \frac{\tau_{1} \tau_{2}^{2} \tau_{3}}{(\tau_{2} - \tau_{1})(\tau_{2} - \tau_{3})}$$

$$s_{3} = \frac{\tau_{1} \tau_{3}^{3}}{(\tau_{3} - \tau_{1})(\tau_{3} - \tau_{2})}$$

where  $k_1 = 0.32851$ .

# Star's FEE Amplifier (cont)

## The amplitude we then get from

$$A = \begin{cases} 0, & t < 0 \\ \sum_{i=1}^{3} \frac{s_{i}}{\tau_{4}s_{0}} \left( e^{-t/\tau_{i}} + \frac{t}{\tau_{i}} - 1 \right), & t \in [0, \tau_{4}] \\ \sum_{i=1}^{3} \frac{s_{i}}{s_{0}} \left( \frac{\tau_{i} + \tau_{4} + \tau_{5} - t}{\tau_{i}\tau_{5}} + \frac{1}{\tau_{4}} e^{-t/\tau_{i}} - \left( \frac{1}{\tau_{4}} + \frac{1}{\tau_{5}} \right) e^{(\tau_{4} - t)/\tau_{i}} \right), & t \in [\tau_{4}, \tau_{4} + \tau_{5}] \\ \sum_{i=1}^{3} \frac{s_{i}}{s_{0}} e^{-t/\tau_{i}} \left( \frac{1}{\tau_{4}} + \frac{1}{\tau_{5}} e^{(\tau_{4} + \tau_{5})/\tau_{i}} - \left( \frac{1}{\tau_{4}} + \frac{1}{\tau_{5}} \right) e^{\tau_{4}/\tau_{i}} \right), & t > \tau_{4} + \tau_{5} \end{cases}$$

Where  $0 = \text{meantime} - \text{induction time} = t_0 = t_m - t_i$ This is a semi-emperical fitted equation to frontend electronics used in the Star Experiment Implemented into Mokka just as an example

# **Analog to Digital Converter**

#### FlashADC

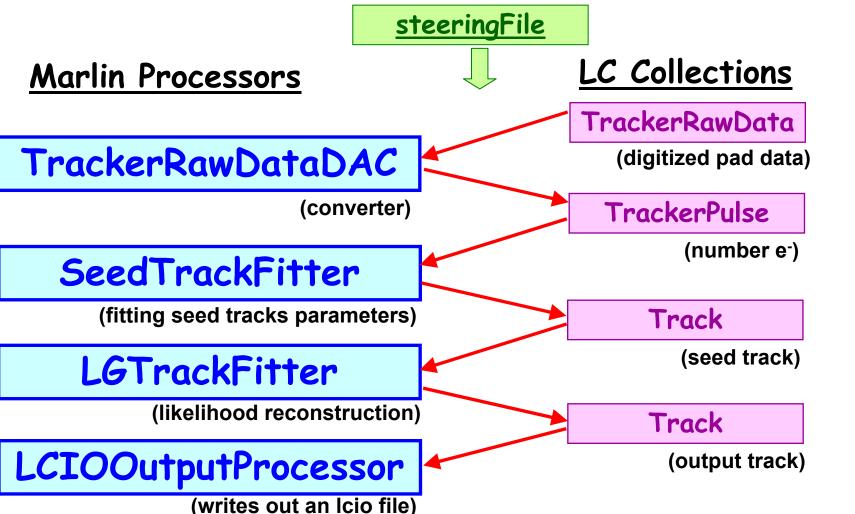
TrackerData

TrackerRawData

- Calculates the pedestal (hard coded for now ... Gear?)
- Converts time bins into channels
  - Floating numbers → integers
  - Add pedestal → unsigned integers
    - · if pedestal not big enough some values are truncated
- Reads in parameters from Gear file
  - **gain** 1
  - bits per channel10
  - mV per channel 0.1

## **TPC Marlin Reconstruction**

 A steering file will control the LC Collections flow between the Marlin Processors



# Digital to "Analog" (#e-) Converter



- The processEvent() function gets an LCEvent
  - Opens TrackerRawData collection from the LCEvent
  - Checks that all parameters are in the LCEvent
  - Converts all ADC values in the TrackerRawData to
    - TrackerData = Number electrons per time bin
    - TrackerPulseData = TrackerData and total number of electrons in the pad

# Fitting the Seed Track



- The SeedTrackFitter gives a rough estimate of a Track to LGTrackFitter
- Assumes pattern recognition already done, i.e. all hit pads from one track
  - will add established pattern recognition code later

## Parameters of an LCIO Track

#### Track

(LCIO)

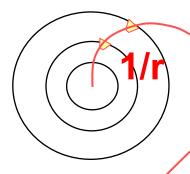
- To define a Track it's needed
  - Reference point
    - default; PCA ... to what? To origo or to collision point?
  - $-\Omega$ 
    - curvature, 1/r, sign = charge of particle
  - φ
    - phi angle for the track at the reference point
  - $tan(\lambda)$ 
    - · lambda is the dip angle at the reference point
  - $-D_0$ 
    - impact parameter in the r- $\phi$  plane ( = 0 if PCA is 0)
  - $-Z_0$ 
    - signed impact parameter in the r-z plane ( = 0 if PCA is  $\mathbf{0}$ ) -  $Z_0$  = ( z @ r =  $\mathbf{0}$  )
- Is there a documentation of LCIO's Track parameters?

# Fitting the Seed Track

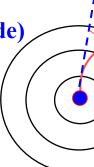
## SeedTrackFinder

TrackerPulse

Track



- SeedTrackFinder gets #e- in each pad & time bin
- Find two seed rows
  - First seed row: the first hit from outside
  - Second seed row: mid between origo and first
- Find seed pad with maximum # e for each seed row
- Radius from seed pads and origo (eq on next slide)
- Assume reference point = 0
- Get lambda using seed pads (more later)
- Get phi using seed pads (more later)
  - Assume both impact parameters zero



## Curvature

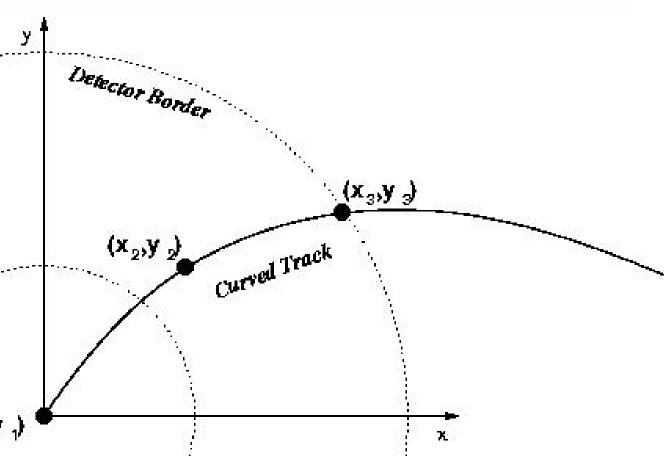
Three points on a circle  $([x_1, y_1], [x_2, y_2], [x_3, y_3])$  give the radius:

$$r = \sqrt{\frac{(y_2(x_3^2 + y_3^2) - y_3(x_2^2 + y_2^2))^2 + (x_3(x_2^2 + y_2^2) - x_2(x_3^2 + y_3^2))^2}{4(x_2y_3 - x_3y_2)^2}}$$

if  $x_1 = y_1 = 0$ .

Perfect circle is assumed, i.e. no energy loss

Good approx for Seed Track



# Lambda and Phi

Three points on a circle  $([x_1, y_1], [x_2, y_2], [x_3, y_3])$ , assuming  $x_1 = y_1 = 0$ , give the center of the circle:

$$x_c = -\frac{y_2(x_3^2 + y_3^2) - y_3(x_2^2 + y_2^2)}{2(x_2y_3 - x_3y_2)}$$

$$x_3(x_2^2 + y_2^2) - x_2(x_3^2 + y_3^2)$$

$$y_c = -\frac{x_3(x_2^2 + y_2^2) - x_2(x_3^2 + y_3^2)}{2(x_2y_3 - x_3y_2)}$$

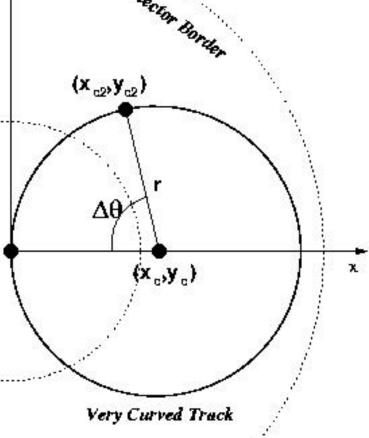
Changing origo to  $[x_c, y_c]$  we get  $\lambda$  from

$$\tan \lambda = \frac{p_z}{p_t} = \frac{\Delta z/\Delta t}{\Delta \theta r/\Delta t} = \frac{\Delta z}{\Delta \theta r}$$
 where 
$$(\mathbf{x}_{\text{c1}}, \mathbf{y}_{\text{c1}})$$

 $\Delta \theta = \left| \arctan \frac{y_{c1}}{x_{c1}} - \arctan \frac{y_{c2}}{x_{c2}} \right|$ 

And φ from using

Hep3Vector::deltaPhi(tangent, x-axis)



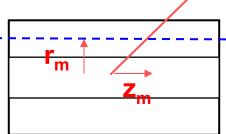
# Fitting the Track

#### **LGTrackFitter**

Track

Track

- The processEvent() gets the seed track
  - Initilize Minuit(LogLikelihoodFunction)
  - Call Minuit(seed track)



- The LogLikelihoodFunction(track parameters,  $\sigma_m$ )
  - $\sigma^2 = \sigma_m^2 + (z z_m) D^2$ 
    - D = diffusion constant (in Gear file ?)
    - $\sigma_m$  = characteristic diffusion for that track  $(\sigma_m = \sigma @ r = r_m)$
    - $\sigma_m$  is good to add to the minimization parameters since it
      - is uncorrelated to the others → does not increase errors in the other parameters
      - can be used to check gas properties from experimental data
      - indicates the fit quality (a  $\sigma_m$  way off  $\rightarrow$  bad fit)
  - Impact parameters not zero due to
    - reconstruction imperfections
    - b-hadron → new vertex

# Suggestions of use of GEAR

- We use Gear as input both to Mokka and Marlin (e.g. PadLayout is needed by both simulation and reconstruction)
- In Gear now; Drift velocity and readout frequency, so not only geometry... (?)
- Could Gear be edited to take care of dimensions?
- Organize the Gear file in sections
  - Gap Sections
  - Gem Sections
  - ... and so on ...

```
<!-- build the TPC inward from the readout electronics -->
<gap name="induction_gap" width="5mm" eField="0 0 1000V"/>
<gem name="gem2" gain="40" width="0.5mm" eField="0 0 1000V"/>
<gap name="transfer_gap" width="0.5mm" eField="0 0 1000V"/>
<gem name="gem1" gain="40" width="0.5mm" eField="0 0 1000V"/>
<gap name="drift_gap" width="*" eField="0 0 1000V"/>
```

# **Upgrade of CED**

- Can now draw curved tracks in 3D
- Can now draw keystones (for pads)
- Much faster
  - changed so that "DisplayList" is used to redraw objects and store geometry
  - and more …

## UVic's "Wish List"

- Standardized description of whole of the TPC (Gear or MySql ...?)
  - GEM's (positions, widths, gains ...)
  - Micromegas (positions, widths, gains ... )
  - GasVolume (drift velocity, widths, gains ...)
  - and more …
- More structured Gear file
  - Sections
  - Dimensions

```
<!-- build the TPC inward from the readout electronics -->
<gap name="induction_gap" width="5mm" eField="0 0 1000V"/>
<gem name="gem2" gain="40" width="0.5mm" eField="0 0 1000V"/>
<gap name="transfer_gap" width="0.5mm" eField="0 0 1000V"/>
<gem name="gem1" gain="40" width="0.5mm" eField="0 0 1000V"/>
<gap name="drift_gap" width="*" eField="0 0 1000V"/>
tpcParemeters.getGem("gem1").getGain();
theGems = tpcParameters.getGems();
```

- Better documentation for the LCIO Track Parameters
  - Reference point is the PCA ...to what? Collision point or origo?
  - Signed impact parameters?
  - Diagram for angles
    - Phi and Lambda are respect of which axis?
- Can phpMyAdmin handle Mokka's MySQL database

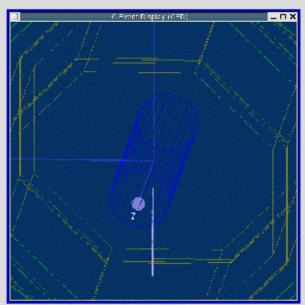
# **Home Pages**

Installation Home Page:

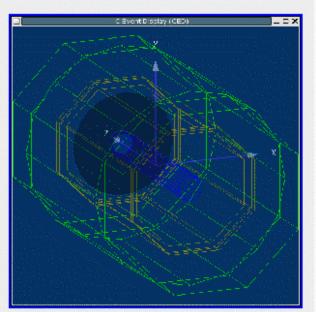
http://particle.phys.uvic.ca/~hansen/ILC/MOKKA/installation.html

Results and Download Home Page:

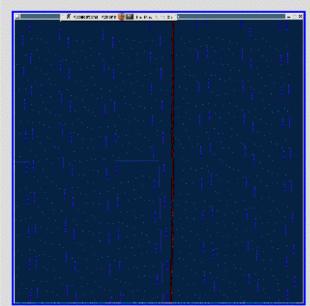
http://particle.phys.uvic.ca/~mcgeac00



Raw track data generated from Mokka single colour pads - about 2000 were hit in this picture



The TPC viewed in CED with Marlin. The semi-transparent circle is the pad layout.



A close-up of the representation of the TrackerPulse data reproduced in Marlin

# **Conclusions and Future Work**

**Installation** 

• Installation of Mokka, LCIO, Gear and Marlin has been done on SL3 and FC4

**Objective** 

• Simulation is needed to understand the LC TPC's magnetic field requirements and possible corrections for the magnetic field distortions

**Strategy** 

- Make a more detailed TPC simulation in Mokka
- Study what effect inhomogeneous magnetic field has on the momentum resolution of the LDC concept
- Study possibility to correct for field distortions with either a B-field map or external track points

Web

• More info here:

http://particle.phys.uvic.ca/~mcgeac00

http://particle.phys.uvic.ca/~hansen/ILC/MOKKA/installation.html

## **Extra Slides**

# Momentum Resolution from a Toy MC

- Plan to study momentum resolution from SeedTrackFinder with a Toy Monte Carlo
- Send out many charged tracks with random (reasonable) momentum
- Get the reconstructed momentum, p, from the reconstructed curvature
- Histogram the resolution,  $(p p_0) / p_0$ 
  - where  $p_0$  is the true momentum



## Mokka installation

- Installations done on two different system Scientific Linux 3 (SL3) and Fedora Core 4 (FC4)
- Installed needed software CLHEP, Wired, OpenGL, Geant4, MySQL...
- Installed LCIO
  Had to add an include statement due to new gcc version in FC4
- Installed Mokka
  Had to create shared libraries and edit files for compile and link
- Created Local Mokka MySQL Database
  To be able to define our own Sub Detector
- Installed Gear and linked it inside Mokka
  Upgraded the implementation of Gear to define the TPC pads
- Installed Marlin and CED (C Event Display)

#### **Details described step by step:**

http://particle.phys.uvic.ca/~hansen/ILC/MOKKA/installation.html

# **Ionization in Mokka's TPC**

- Control stepsize for ionizating particles in the TPC gas E.g. 1mm
- G4 gives the energy loss for that step 100-400 eV/mm
- One electron cloud per step
- Number electrons per cloud is given by the energy loss from G4 (26 eV/e<sup>-</sup>)

ElectronCloud.hh/cc

TPCSDUVic.hh/cc