

Top/Heavy Flavor Meeting

SSbar 250 GeV Analysis

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Objectives

- **Efficiency Correction**

- Calculate the correction factor for Kaon reconstruction efficiency due to the detector acceptance.
- Retrieve the loss in efficiency at the backward region.

- **Leading Pion Identification**

- Use pion as a signature of the event.
- uu/dd identification can be realized.
- Same method as Kaon ID.

Efficiency Correction

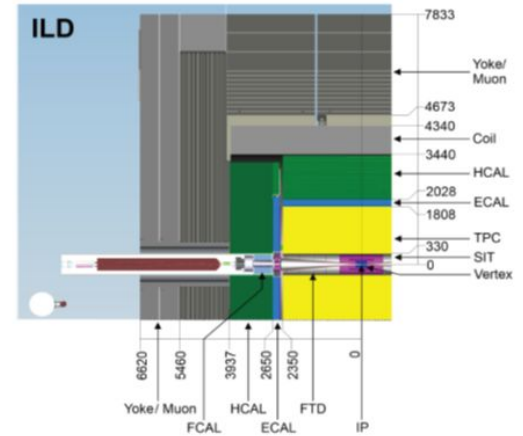
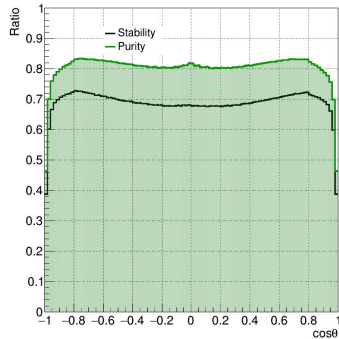
Efficiency Correction

- Detector acceptance

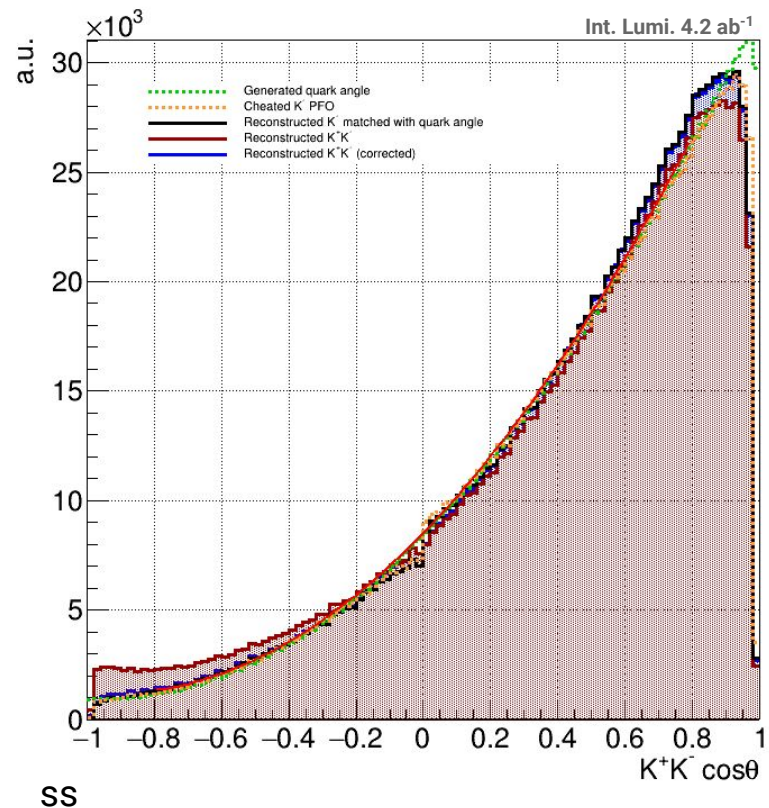
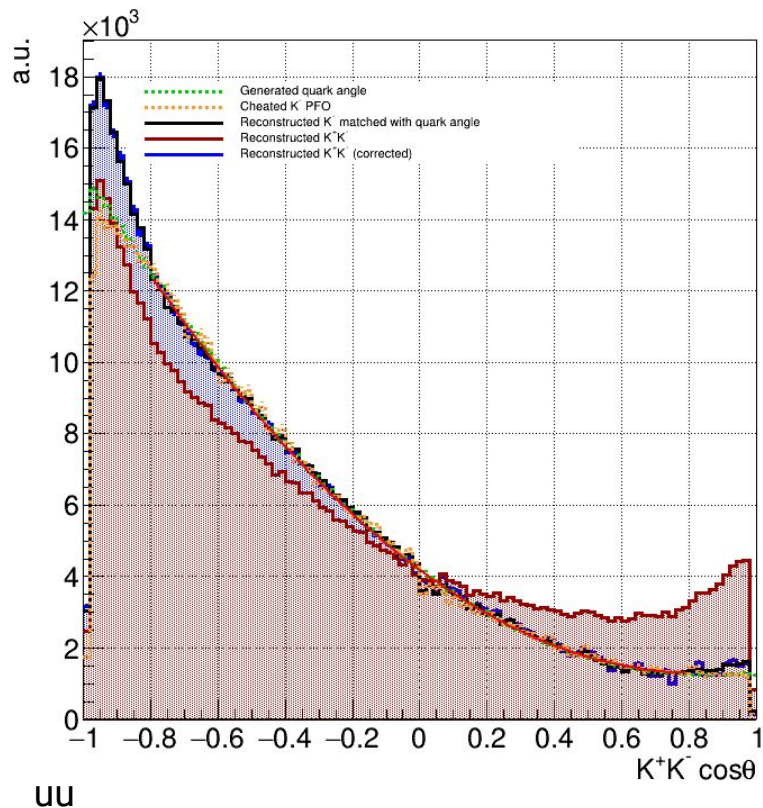
- Ability to extend the particle reconstruction at the far edge of the detector?
- One requires reconstruction efficiency correction.

$$\text{Efficiency} = \frac{N_{reco}}{N_{gen}}$$

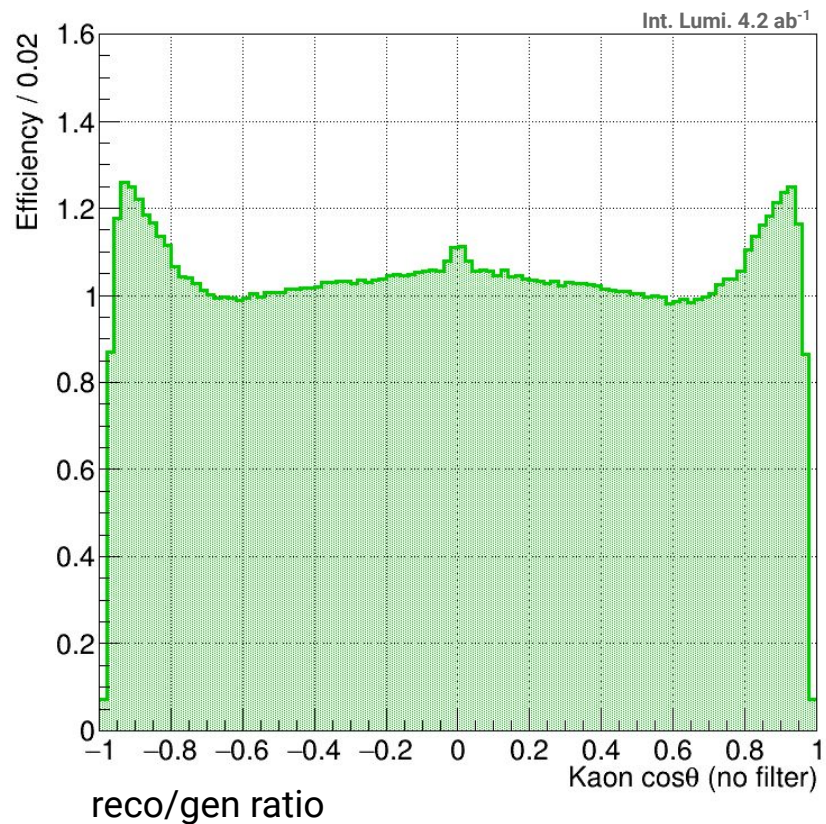
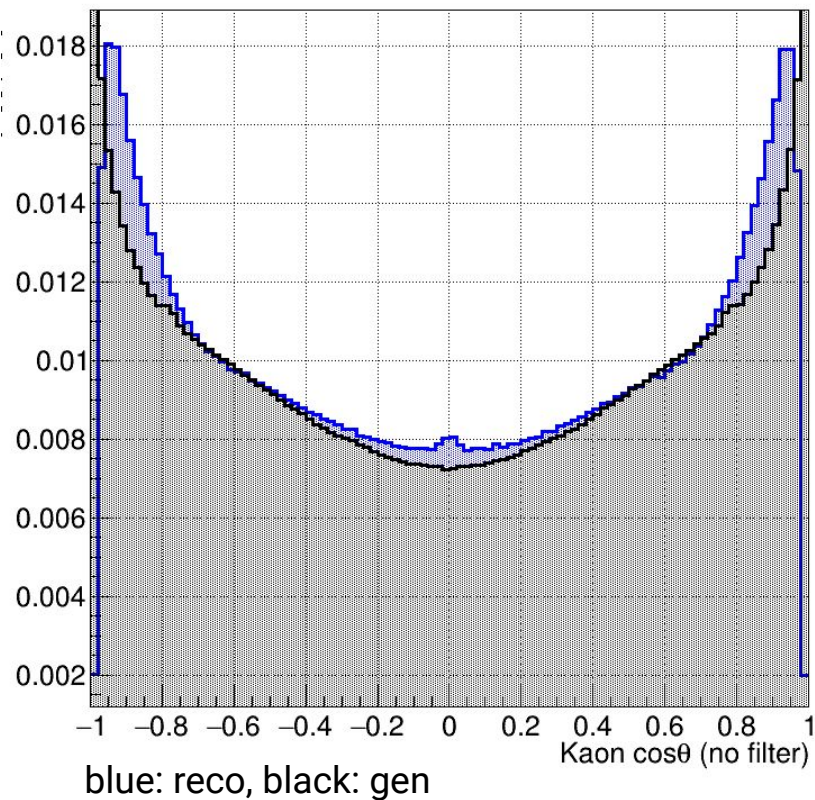
- Throughout the entire polar angle.



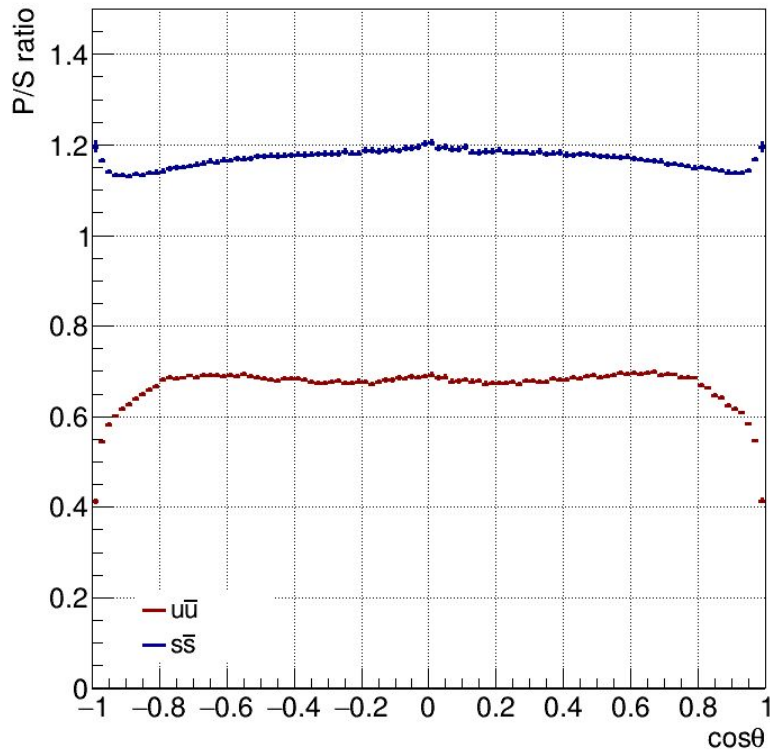
Polar Angle (w/o Efficiency corr.)



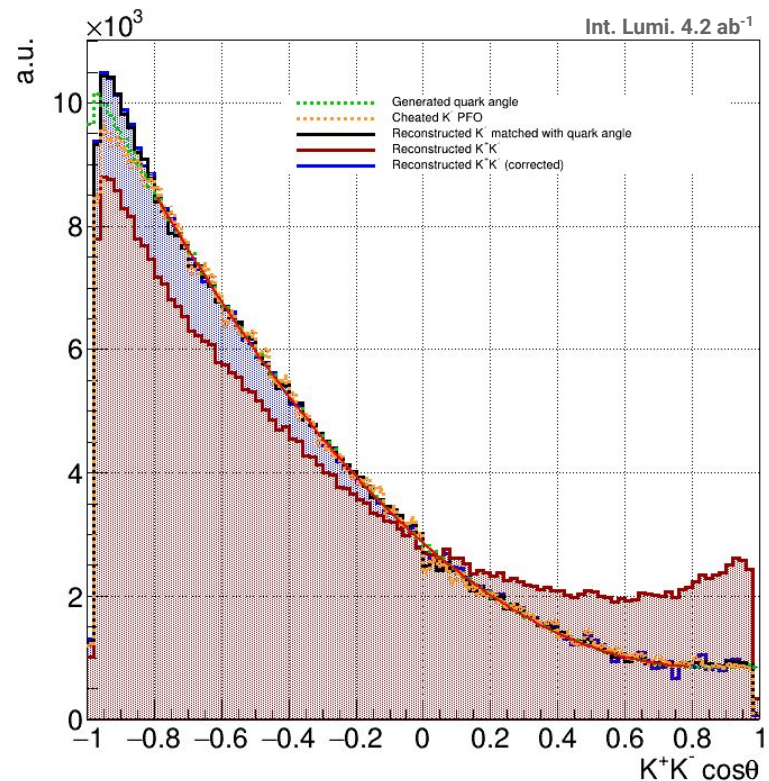
Cos θ Gen & Reco (uu)



Polar Angle (w/o S/P corr.)

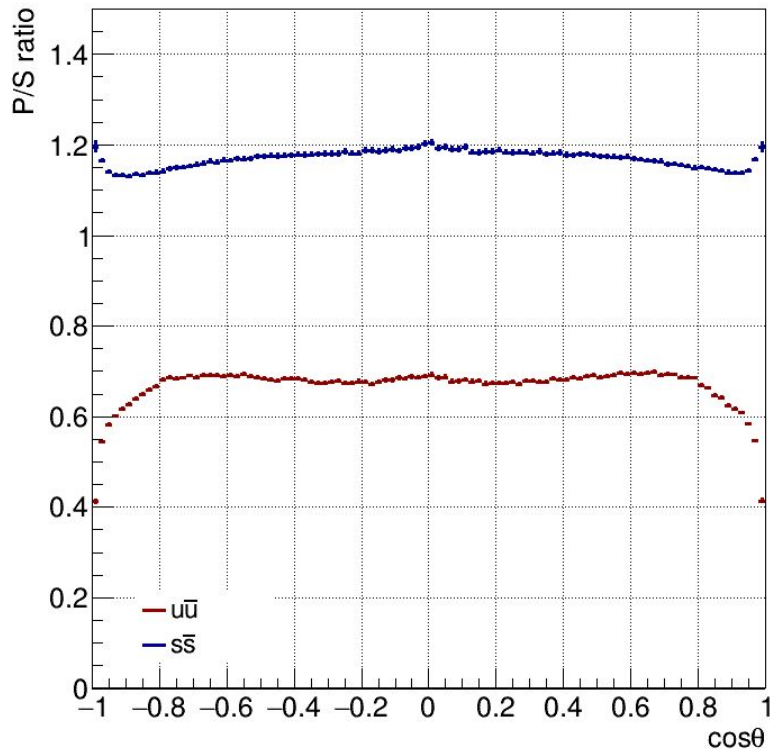


P/S ratio used for correction

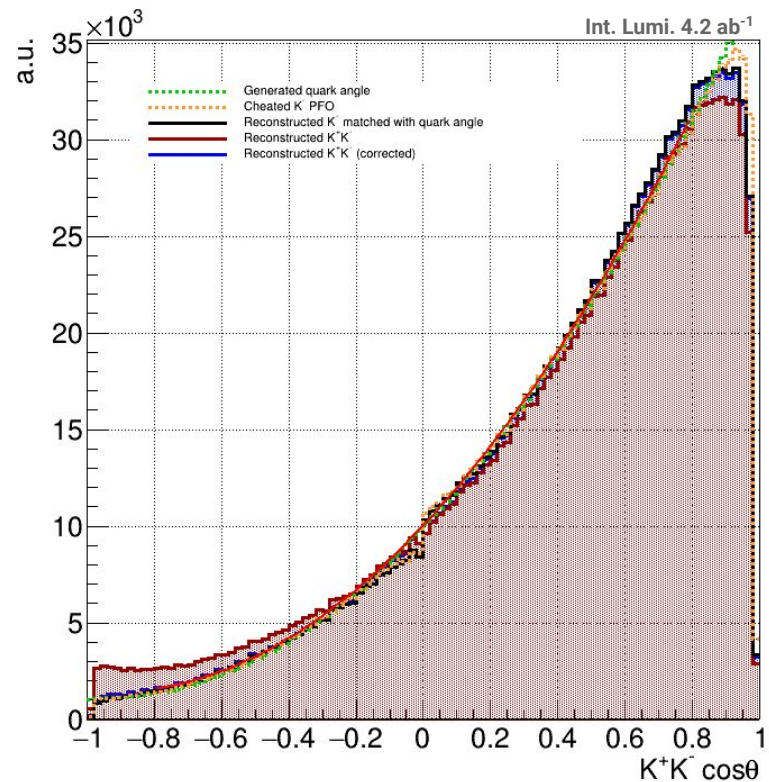


uu polar after correction

Polar Angle (w/o S/P corr.)

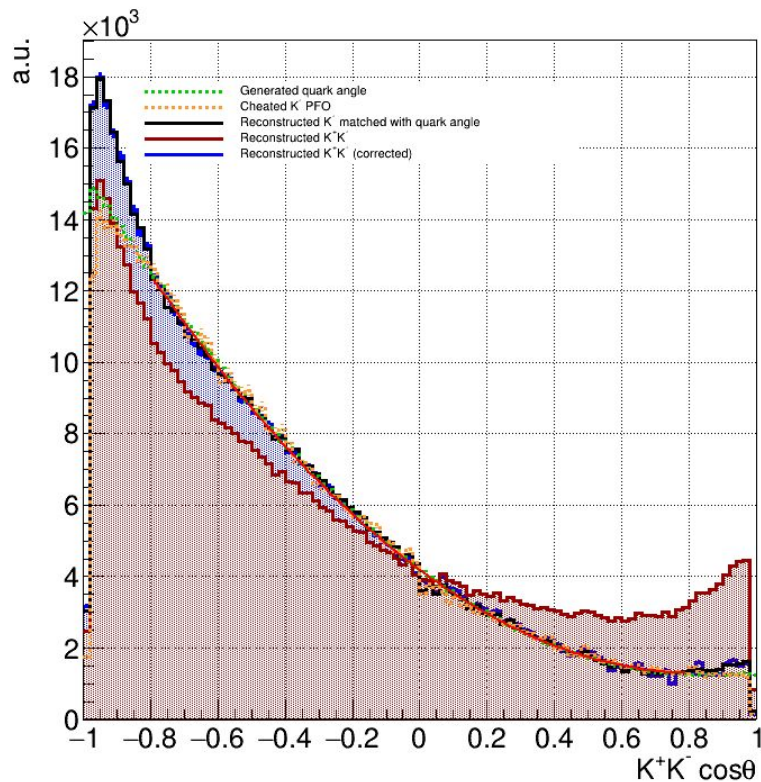


P/S ratio used for correction

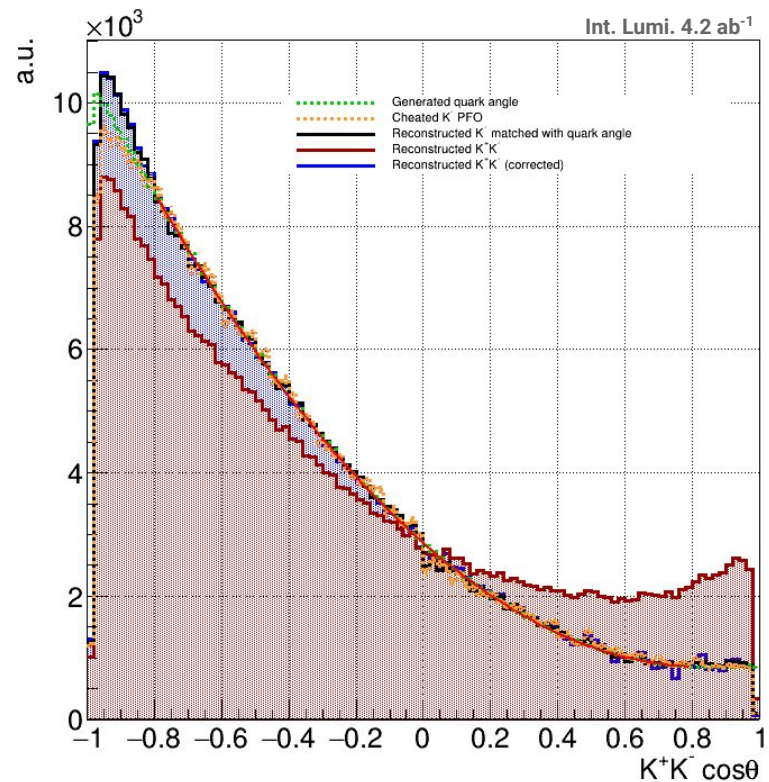


ss polar after correction

Polar Angle (w/o S/P corr.)

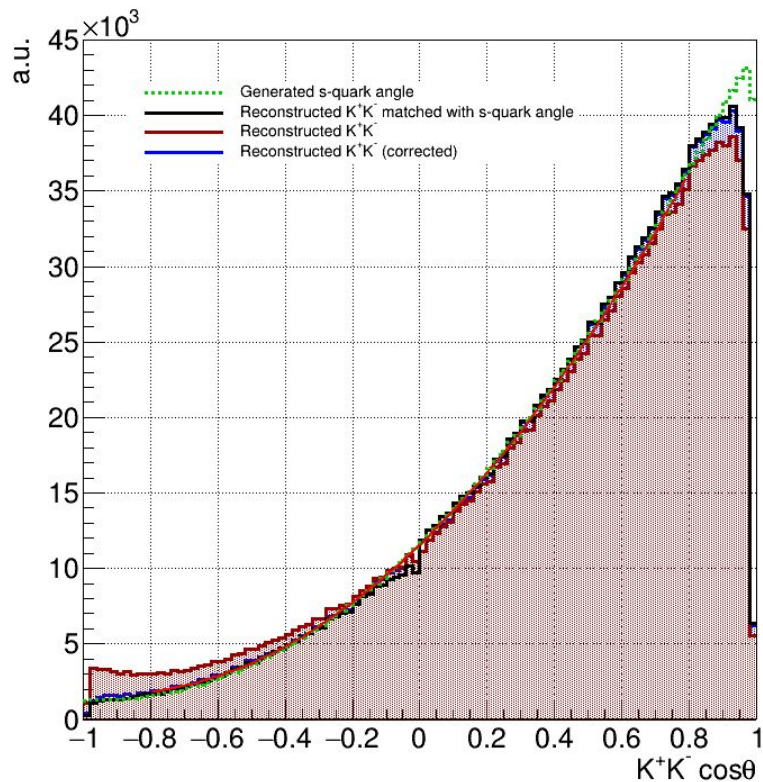


uu polar before correction

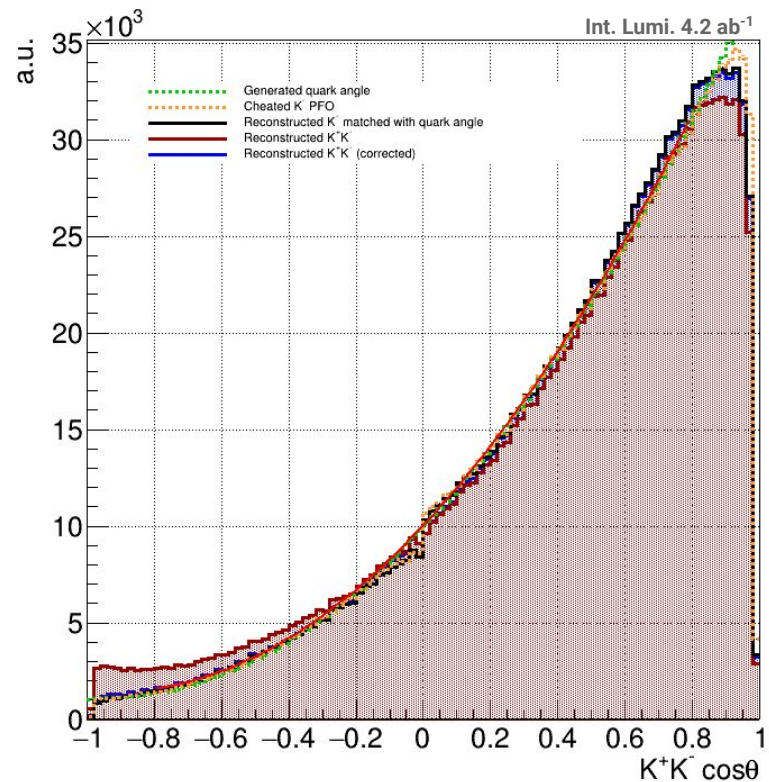


uu polar after correction

Polar Angle (w/o S/P corr.)



ss polar before correction



ss polar after correction

Leading Pion Analysis

Event Structure

s-tag

Charged Kaon track will give the original quark information. Kaon ID becomes the key.

u/d-tag

Charged Pion track will dominate throughout the entire polar angle. Pion ID becomes the key.

- Can distinguish well from Kaon (not bothered by proton or other competitors.)

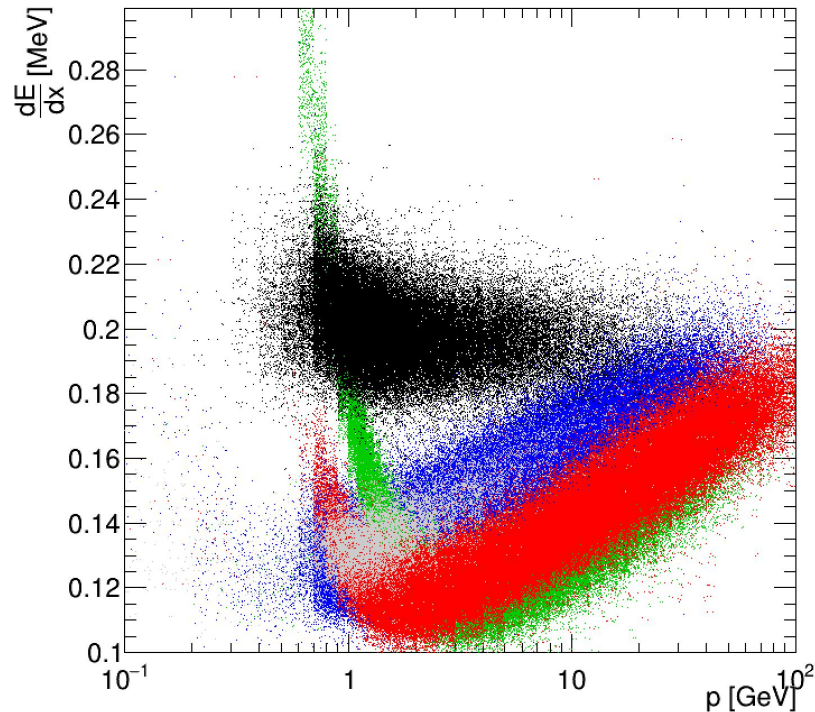
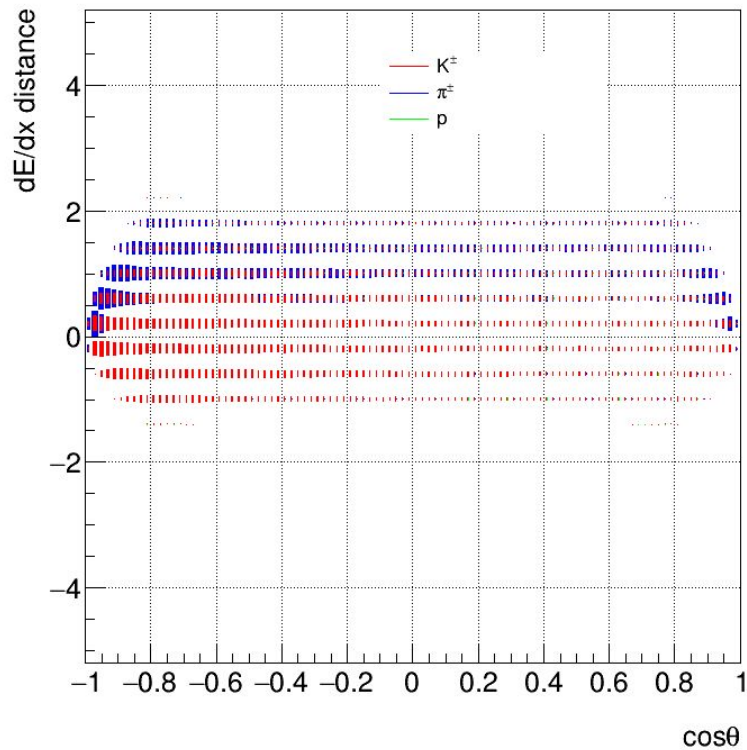
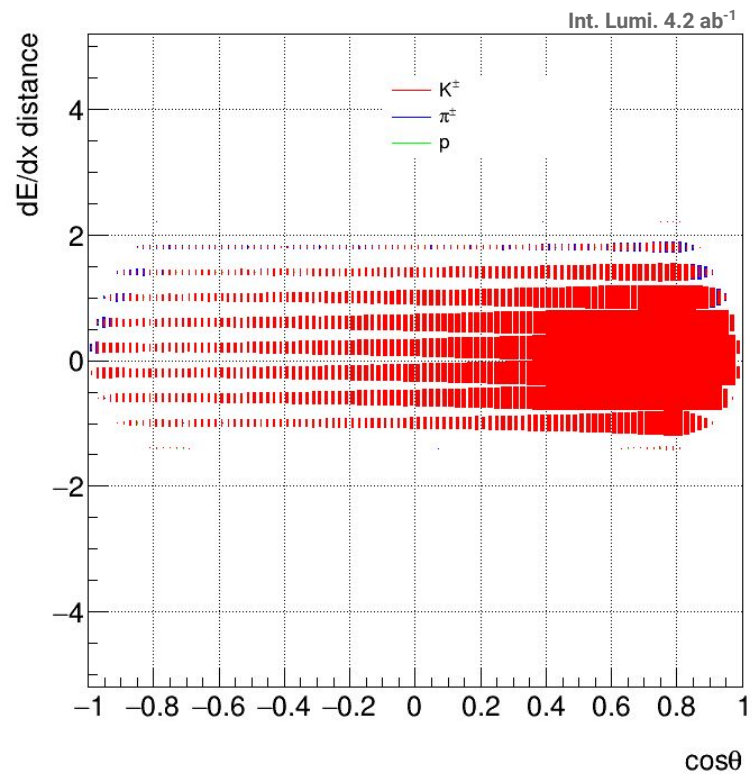


Figure: dE/dx vs p for $ss\bar{s}$ sample

dE/dx distance vs $\cos \theta$ (Kaon)



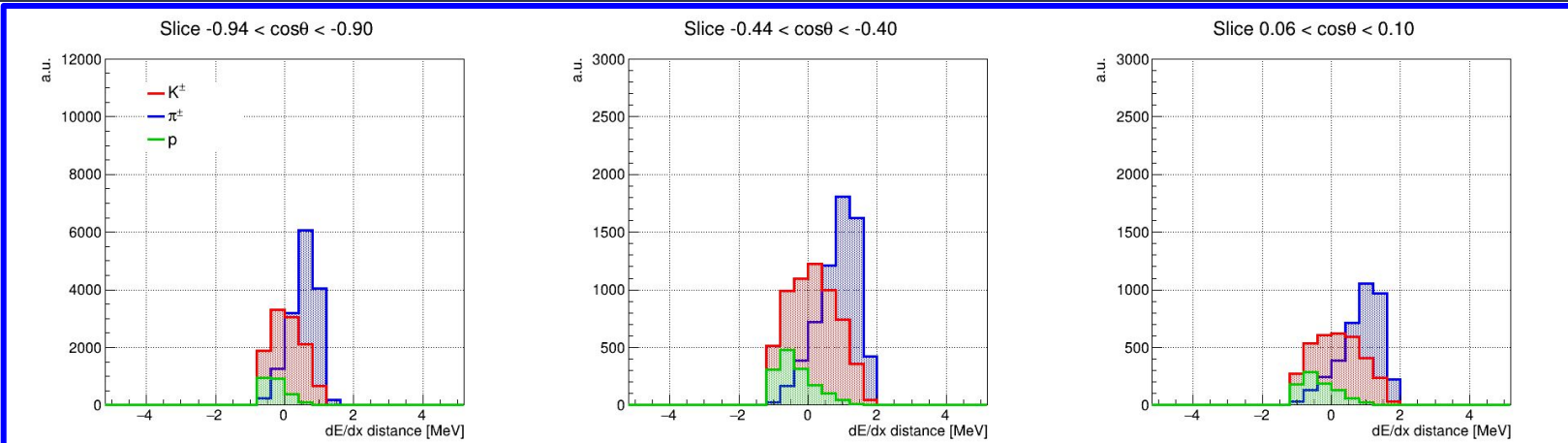
uu



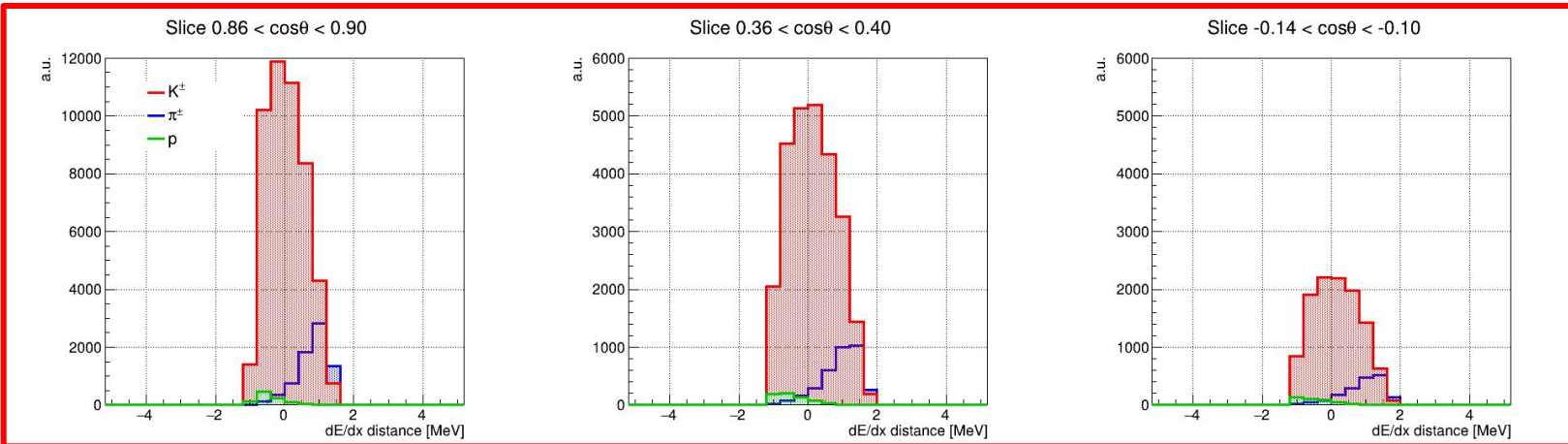
ss

dE/dx distances (Kaon)

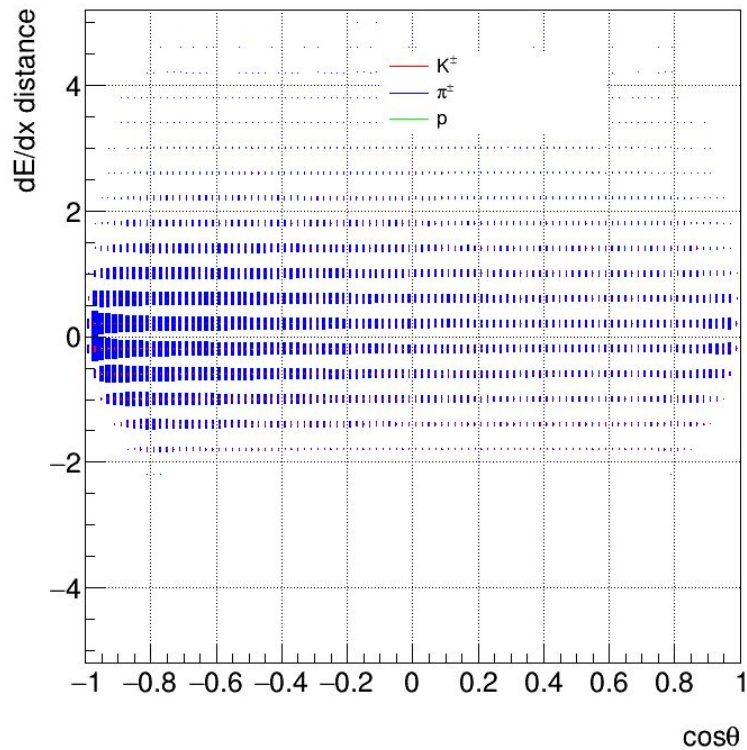
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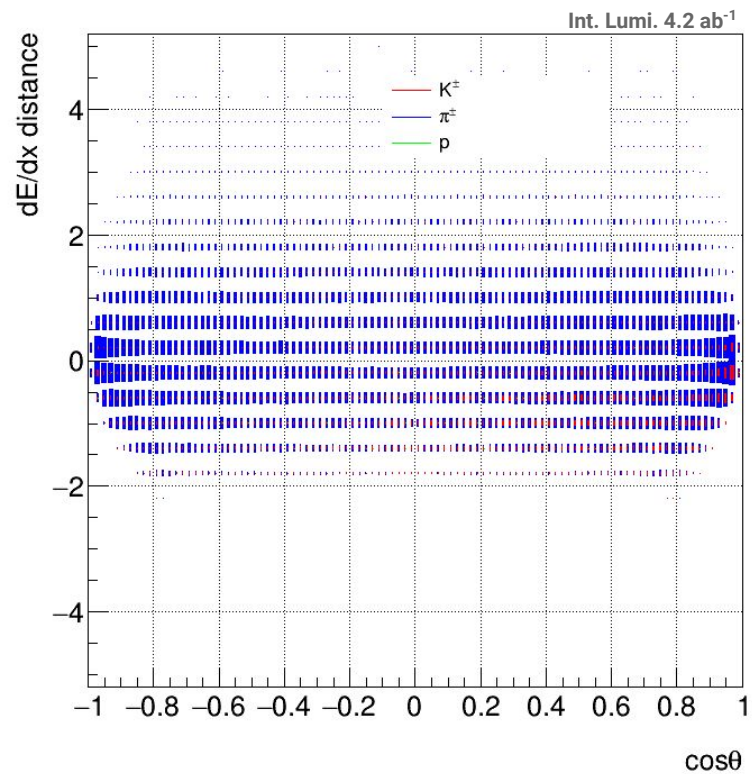
SS



dE/dx distance vs $\cos \theta$ (Pion)



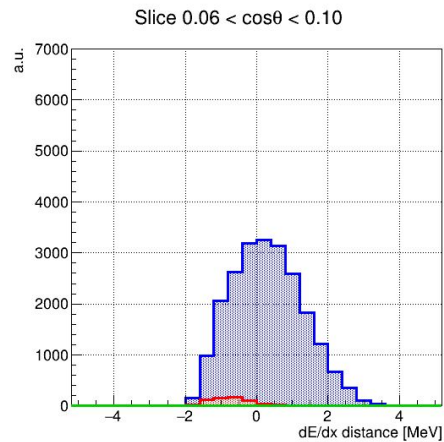
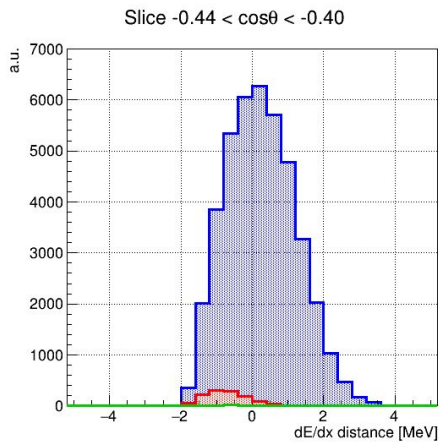
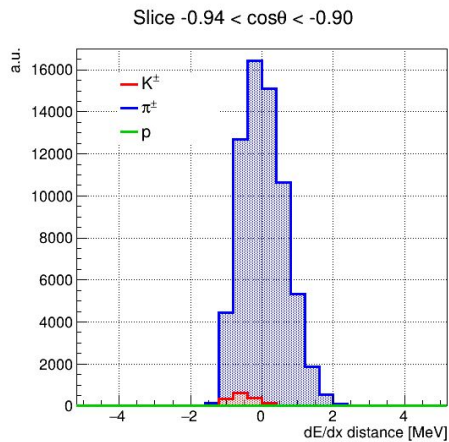
uu



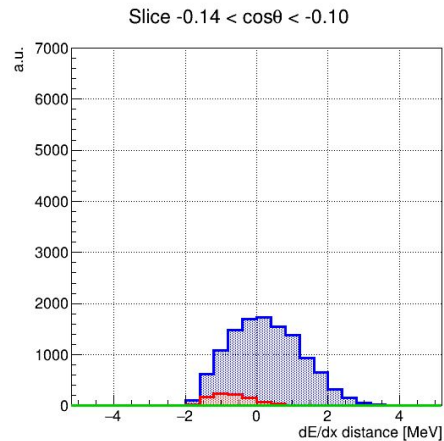
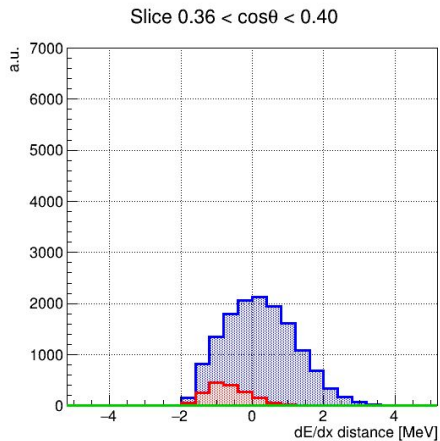
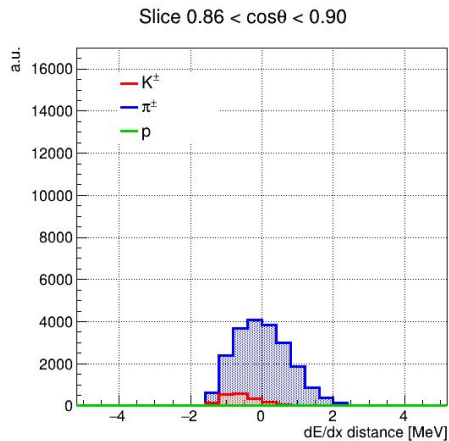
ss

dE/dx distances (Pion)

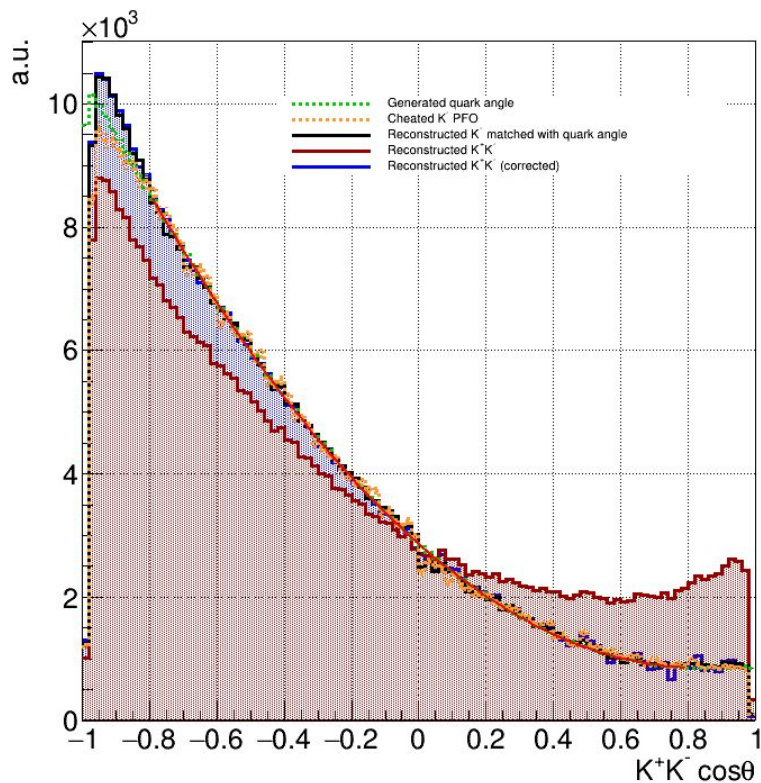
uu



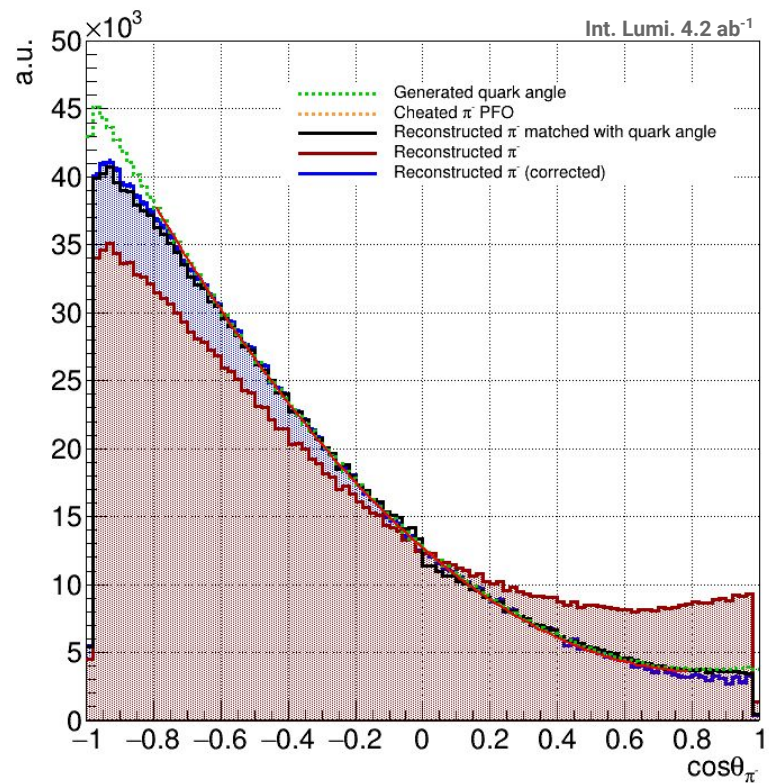
ss



Polar Angle (PiLPFO)

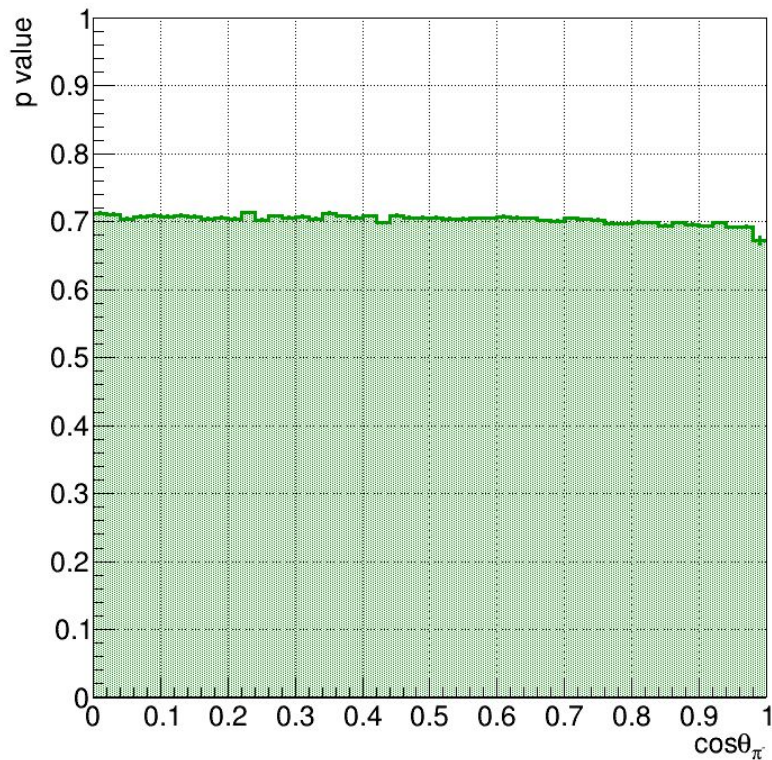


uu KL PFO polar angle (after eff. correction)

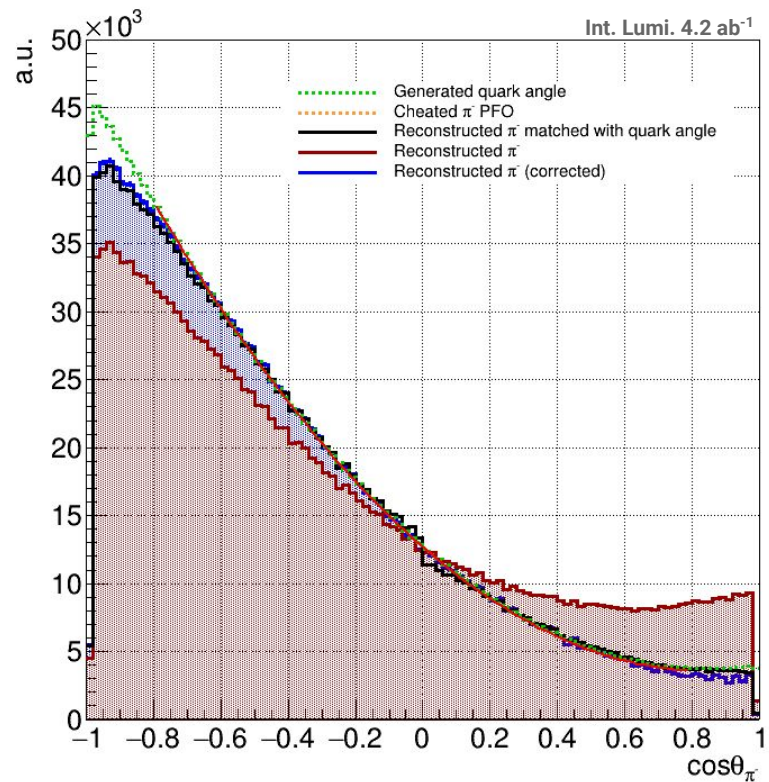


uu PiLPFO polar angle (no eff. corr)

Polar Angle (PiLPFO)

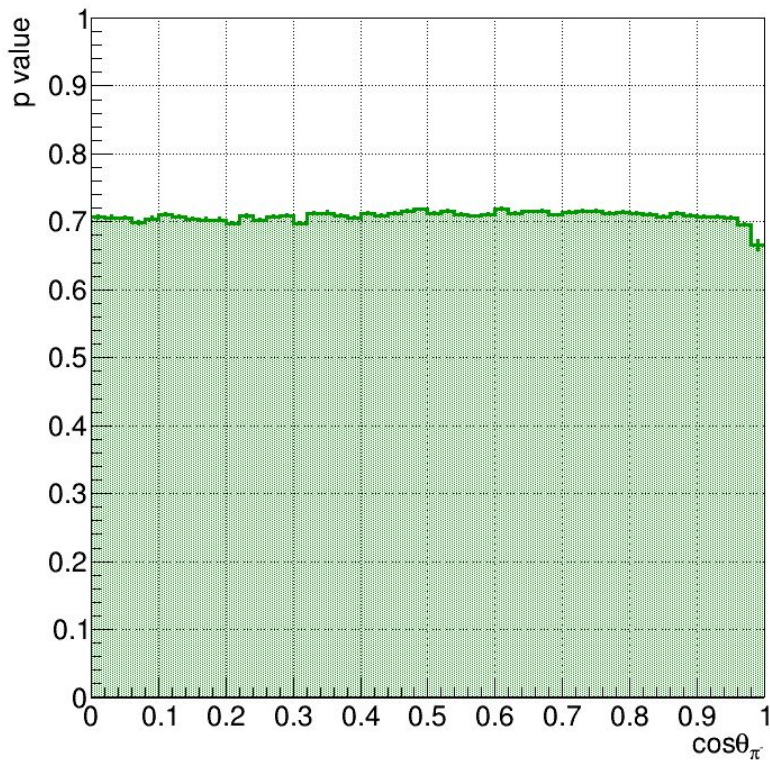


uu PiLPFO p value

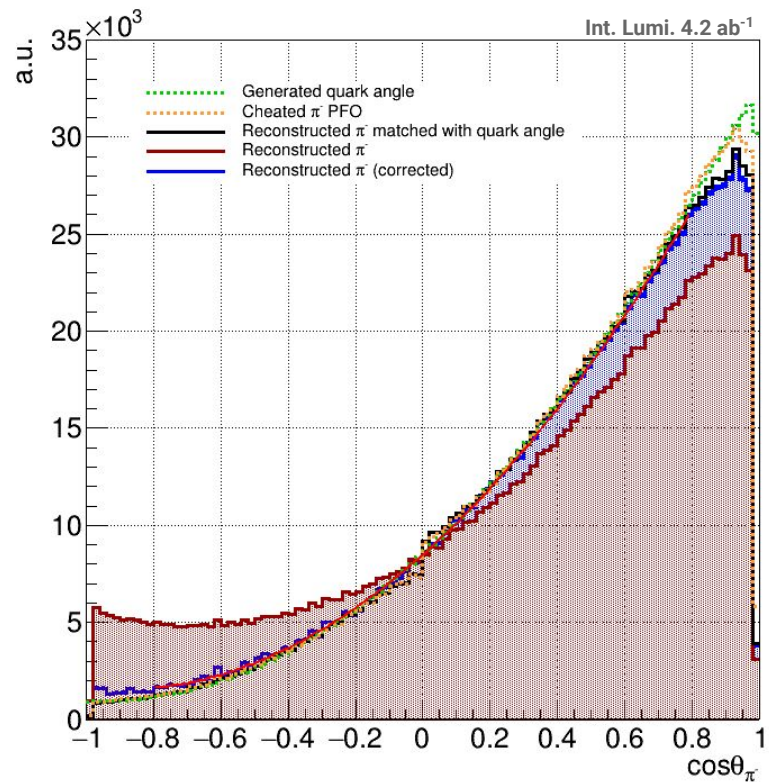


uu polar PiLPFO polar angle (no eff. corr)

Polar Angle (PiLPFO)

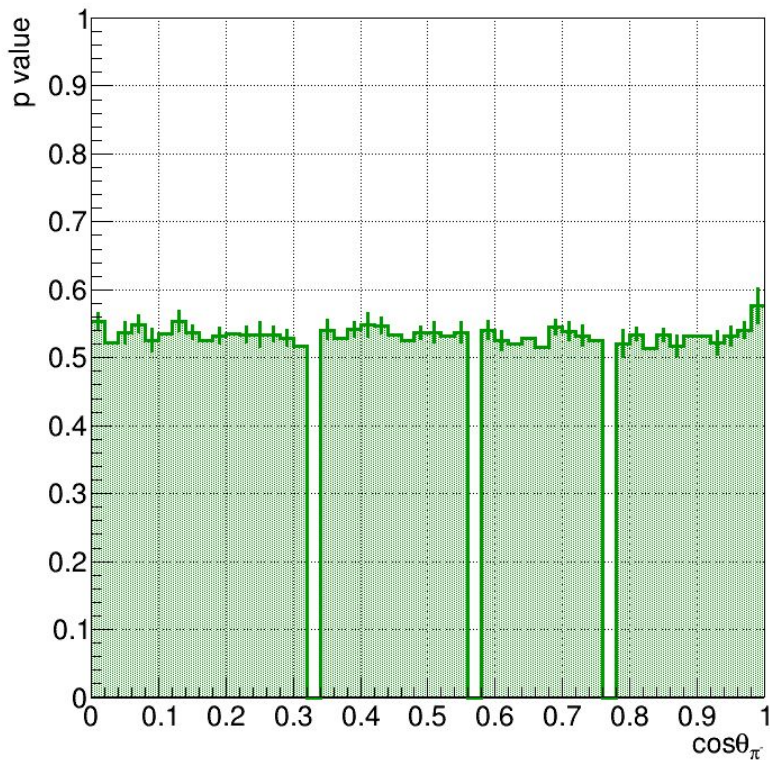


dd PiLPFO p value

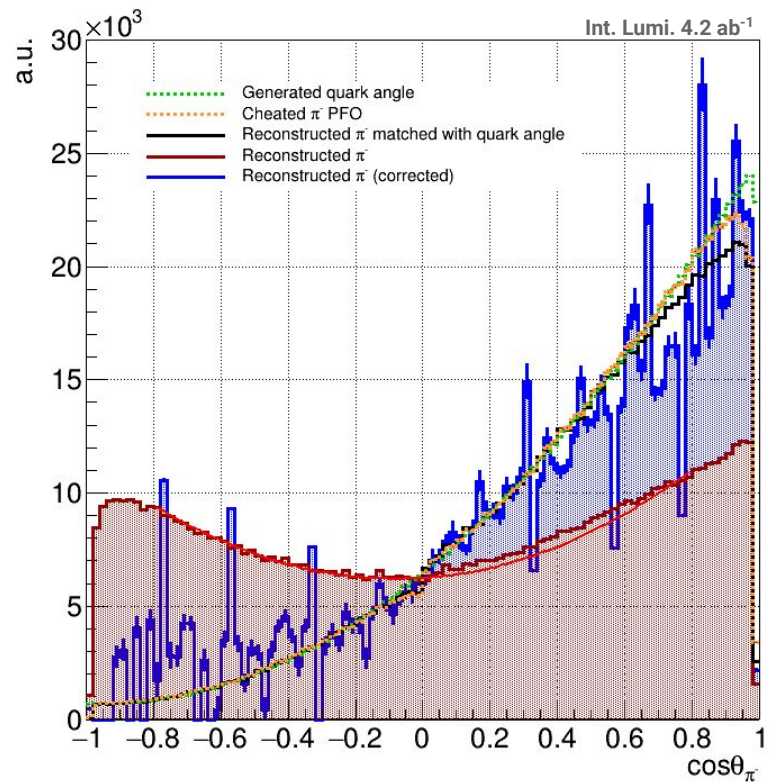


dd polar PiLPFO polar angle (no eff. corr)

Polar Angle (PiLPFO)

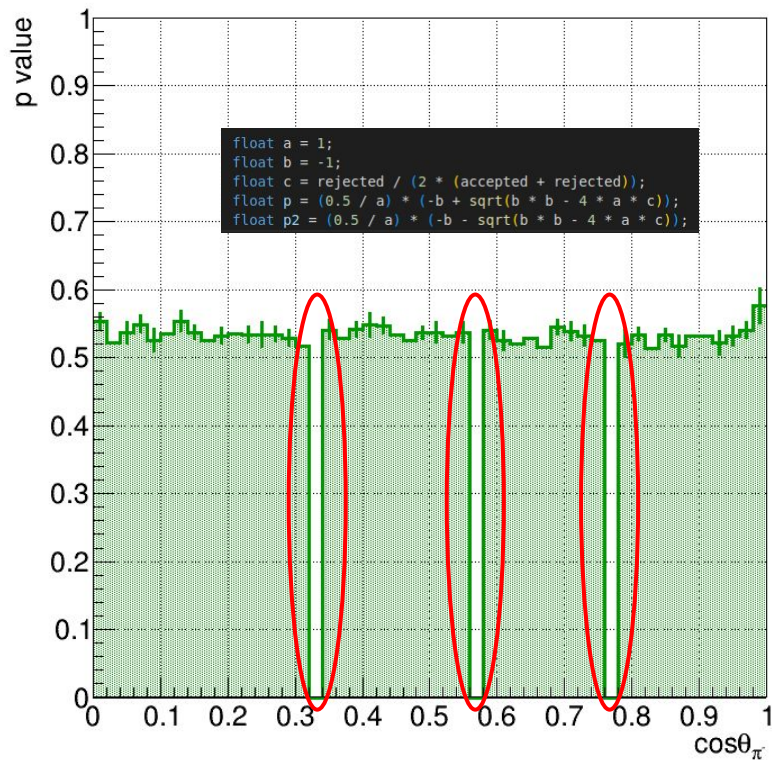


ss PiLPFO p value

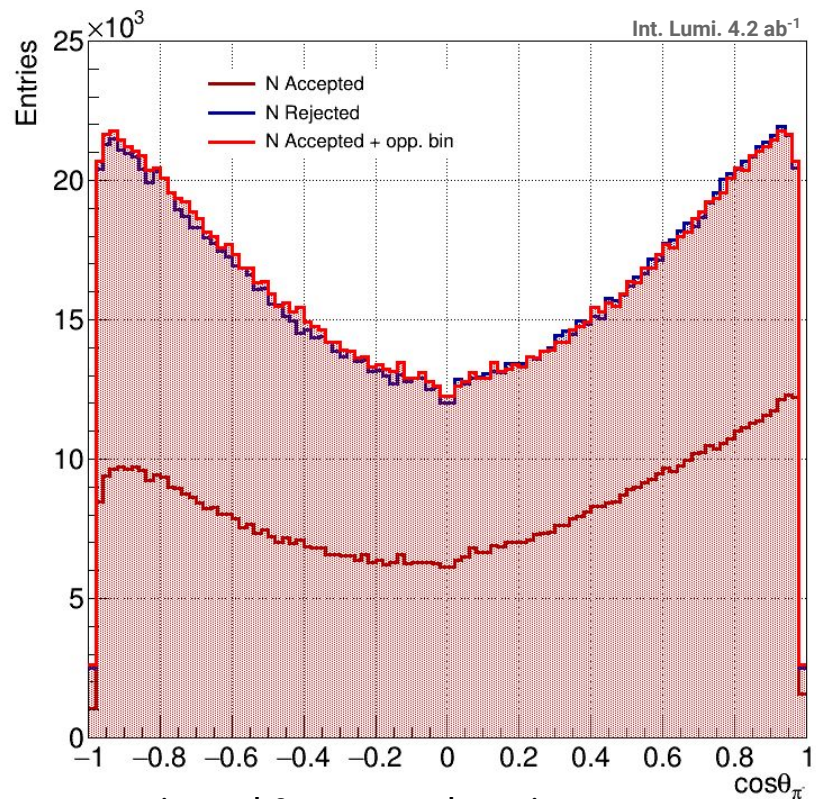


ss polar PiLPFO polar angle (no eff. corr)

Polar Angle (PiLPFO)

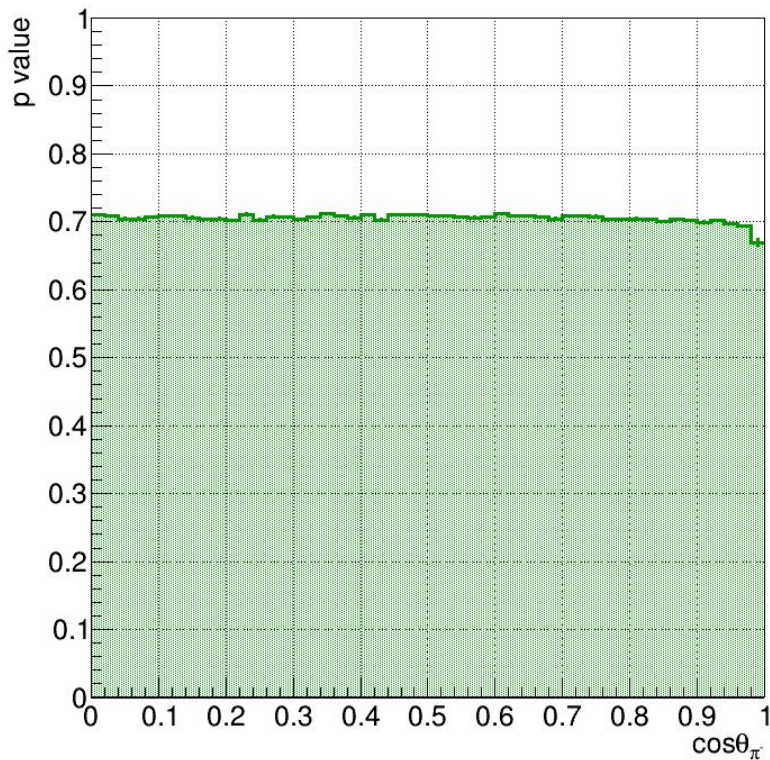


ss PiLPFO p value

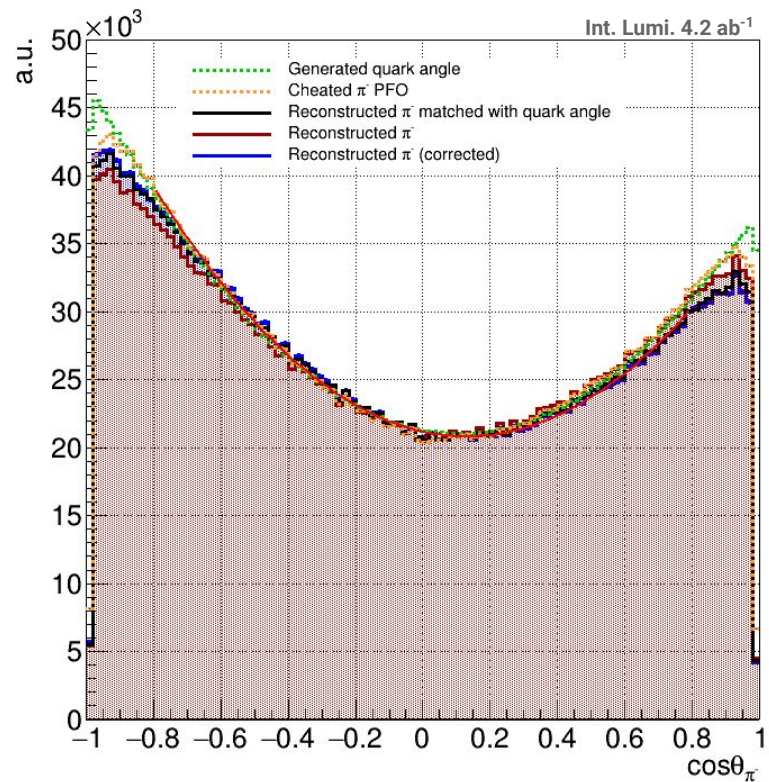


ss rejected & accepted entries

Polar Angle (PiLPFO)



ud PiLPFO p value



ud polar PiLPFO polar angle (no eff. corr)

Summary & Prospects

Summary

- **Efficiency Correction**
 - Apply correction based on the reconstruction efficiency
 - Correction for acceptance
- **Leading Pion Identification**
 - Effective way to identify u/d process
 - Works very well throughout the entire polar angle.
 - u/d mix sample tested

Prospects

- Finally mix **uds** sample?
 - a. Implement both Kaon and Pion ID
- Fit and subtract distributions (discussion)
 - a. Extract histogram from the uds mixture using Pi LPFO
 - b. Extract histogram from the uds mixture using K LPFO
 - c. Fit both histograms
 - d. Subtract PiLPFO fit function from KLPFO histogram
 - e. Compare the result with b)?