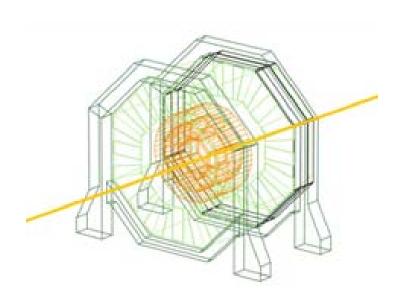
# **The SiD Detector Concept**

### **Opportunities in Vertexing and Tracking**



Marcel Demarteau

For the SiD Tracking and Vertexing Group

TILCO8 Sendai, March 3-6, 2008

## **Current Participants**



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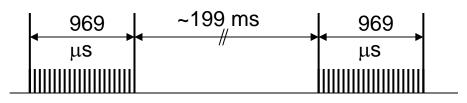
- 1. Argonne
- 2. Brown University
- 3. Caltech
- 4. Fermilab
- 5. Kansas State University
- 6. LPNHE Université de Paris 6/IN2P3-CNRS
- 7. Oxford University
- 8. Rutherford Appleton Laboratory
- 9. SLAC
- 10. UCSC
- 11. University of Colorado
- 12. University of New Mexico
- 13. University of Oregon

apologies to those we forgot

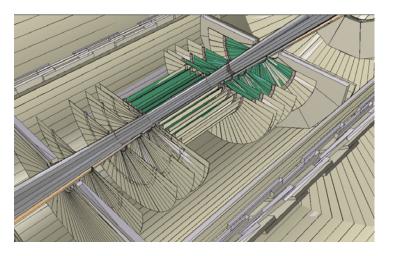
### **Pixel Detector**



- Pixel detector requirements
  - Transparency: 0.1% X<sub>0</sub> per layer (equivalent of 100 μm of Si)
  - Low power consumption (~50 W for 1 Giga pixels)
  - High resolution thus small pixel size
    - Excellent point resolution (< 4 μm)</li>
    - Superb impact parameter resolution (5μm ⊕ 10μm/(p sin<sup>3/2</sup>θ))
  - Good angular coverage; robust pattern recognition (track finding in vtx alone)
  - Modest radiation tolerance for ILC applications
  - EMI immunity
- Combination of small pixels, short integration time, low power required for ILC is difficult to achieve
  - Small pixels tend to limit the amount of circuitry that can be integrated in a pixel
  - Small pixels also mean that the power/pixel must be kept low



ILC Beam structure: Five trains of 2625 bunches/sec Bunch separation of 369.2 ns

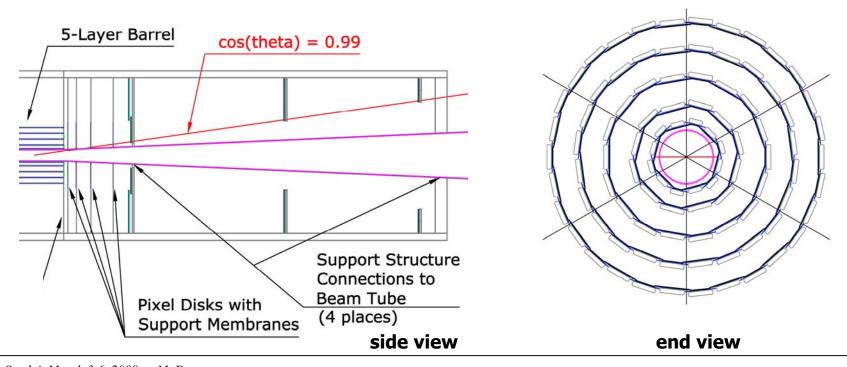


- The low occupancy/pixel/train (~0.5%) means that a sparse scan architecture would be appealing if:
  - Signal/noise is high
  - Enough electronics can be integrated on a pixel

## **Pixel Detector Mechanical Design**



- Baseline vertex detector has a central, 5-layer barrel, two 4-plane end disk assemblies and three additional disks per end for extended coverage
- All elements are supported indirectly from the beam tube via double-walled, carbon fiber laminate half-cylinder
- Barrel Region
  - Five layers
  - Longitidunal coverage: ± 62.5 mm
  - Radial coverage: 14 < R < 61 mm
- Forward regions
  - Four disks
  - $-z = \pm 72, \pm 92, \pm 123, \pm 172 \text{ mm}$
  - Radial coverage: R < 71 mm</li>



## **Mechanical Layout: V1**

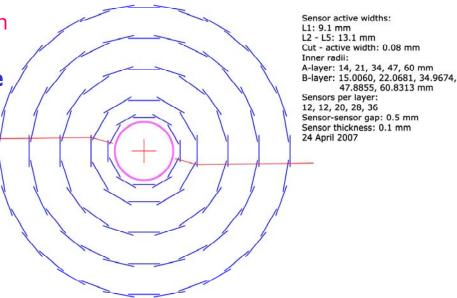


- New layout compared to original baseline design
  - Sensor counts increased in L3, L4, L5 to obtain multiples of 4 and fully identical barrel halves
- Goal of understanding how to optimize the geometry of the carbon fiber / epoxy composite frame to minimize deflection due to gravity and temperature changes.
- Various configurations being studies
  - 4-layer (0,90,90,0 degree) lay-up
    - The maximum gravitational deflection vector is about 0.6 µm in each case.
  - 3-layer CF structures

 mass optimization and minimization of thermal deflections.

Thermal distortions are a serious issue for sensors below ~ 10 °C

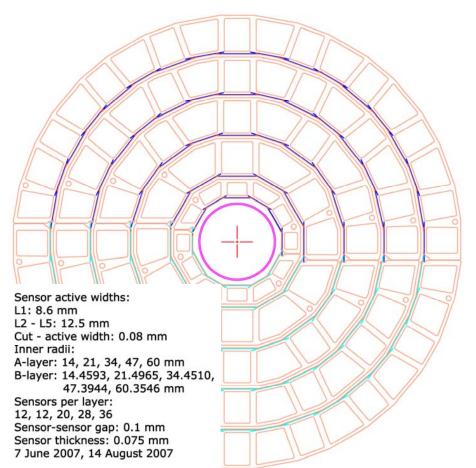




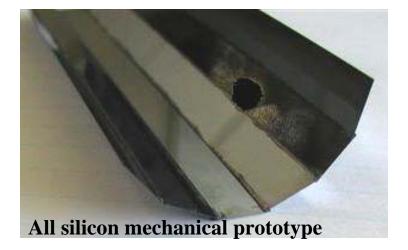
## **Mechanical Layout: V2**



- All Silicon layout: proposed to mitigate CTE issues
  - Uses only the silicon sensors in "cylindrical" portions of the structure
- Sensors glued to one another along edges by thin beads of epoxy and supported by thin, flat carbon fiber/epoxy end membranes



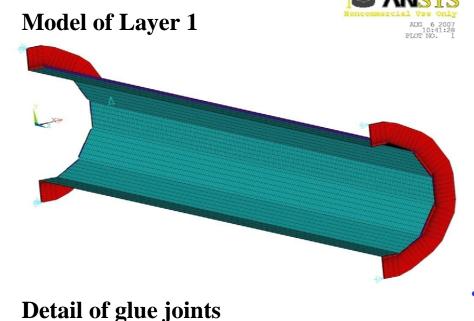
- 75 µm silicon thickness assumed
  - Could be modified for thicker or thinner sensors
- Parametric FEA model for all 5 layers of this detector (UW)



## **Mechanical Layout: V2**



All silicon layout



0.7 mm

FEA study of gravitational sag and maximal displacements for a ∆T of 10 °C

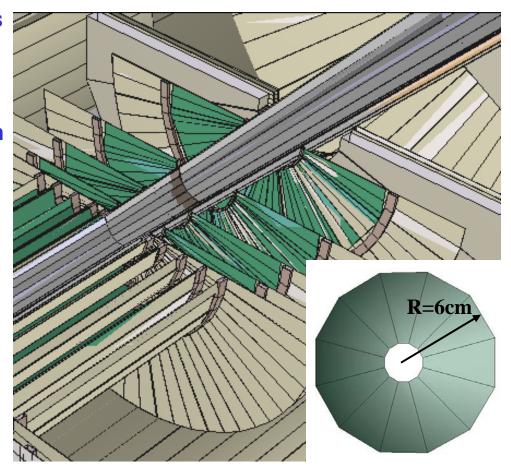
Layer	Gravity (μm)	Δx (μm)	Δy (μm)	Δz (μm)
1	0.1	0.9	1.8	5.3
2	0.1	1.0	3.0	5.6
3	0.3	1.6	4.0	5.8
4	0.6	2.6	5.7	6.2
5	1.4	4.4	8.1	6.6

- Note that the Z deflection is composed mainly of the simple change in length of the detector
  - Results independently verified by LCFI collaboration
- Less temperature dependent than CF support structures

# Mechanical Layout: Forward Region SiD



- Forward pixel detectors are notoriously difficult to build in low mass, low power configuration with very little additional mass due to cables
- **Currently thinking of silicon disks** with support and readout at the periphery
- Area not well studied; many open issues
  - **Long barrels vs short barrels**
  - Cable routing
  - Power delivery

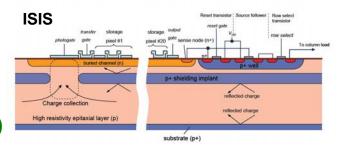


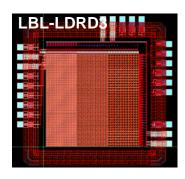
### **Vertex Detector Sensor Technology**



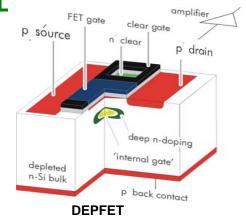
 Collaborating with many specific sensor R&D groups and considering broad spectrum of technologies

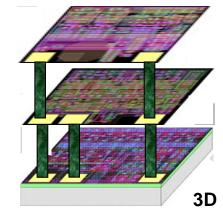
- CCD's
  - Column Parallel (LCFI)
  - ISIS (LCFI)
  - Split Column (SLAC)
- CMOS Active Pixels
  - Mimosa series (Ires)
  - INFN
  - LDRD 1-3 (LBNL)
  - Chronopixel (Oregon/Yale)





- SOI
  - American Semiconductor/FNAL
  - OKI/KEK
- 3D
  - VIP (FNAL)
- DEPFET (Munich)





## **Vertex Detector Sensor Technology**



DØ IIb

- So far no 'ideal' technology that performs best in all categories
  - Attempts to reduce hit density via faster readout or time stamping seem to be invariably associated with more power
- Issues
  - The first layer carries a large weight in determining the ultimate impact parameter resolution and is in the most dense environment
    - May compromise on power to get lowest hit density and best time stamping
  - Services and handling of Lorentz forces much more important for outer layers but should not compromise performance

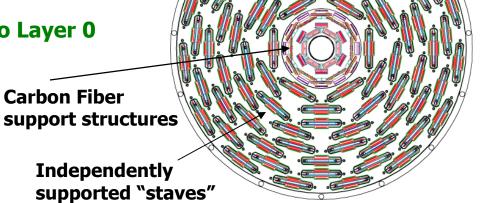
End cap sensor issues are very different from barrel

 Tracks nearly perpendicular; Lorentz forces less of an issue

Considering the option of mixed technologies both for support and sensors

e.g. Dzero Run IIb, CDF/Dzero Layer 0

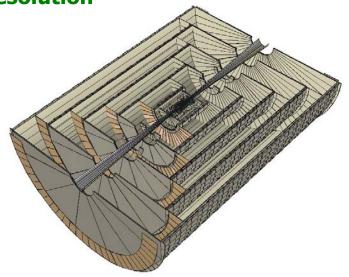
We need new, clever ideas!

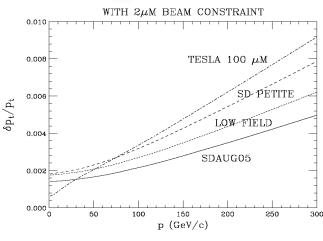


### **Tracking Detector**



- Tracking detector requirements
  - Transparency:  $0.8\% X_0$  per layer average over full fiducial volume
  - Superb point resolution and momentum resolution
    - Strip pitch of 25 μm
    - $\sigma(1/p) = 2 \cdot 10^{-5} \text{ (GeV}^{-1})$  at 90 degrees
  - Good angular coverage; robust pattern recognition
    - Single bunch timing
    - Very high tracking efficiency for PFA
  - Robust against aging and beam accidents
  - Modest radiation tolerance
- Silicon technology chosen
  - Mature technology which allows emphasis on phi resolution
    - Superior asymptotic p<sub>T</sub> resolution
  - Allows for flexibility in minimizing material distribution through fiducial volume

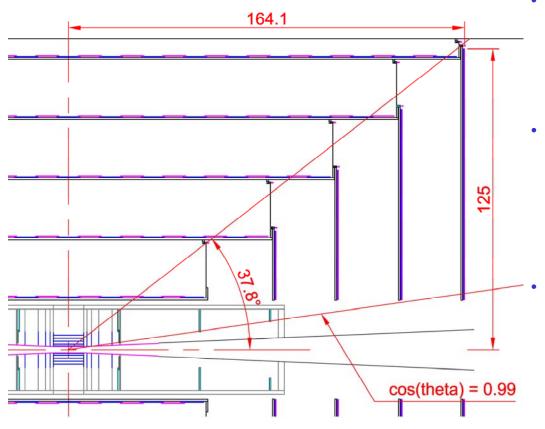




## **Tracker Mechanical Design**



- 5-Layer silicon strip outer tracker, covering R<sub>in</sub> = 20 cm to R<sub>out</sub> = 125 cm
- Barrel Disk structure: goal is 0.8% X<sub>0</sub> per layer



#### Support

- Double-walled CF cylinders
- Allows full azimuthal and longitudinal coverage

#### Barrels

- Five barrels, measure Phi only
- 10 cm z segmentation
- Barrel lengths increase with radius

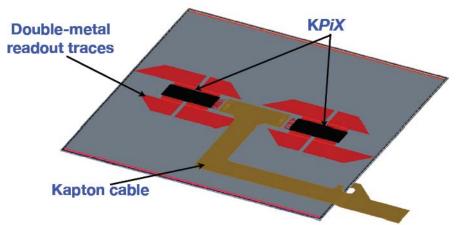
#### **Disks**

- Four double-disks per end
- Measure R and Phi
- varying R segmentation
- Disk radii increase with Z

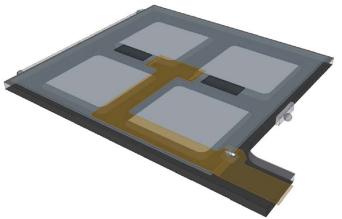
# Sensor and Module Design



- Hybrid-less design
  - 93.5 x 93.5 mm<sup>2</sup> sensor from 6" wafer with 1840 (3679) readout (total) strips
  - Read out with two asics (kPix) bump-bonded to sensor
  - Routing of signals through 2<sup>nd</sup> metal layer, optimized for strip geometry
    - Minimize capacitance and balance trace resistance for S/N goal of 25



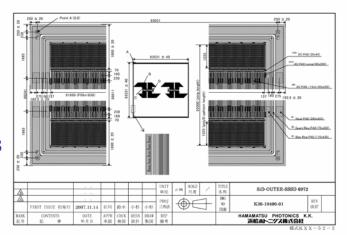
- Power and clock signals also routed over the sensor
- Module support
  - Minimal frame to hold silicon flat and provide precision mounts
    - CF-Rohacell-Torlon frame w/ ceramic mounts
    - CF-Torlon clips glue to large-scale supports
  - Ease of large scale production, assembly and installation/replacement
- Power pulsing for tracker allows for air cooling
  - Factor of >80 in power reduction
  - But have to deal with enormous Lorentz forces

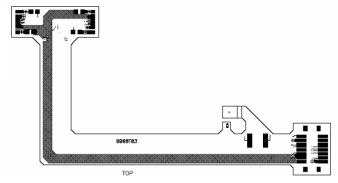


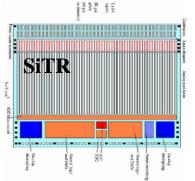
## **Prototyping Status**



- Sensors ordered from Hamamatsu; due May '08
- 64-channel KPiX-V5/6 in hand
  - ADC noise too high
  - KPiX64-V7 submitted to resolve noise issue
- Gold stud bump-bonding proceeding at UC Davis in collaboration with ECAL (sensors can also be wirebonded)
- Prototype pigtail cable design completed by Univ. New Mexico
  - ¼ oz. Cu on 50μm Kapton, 8mm width
  - 2 power+ground pairs, 8 control/ro lines
  - HV pair for sensor bias
- Ongoing studies of thin sensors
  - Purdue group 200μm thin Si, S/N>18
  - Fermilab thinned and laser annealed
- Alternative readout of sensors
  - UCSC, long shaping time, TOT
  - LPNHE/Paris, SiTR chip, 130 nm, 128 channels
- Double-sided silicon options pursued by Korea
- A lot of room for collaboration and additional studies



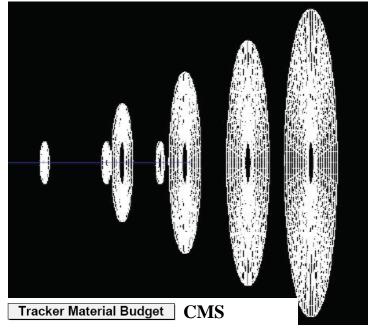


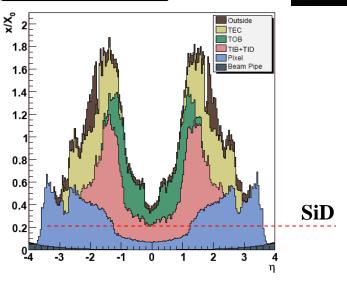


### **Forward Tracker**



- Barrel cylinders capped by CF-Rohacell forward disks
- Design rather conventional, analogous to designs for other detectors (LHC)
- Close attention paid to one serious shortcoming of existing designs: material budget
- Still many outstanding issues:
  - Tiling
  - Readout segmentation
  - Applicability of double-sided silicon
  - Robustness of pattern recognition
  - Integration of very far forward disks
  - Services and cable plant
  - Power pulsing and Lorentz forces
- Needs input from simulation!
- Plenty of room for contributions!

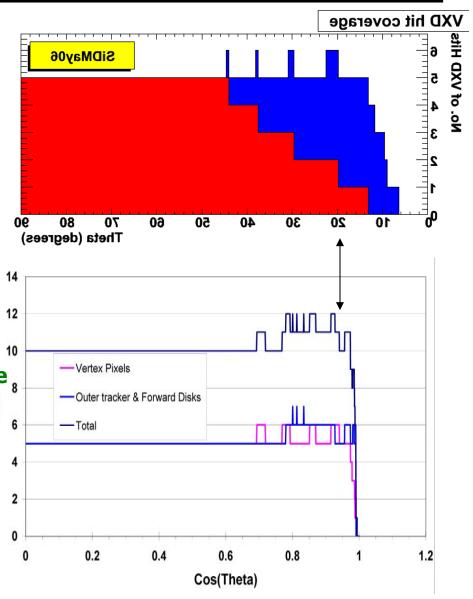




### **Simulation Studies**



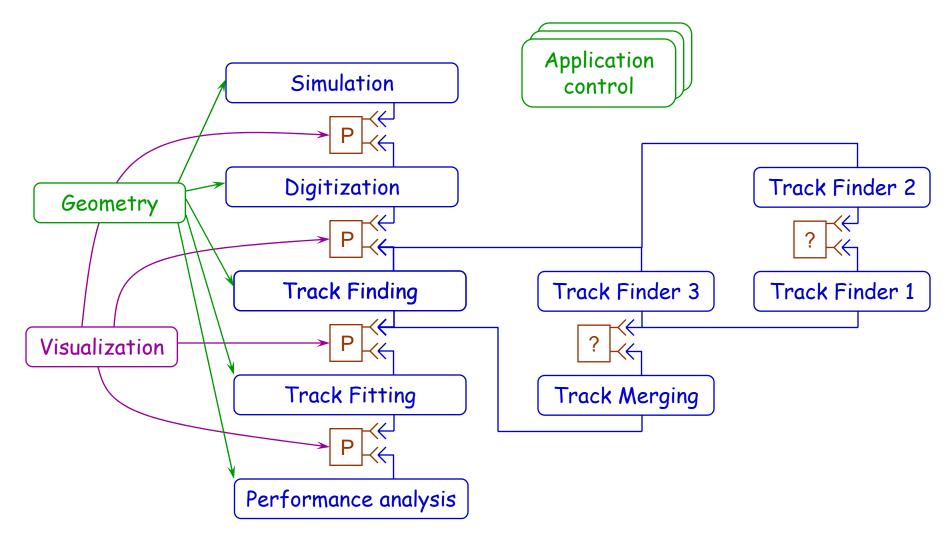
- Uniform coverage up to angles of 11<sup>0</sup>
  - Full coverage of 5 VXD hits and 5 OT hits up to |cosθ|~0.98
- Thus, baseline geometry exists
- Design now needs to be "benchmarked" and optimized
- Ideally, the design optimization is an iterative process:
  - Start from a baseline design and understand its performance
  - Perform variations on the baseline to establish "performance derivatives"
  - Establish new baseline design with improved performance
  - Repeat until you achieve convergence



# **Tracking Toolkit**



Tools required:

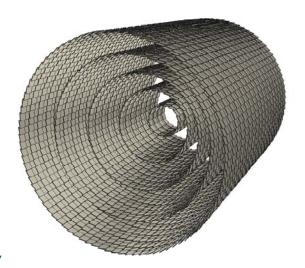


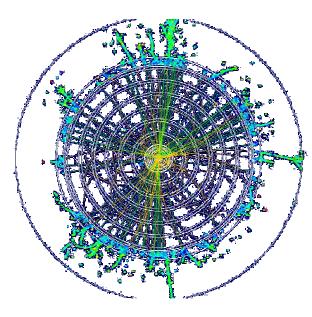
from: D. Onoprienko

# **Tracking Toolkit Inventory**



- Detector modeling
  - Complete barrel and disk geometry available
    - Poly-hydra geometry definition
    - Virtual segmentation
  - Output is a "hit"
- Digitization
  - Complete simulation of charge deposition in vertex pixels (ccd) and strips available
  - Output is clustering of hits to form "tracker hits"
    - Ghosting still an issue
- Track finding algorithms
  - Vertex seeded tracking (complete)
  - Conformal mapping algorithm (complete)
  - Stand alone outer tracking (in progress)
  - Calorimeter seeded tracking (complete)
- Track fitting algorithms
  - Weight matrix
  - Kalman filter
  - Fast helix finder for track finding





## **Optimization Process**



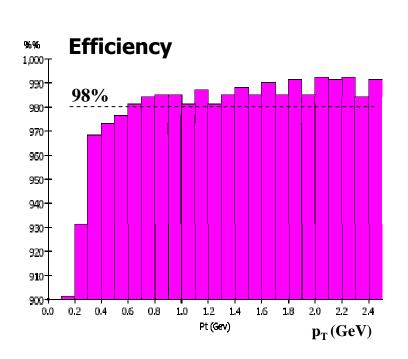
- Generally two metrics used:
  - Traditional metric: efficiency, coverage, resolution, fake rate, ...
  - Physics metric: benchmark processes, integrated detector performance (PFA); receives non-uniform weight
- Caveat Emptor: this only works if
  - Your performance metrics are relevant to the ILC physics program
    - Danger #1 optimize for an irrelevant physics benchmark
    - Danger #2 fail to optimize for the actual requirements needed at the ILC
  - Your simulation tools are sensitive to the design variations that will ultimately improve performance
    - Danger #3 the simulation tools, not the detector design, limit the measured performance
    - Danger #4 the level of simulation modeling is too coarse and misses important effects
  - Your backgrounds and hardware performance requirements are realistic
    - Danger #5 backgrounds will be worse than expected
    - Danger #6 hardware problems will not allow simulated performance to be achieved
- Important to retain / demonstrate "performance contingency"

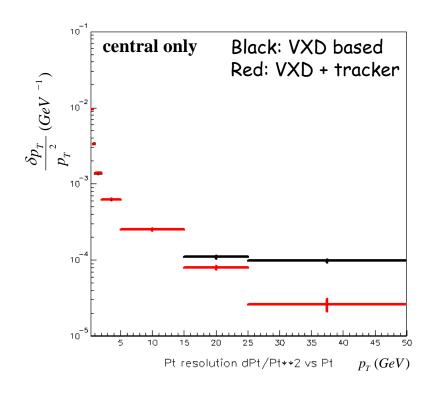
From: R. Partridge

### **Performance**



- Vertex detector seeded pattern recognition (3 hit combinations)
  - ttbar-events, full detector simulation and digitization, √s = 500 GeV,
    background included
    - Efficiency and purity for prompt tracks is good
      - Fake rate <1%; all forward and at low p<sub>T</sub>
    - Momentum resolution for central region only
    - Tracks with p<sub>T</sub> < 200 MeV difficult in presence of backgrounds

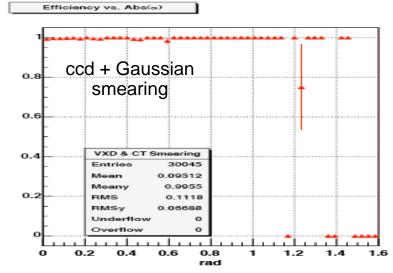


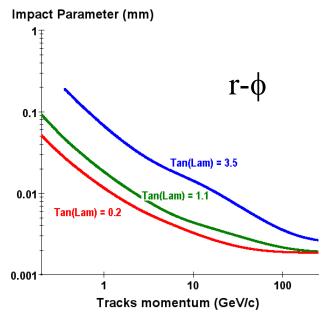


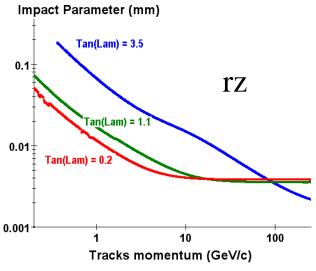
### **Performance**



- Vertex Seeded Tracking
  - Pick three hits in vertex detector and fit helix, pick up hits in outer tracker
- Impact parameter
  - Resolution in  $r\phi$  (rz) plane asymptotically approaches  $\sim 2\mu m$  (4 $\mu m$ ) in the limit of high  $p_T$
- Tracking in dense environment
  - qqbar events at  $\sqrt{s}$  = 500 GeV
  - Central region only, realistic ccd simulation
    - Angle with respect to Thrust axis,  $\boldsymbol{\alpha}$



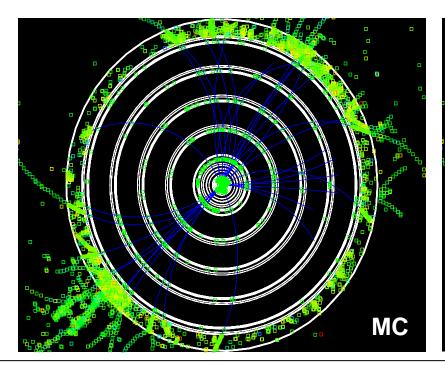


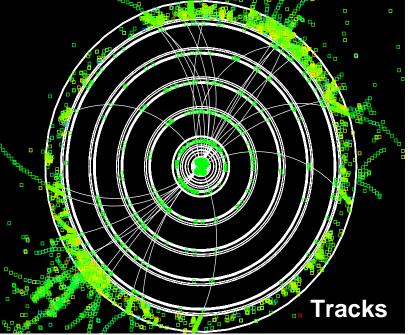


### Performance Seedtracker



- Seed Tracker Algorithm:
  - Form track seed candidate by picking 3 hits from the seed layers and fit seed candidate to determine helix
  - Confirm seed candidate by looking for hits in confirm layers
  - Extend seed candidate by looking for hits in extend layers
  - Eliminate duplicates
- Example for  $Z \rightarrow qqbar$  at  $\sqrt{s} = 500$  GeV, Layers 3,4,5 seed layers

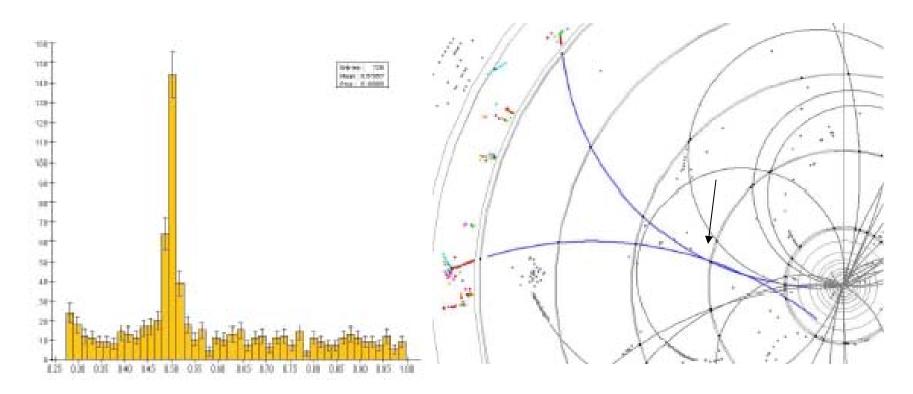




# **Calorimeter Assisted Tracking**



- With a fine grained calorimeter, can do tracking with the calorimeter
  - Find MIP stubs in the calorimeter, extrapolate them into tracker, picking up hits to capture events that tracker pattern recognition doesn't find
  - Can be used to reconstruct long-lived particles:  $K_s^0$  and  $\Lambda$  or V's in general
  - In a sample of simulated Z-pole events: reconstruct  $\sim\!61\%$  of all charged pions with transverse momentum above 1\_GeV, produced by  $\rm K^0_s$



### Help!



- Not all tools in hand yet, notably full track fitting
- Performance characterization not started within fully consistent platform
  - Single particle response
  - Physics processes
- Optimization process not really started
  - Number of layers
  - Long barrels versus short barrels
  - Endcap layout and tiling
  - Segmentation and need for double-sided sensors
- Benchmarking studies
  - Pick your plot
  - e.g. efficiency versus purity for b-jets, c-jets, light quarks
  - Higgs branching ratios
  - ...

# **Summary**



- More work than people to do the work
- Characterizing the performance of the design in the traditional metric has just started; physics metric barely touched, let alone optimization of design
- The problems are challenging and some are rather generic
  - Applicability beyond the ILC
  - Technology issues that apply to other projects
- SiD welcomes new participation in all areas, but especially in the area of benchmarking and simulation!

