

Detailed simulation of Silicon tracking system for Linear Collider

**International Workshop on Linear Colliders 2010
(ECFA-CLIC-ILC Joint Meeting)**

**Frederic Kapusta presenting on behalf
of
Alexandre Charpy
& Konstantin Androsov**

LPNHE - Paris

Silicon Tracking System

SiLC Goal

Goals of the SiLC (Silicon Tracking for Linear Collider) collaboration

- Optimisation studies of the geometry of the silicon trackers
- Access to different sensors and electronics technology
- Develop a tool to facilitate the optimisation studies
- Provide drivers for ILD concept and CLIC detectors

Main ideas

- Generate different kind of geometry very easily (number of silicon layers, false/true double-sided, technology ...) → dynamic aspect
- Possibility to introduce mis-alignment studies according a mechanical structure
- Materiel budget effects induce by the supports and the cabling
- Could be used in different framework

Silicon Tracking System

Code history

History

- Developing a silicon tracker through ILCRoot framework (2008)
First integration in the 4th concept
- Switch to Mokka framework (end of 2009) for a more detailed description of the ILD concept

- Re-design the design pattern in 2010 (more flexibility for CLIC study):

- Integration in different framework
- More flexibility = fewest fixed parameters
 - creation of sub-detector families
 - sub-detectors configuration
 - cross setup
- Different input

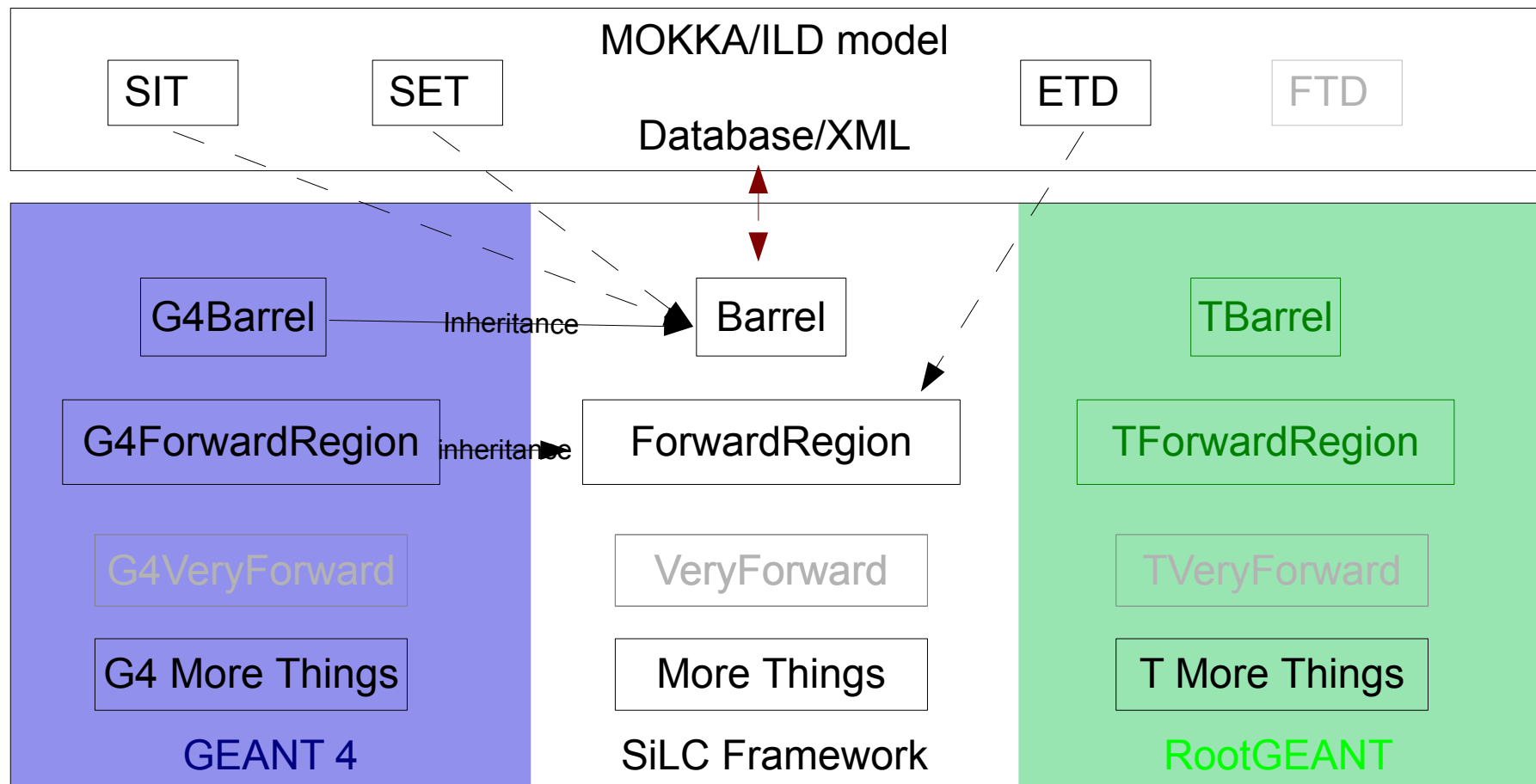
Available for ILD_01 release
Actually in MOKKA trunk version

Silicon Tracking System

Code description

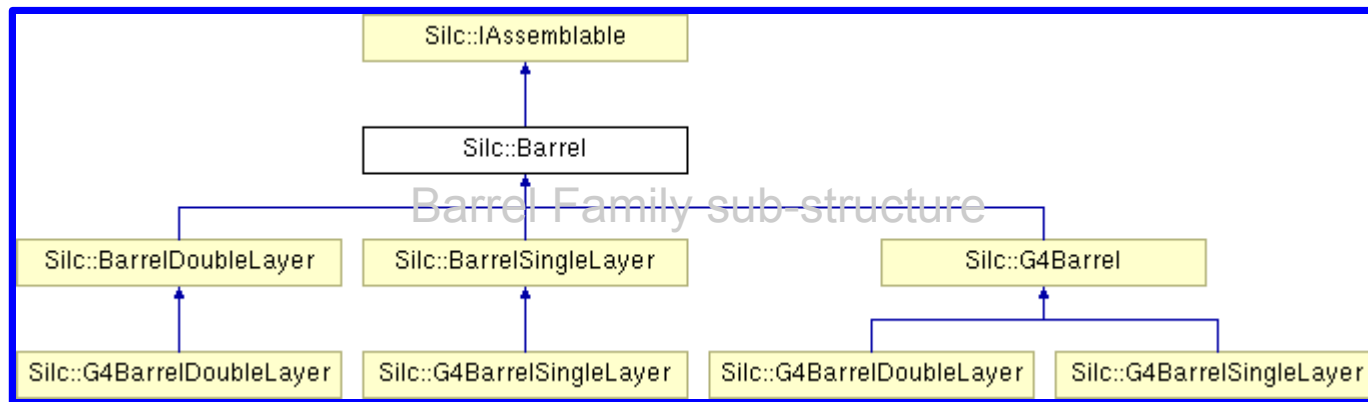
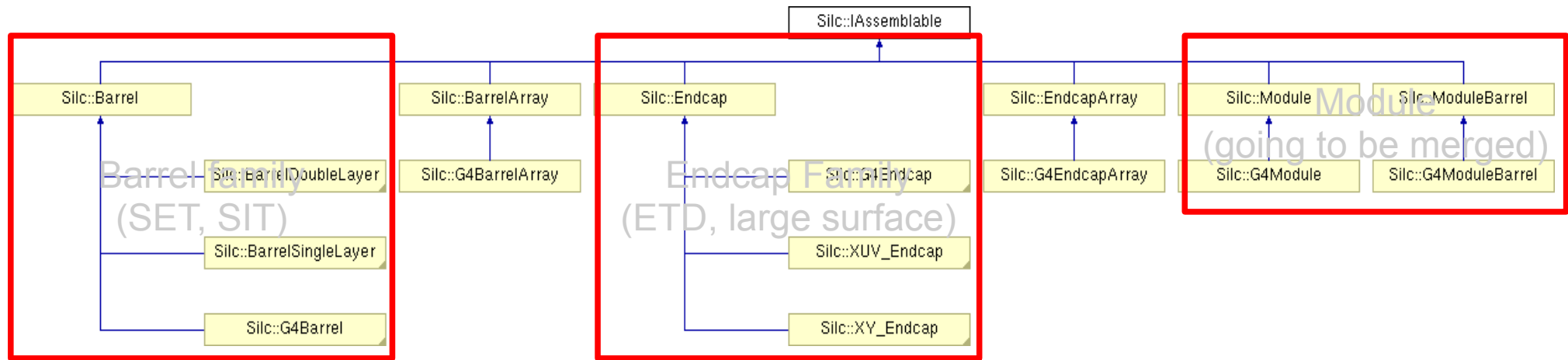
RootGeant and Geant 4 (ideas and plans)

- build independent classes
- can be extended
- connect it to the geometry builder according the framework
- possibilities to merge the concepts (example: use database and use Root Framework)

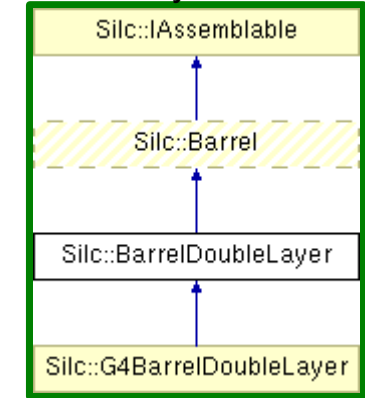


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Design Pattern – UML class diagram



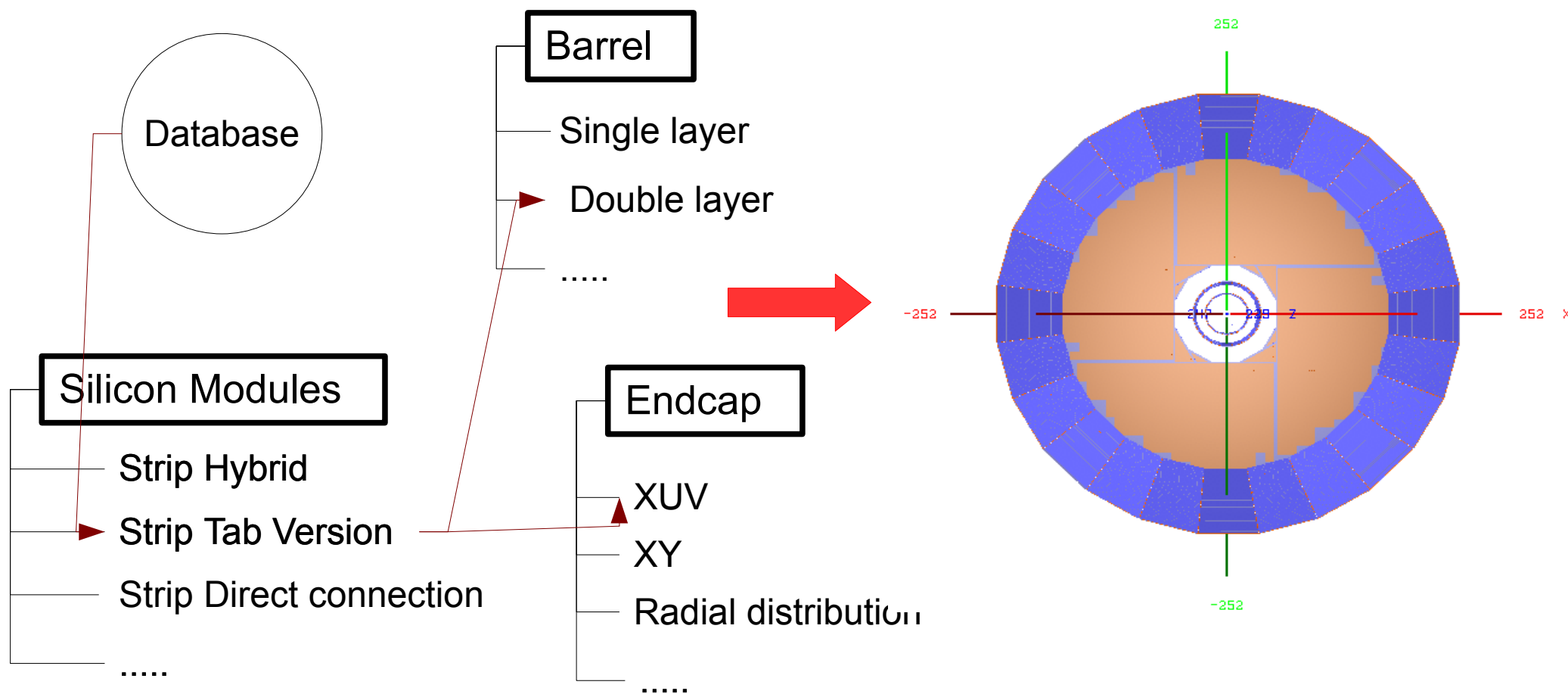
One cylinder
Double layer structure



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Interest of this complex structure

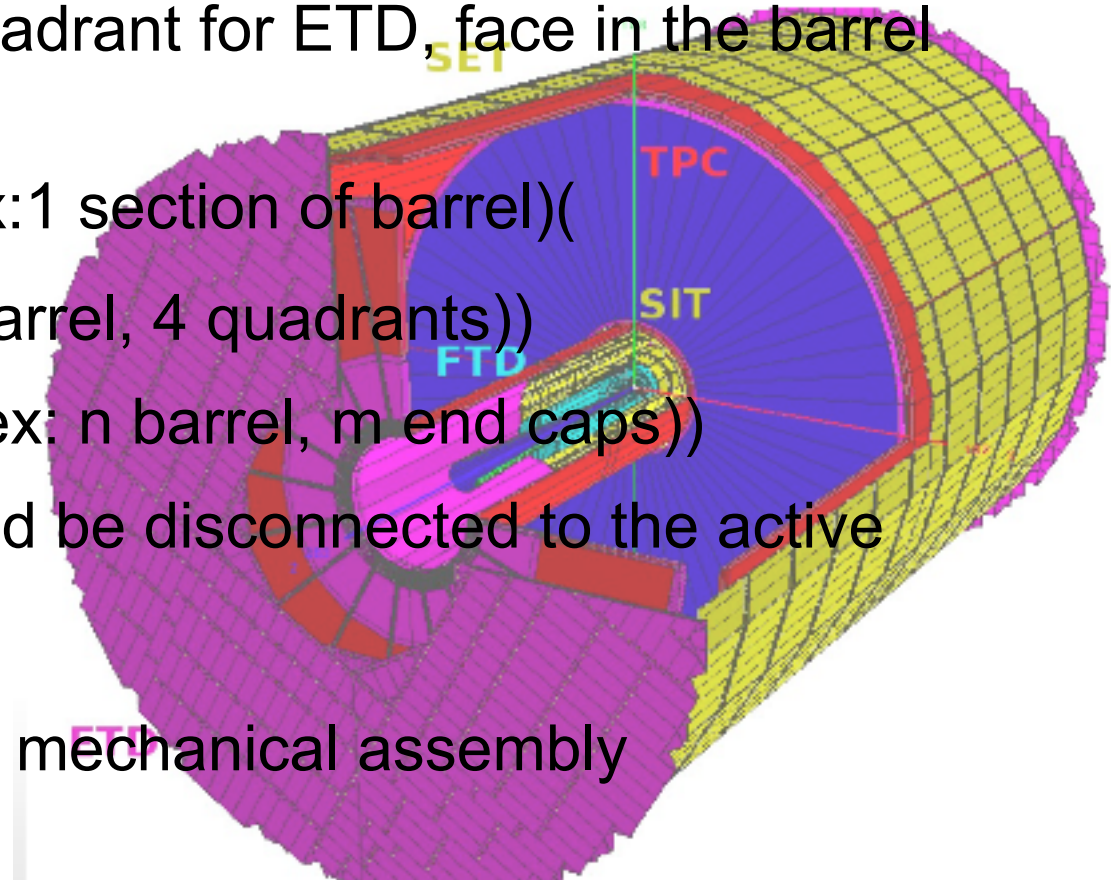
- Build the detectors from basic elements → LEGO game (pick up all the element requested by the user, checking the consistency and build the sub-detectors) = we add more flexibility



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Geometry builder – hierarchy with ILD example

- All “family” are built into a common hierarchy (generic name)
 - the silicon module
 - the super-module (ex: quadrant for ETD, face in the barrel region)
 - the detection element (ex: 1 section of barrel)(
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- Supports/cables builder could be disconnected to the active area for material budget effect
- Mis-alignment according the mechanical assembly

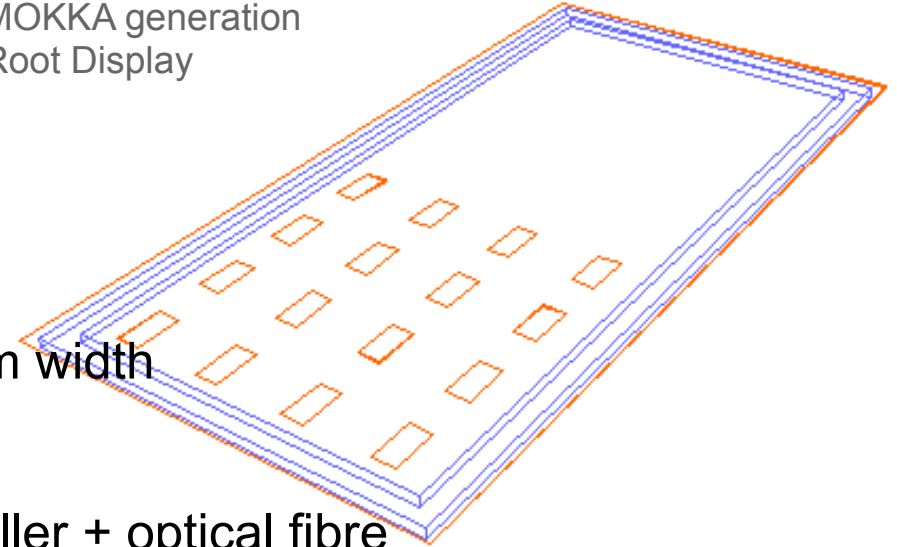


Example of Application ILD Concept

Silicon Tracking System

ILD Silicon Module Detector

Silicon module (1*2 sensors)
MOKKA generation
Root Display



- **Baseline**

- 100.12*100.12*200 mm²*μm
- Strip technology
- 50μm pitch (~2048 channels), 12;5μm width
- Edgeless
- Chips on board: SiTr130-128+ controller + optical fibre

→ A silicon module consists into n chained silicon sensors

- **GEANT 4 description**

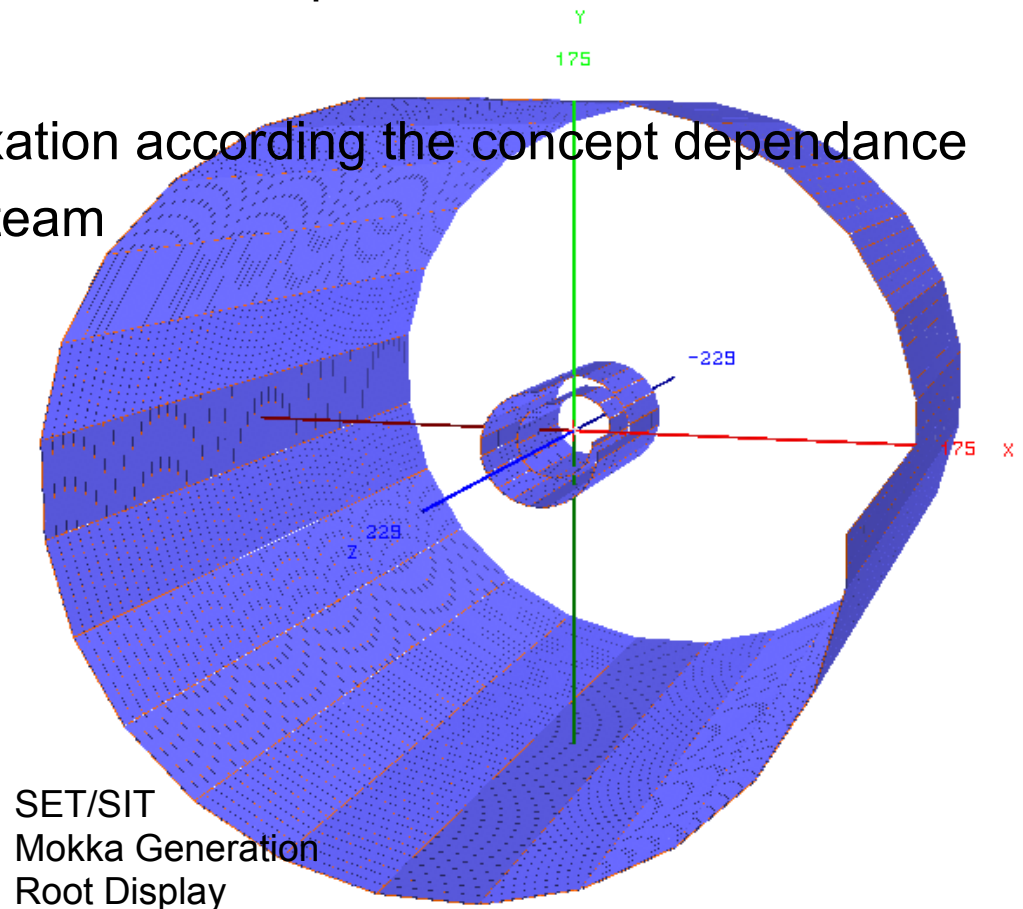
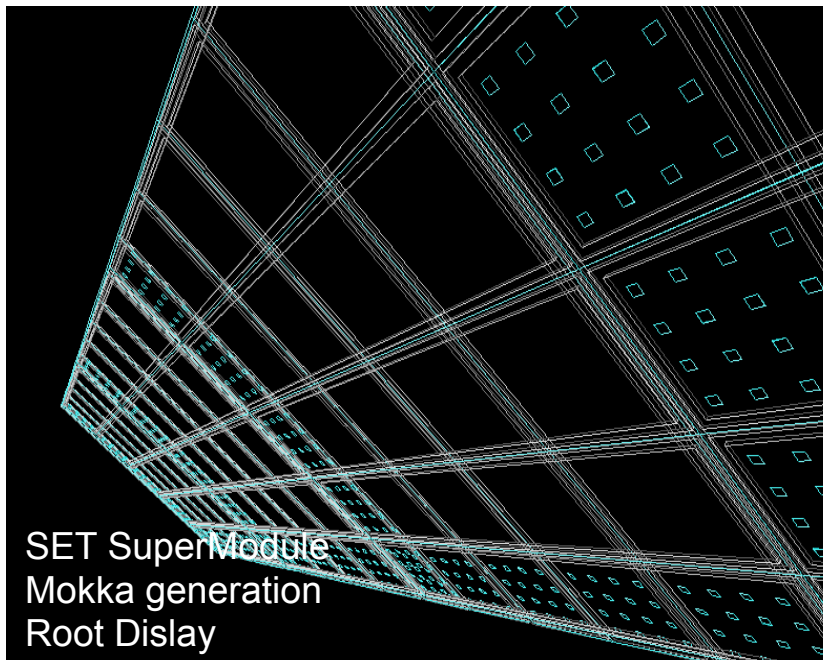
- Module size: 1*n sensors+50 μm gap
- The module segmentation and the sensors misalignment (rotation+shift) are included in the digitisation process
- Chip+controller included
- Support: graphite

Silicon Tracking System

ILD SIT/SET

- Geant 4 description:

- Using the edgeless properties
- false double sided strip detectors
- Gaps: 50 micron gap between modules, Super Module, Detection Element
- Support:
 - SET → partially defined/fixation according the concept dependance
 - SIT → waiting integration team

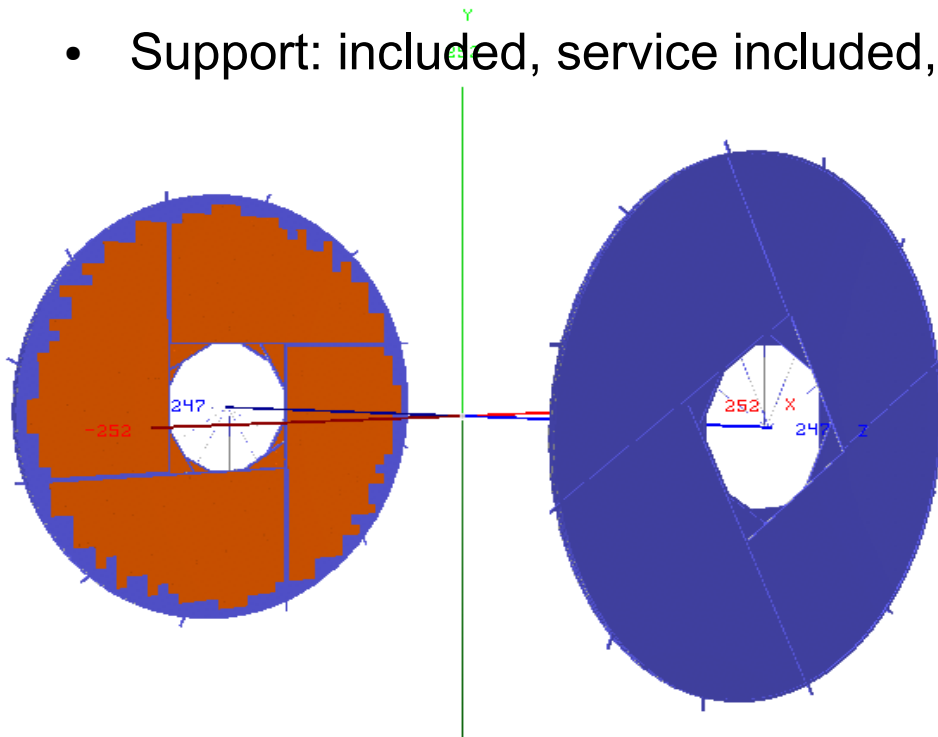


Silicon Tracking System

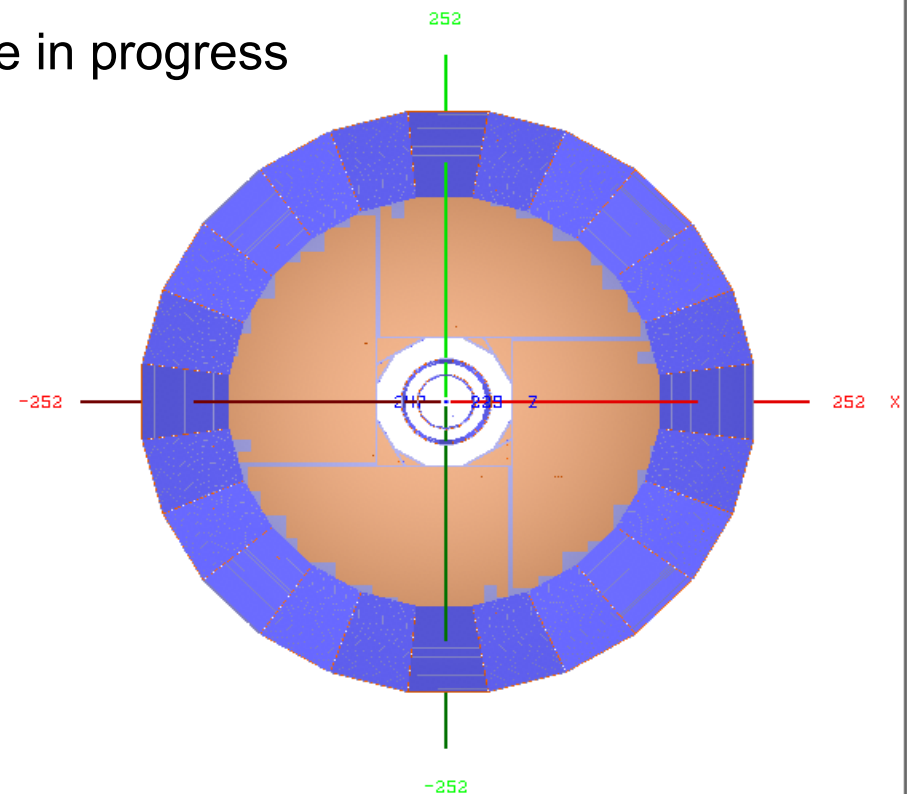
ILD ETD

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- Support: included, service included, cable in progress



A]



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Silicon Tracking System

Overlapping

Overlapping in the Silicon tracking components:

- checked through Root within 10 μm
- according the present status of the development

→ SIT, SET, ETD : ok

Overlapping with other detectors:

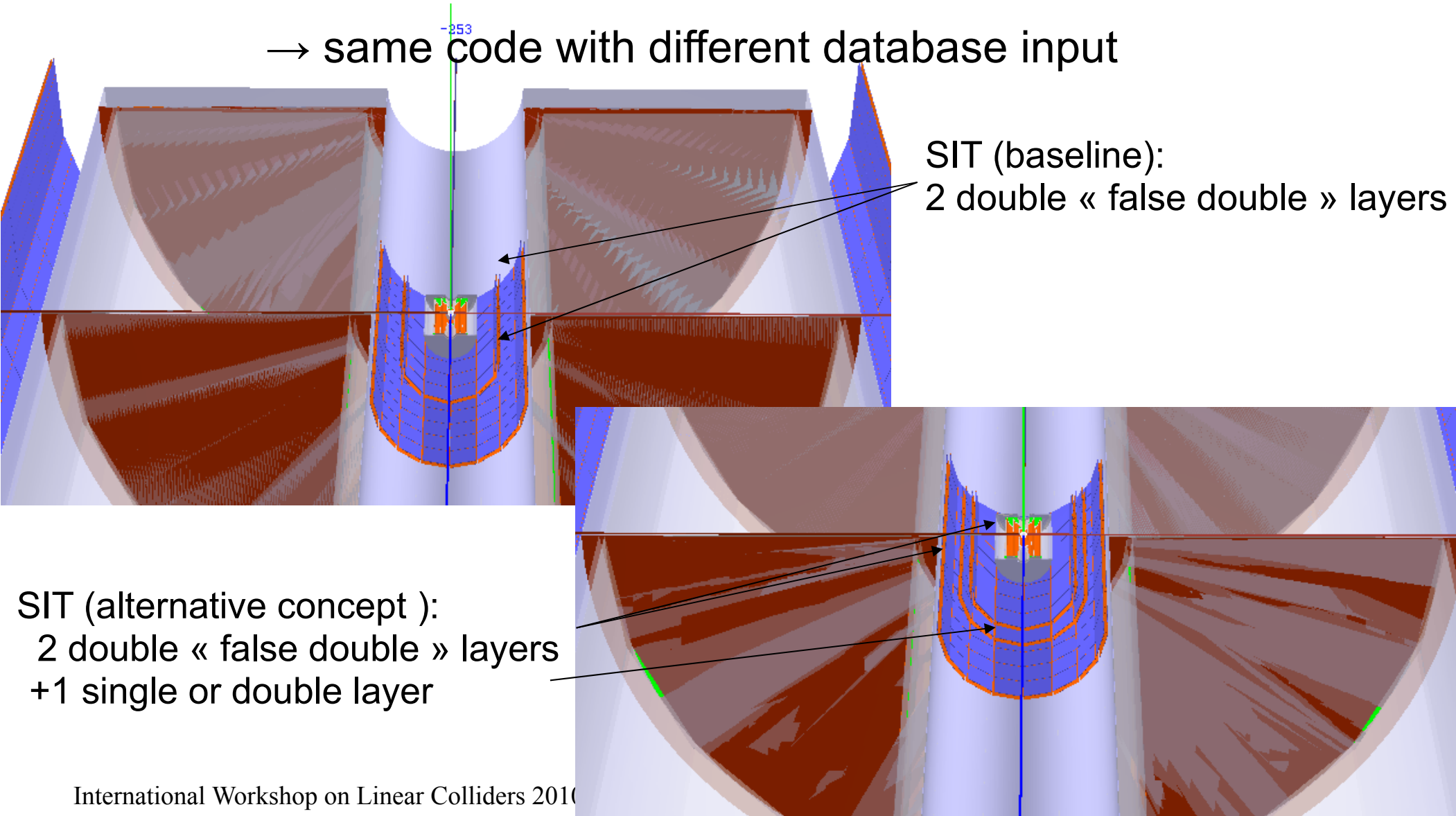
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- SIT/FTD → fixed
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Silicon Tracking System

Easy customisation

- Modification of the number of silicon barrels in the internal part of ILD

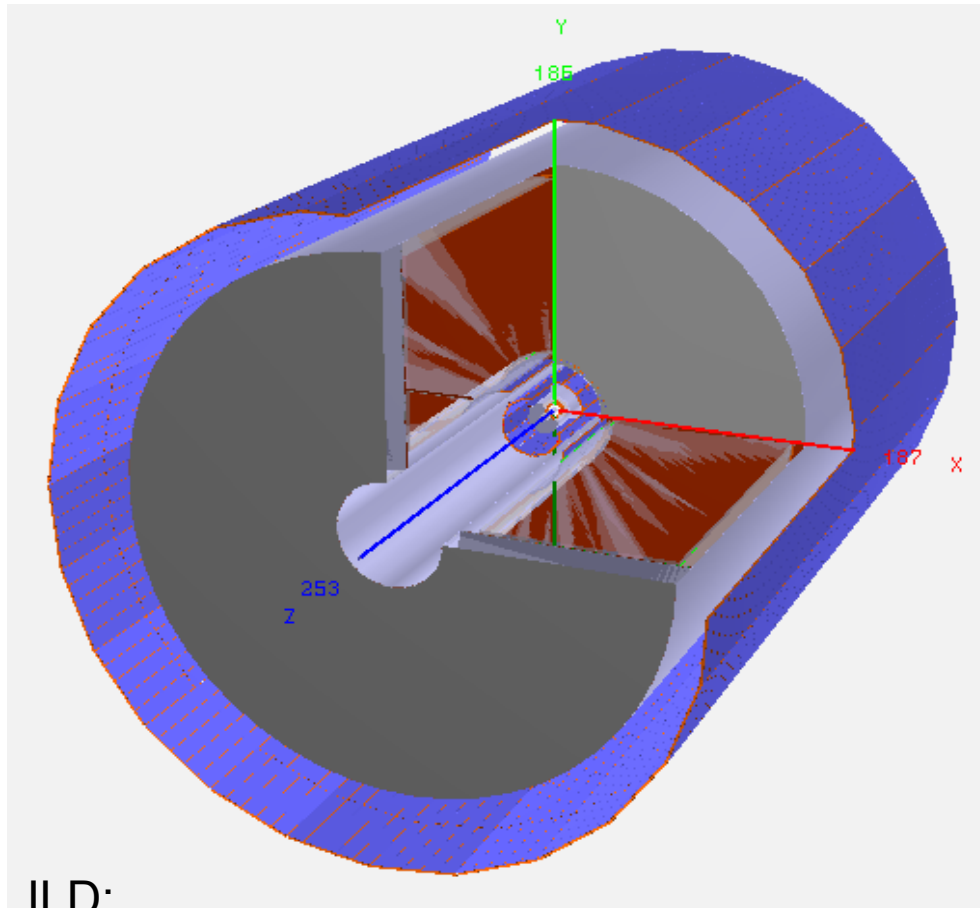
→ same code with different database input



Silicon Tracking System

Not only ILD – CLIC studies

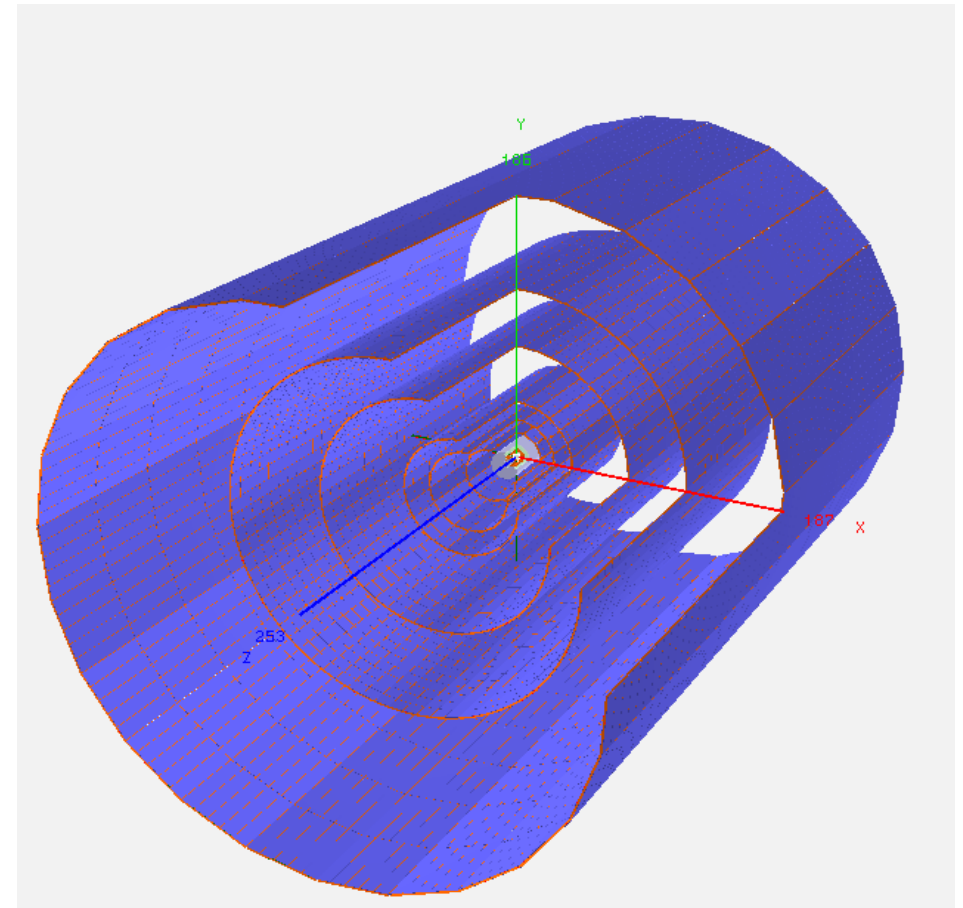
Full Silicon tracker: free to choose the shape and the sensor technologies for each layer :)



ILD:

VXD+SIT+SET+ETD+TPC

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VXD+7couches silicium

Alexandre.Charpy@lpnhe.in2p3.fr

Silicon Tracking System

Other Features

- Flexible parameters
 - Sensors and module sizes
 - Support type/activation
 - Module orientation (face to the beam, length along Z or orthogonal, module angle, shifting for coverage)
 - Sub-detector dimension and shape
 - Number of sub-detectors, of layers etc ...

sharing @models03 (Local)

Grid View Form View Image Text Hex Filter Wizard Import Wizard Export Wizard

driver	parameter	driver_default_val
driver	parameter	driver_default_val
sit	sit_barrel_module_direction_angle	90;0;90;0
sit	sit_barrel_support_type	sit_ild01;sit_ild01
sit	sit_barrel_sensor_technology	SD;SD;SD;SD
sit	sit_barrel_module_support_type	sit_ild01;sit_ild01
sit	sit_barrel_sensor_nb_channels_x	1;1;1;1
sit	sit_barrel_sensor_nb_channels_y	2048;2048;2048;2048
sit	sit_barrel_sensor_pitch_y	0.05;0.05;0.05;0.05
sit	sit_barrel_sensor_width_x	96;96;96;96
sit	sit_barrel_type	DoubleLayer;Dout
sit	sit_barrel_module_gaps_y	0.05;0.05;0.05;0.05
sit	sit_barrel_radial_adjust	expand;shrink
sit	sit_barrel_length	642; 1290
sit	sit_barrel_sensor_width_y	0.0125;0.0125;0.0125;0.0125
sit	sit_barrel_support_enable	true>true
sit	sit_barrel_z_position	0.;0.
sit	sit_barrel_module_face	0;180;0;0
sit	sit_barrel_module_rotation_psi	0;0;0;0
sit	sit_barrel_module_support_edge	5;5;5;5
sit	sit_barrel_module_support_width	10;10;10;10
sit	sit_barrel_module_support_thickness	2;2;2;2
sit	sit_barrel_shape	cylinder;cylinder
sit	sit_barrel_nb_face	0;0
sit	sit_barrel_radius	179.2;287.7
sit	sit_barrel_nb_layers	2;2
sit	sit_barrel_longitudinal_adjust	expand;expand
sit	sit_barrel_nb_sections	1;1
sit	sit_barrel_symetry	true>true
sit	sit_barrel_sensor_dim_x	96;96;96;96
sit	sit_barrel_module_rotation_theta	0;0;0;0
sit	sit_barrel_module_rotation_phi	0;0;0;0
sit	sit_barrel_module_support_enable	true>true>true>true
sit	sit_barrel_sensor_pitch_x	0;0;0;0

MOKKA DB - ILD01

update 'models03'. 'sharing' set 'driver_default_value'='0;180' wh

Record 291 of 1000 in page 1

Present status

What is done:

- The design pattern is frozen
- The module distribution is done → gap and basic support included

Tasks priority:

- complete the integration in Mokka and the ILD concept → sub-detectors dependency in progress (depend of TPC)
- Hits management with derivated TRKSD00 class – debugging progress
- write the GEAR part according the interface provide by A. Munich and depending the reconstruction request (S. Aplin)
 - “old” GEAR version: hope end of this week
 - new GEAR (into two weeks)
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Mémo:

General SiLC goal => R&D for new technology of
Silicon Tracking system

- R&D senseurs silicium
- R&D Front-End Electronic

Physics Goals:

- optimisation of the silicon tracker sub-detectors
(momentum, tagging etc...)

=> need a tools to create easily new geometry
configuration without writing long piece of code

=> completion fast/slow simulation easier

=> provide code and configuration for detector
concept (ILD, ex4th, CLIC ...)

SiLC develop a code in this purpose with these main
ideas

Silicon Tracking System

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History of this task

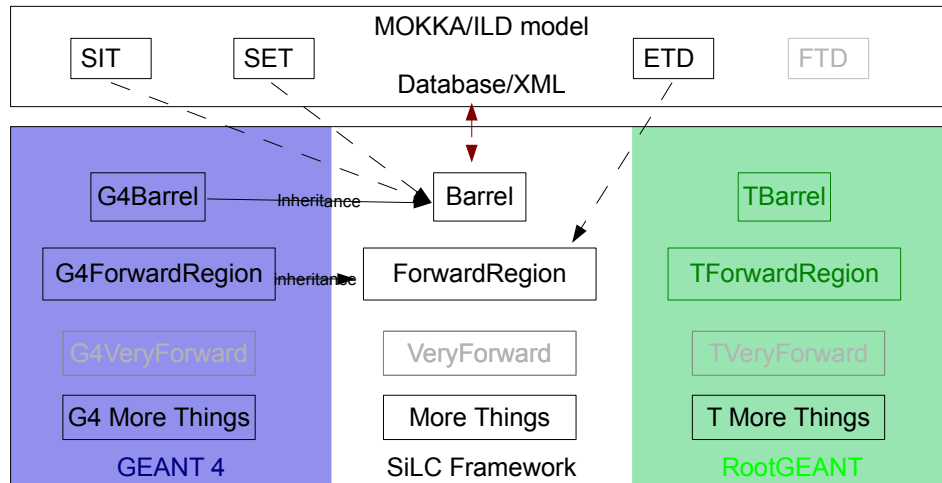
- start in 2008 with ILCRoot (for 4th concept – see if we can use this framework rapidly – it was true :))
(from AliRoot-> meaning natural transition to learn about linear collider)
- in 2009, drivers incomplete for ILD → decide to transfer the code into GEANT 4/ MOKKA – transition
- CliC consideration => give a more flexibility => meaning independence (as much as possible) to the framework (G4, RootGeant), dynamics parameters – philosophie: “forbid” the fixed parameters

Silicon Tracking System

Code description

RootGeant and Geant 4 (ideas and plans)

- build independent classes
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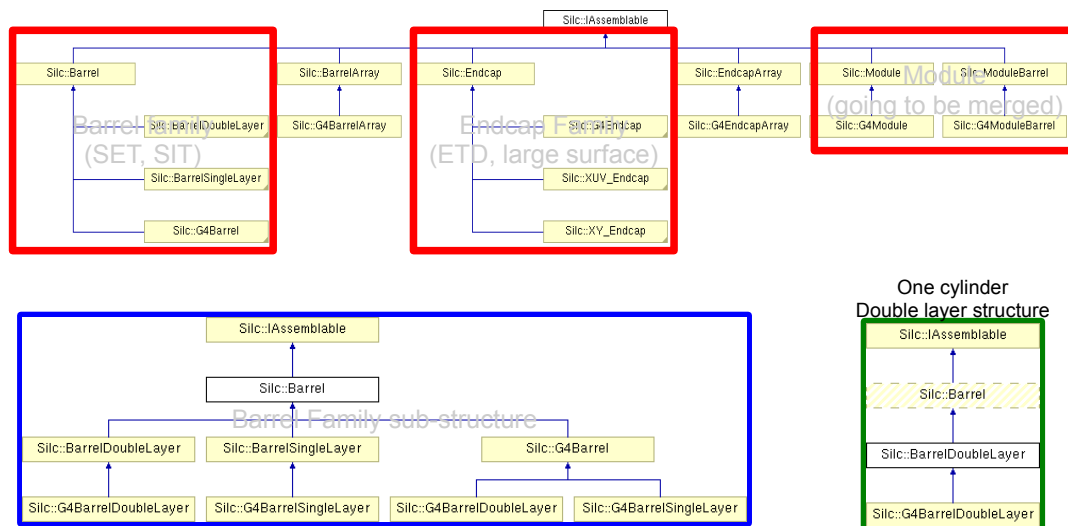
In this purpose:

(vertical lecture)

- starting point MOKKA DB or XML
 - drivers calls
 - use "independent" class to create and check the consistency of the configuration
 - call the geometry class for the geometry builder
- (horizontal lecture)
- Creation of family of sub-detectors according their surface and the physics region (barrel, forward, very forward etc ...)
 - could add more family very easily → because template for the construction

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Design Pattern – UML class diagram



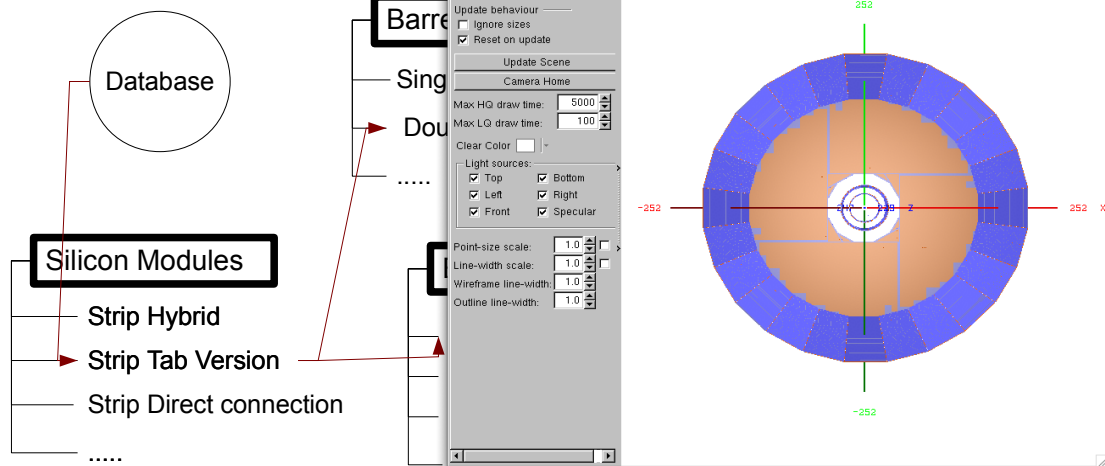
UML diagram: flexibility and modularity mean code abstraction and more complicated to write one class for the geometry (ex ETD00, ETD01 now it is the same code for every version).

- red line: "family" → Barrel with SET/SIT for ILD concept
- each configuration are store in a table of container => each barrel, endcap etc or store inside → persitency of the configuration and Geant object and ease to get back all information (example: volume position, gear etc ...)
- in blue: structure of one family: example: single of double layer structure for one "barrel"
- in green: inheritance of one object (ex: G4barrelXX inherit of BarrelXX inherit of virtual class Barrel inherit of lassemble object

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Interest of this complex structure

- Build the detectors from basic elements → LEGO game (pick up all the element requested by the user, checking the consistency and build the sub-detectors)



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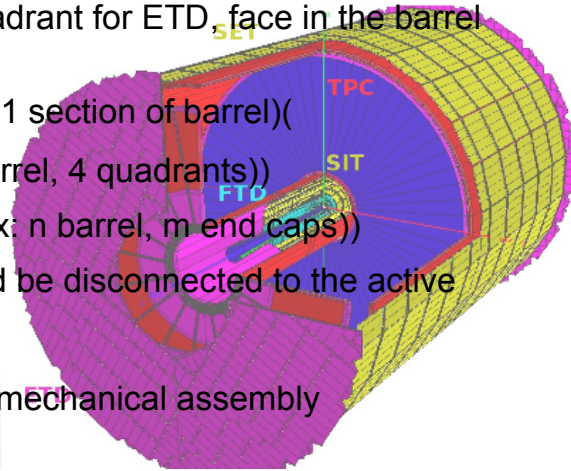
Why more flexibility:

- instead of to store one drivers for one sub-detectors configuration, we propose a kind of lego game or “cooking”.
- from the DataBase we enter the ingredient we wish:
 - I want a full silicon tracker → automatic generation
 - I want an envelop of silicon composed of one 8-Pgon barrel, with one XUV encaps both equipped with active edge sensor with tab configuration (layer of silicon sensor – Kapton – electronics)
 - the drivers pick up all the class needed to build this configuration

Silicon Tracking System

Geometry builder – hierarchy with ILD example

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 - the silicon module
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- Mis-alignment according the mechanical assembly



To offer this modularity we need a predefined structure:

→ here are enumerate of a subdetectors is build → 5 steps

→ the independancy of the support, cabling etc ...

There is example according the ILD concept..

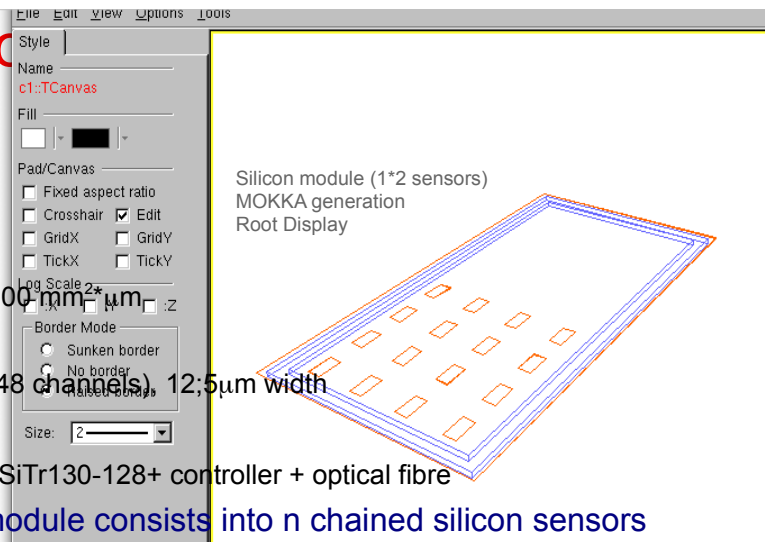
Example of Application ILD Concept

Now application for ILD concept

Silicon ILD

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- Strip technology
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- GEANT 4 description

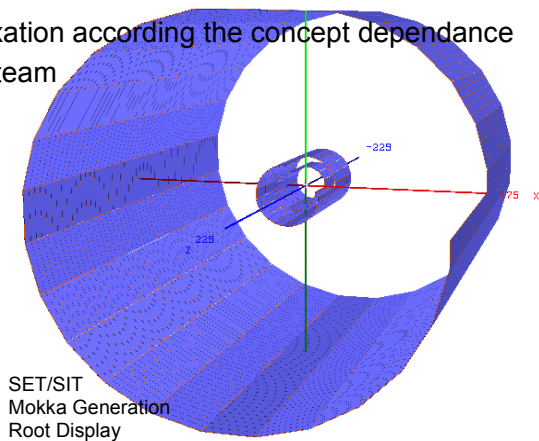
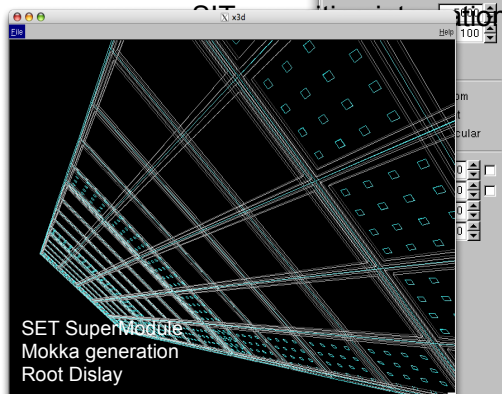
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Silicon Tracking System

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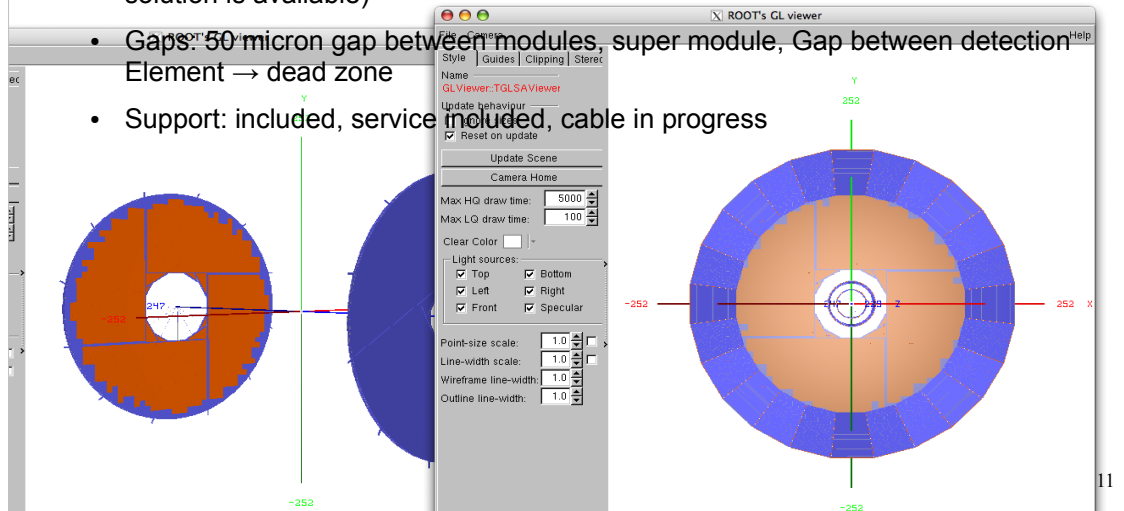


Silicon Tracking System

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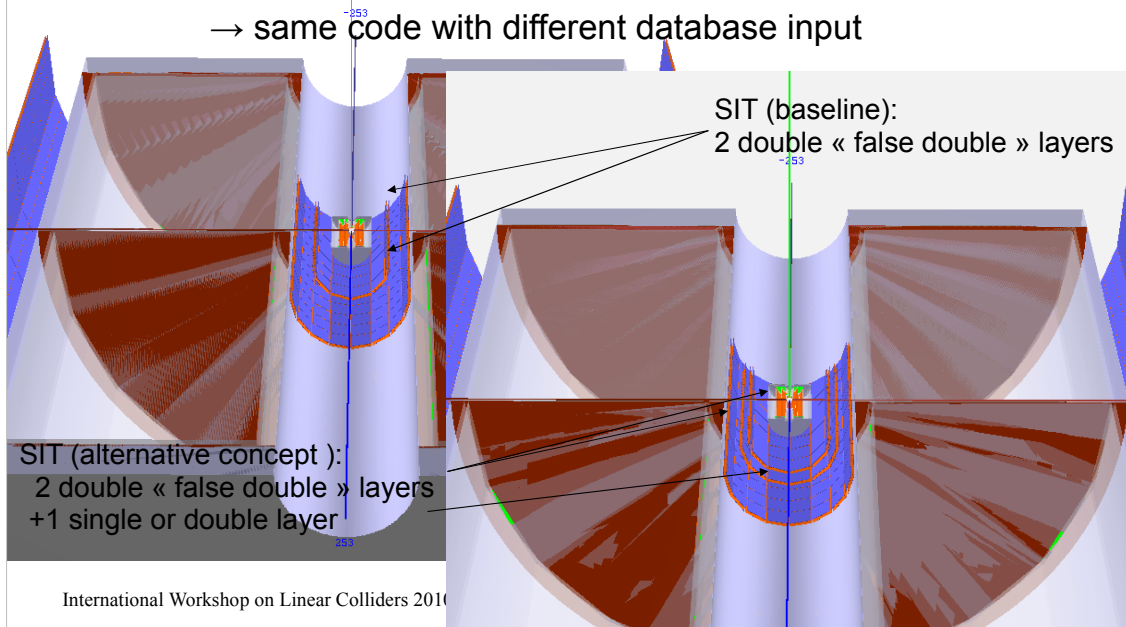
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Silicon Tracking System

Flexibility in configuration

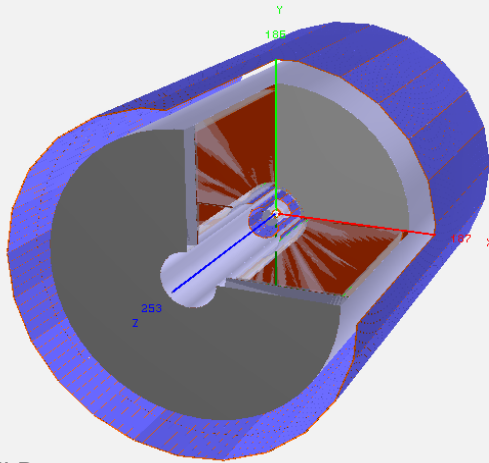
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Silicon Tracking System

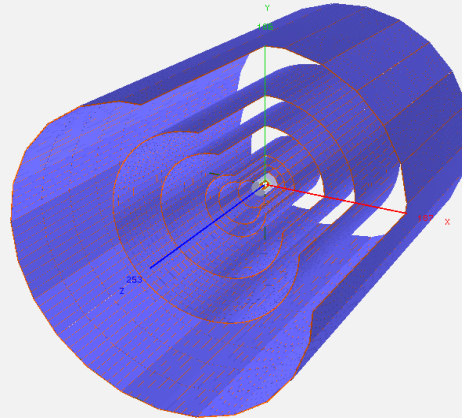
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the shape and the sensor



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VXD+SIT+SET+ETD+TPC

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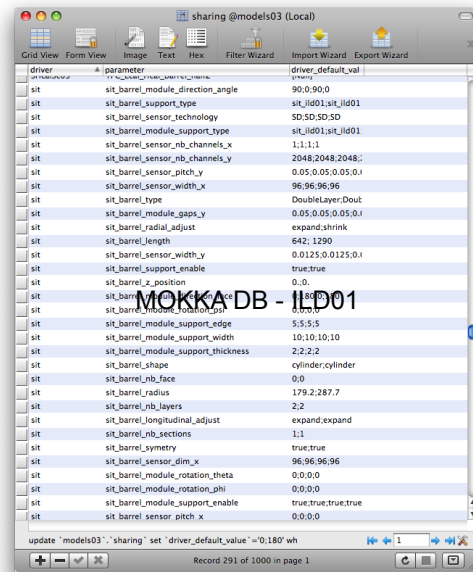
VXD+7couches silicium

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Silicon Tracking System

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