



In search of nc/sc common themes: Working group 3 and 4 joint session



Objective



I will select aspects of CLIC rf structure work for which I believe are common to both our projects and for which we could potentially establish some kind of joint activities.

I hope that during the discussion we can expand on the list, and find a way to establish some joint activity after the workshop.





We need to cross the grain boundary



The list



- 1. rf computation
- 2. Damping materials
- 3. Simulation of high-power effects
- 4. Surface preparation and assembly procedures
- L-band technology and power sources (covered in next session)



rf computation



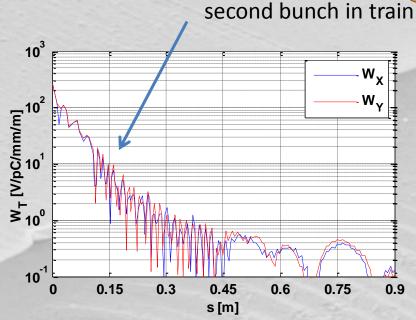
- 1. HOM suppression
- 2. linac/rf optimization
- 3. Advanced computation



HOM suppression in accelerating structures







Bunches sit at a six fundamental mode bucket separation so the transverse wakefield suppression needs to be very fast. Equivalent Q's are below 10 (some help from detuning) and every cell is "waveguide" damped.

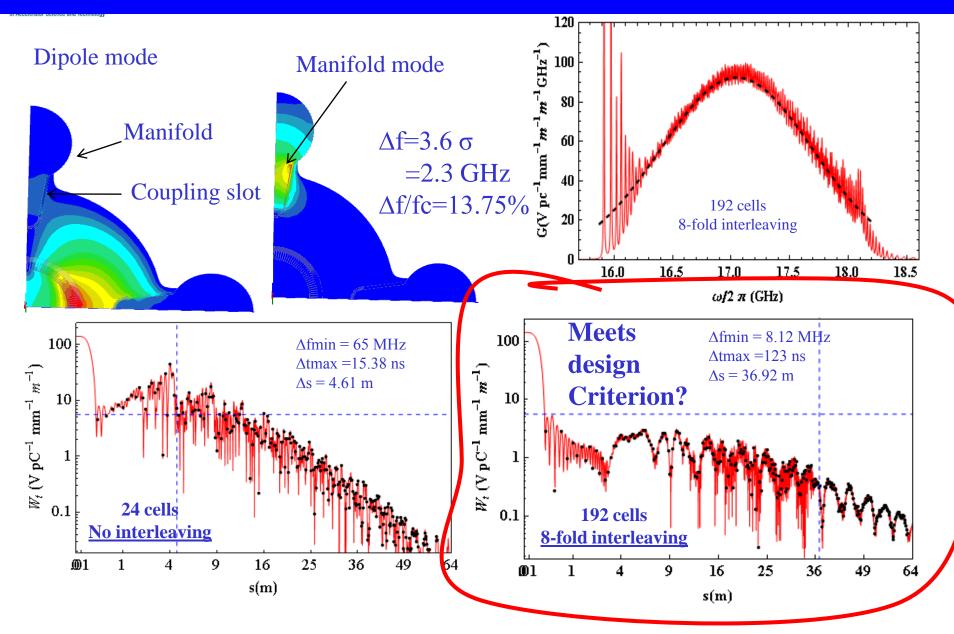
We have very strong beam-structure coupling, for efficiency, so the suppression also has to be very deep. Roughly factor 50 by second bunch.



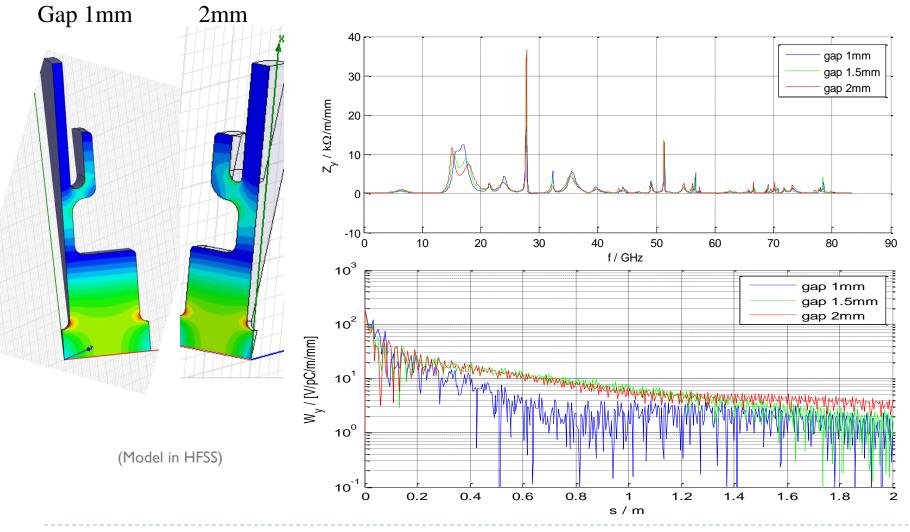


Pursuit of alternatives – potential for better performance or lower cost

2.3 Summary of CLIC_DDS_C



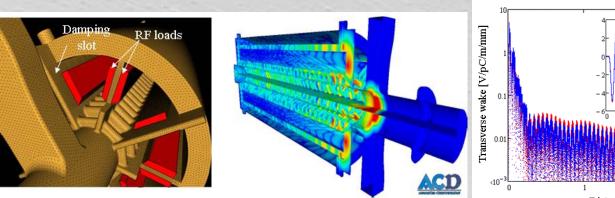
Wake field simulation with Gdfidl

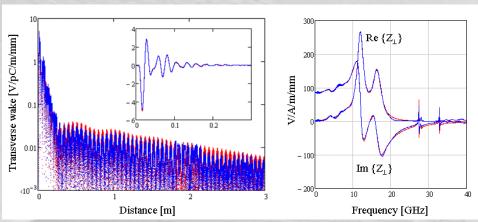




HOM suppression in PETS



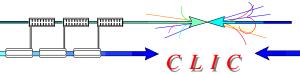




Very low impedance environment (a/ λ =0.46) but bunches sit at every fundamental bucket and the current is 100 A. The drive beam is not a low emittance beam but it is important that instabilities are not amplified by structure resonances – especially when the drive beam is at low energy. Hence specification on effective Q's in HOM spectrum from beam dynamics.

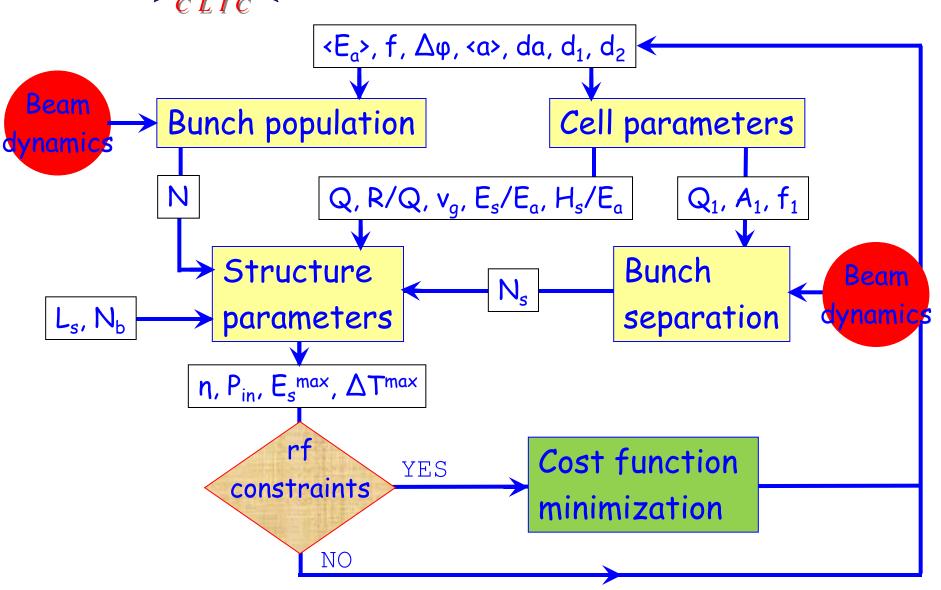
Single bunch transverse wake specification < 8 V/pC/mm/m.

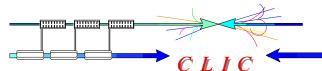
Overmoded structure so transverse wake also at fundamental frequency – damping by symmetry.



Optimization procedure







Beam dynamics input





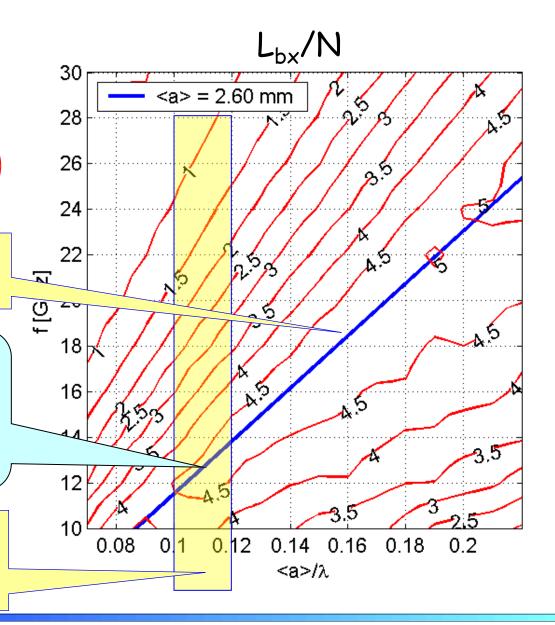
 $\left(\mathsf{BD}\right)$



BD optimum aperture: <a> = 2.6 mm

Why X-band?
Crossing gives
optimum frequency

High-power RF optimum aperture: $\langle \alpha \rangle / \lambda = 0.1 \div 0.12$





Advanced computation



The traditional rf computation tools of the CLIC team have been HFSS and GdfidL and they continue to remain the backbone.

We are now incorporating ACE3P. We do this since it appears to be state-of-the-art accuracy, essential for the really big problems like two-beam acceleration and extendable to issues like breakdown modeling.

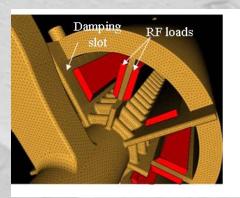
People are learning how to use it and we are working through the associated issues – like access to computational time etc.

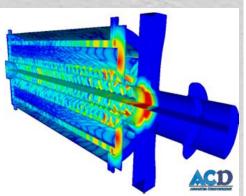
Collaborations are leaders in this activity – SLAC of course but also Oslo University (Eric Adli and Kyrre Sjoebaek) and PSI (Micha Dehler).

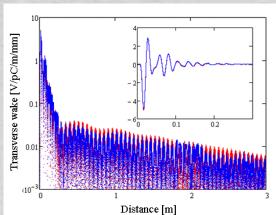


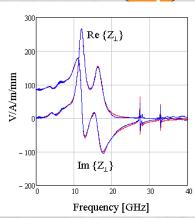
Advanced computation



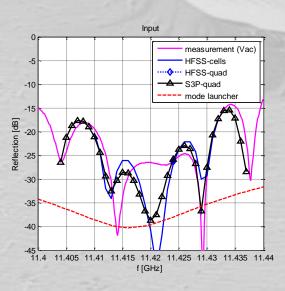


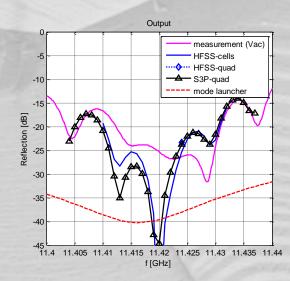






GdfidL ACE3P comparison in PETS

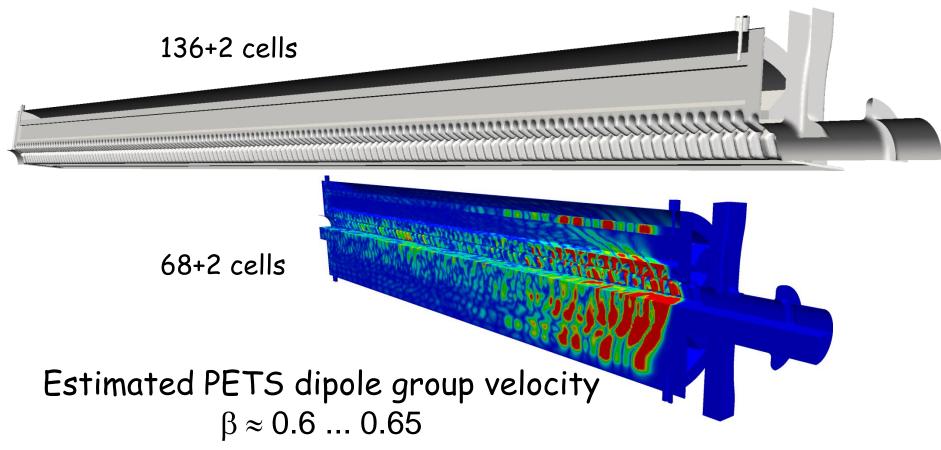




HFSS ACE3P comparison in accelerating structure

T3P: Needed for large structures

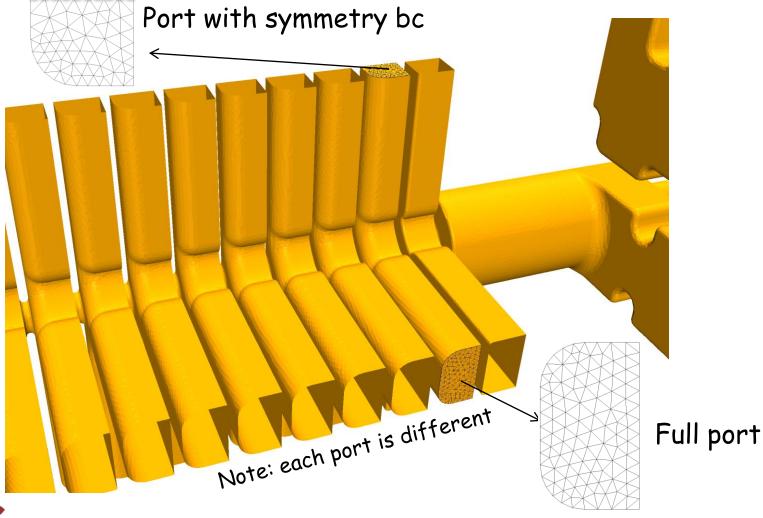
T3P is designed to model large structures with highest geometric fidelity via conformal (curved) meshes.





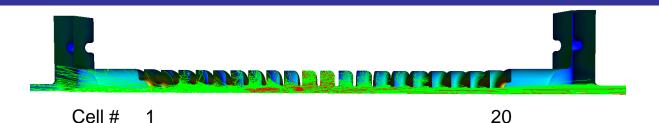
T3P Broadband Waveguide Boundary Conditions

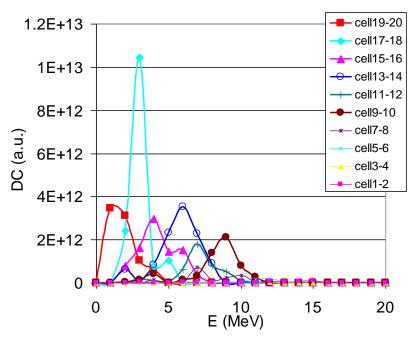
Step 1: Extract 2D mesh of waveguide ports





Energy of Captured Dark Current vs Location





Simulation

Electron energy as function of emission location.

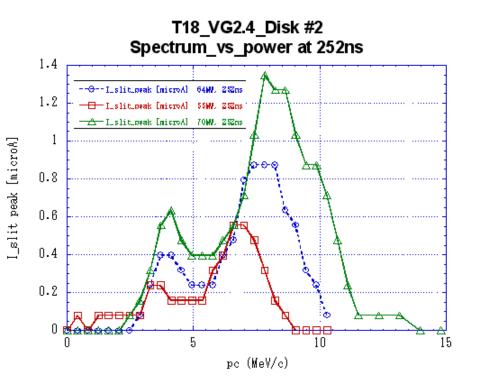
- Eacc=97MV/m.
- Higher cell number indicates downstream location

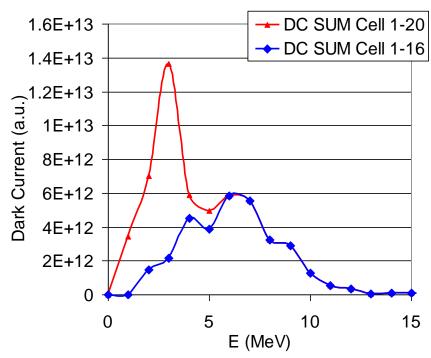
Electrons emitted upstream are accelerated to higher energy (monitored at output end).





Dark Current Spectrum Comparison





Measured dark current energy spectrum at downstream (need to scale by 1/(pc)

Spectrum from Track3P simulation, 97MV/m gradient.

"Certain" collimation of beampipe on dark current is considered in simulation data. More detailed analysis Needed.







rf absorbers



We need lots and lots of microwave absorbing material-both now and in the long term.

We now seem to have a stable supplier of SiC.

But working with SiC seems to be an activity with many surprises.

Our main collaborators in this activity are CIEMAT, EPFL, PSI and Tsinghua University.

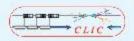
We look with interest in developments on HOM dampers for superconducting cavities – for example for energy recovery linacs.







S-par Measurements of Material in WG



Wave guides

S parameters measurement:

> HFSS + Measurements

(Ref. CLIC-NOTE-766)

Exploring New analysis method



Samples Preparation:

- ➤ Machining of samples
 - ➤ Different sizes (to define geometry effects)
 - ➤ Many samples to have statistics and non-homogeneity effects
- ➤ Measurements also after heat treatment (1000 Celsius)

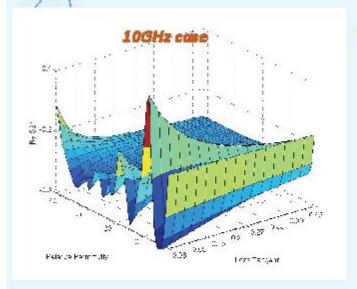






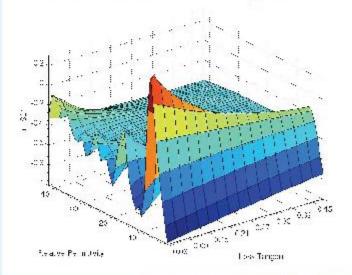






For defined geometry a scan over all possible values of Loss Tangent and Relative Permittivity we have:

Re and Im S21 and Mag S11



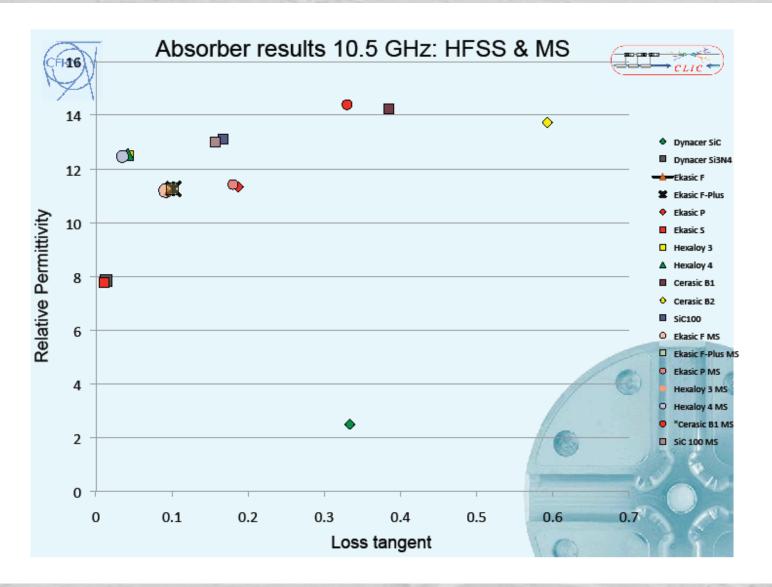
Measured transmission and reflection coefficients define intercepting plane

AT 10GHz ReS21= -0.178 and ImS21= 0.064
Goals come from measurements



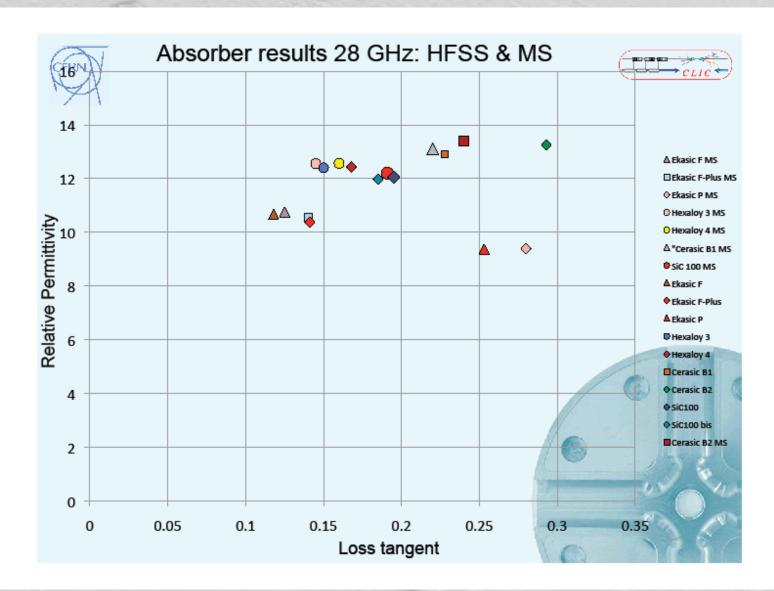














Simulation of high-power effects



We are promoting a collaboration dedicated to the fundamental study of high-gradient and high-power phenomenon. The main areas are breakdown, pulsed surface heating and high-power rf scaling laws.

A major breakdown simulation effort is lead by a group at the Helsinki Institute of Physics.

To compliment the simulation effort and rf tests, we have a dc spark system at CERN. Uppsala University is also preparing a dc spark system built into an SEM and ion beam microscope.

Experimental and simulation efforts are also occurring at the Institute of Applied Physics Sumy, Ukraine.

We are making good progress in understanding how to predict gradients in rf structures in a collaboration between CERN, SLAC and KEK.



Electrical Breakdown in multiscale modeling approach



M

N

E







Stage 1: Charge distribution @ surface *Method:* DFT with external electric field

~few fs





Stage 2: Atomic motion & evaporation

Joule heating (electron dynamics)

Method: Hybrid ED&MD model (includes Laplace and heat equation solutions)

~ sec/min





~ sec/hours

Stage 3a: Onset of tip growth; Dislocation mechanism

Method: MD, Molecular Statics.



Stage 3b: Evolution of surface morphology due to the given charge distribution

Method: Kinetic Monte Carlo

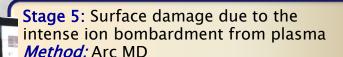


Stage 4: Plasma evolution, burning of arc

Method: Particle-in-Cell (PIC)

iversity of Helsinki





~100s ns





Flyura Djurabel

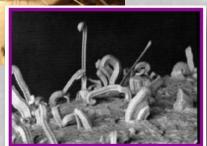
Step 3a: Are tiny whiskers possible?

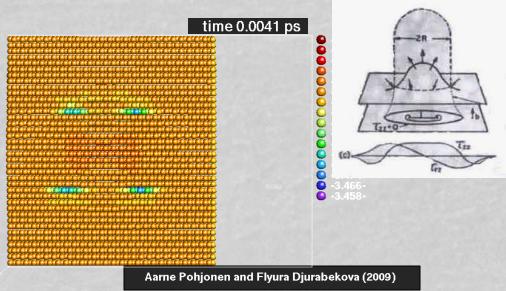
There is a number of mechanisms which might make the dislocations move coherently causing a directed mass transport, thus forming a whisker growth. We are looking for the most probable at our condition.

Stage 3a: Onset of tip growth; Dislocation mechanism

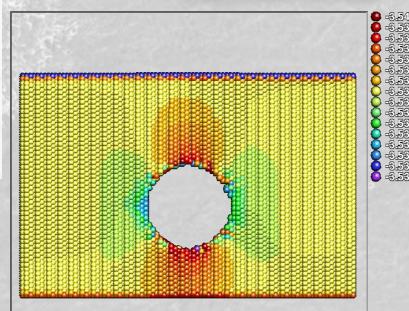
Method: MD, Molecular









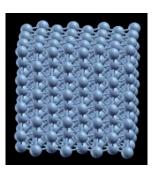


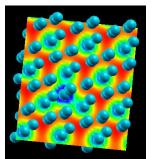


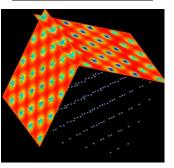




Stage 1: DFT Method for charge distribution in Cu crystal







- Writing the total energy as a functional of the electron density we can obtain the ground state energy by minimizing it.
- This information will give us the properties of Cu surface
 - Total energy, charge states (as defect energy levels)
- The calculations are done by SIESTA (Spanish initiative for electronic structure with thousands of atom)
- The code allows for including an external electric field
- The surface charges under the field are analyzed using the Mulliken and Bader charge analysis

Helga Timkó IWLC 2010 Oct. 21st, 2010

27



Stage 2: What about electrons?



At this high electric fields the field emission is non-negligible phenomenon.



- with the significant current will heat the sharp features on the surface, causing eventually their melting.
- The change of the temperature (kinetic energy) due to the Joule heating and heat conduction calculated by 1D heat equation

$$\frac{\partial T(x,t)}{\partial t} = \frac{K}{C_{V}} \frac{\partial^{2} T(x,t)}{\partial x^{2}} + \frac{\rho(T(x,t))J^{2}}{C_{V}}$$

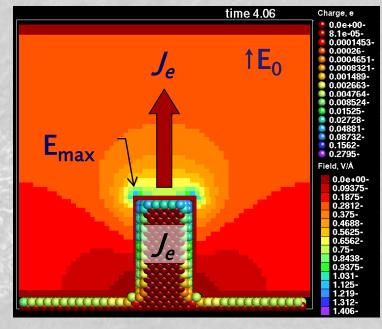
More details at Poster by Stefan Parviainen

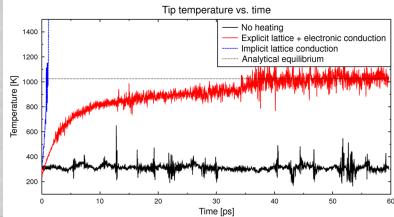
Flyura Djurabekova, HIP, University of Helsinki

Stage 2: Atomic motion & evaporation

-
Joule heating (electron dynami

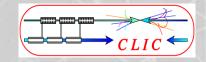
Method: Hybrid ED&MD model (includesLaplace and heat equation solutions)







Overview of the CLIC R&D program on breakdown continued

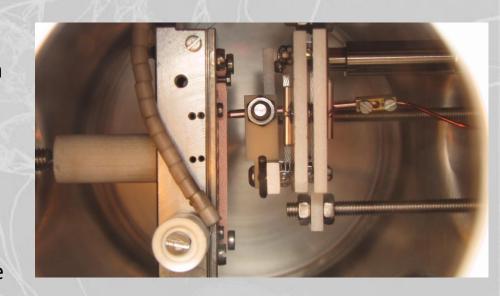


In order to increase our experimental capacity (and constrain speculation) we have also invested in two **dc** spark systems.

Advantages: The systems and samples are far cheaper than for rf. Easier to introduce alternative materials, new diagnostics, test ideas like temperature dependence etc. Easier to geometry to think about and to simulate.

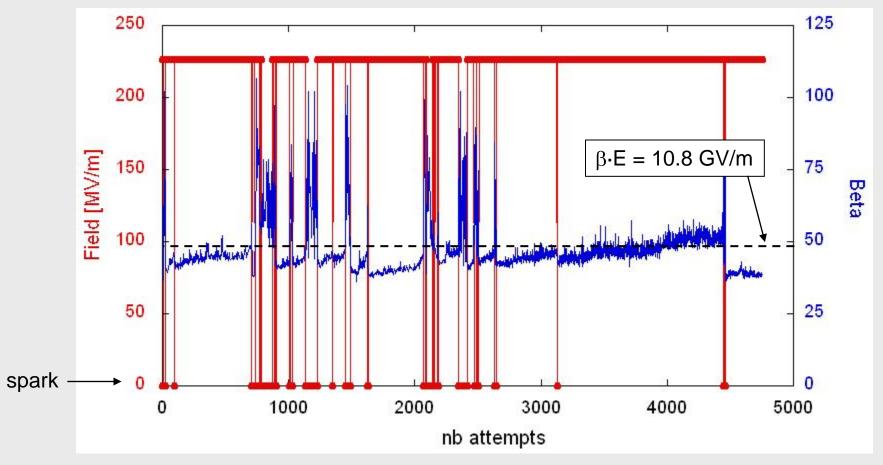
But aren't rf and dc sparks "different?" Mostly not and where they are - the total voltage, single polarity – the differences are telling us a lot.

Haven't lots of people done dc tests before? Yes, but we have many specific questions especially, what is the breakdown rate vs. field dependence and where does it come from? Also practical stuff like: What is our copper like or what effect does this surface treatment have?



Sergio Calatroni, 14:00 today

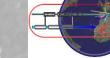
Evolution of β during BDR measurements (Cu)



- breakdown as soon as $\beta > 48$ ($\leftrightarrow \beta \cdot 225$ MV/m > 10.8 GV/m)
- consecutive breakdowns as long as $\beta > \beta_{\text{threshold}}$
- length and occurence of breakdown clusters \leftrightarrow evolution of β





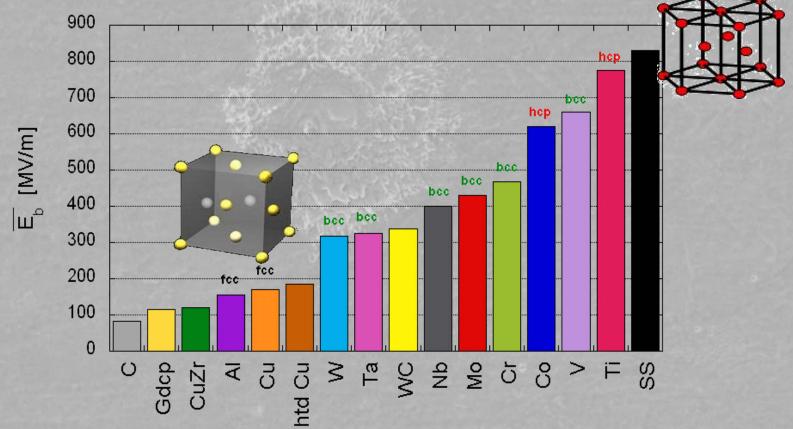


Recent experiment at CERN: CLIC-note





The dislocation motion is strongly bound to the atomic structure of metals. In FCC (face-centered cubic) the dislocation are the most mobile and HCP (hexagonal close-packed) are the hardest for dislocation mobility.



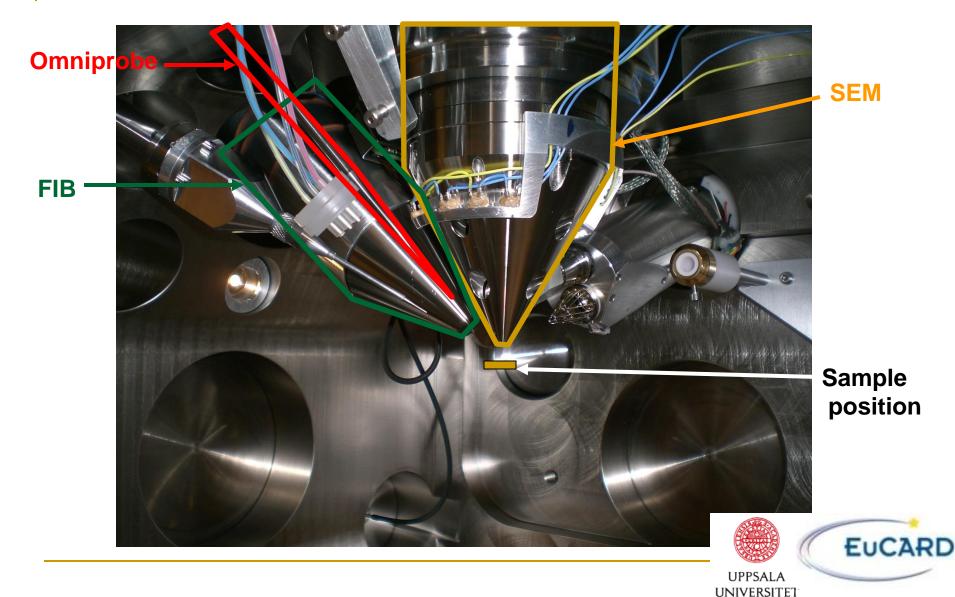
Instruments: FIB



- FIB: combined Focussed Ion Beam and SEM
- -> Create surface corrugations, pillars and tips with Focussed Ions,
 Observe surface both by SEM and by FIB
- 3D structure fabrication by FIB milling
- EDX (big cylinder)
- Omniprobe manipulator as a HV tip

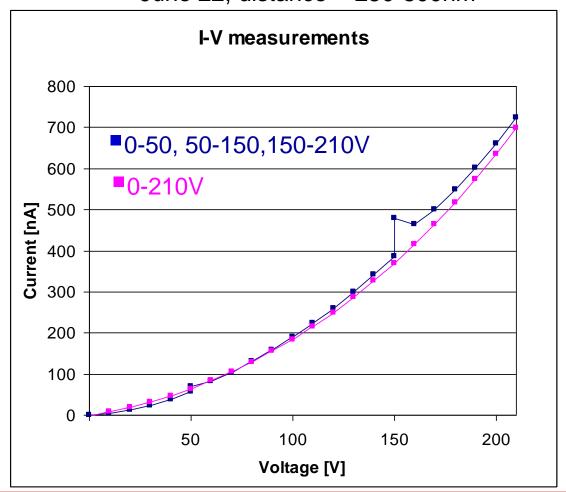


Instruments: inside view of FIB

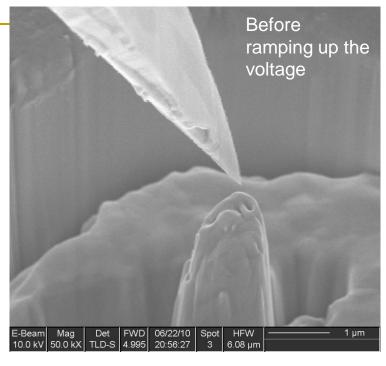


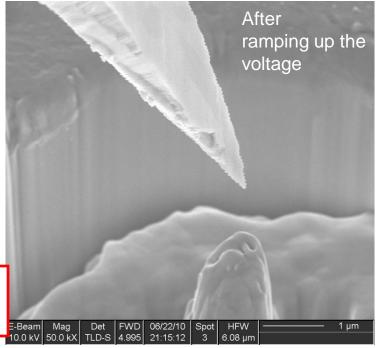
I-V measurements

June 22, distance ~ 250-800nm

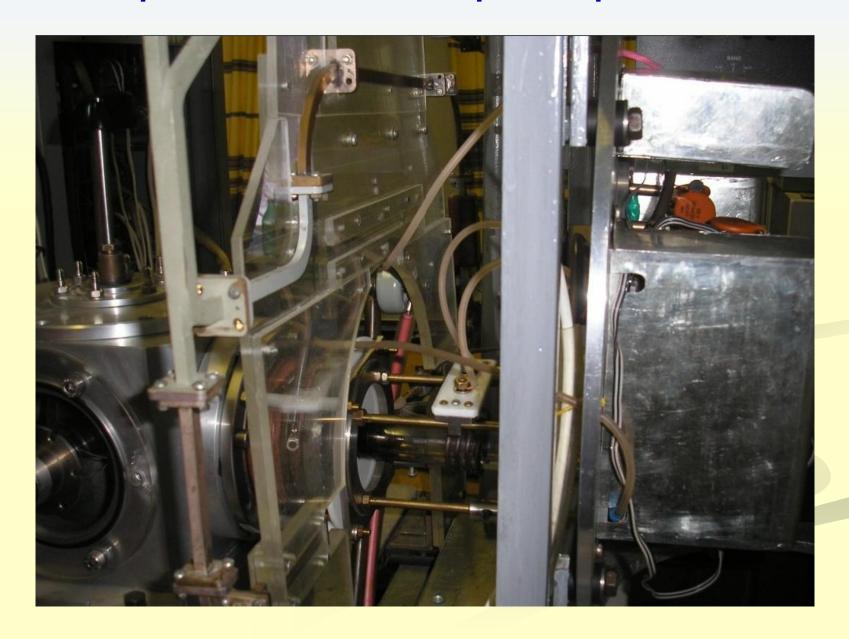


-Distance between the needle and the pillar changes - "Relaxation" of current has been observed





Setup for measurement of plasma parameters



Fluid model

Equations system of the two fluids hydrodynamics

$$\begin{split} div(n_{i}\mathbf{u}_{i}) &= n_{i} \Big(< v^{i} > - < v^{r} > \Big) \\ div(n_{i}\mathbf{u}_{i}\mathbf{u}_{i}) &= \frac{Z_{i}en_{i}}{m_{i}} \Big(-\nabla \varphi + \frac{1}{c} \Big[\mathbf{u}_{i} \times \mathbf{B}_{0} \Big] \Big) - \frac{1}{m_{i}} \nabla (n_{i}T_{i}) - n_{i} \frac{\delta \mathbf{u}_{i}}{\delta t} \\ div(n_{e}\mathbf{u}_{e}) &= div(n_{i}\mathbf{u}_{i}) \\ div(n_{e}\mathbf{u}_{e}\mathbf{u}_{e}) &= -\frac{en_{e}}{m_{e}} \Big(-\nabla \varphi + \frac{1}{c} \Big[\mathbf{u}_{e} \times \mathbf{B}_{0} \Big] \Big) - \frac{1}{m_{e}} \nabla n_{e}T_{e} - n_{e} \frac{\delta \mathbf{u}_{e}}{\delta t} \\ div \Big(\mathbf{q}_{e} + \frac{5}{2} n_{e}\mathbf{u}_{e}T_{e} + n_{e}\mathbf{u}_{e} \frac{m_{e}u_{e}^{2}}{2} \Big) &= -en_{e}\mathbf{u}_{e} \nabla \varphi + P_{abs} + \left(\frac{\delta (n < K >)}{\delta t} \right)_{st} + \left(\frac{\delta (n < K >)}{\delta t} \right)_{st} \end{split}$$

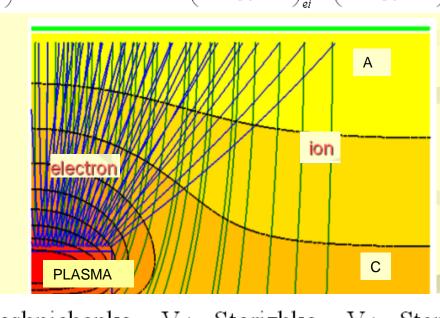
Poisson equations

$$-\nabla(\nabla\varphi) = \rho/s_0;$$

$$\rho = e(n_4 - n_2 - n_3).$$

Equation of motion

$$\begin{split} n_i \, \frac{\delta \mathbf{u}_i}{\delta t} &= \frac{1}{m_i} \Big(\mathbf{R}_{ia} + \mathbf{R}_{ie} \, + \mathbf{R}_{ie}^T \, \Big), \\ \mathbf{R}_{ia} &= -\mu_{ia} \nu_{ia} \mathbf{u}_i \, , \end{split}$$

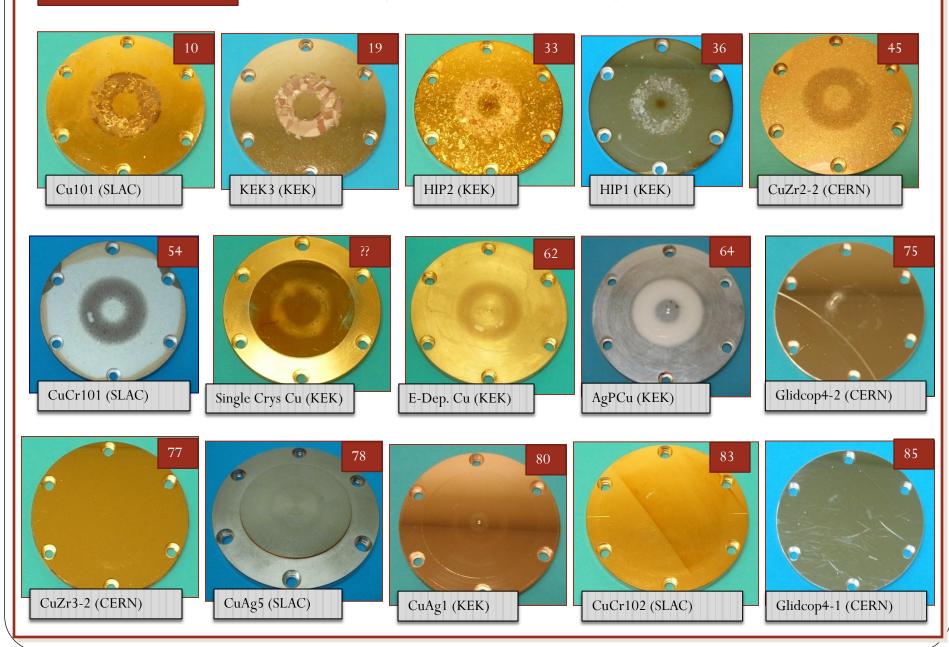


Mordyk, S.; Alexenko, O.; Miroshnichenko, V.; Storizhko, V.; Stepanov, K.; Olshansky, V. Investigation of rf power absorption in the plasma of helicon ion source//Review of Scientific Instruments, Volume 79, Issue 2, pp. 02B907-4 (2008).

Hardness Test Value

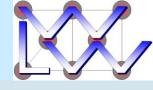
Lisa Laurent, SLAC

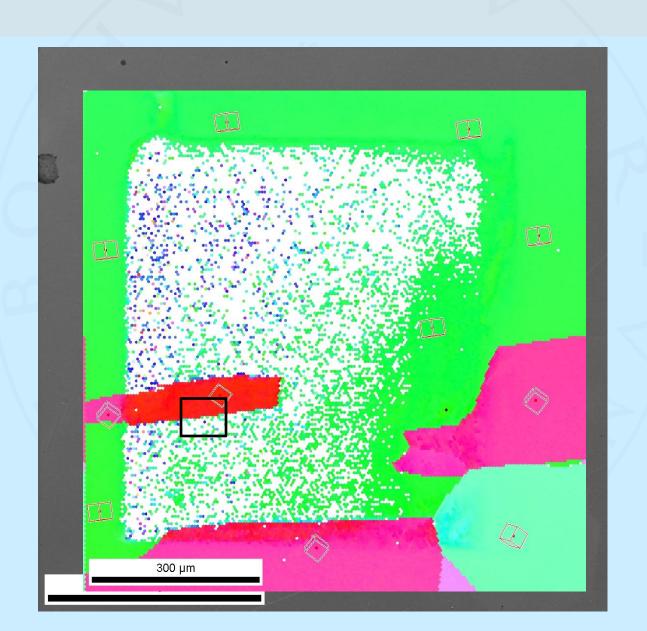
Pulse Heating Samples (CLIC09)

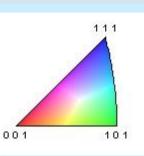


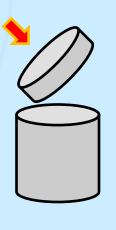


C10100_2h@1000_EP_45°Probe3_C1

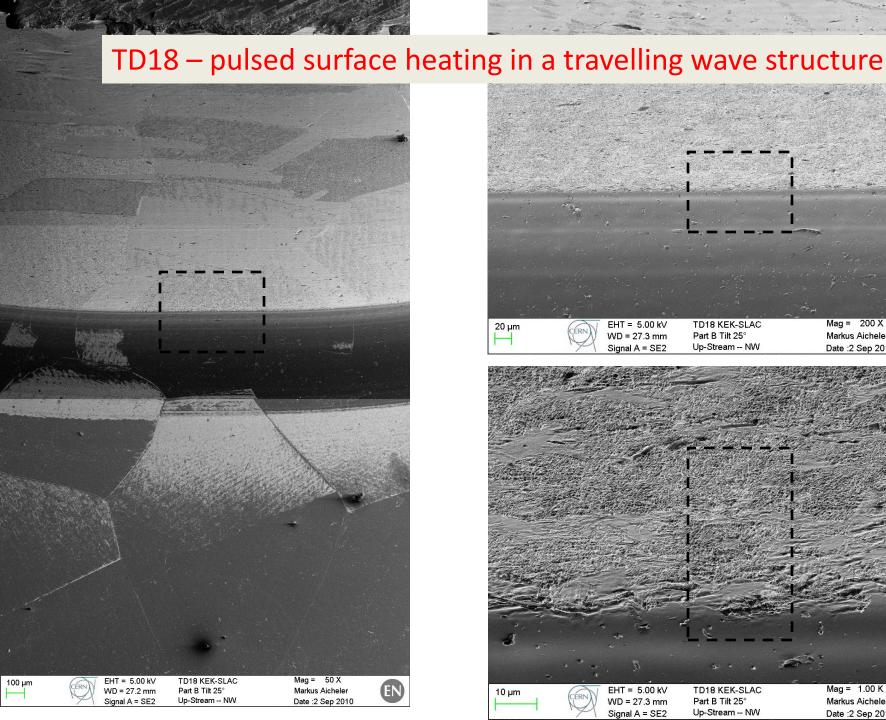


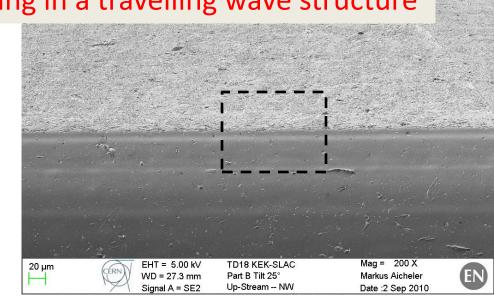


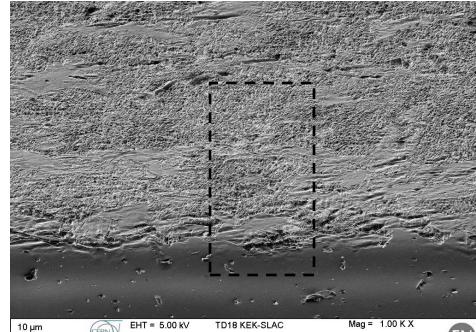




Markus Aicheler 15.10.2009







Part B Tilt 25°

Up-Stream -- NW

Markus Aicheler

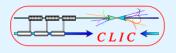
Date :2 Sep 2010

WD = 27.3 mm

Signal A = SE2



High-power rf theory and simulation effort



Over the past couple of decades computational tools have developed to the point that we can now accurately design complex, 3-D and even multi-moded rf structures.

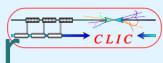
The ability to predict high-power performance has lagged behind:

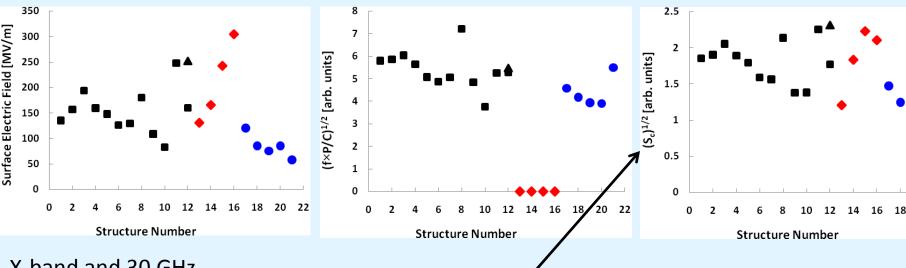
- A lot depends on preparation. But NLC/JLC made enormous progress in improving performance and reproducibility.
- The phenomena are extremely complex.

CLIC aims to run very close to the performance limit (for a given breakdown rate) so we had better understand the limit pretty well.



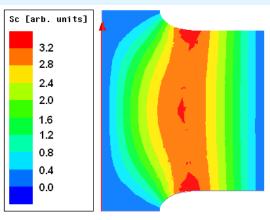
S_c: high-power design parameter





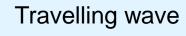
X-band and 30 GHz, pulses of the order of 100 ns.

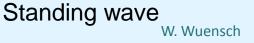
Travelling and standing wave

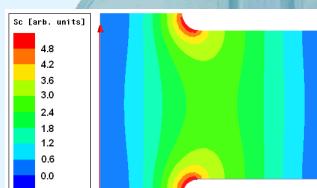


Related to the complex Poynting vector:

$$S_c = \Re \vec{S} \pm g_c \cdot \vec{S} \vec{S}$$







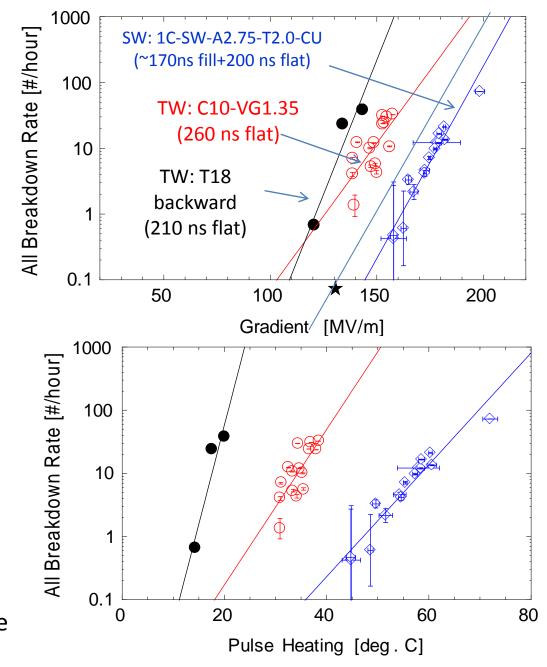
Geometrical studies

TW vs. SW: At low

breakdown rate < 5 *10⁻⁵/per pulse/meter (<10 per hour@60Hz) the statistical behavior of the SW and low group velocity TW structures is very similar but TW structures has ~20-30% lower gradient and about 2 times lower peak pulse heating.

Valery Dolgashev

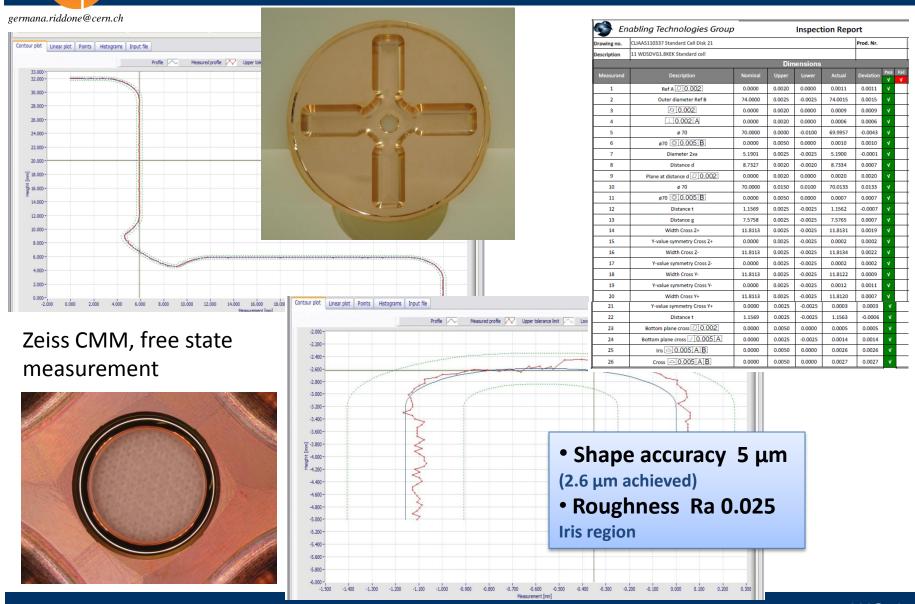
Breakdown rate vs. gradient and pulse heating for one SW and two TW structures with ~3mm aperture



C10 and T18 TW structures: R. Zennaro et al., Design and Fabrication of CLIC test structures, LINAC08



DETUNED DAMPED DISK FROM VDL (TD24)





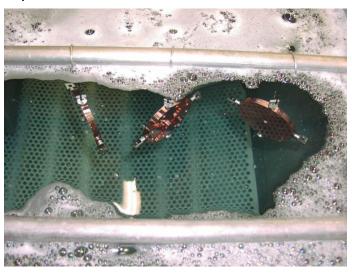
CLEANING PROCEDURE

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A. Degreasing with solvents Topklean MC 20A and Promosolv 71IPA



B. Degreasing with detergent NGL 17.40 spec. ALU III and ultrasound



C. Etching - Concentration :

- •phosphoric acid 70 %
- nitric acid 23.3 %
- •acetic glacial acid 6.6 %
- •hydrochloric acid 0.49 %



D. Final rinsing with demineralised water and ultrasound, followed by rinsing with ethylic alcohol and ultrasound

E. Drying and packaging



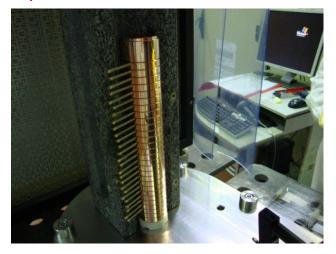
ALIGNMENT AND BONDING (T24@12 GHz)

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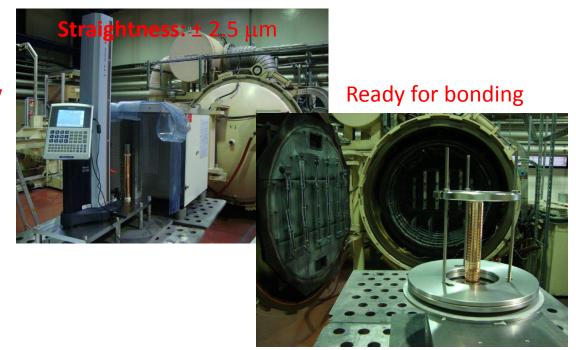
Individual inspection



Operation done under laminar flow



- Reference on the external diameter:
 - tolerance on external diameter: $\pm 2 \mu m$
 - tolerance on the ref. line : \pm 2 μ m
- Alignment on a V-shape vertical support in granite (accuracy of $\pm~1~\mu m$)
- Straightness measurements before and after diffusion bonding cycle





DIFFUSION BONDING PARAMETERS AND HEAT CYCLE

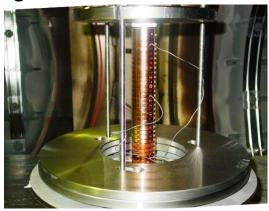
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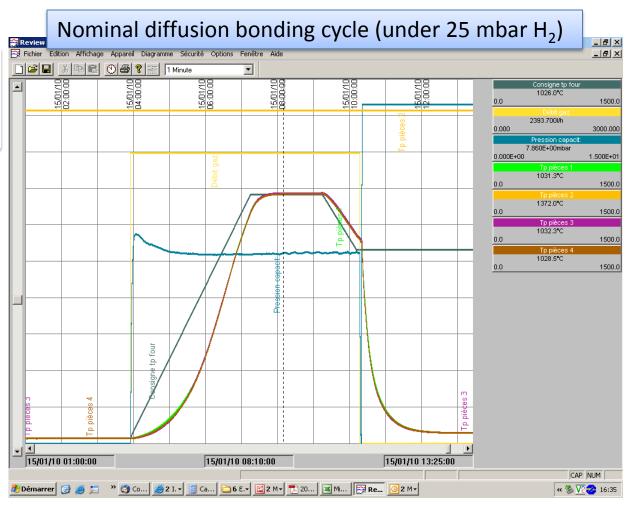
Temperature: up to 1040°C

Pressure: 0.28 MPa

Holding time: 2 h

New infrastructure to guarantee uniform load



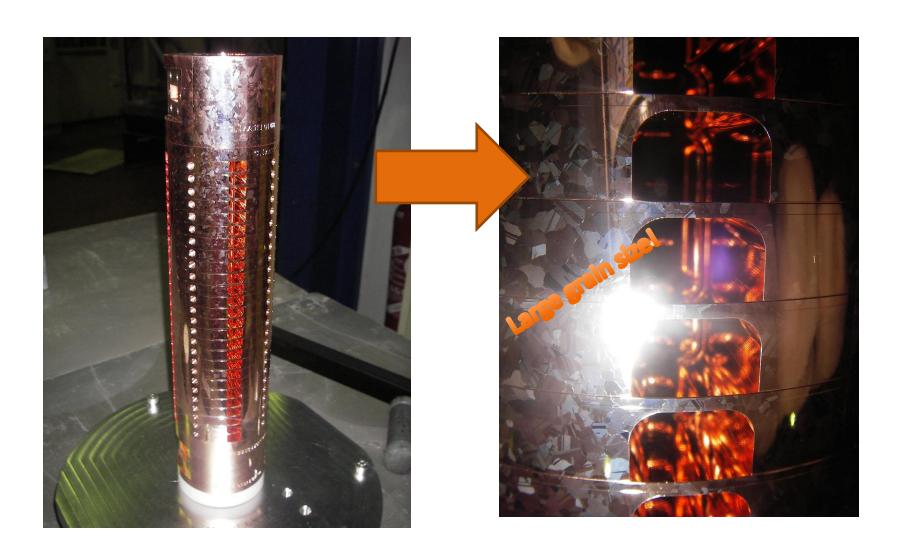


Straightness measurement after diffusion bonding: variations within \pm 1.5 μm



ACCELERATING STRUCTURE AFTER DIFFUSION BONDING

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CLEAN ROOM FOR ASSEMBLY AND MEASUREMENTS

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