

The ILD concept

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on behalf of the ILD concept group

IWLC 2010 Genève not to be confused inadvertently with the International Women's Leadership Conference





What has driven the ILD conception?

The main features of the concept

The ILD group

Preparing for the DBD, where do we go, where do we stay.

A large effort stemming from the R&D developments taking place in the R&D collaborations (see JC.Brient talk).



What has driven the ILD conception?

Physics aims

The physics under consideration: everything you can dream of seeing, directly or indirectly produced in the energy range under consideration, Z to TeV.

Specific goals: top, Higgs properties, sleptons, WW scattering, Z' s...

To maximise the use of the luminosity, we need an efficient and precise detector

We want an excellent lepton identification and measurement but we need to exploit fully the hadronic decays of the bosons, W, Z, H.

To extract the best out of each sub-system, vertexing, tracking, calorimetry optimally combining their informations we intend to design the detector along the principles of PFA:

measure at best in the relevant sub-system the different particle species isolated or in jets, which means first separating them.



Accelerator constraints

The detectors have to cope with a certain number of constraints coming from the accelerator design:

the energy range, from the Z peak to 1 TeV, a lot of particles is at low energy, but high tails

the time structure, long trains (1ms) at 5Hz. offers power pulsing possibility

the crossing angle, may impose, together with background a DID, generates an asymmetry

the beamstrahlung, induces a flux of pairs to be contained by a large B,

the L*, the last quadrupoles sit inside the detector, hermeticity, vibrations

But also the constraints coming from the hall design, deep or not, ...

and from the concept of <u>push-pull</u>, what do we gain, what do we loose? Can we switch the detectors fast enough not to waist luminosity? What is the impact on the detector design?



Henri Videau IWLC 2010 Genève

Design N.S. ETH-Z, January 2009.



The main features of the concept

It is meant to be not a collection of beautiful sub-systems but a detector globally optimised and integrated

We try to reach an equilibrium between very advanced technologies developed in R&D collaborations and a strong integration in ILD.

The driving idea: A strong commitment to the "image quality" precision, resolution

a question of topology



Large

precise and redundant for pattern offering as much as possible a continuity: TPC, tracking calorimetry hermetic, small angle coverage, no pointing cracks, thick enough reduce inefficiencies and fakes.

Some sub-detectors exist in different options



The main features of the concept

Global mechanical design

a cylindrical aspect with a barrel and two end caps a strong axial field (3.5T) at 7mrad with the beams

meant to provide good p_T measurement and

to keep the background inside the beam tube

a heavy return yoke

to keep the stray field acceptable for the others. Muon detection

an inner ensemble of detectors in silicon, vertex detector, intermediate and forward tracking efficiency at low p_T, precise impact parameter, transparency

a large (180 cm) TPC for tracker,

redundancy and dE/dx, V⁰'s, backscattering, electrons transparency, distortions, track resolution (for eg taus in 3 prongs) backed by a silicon envelope

a calorimeter inside the coil, in two sections electromagnetic and hadronic, with a very fine grain, 25mm² for ecal, 1 to 9 cm² for the hcal digital or analogue

a calorimeter closing at small angle: luminosity monitor, Lhcal, beam cal





The number of electronic channels is very large, e.g. ~10⁸ for calorimeters and the front-end (including digitalisation) is embedded in the detector There is no global trigger, each channel is self-triggered. The power consumption , hence the heat, is reduced by power pulsing

The full detector is simulated in detail in a Geant4 application: MOKKA

A common software framework, MARLIN, hosts the reconstruction tools



ILD is not a formal collaboration with clear commitments but rather a congregation or a partnership between individuals more than institutions to produce a realistic design for a detector.

> It has a light organisation: JSB for more political issues Executive Board for more technical points, congressional meetings.

A common spirit rather than a common structure

It has produced a Letter of Intent accepted by IDAG and goes for something more elaborate and more proven from the technical point of view:

a DBD

The LoI has been signed by hundreds of people from all around the world



Our roadmap for publishing in 2012 a Detector Baseline Document has been defined by the Research Director

We can extract the following:

Demonstrate proof of principle on critical components.

When there are options, at least one option for each subsystem will reach a level of maturity which verifies feasibility.

Define a feasible baseline design.

While a baseline will be specified, options may also be considered.

- Complete basic mechanical integration of the baseline design accounting for insensitive zones such as the beam holes, support structure, cables, gaps or inner detector material.
- Develop a realistic simulation model of the baseline design, including the identified faults and limitations.

Following these lines



It is the role of ILD to select technologies proposed by R&D collaborations to fulfil the needs of the design described above. It is the role of these R&D collaborations to bring the proof of principle. The procedure for selecting an item is not yet defined but contains surely: the proof of principle the demonstration that it can be properly integrated in the detector, mounted, serviced the existence of a detailed simulation and a proof of performances

The agreement on putting an option in the baseline implies certainly the existence of reviews asserting the state of these options, we start discussing their organisation.

An important step is to provide a global model of detector implementing the different options in situ with all their services.

The way ILD has chosen is to elaborate a global CAD model integrating contributions by the different sub-detectors. To make available the related information and in particular dimensions, a structure has been created in the ILC-EDMS

Enforcing the compliance

A parallel step is to provide a detailed simulation for every option, in adequacy with the CAD.



Goal: Handling and sharing ILD information parameter definition, CAD models, simulation models, technical documents





EDMS has a viewer to manipulate the models and compare them.

Comparing Simulation and Detailed Model (1)



Example: superposing ECAL CAD with simulation

CAD and MOKKA provide 3d pdf of their models





The ongoing effort in designing globally the detector is in two steps

From the actual proposals for sub-detectors, derive their envelopes, and define the corresponding place holder. Publish them. The different options have then to fit in the corresponding place holders ensuring that there is no conflict.

The second step consists in defining the space needed for services: cables, cooling, etc. and make sure that there is no conflict. The space taken by the services is part of the evaluation of options since it may have a direct impact on physics for example dead material in the inner part of the detector or region between barrel and end cap.

There has to be a schematics for assembly, and for accessing parts for maintenance this implies ways to get the services into the different regions and places to disconnect

The detailed simulation will contain these pieces to infer their impact.



Defining the dead zones and the materials

Defining the minimal gaps between sub-detectors

Implementing dead zones and materials, imposing gaps in the simulation model

up to what detail?

Dead material

Services:

cables (size and number) cooling pipes supports and screens Electronics protruding out of the space holders Sub-detectors supports Patch panels needed for assembly or maintenance

Gaps

Space for services, supports, screens, patch panels Space for assembling tools Watching plays imposed by construction alignment, mechanical deformations,

Example of services crossing the overlap region





Transposing in the simulation





We are currently elaborating all the elements of a **software** baseline

i.e. a baseline to run large samples of events for a fine tuning of the defined benchmarks and any reaction likely to measure the physics impact of still pending options.

We intend to have an iteration of discussions by May 2011 in KEK and get to a final baseline at the latest at the time of the LCWS 2011 in Granada

The proper evaluation of options will take place later but we will have first to identify where we lack an option.





